

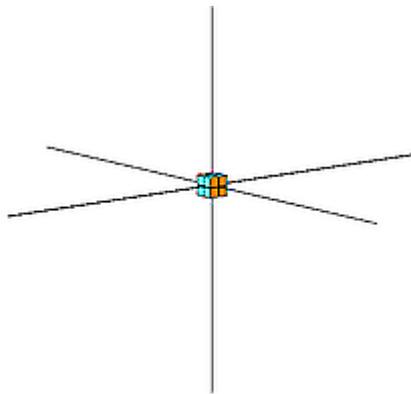
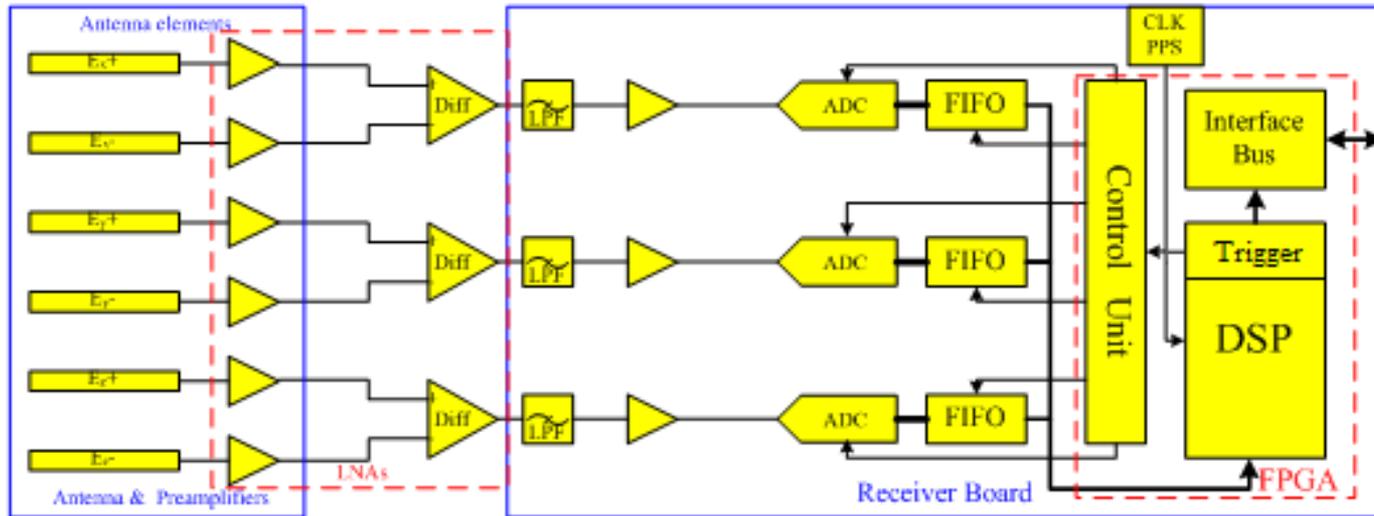
DSL Mission Concept at Lunar Orbit

Jingye Yan

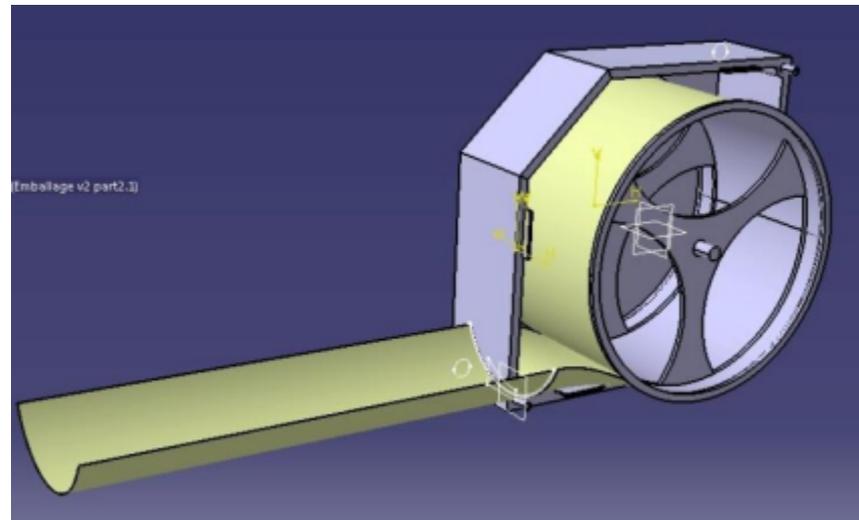
National Space Science Center (NSSC)
Chinese Academy of Sciences (CAS)

2015-02-02, ASTRON, The Netherland

Payload onboard single nano-sat



Element antenna



Outline

- Requirements
- Mission concept and preliminary design
- Summary

Qualitative requirements

- RFI free/minimum
 - Moon shielding is better than mitigation
- Long baseline for high resolution
 - Long distance high speed communication
- Dense UV coverage
 - Discover unknowns
- S-mission

