

Probing the interstellar magnetic field with LOFAR

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Outline

- Introduction
- Investigation of magnetic field with RM synthesis technique
- Behavior of RM in ionosphere and ISM
 - Results and Discussion

The role of Magnetism in the Universe

In Cosmology:

- Origin of magnetism (e.g. via RM of CMB)
- Role in birth of first star and galaxies

In everyday astrophysics:

- Dynamics of cosmic rays
- Extremes of dynamo theory
- Physics of active galaxies and SMBHB
- Influence on formation processes of stars, supernovae explosions



Credit: Bryan Gaensler

Different ways of magnetic field investigation

- Optical starlight polarization B_{\perp} (*orientaton, but not direction*)
- Synchrotron emission/polarization
- Zeeman splitting B_{\parallel} (*really high magnetic fields*)

Different ways of magnetic field investigation

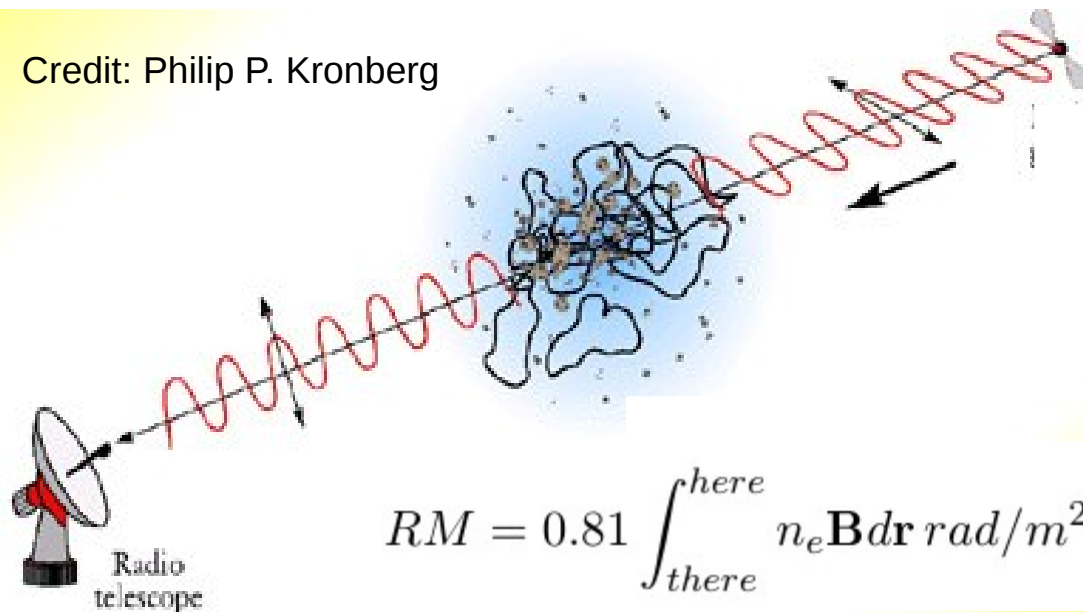
- Optical starlight polarization $B \perp$ (orientaton, but not direction)
- Synchrotron emission/polarization
- Zeeman splitting $B \parallel$ (really high magnetic fields)

- Faraday rotation

$$\psi = \psi_0 + RM\lambda^2$$

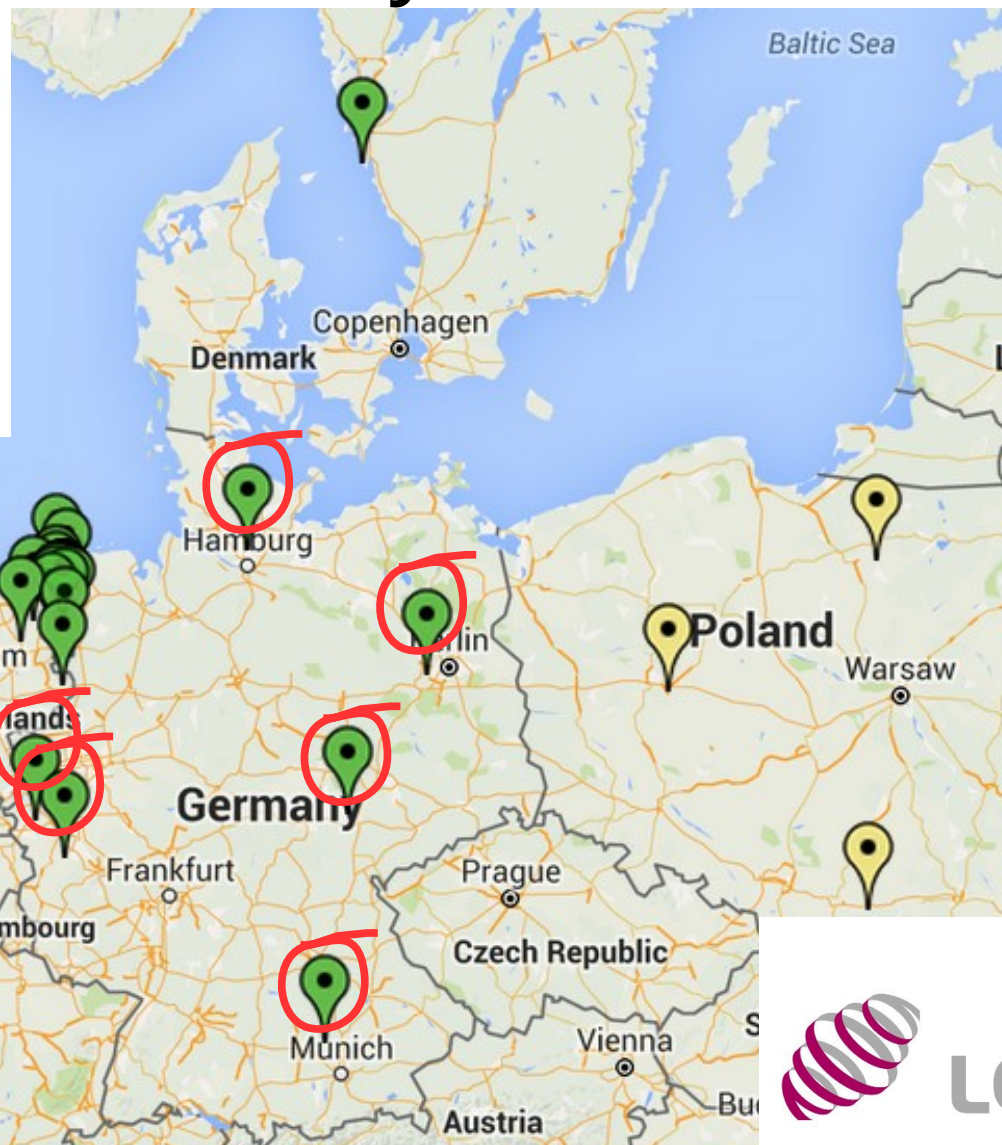
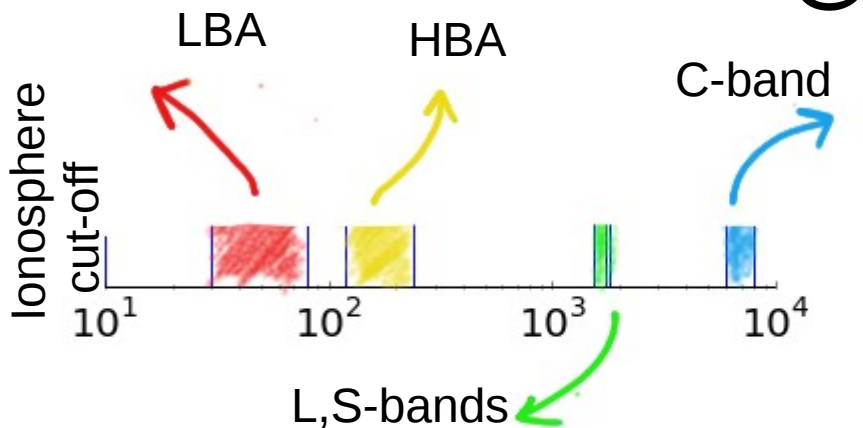


