

International Centre for Radio Astronomy Research

Transients

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Pulsars and transients

though similar, require subtly different detection strategies

You cannot

CRAF

- trade integration time for instantaneous sensitivity on a transient
- [usefully] perform a Fourier periodicity search on a transient
- deduce its position to sufficient precision to be useful unless multiple stations observe it
- verify it after the fact unless you have buffers holding station voltages

 The single greatest specifications driven by transients are

- access to pre-correlation datastream
 - to enable high time resolution
- a sizeable voltage-stream buffer
 - for after-the-fact verification and localization

What is there to find? E.g. Lorimer Transients

- First detection of local ionized IGM?
 - DM suggests extragalactic
- Position poorly localised
- Verification difficult with single antenna
- Large FoV needed to detect even relatively common events (e.g. GRBs ~1 sky⁻¹day⁻¹)

Lorimer Burst Mk

CRAF





Figure 3. (Top) A plot of the J1852–08 burst in frequency-To detect one extragalactic burst may be regarded as a mistake; to detect two looks like carelessness.

This station is now the ultimate power in the Universe. I suggest we use it.

Prominent Operational & Upcoming Projects

- 1. V-FASTR a fully operational and automated transients detection pipeline
 - showcasing a suite of new detection algorithms
- 2. LOFAR Transients Key Science Project & Variants
- 3. CRAFT (ASKAP)





V-FASTR - incoherent power search with coherent followup

ICRAR-Curtin/JPL/NRAO

- [incoherent] DiFX software correlator pipes 1ms telescope powers to a dedispersion/search engine
- [coherent] Candidates identified and 1s sections of baseband data on candidates dumped
- Telescope separation excellent signal localisation & false +ve rejection
- Proving ground for new approaches: JPL machine learning algorithms, FPGAbased dedispersion hardware



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ICRAR

ASKAP and CRAFT



TD Incoherent Processor

Dedispersion & Detection on an FPGA A detection solution for CRAFT

ICRAR





5.109E-7 516510.219 Count: 19200000 Min: 5.109E-7 Mean: 73.198 Max: 516510.219 StdDev: 3836.309 Mode: 1041.351 (191929 Bins: 248 Bin Width: 2082.702

filterbank noise pre-filtering

A CPU/GPU machine for real-time searches of fast transients

dynamic noise modelling

for effective RFI removal and transient detection



filterbank noise post-filtering



Fly's Eye, Incoherent widefield, or coherent survey?

• For an array of N stations, each with limiting sensitivity S₀

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- Fly's eye covers N x primary field of view down to S_0
- Collimated Incoherent covers 1 x primary FoV down to sensitivity $S_0/N^{1/2}$
- Coherent covers $\xi \Omega_{synth} = \xi \pi (\lambda/d)^2 [\Omega_{synth} \ll \Omega_{primary}]$ down to S_0/N
- Which is best depends on the slope of the Rate vs S_0



Fly's Eye, Incoherent widefield, or coherent survey?

• Fly's eye or coherent?

number of tied-array beams

- $\frac{\mathcal{R}_{\text{coher}}}{\mathcal{R}_{\text{fly's-eve}}} = \xi \frac{\mathscr{H}_{\text{synth}}}{\Omega_t} N^{1/2-\delta}$
- ξ must be large for the coherent approach to win
- If $0.5 < \delta < 1.5$ we eventually lose for large N with a coherent survey
- Coherent or collimated incoherent?

$$\frac{\mathcal{R}_{\text{coher}}}{\mathcal{R}_{\text{col}}} = \xi \frac{\Omega_{\text{synth}}}{\Omega_t} N^{3/4 - \delta/2}$$



Maximising bang for buck

see Colegate & Clarke, PASA 2011

Station

D=180 m

- We consider the AA-lo layout of Memo 130 (Dewdney et al. 2010)
 - Diameter 180 m, 50 stations, 11200 elems/station
 - 25 stations at (r <0.5 km)
 - 10 stations (0.5 < r < 2.5 km)</p>
 - 15 stations (2.5 < r < 100 km) \setminus N_e=11 200
 - 70 450 MHz
 - Dense-sparse transition at 115 MHz
 - $T_{sys} = 150K + T_{sky} T_{sky} = 60 \lambda^{2.55} K$





Relative Detection Rate per beam assuming $R \propto \Omega S_0^{-3/2}$

CRAR



Relative Detection rate per Operation

(beamforming dominates ops count)

CRAR



v (MHz)

18

Relative Detection rate per Operation

CRAF

(if beamforming paid for us, so dedispersion dominates) assuming $R \propto \Omega S_0^{-3/2}$



Transients detection is compute and I/O limited

- Cannot possibly tile the entire array FoV using a coherent approach involving all stations
 - Follow LOFAR approach and just use the inner stations
- N_{pix}~(max baseline/station diameter)²~309000
 - could be as low as 192 if we use inner 2.5km stations
 - but localisation only to 3' at 150 MHz
 - arguments that longer baselines better for ionospheric correction for observations over a wide FoV

 Find a better solution to the detection and disdispersion problem than the brute force approach

What do we what?

 A modular/spigot-based philosophy to system design that enables us to

- access total powers of stations
- access station voltages
- place buffers at a variety of levels in the hierarchy (lowest access point TBD, but likely close to the stationlevel, certainly not antenna level)

When do we want it?

- we are not so foolish as to believe that the SKA itself will furnish purpose-built transients detection hardware gratis
- Spigots allow us to attach hardware as its capabilities improve

Good systems design is 99% of our requirement

- Transients are a no-/low-cost addition that ensures good systems design is built into the telescope from the beginning
- Must be built into AA precursors AAVS1/2
- Transients science is one of the few useful scientific things such low sensitivity instruments could do
- They ensure a modular design that future proofs the hardware for correlator upgrades 15++ years down the track
- Needs to be included in the SKA DRM for Phase I
 - ensure that engineers at the end of the production line do not design out functionality even though it may not be immediately required