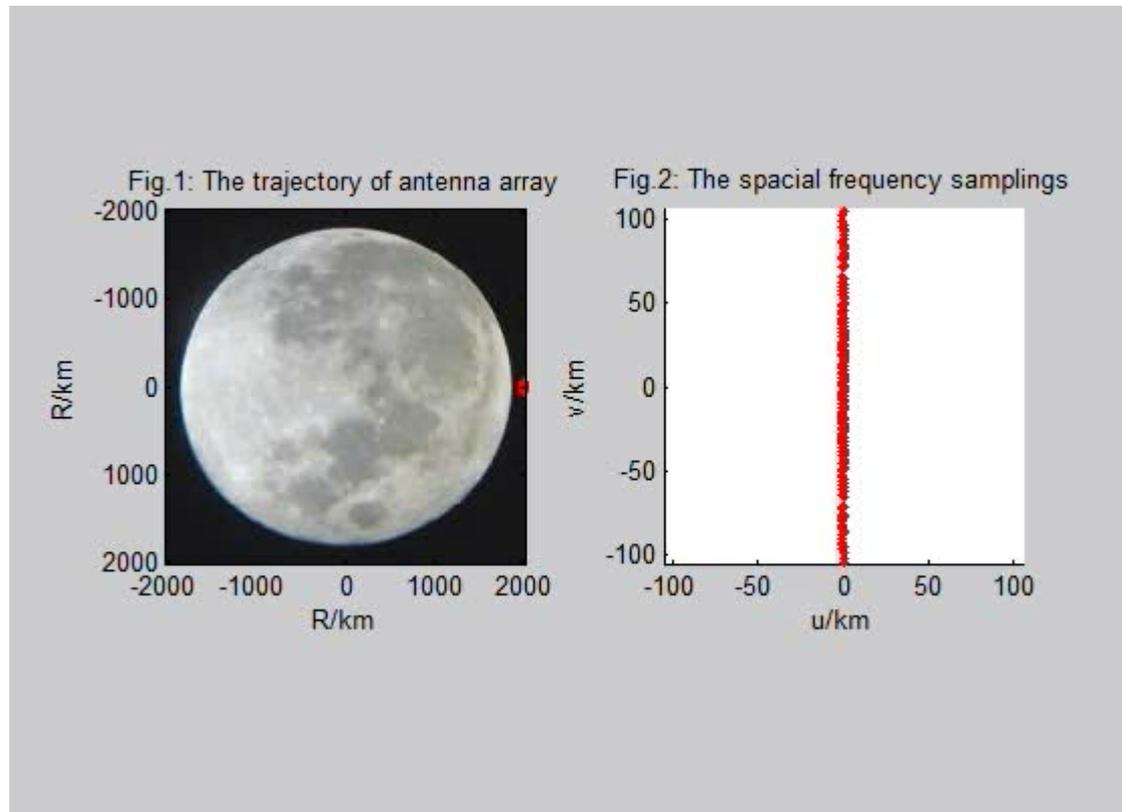
Quantitative requirements

- Angular resolution
- Frequency
- Spectral resolution
- Integration time
- Polarization

Array design = Optimize the UV coverage

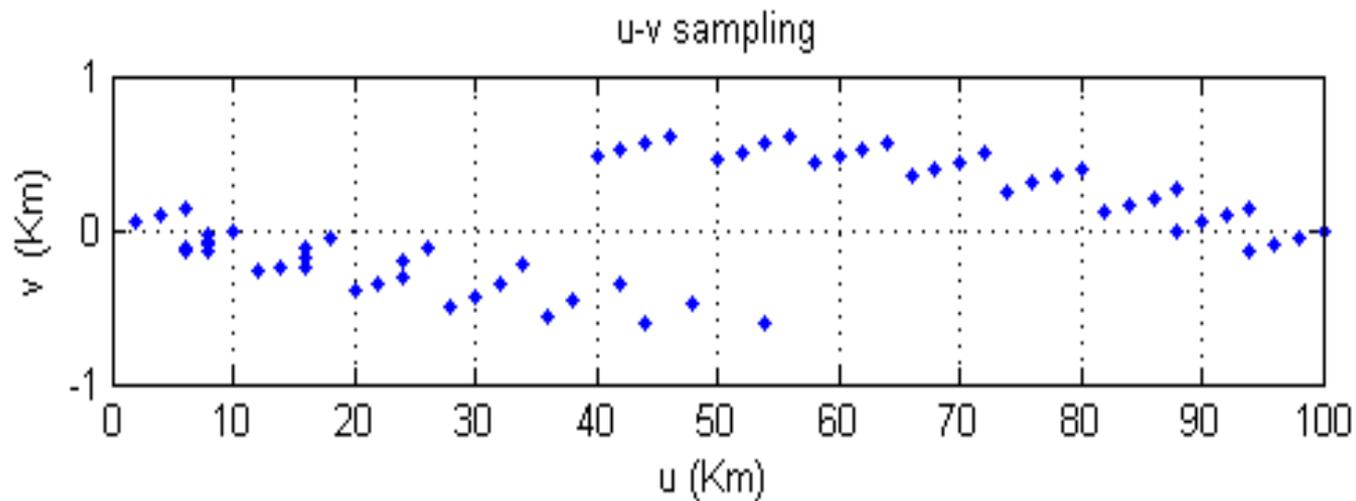
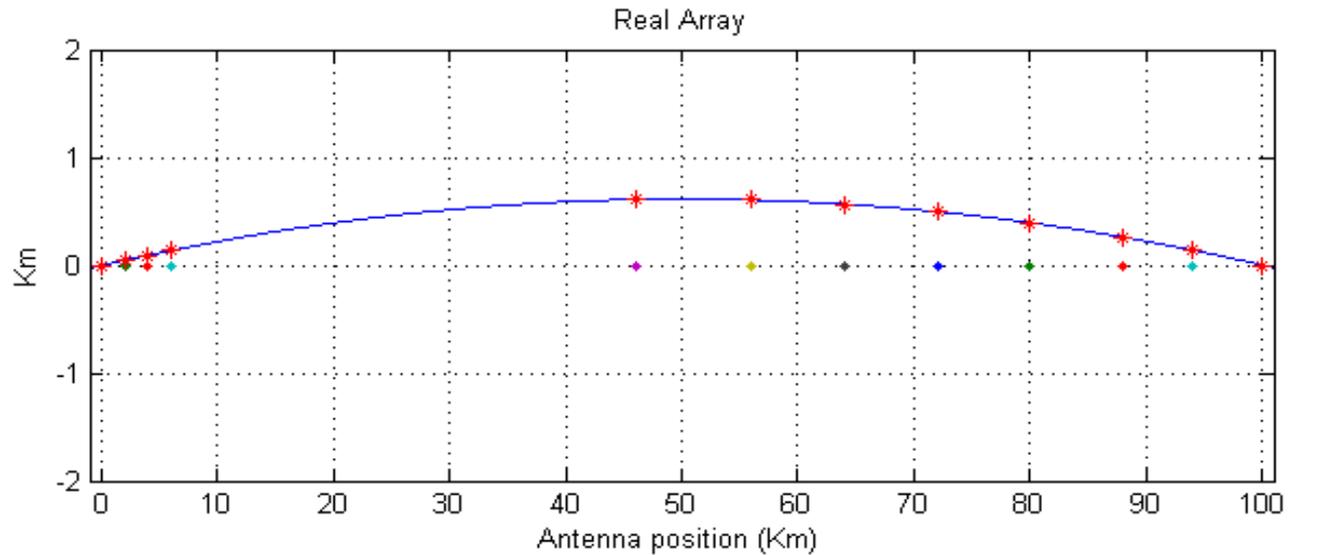
DSL array at Lunar orbit