Credit: Philip P. Kronberg

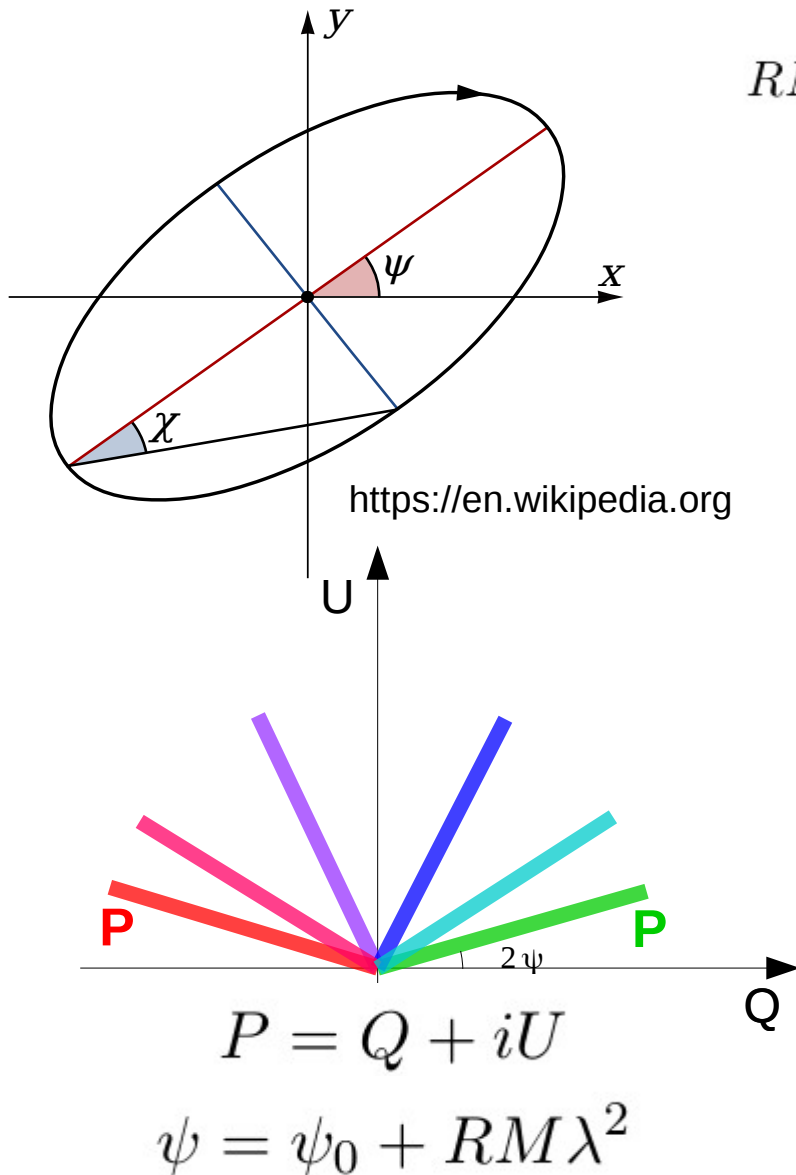


$$RM = 0.81 \int_{there}^{here} n_e \mathbf{B} dr \text{ rad/m}^2$$

GLOW: LOFAR found shelter in Germany



RM synthesis: brief theory



$$RM = 0.81 \int_{there}^{here} n_e \mathbf{B} d\mathbf{r} \text{ rad/m}^2$$

$$E_x, E_y, \delta$$

↓

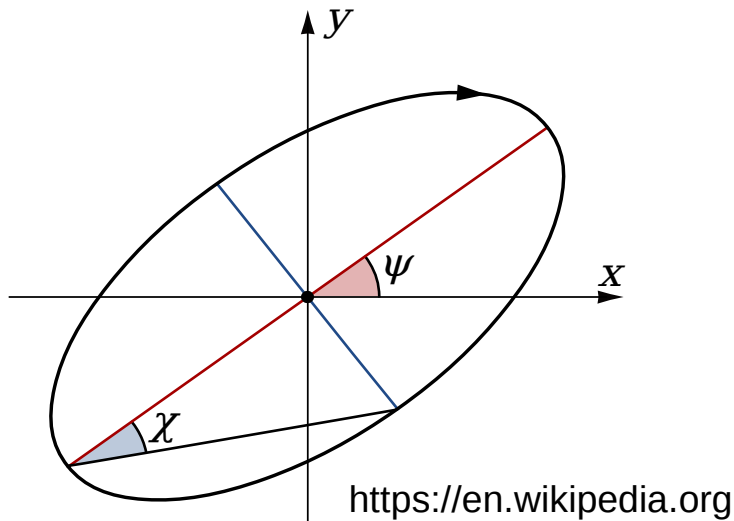
$$I(\lambda^2)$$

$$Q(\lambda^2) = I \cos(2\chi) \cos(2\psi) = I_L \cos(2RM\lambda^2)$$

$$U(\lambda^2) = I \cos(2\chi) \sin(2\psi) = I_L \sin(2RM\lambda^2)$$

$$V(\lambda^2) = I \sin(2\chi)$$

RM synthesis: brief theory



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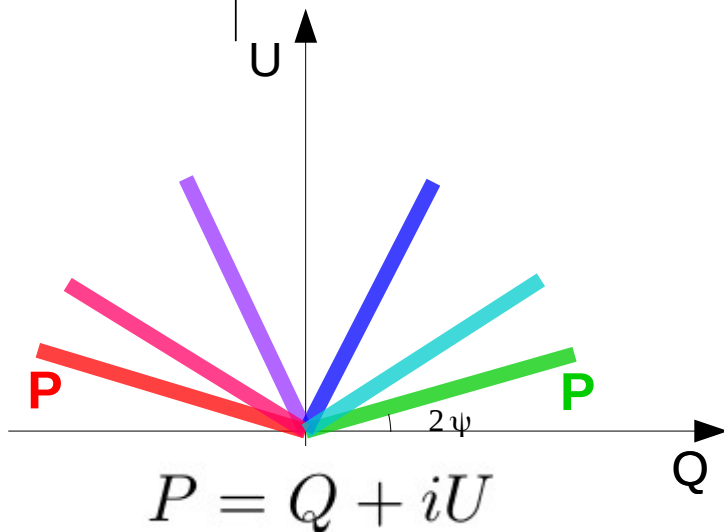
↓

$$I(\lambda^2)$$

$$Q(t) = I \cos(2\chi) \cos(2\psi) = I_L \cos(2\omega t)$$

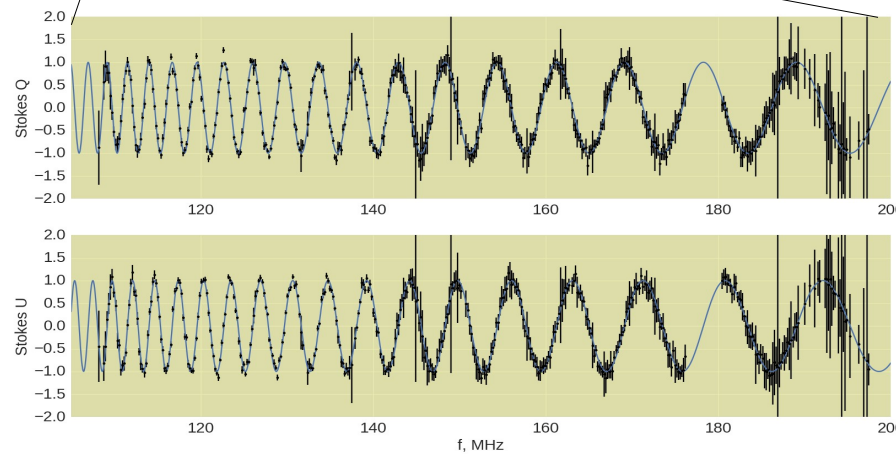
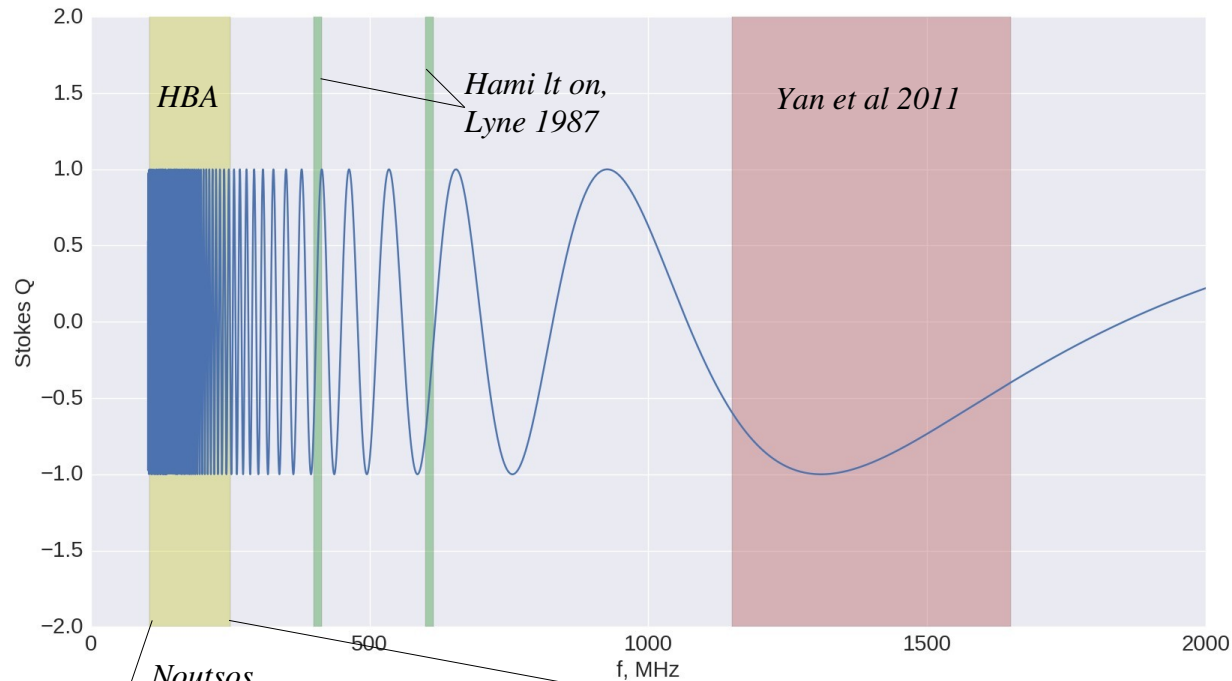
$$U(t) = I \cos(2\chi) \sin(2\psi) = I_L \sin(2\omega t)$$

$$V(\lambda^2) = I \sin(2\chi)$$



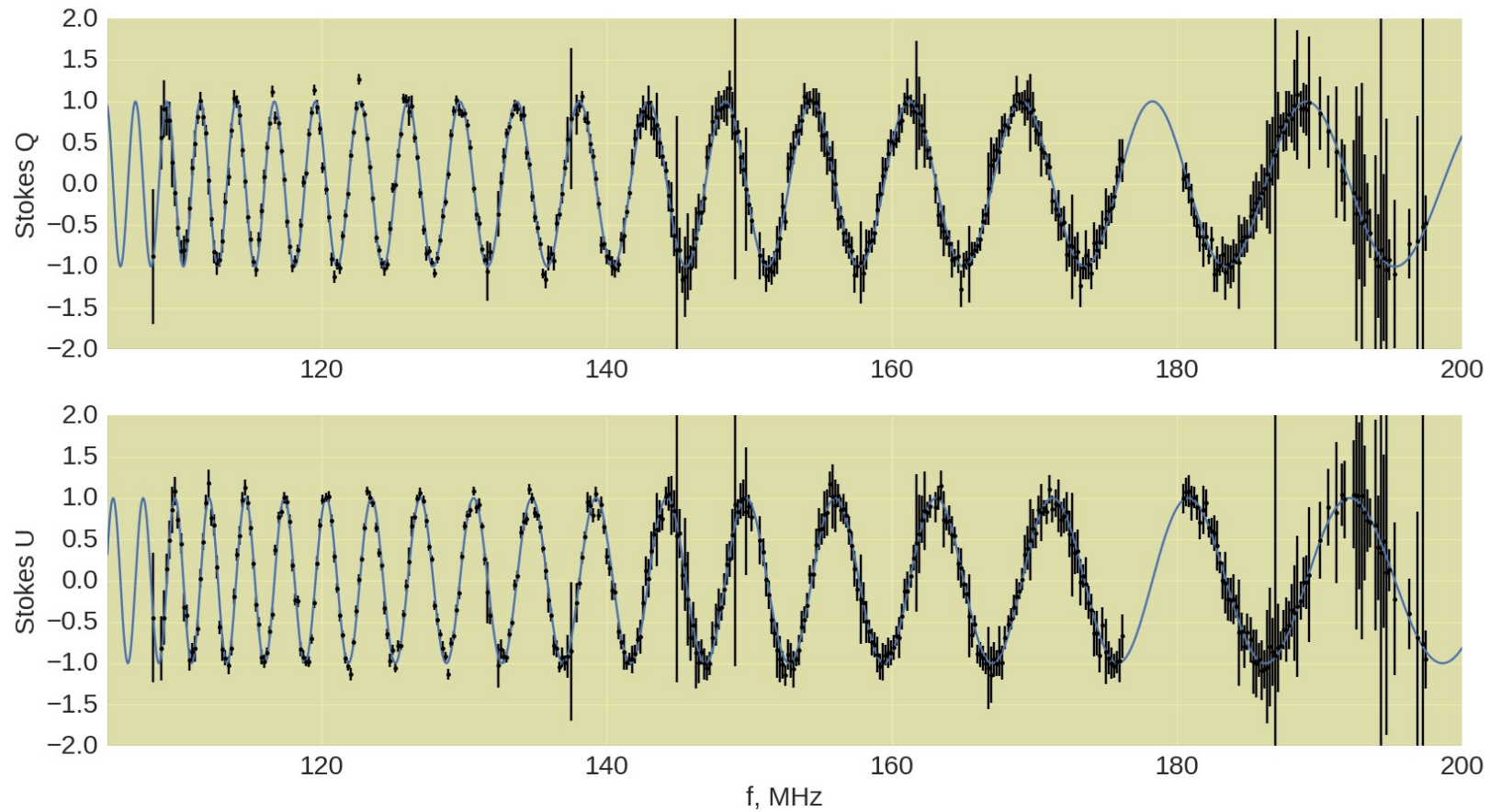
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Q and U Stokes: examples