- Linear array along the same orbit
- Dish UV coverage every half orbit
- Baseline's length varies from orbit to orbit by maneuver, Full UV coverage (Nyquist) every 10 days
- UV coverage is configurable in orbit according to particular scientific goal
- Linear array simplifies the formation maintenance and maneuver
- 30% of the life time is RFI FREE



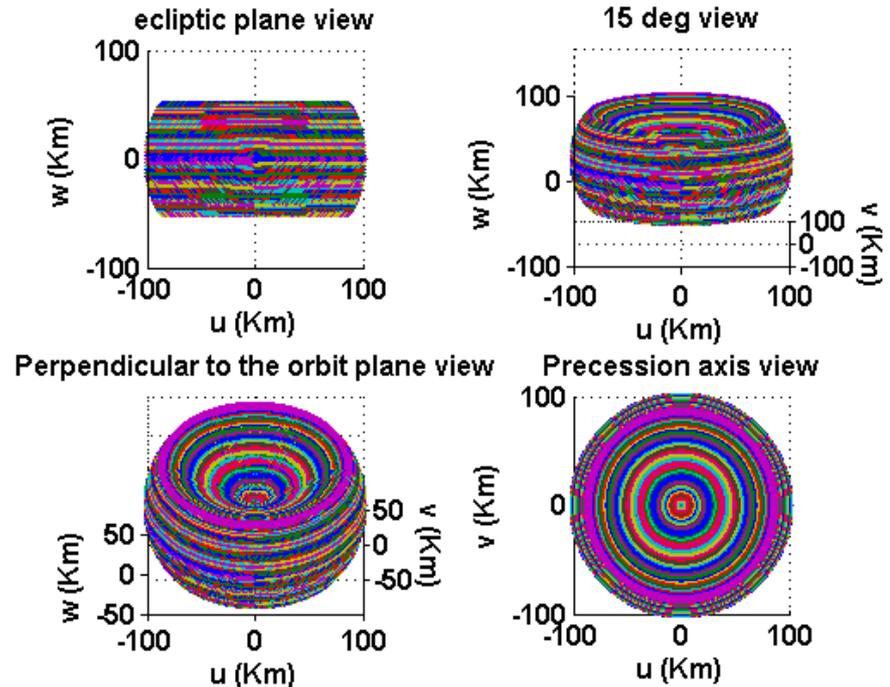
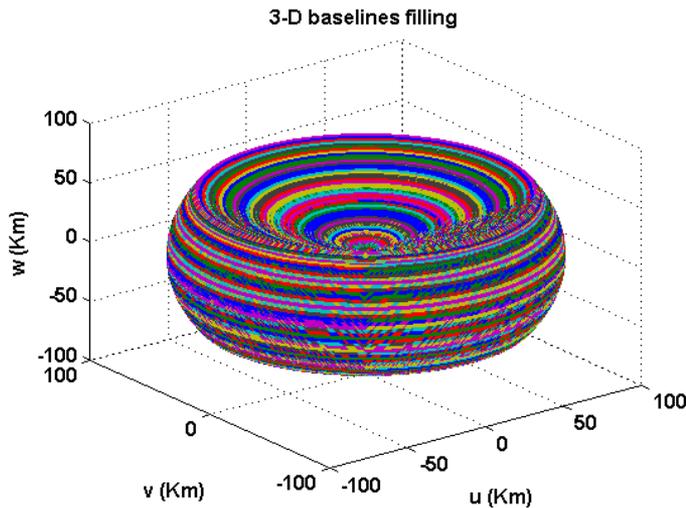
Example array: 1 4 10 22 24 35 39 52 63 71 74 78 79 km

Snapshot



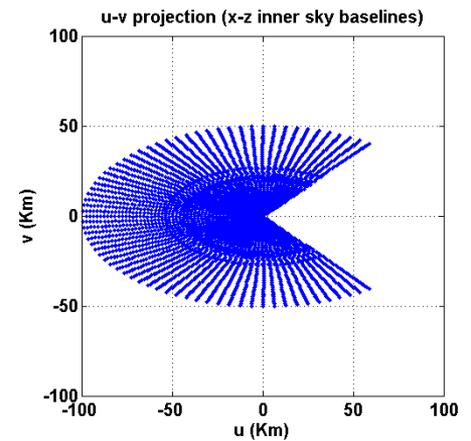
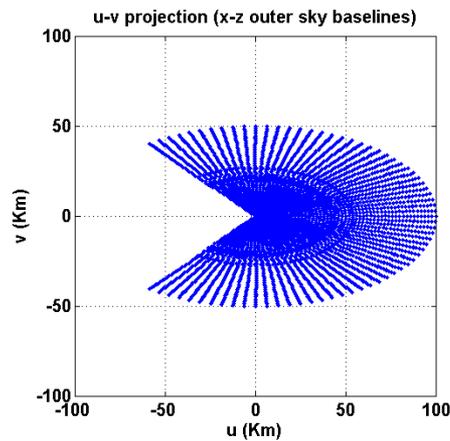
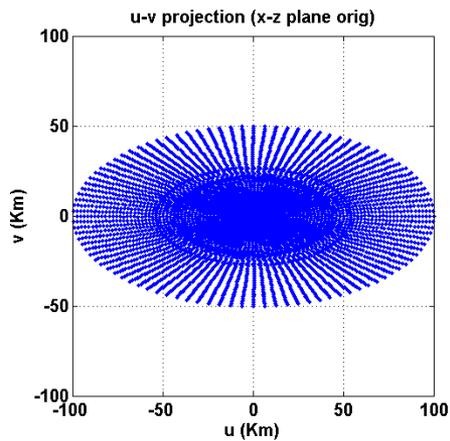
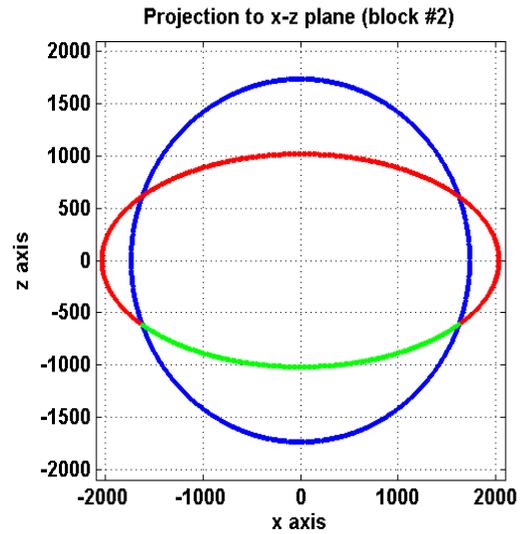
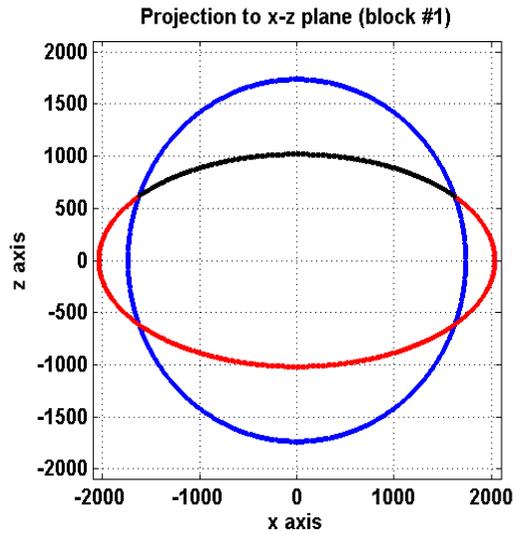
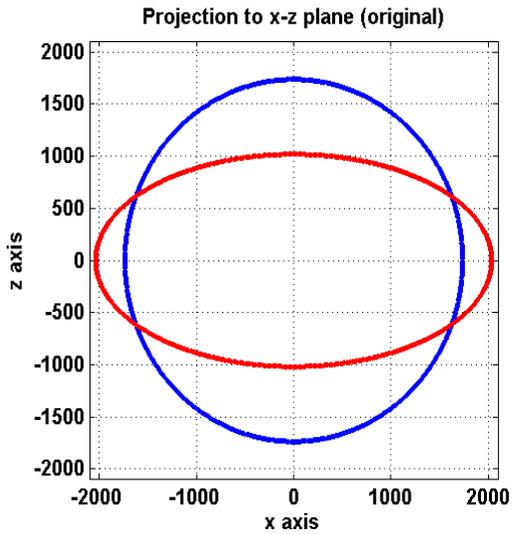
u-v-w filling

- 3-D u-v filling after a full precession period (360°);
- In DSL case, ~ 450 days is required to have a full u-v filling in 3-D (0.76° precession per day);



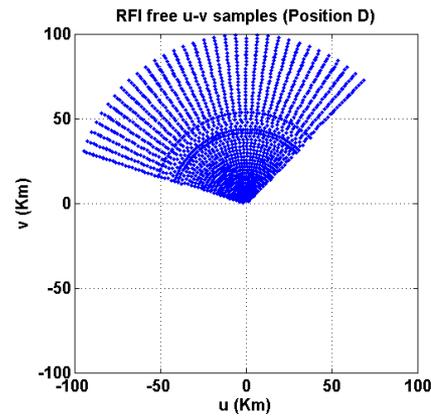
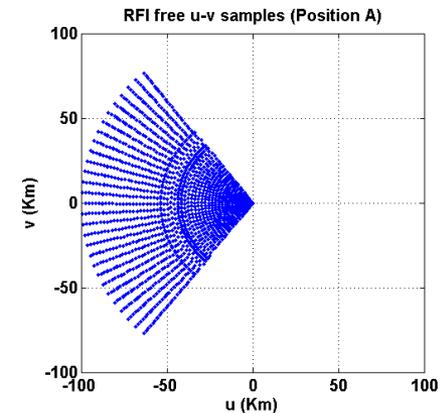
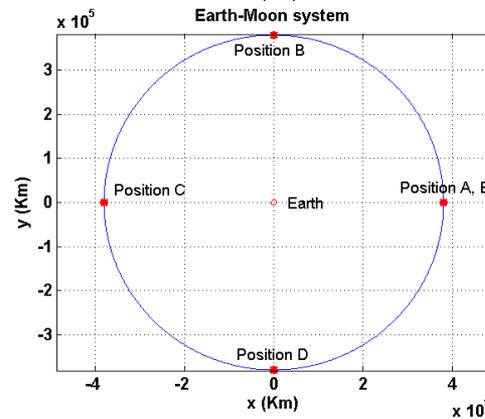
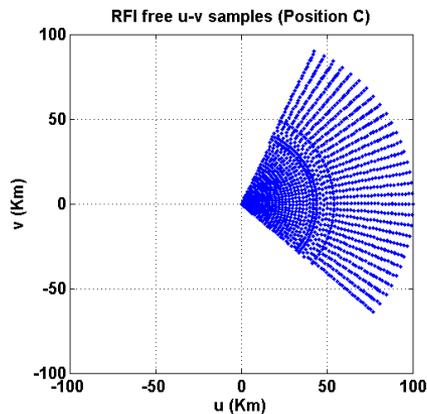
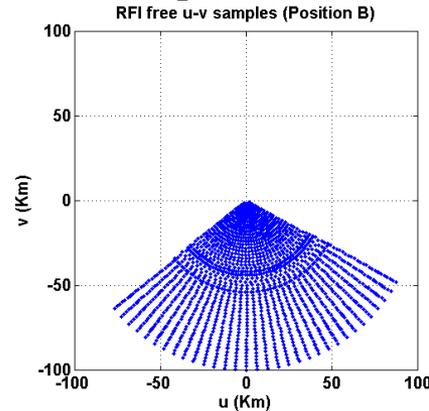
6° precession per orbit is assumed for better demonstration.