Bandpass is particularly good for **investigation of ISM effects** (DM, RM, scintillations, scattering)

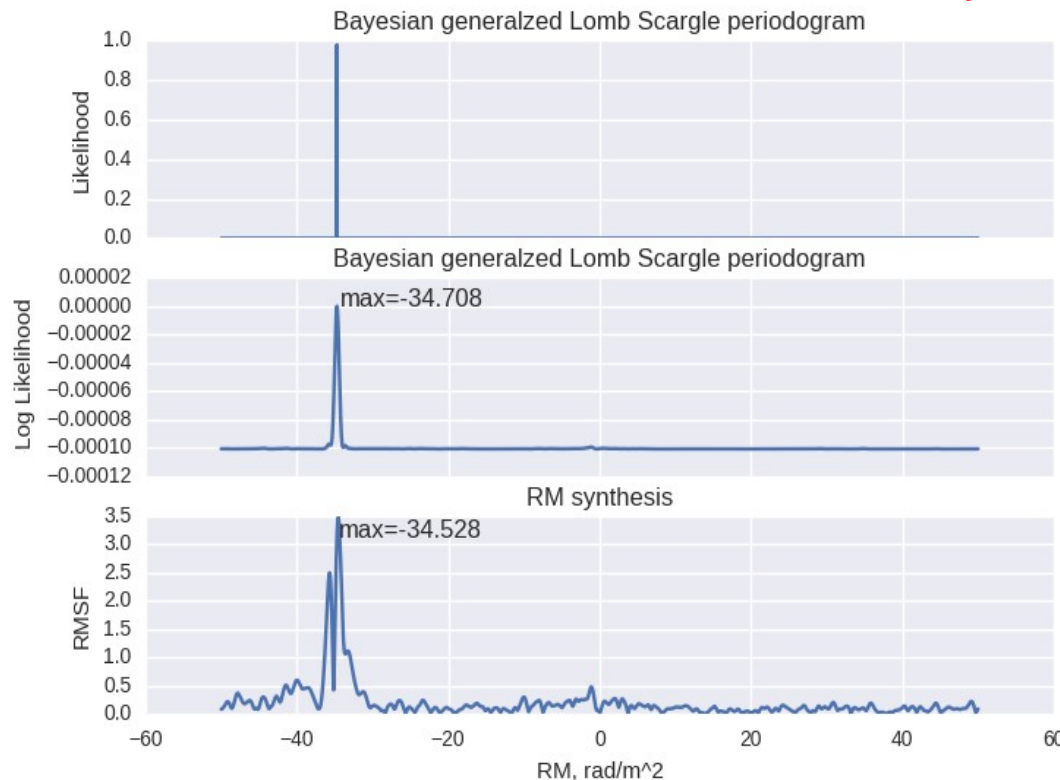
Q and U Stokes: examples



Bayesian LSP vs RM synthesis

- Works with unevenly sampled data
- Accounts for error bars
- Correct estimation of the error

Results for J2219+4754,
 $RM \sim -34 \text{ rad/m}^2$



Bretthorst 2001, Mortier

$$P(RM | data) \sim \int P(RM, A, B, \gamma_{\text{I}}, \gamma_{\text{R}} | data) dA dB d\gamma_{\text{I}} d\gamma_{\text{R}}$$

Posterior probability

Discrete Fourier transform

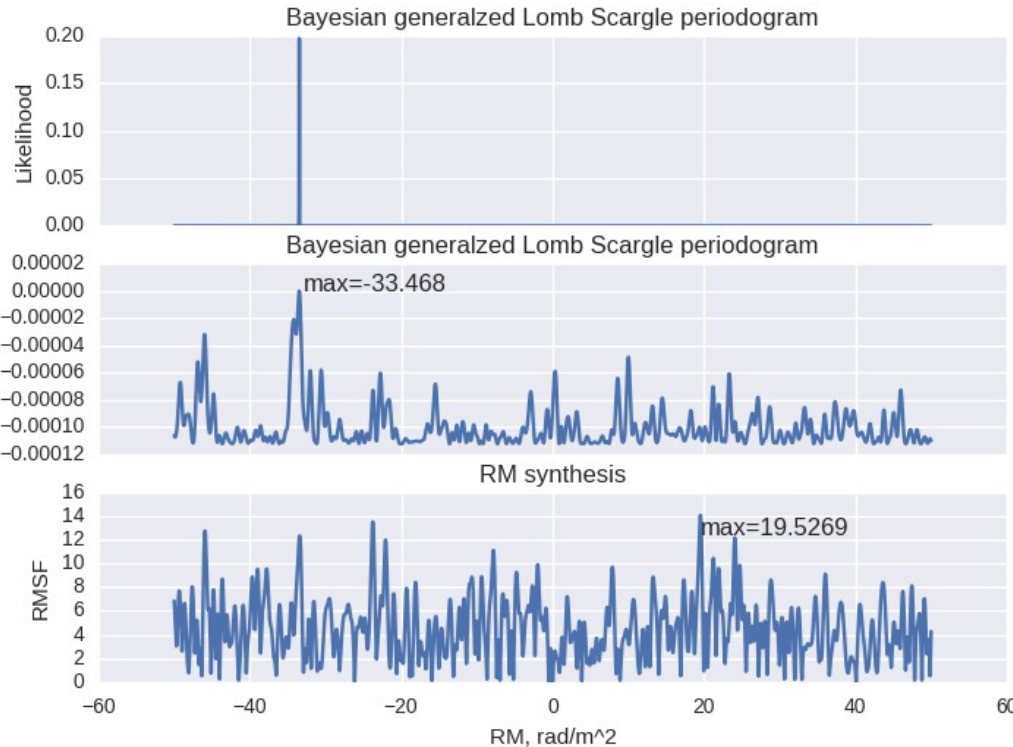
$$S(RM) \sim \left(\sum P(\lambda^2) \exp(-2RM\lambda^2) \right)^2$$