Moon blockage

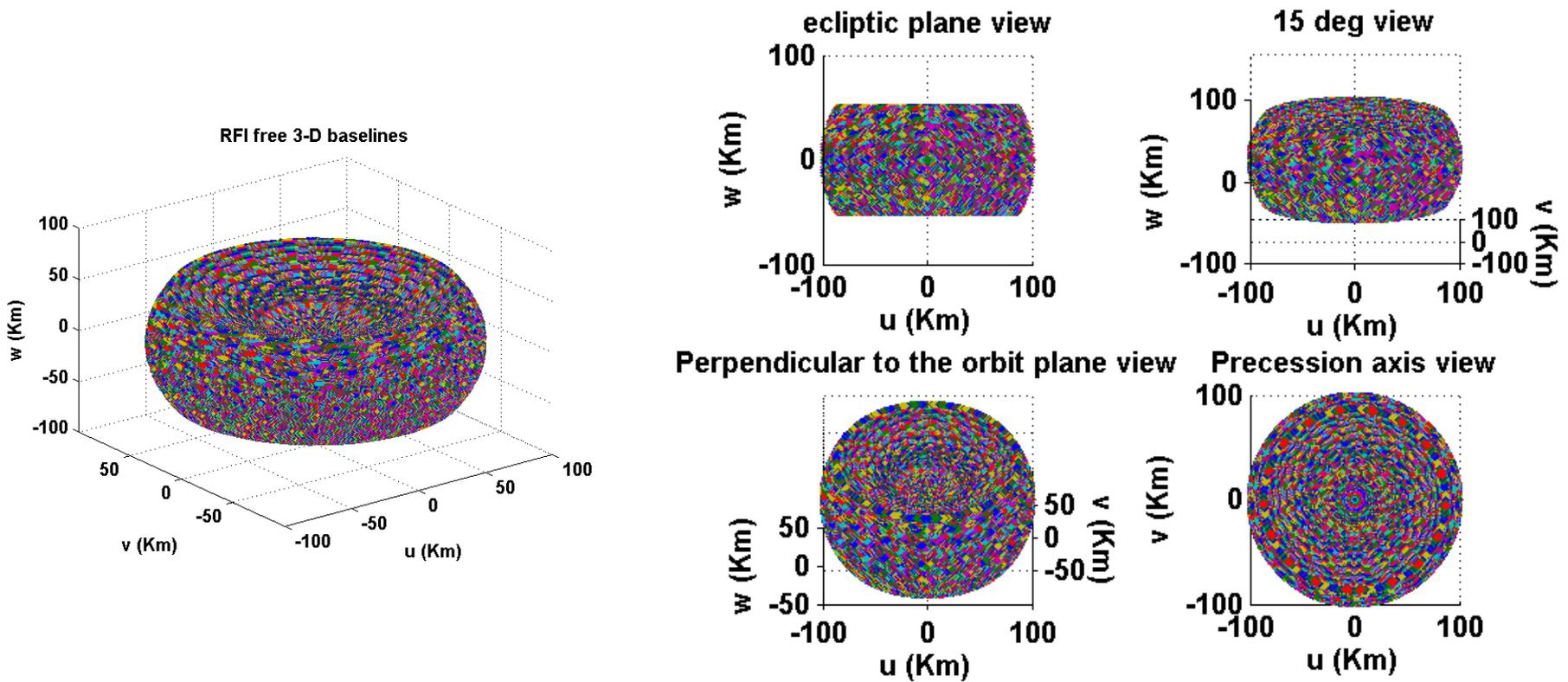


Earth-Moon system and RFI free

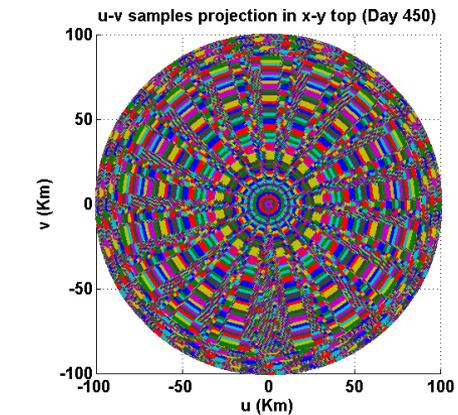
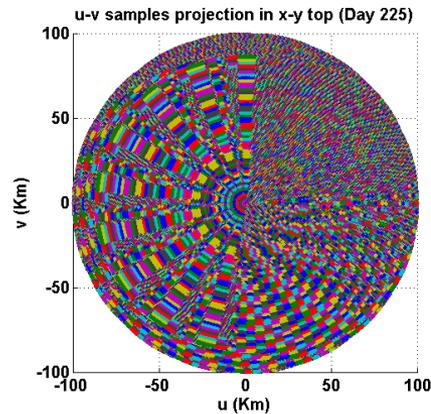
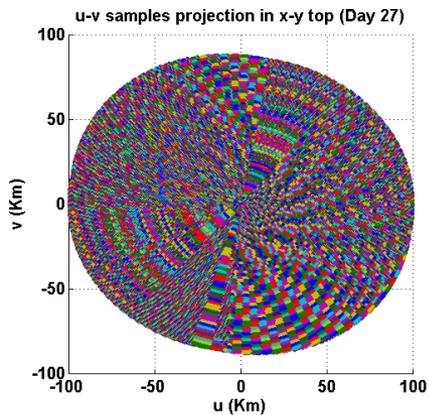
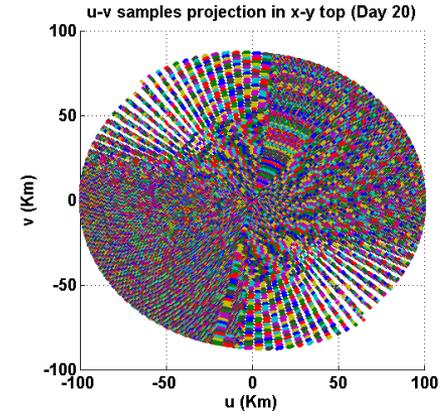
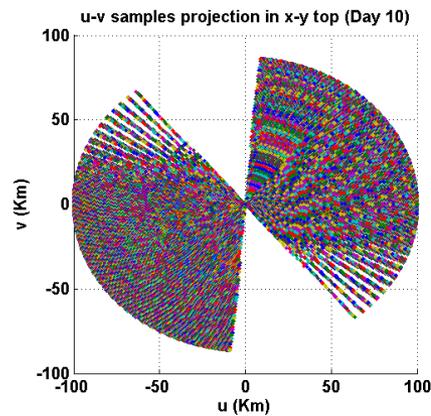
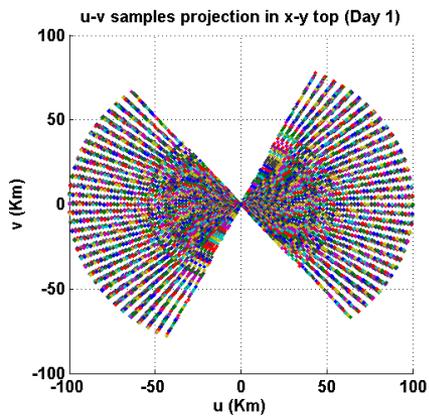
- 30% RFI free
- 60% coverage (taking into account the conjugate points)
- RFI mitigation (if works) improves the coverage



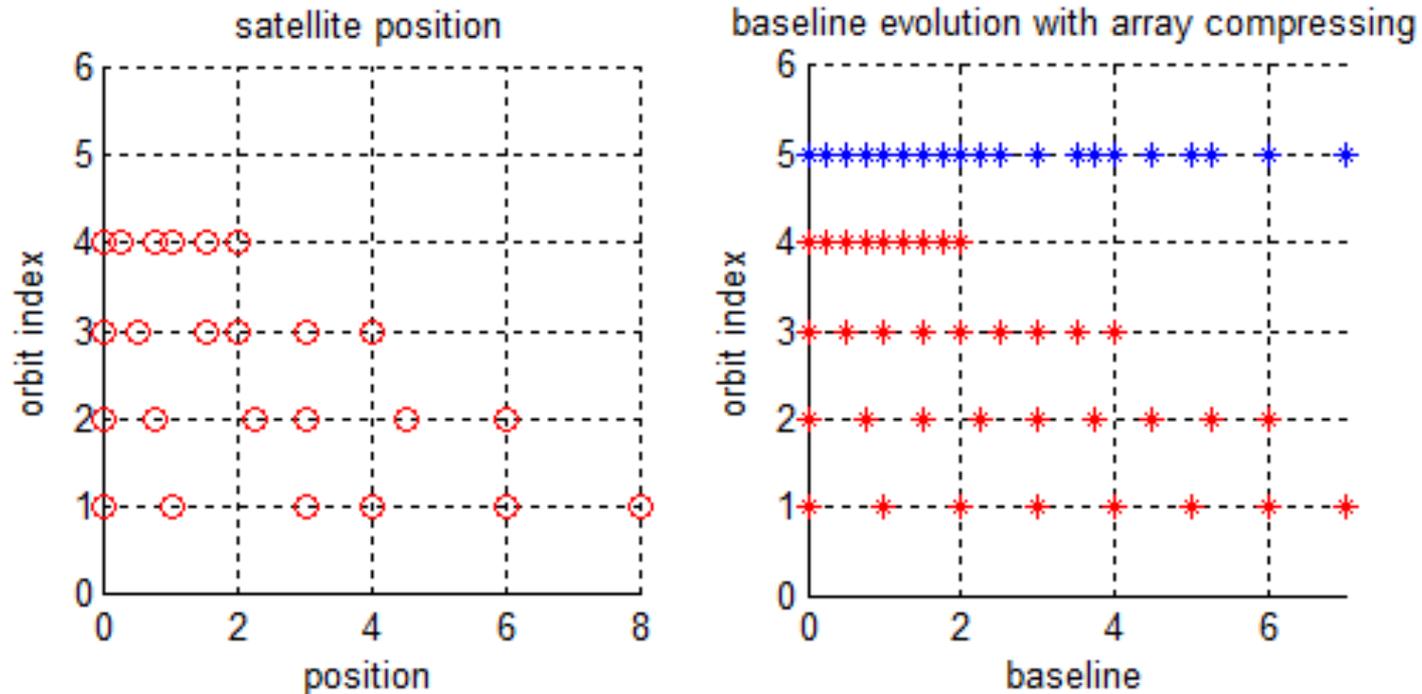
RFI free + precession



RFI free + Moon blockage + precession



Make denser coverage in UV plane

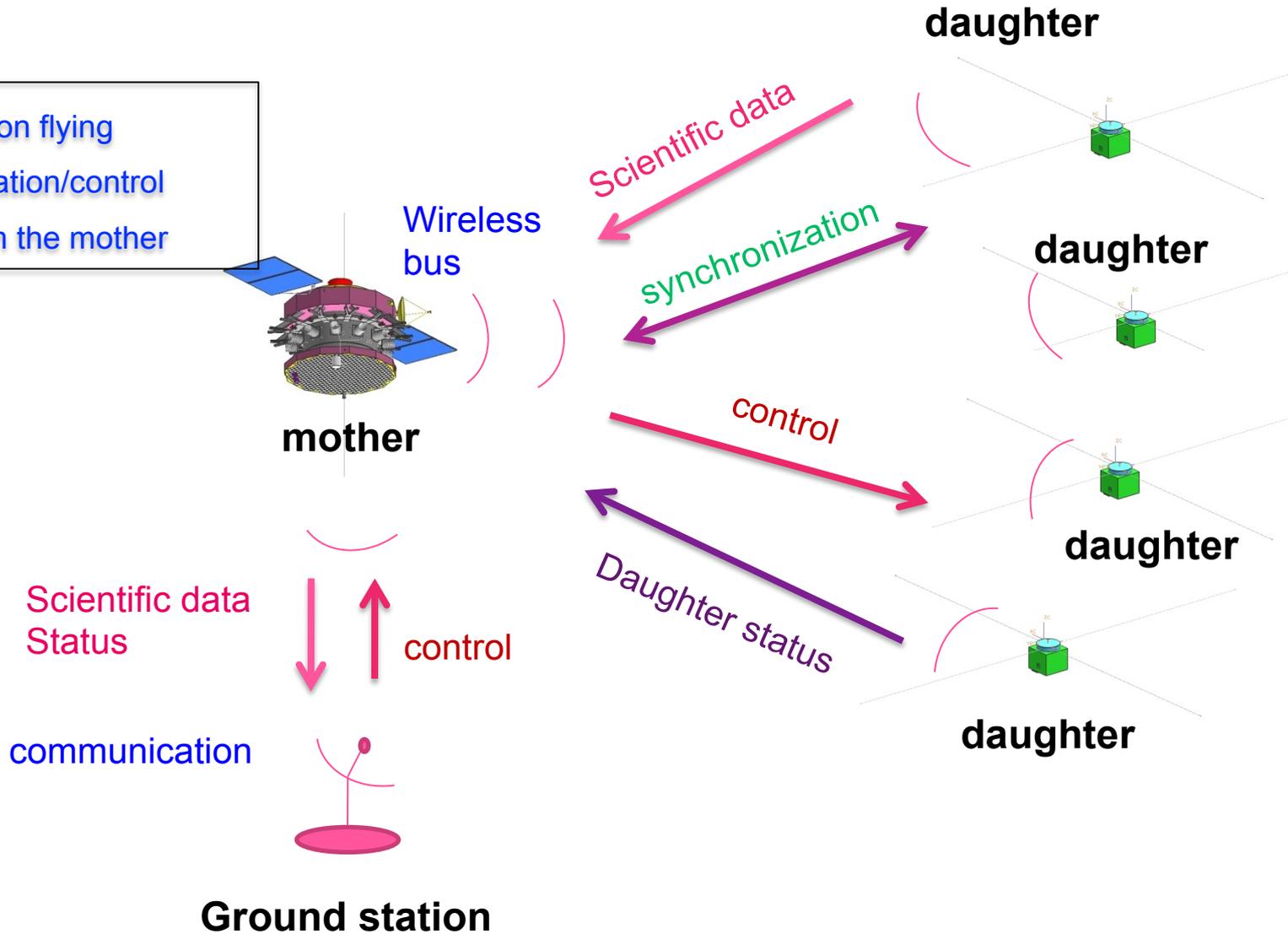


Advantages:

- ✓ Easy change the baseline in a linear array
- ✓ Dense and controllable coverage