Burn 1966, Brentjens and de Bruyn 2005

Bayesian LSP vs RM synthesis

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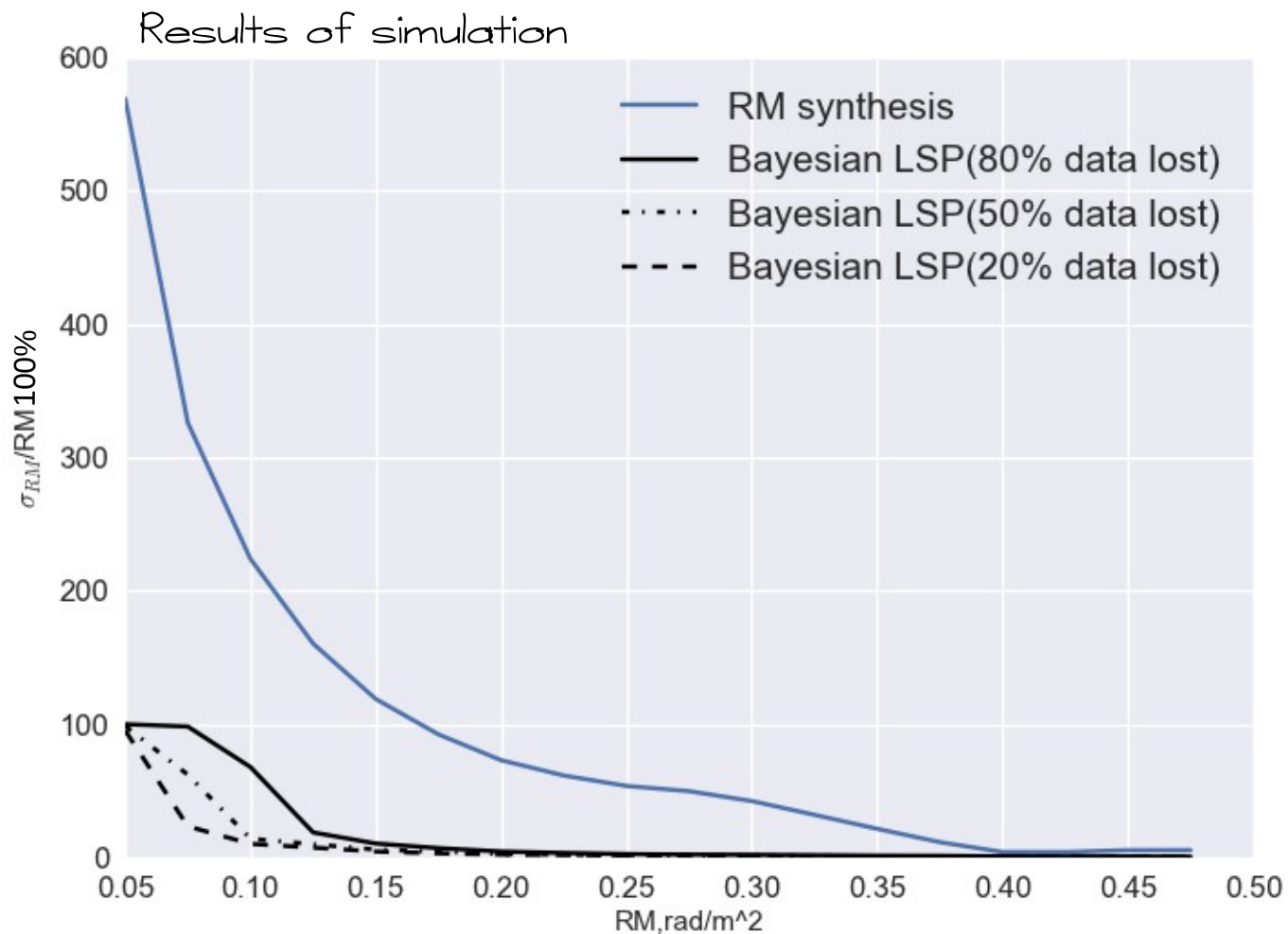
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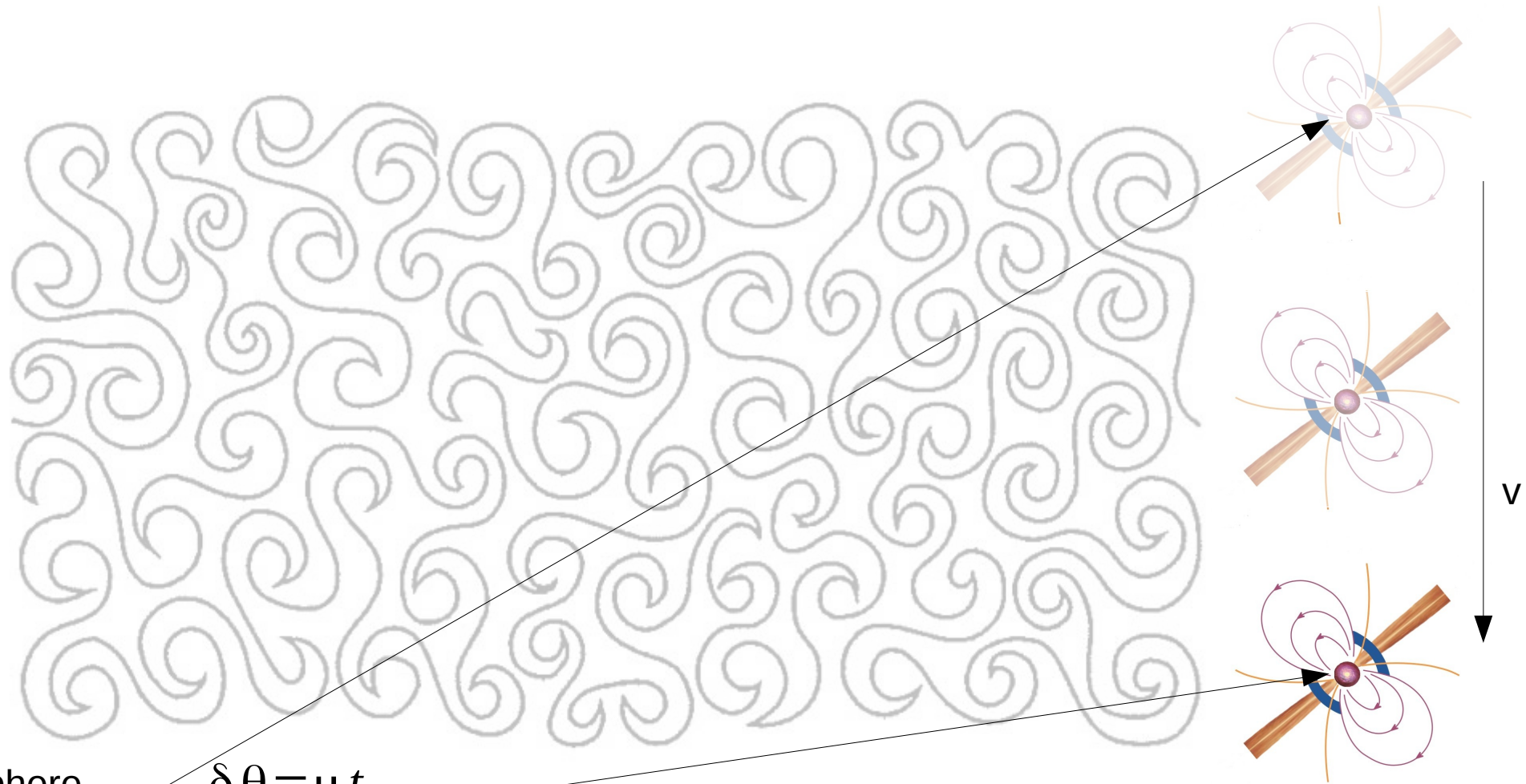


To do:

Determine
significance
of the pick!