- ✓ Image quality is improving orbit by orbit

Mission concept

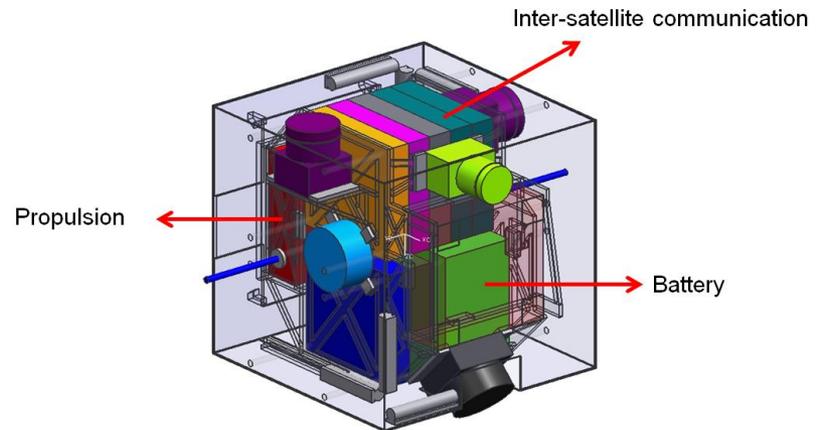
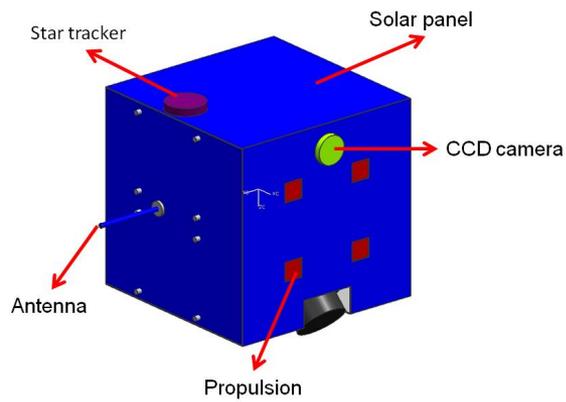
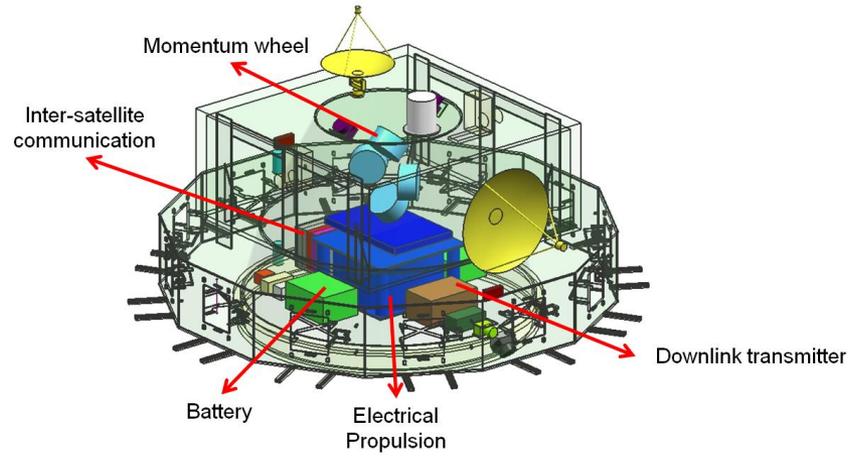
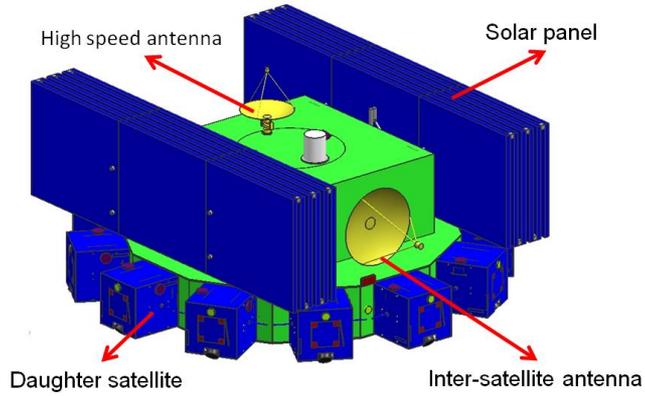
- ▣ Linear formation flying
- ▣ Central correlation/control
- ▣ Downlink from the mother