Schnitzler et al, in prep.

Sources of RM variations












Ionosphere

$$\delta\theta = \mu t$$

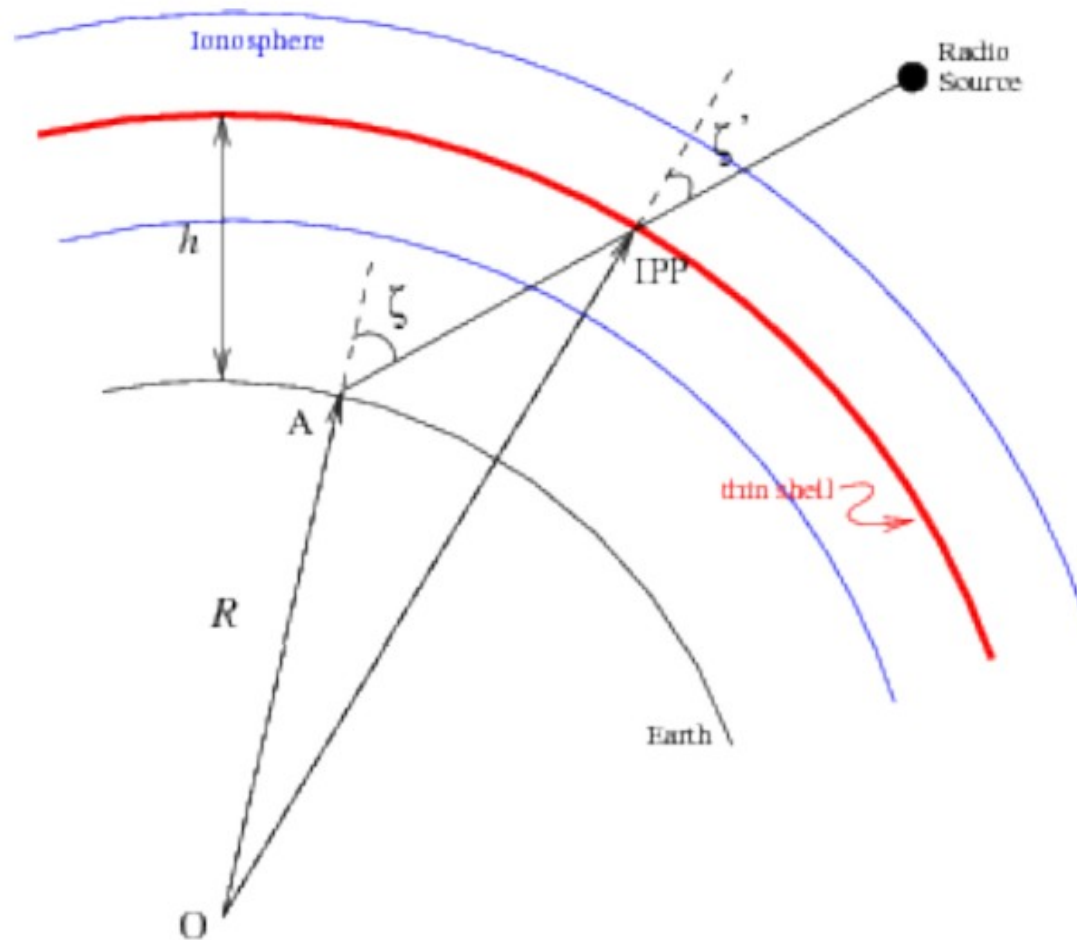
Earth

Sources of RM variations

- For ionosphere we are using ionFR script with

ROBR data         

<http://sourceforge.net/projects/ionfr/>,
Sotomayor-Beltran et al, 2013



Sources of RM variations

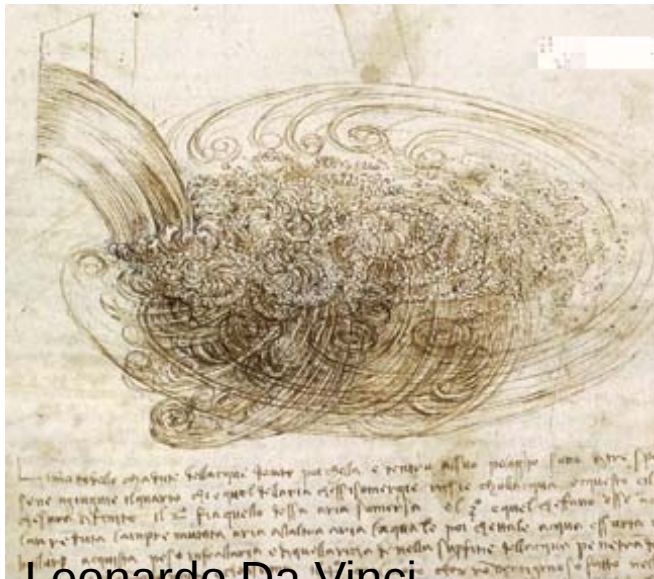
- For ionosphere we are using ionFR script with

ROBR data  <http://sourceforge.net/projects/ionfr/>,
Sotomayor-Beltran et al, 2013

- For ISM we assume red noise energy wavenumber spectrum for both magnetic field and electron density

$$E_n = C_n^2 \left(\frac{k}{k_0} \right)^\alpha$$

$$E_B = C_B^2 \left(\frac{k}{k_0} \right)^\beta$$



Leonardo Da Vinci

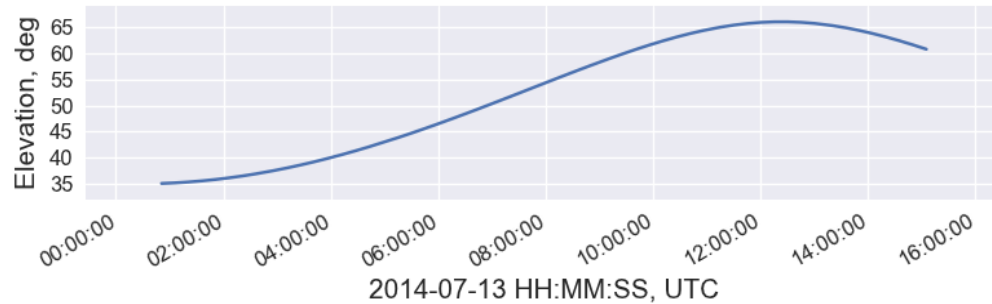
$$D_{RM}(\delta t) = \langle [RM(t) - RM(t + \delta t)]^2 \rangle$$

Minter, Sapgler 1996, Haverkorn 2008

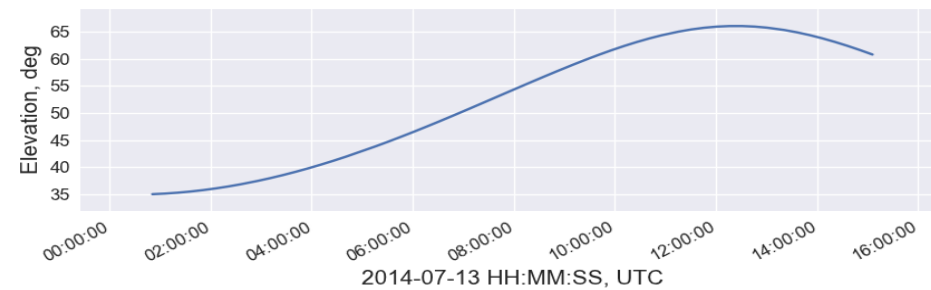
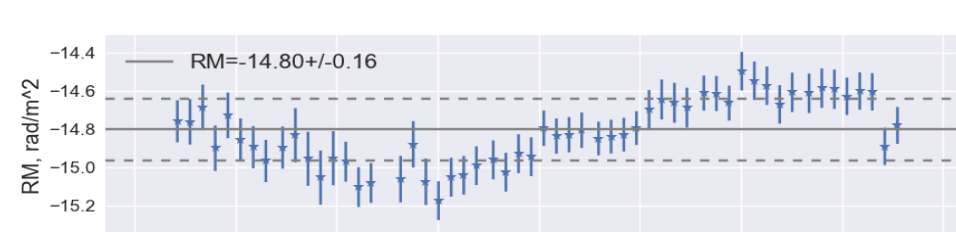
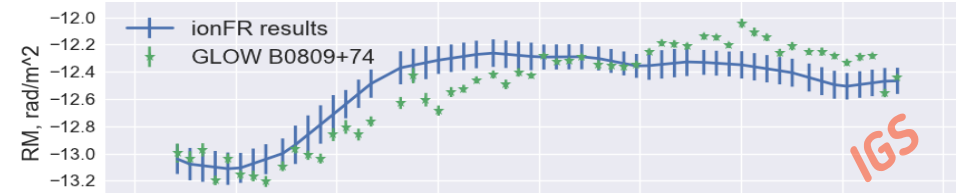
$$C_{RM}(\delta t) = \langle [RM(t)RM(t + \delta t)] \rangle$$

IonFR implementation

Rotation measurement B0809+74



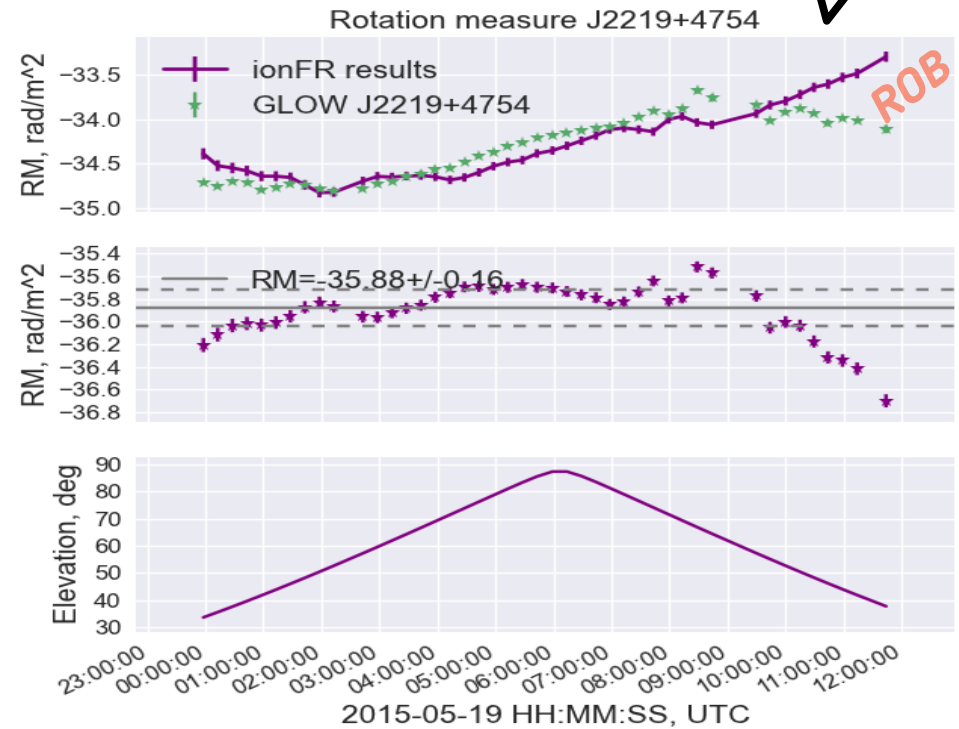
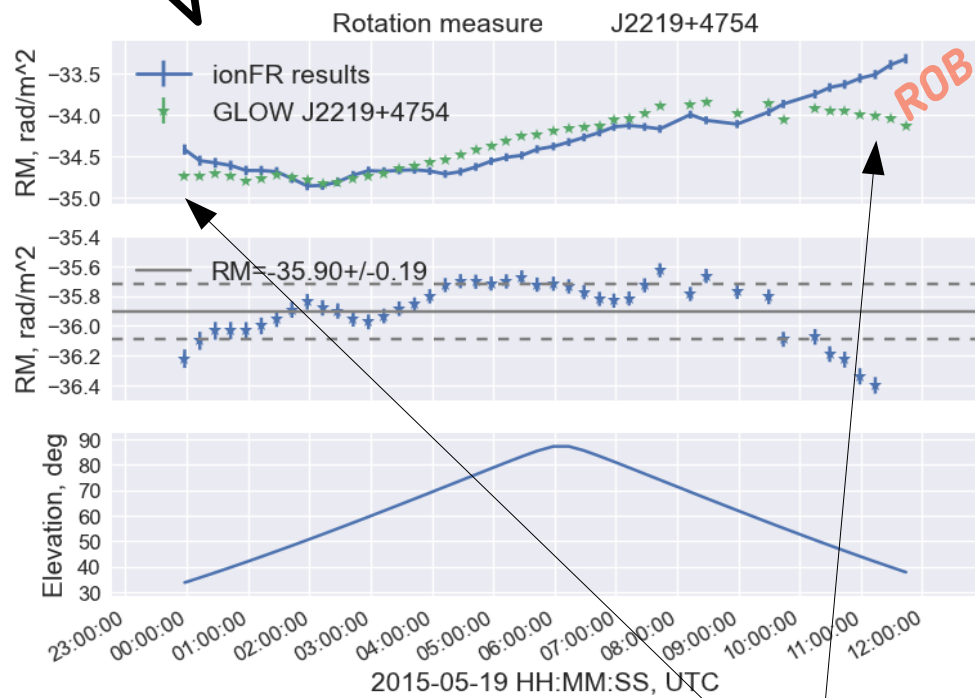
Rotation measurement B0809+74



IonFR implementation

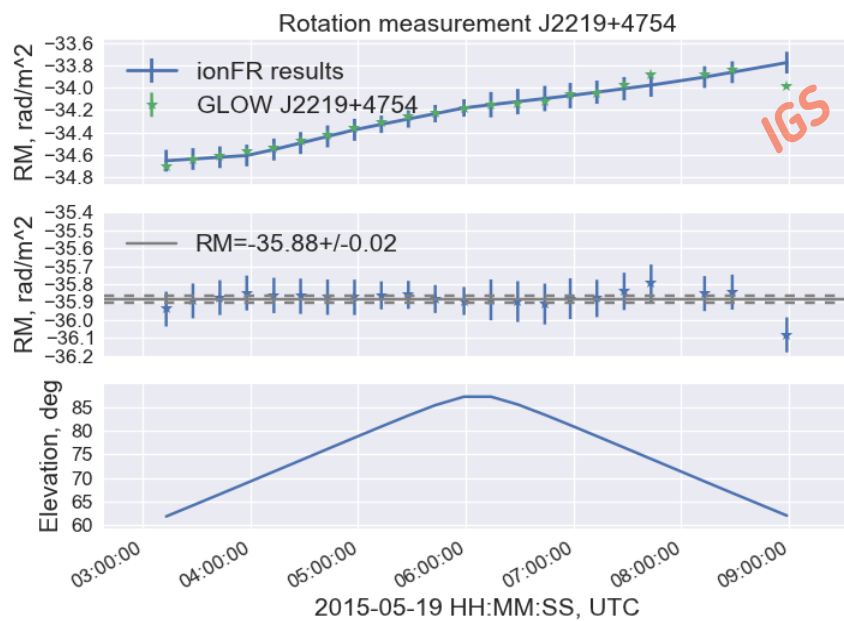
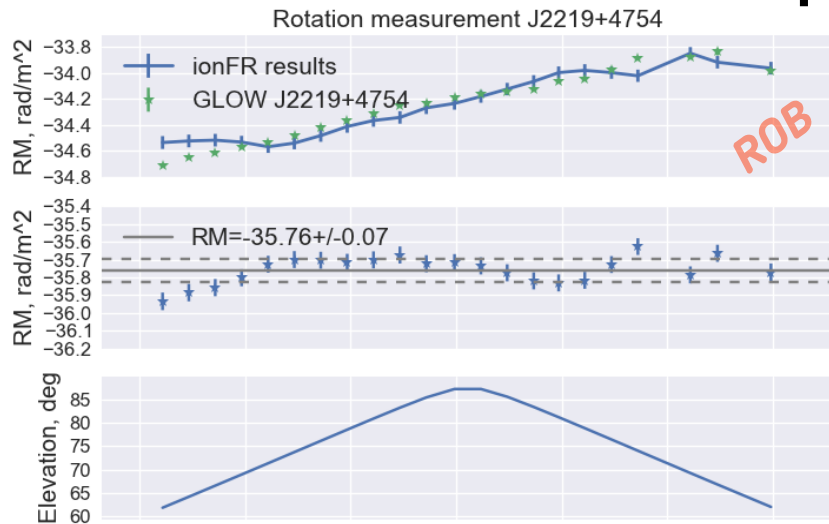
After
calibration

Before
calibration



Single layer model
can't be used

IonFR implementation



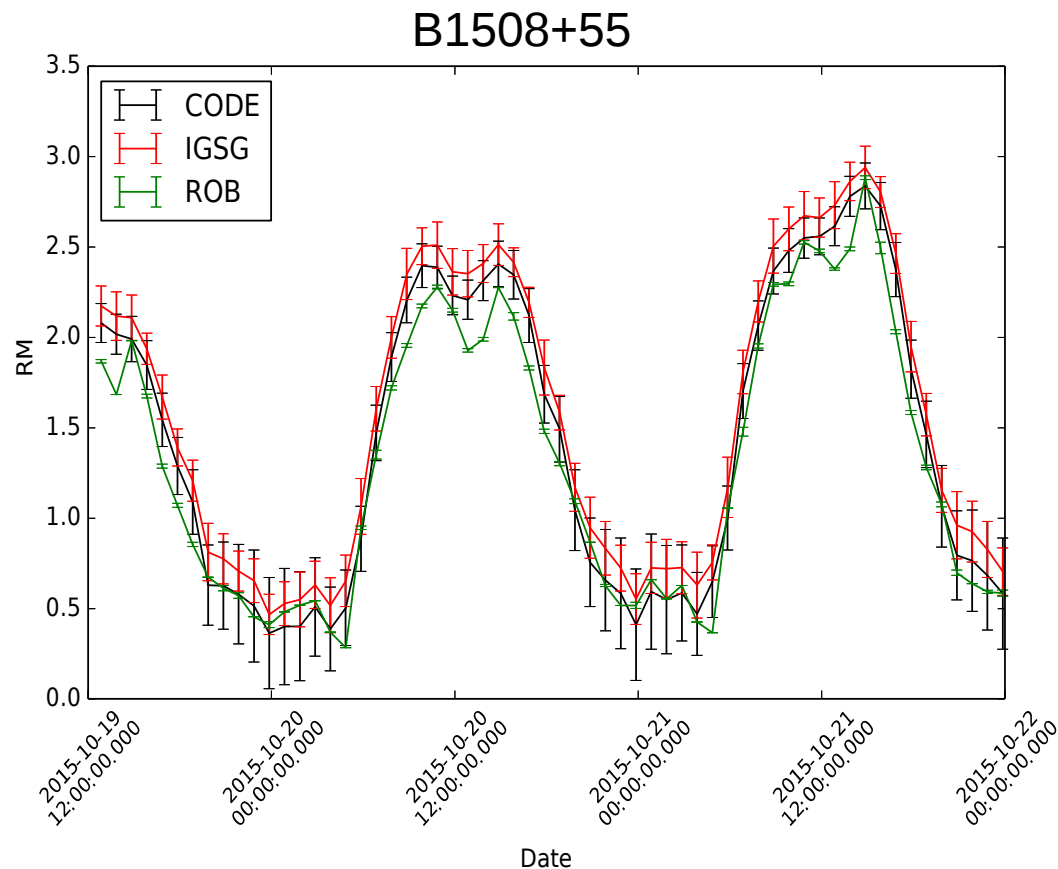
- Single layer model fails at low elevations
- Features of unmodeled ionospheric variations

To do:

More accurate investigation of ROB ionospheric maps for **correct error bars**

Determination of RM with likelihood analysis in the **presence of red noise**

IonFR implementation



By C. Tiburzi

- Single layer model fails at low elevations
- Features of unmodeled ionospheric variations

To do:

More accurate investigation of ROB ionospheric maps for **correct error bars**

Determination of RM with likelihood analysis in the **presence of red noise**

Conclusions

- We are using GLOW observations from sufficiently polarized pulsars to investigate the variations of RM
- Variations could be the result of proper motion of the pulsar, the line of sight of which will intersect different parts of ISM
- Variations are believed to show red-noise component in the spectrum



Thank you for
attention!

Rotation measurement J2219+4754