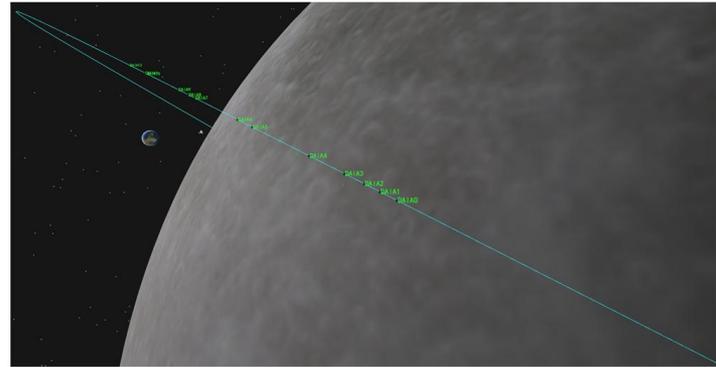
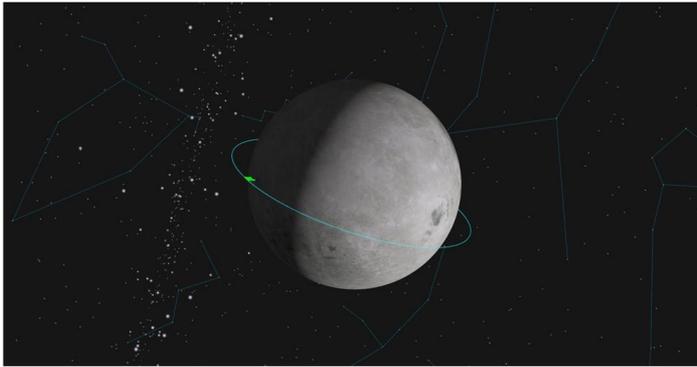
Mission concept

Baselines change from 100km to 100m within 5 days needs
15g cold gas for 12 satellites maneuver

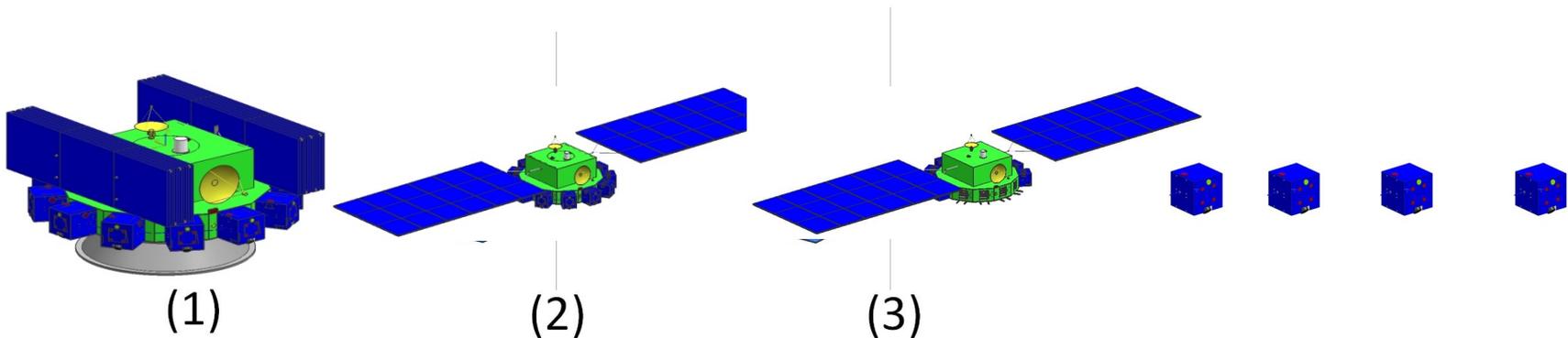
Satellite



Mission Concept



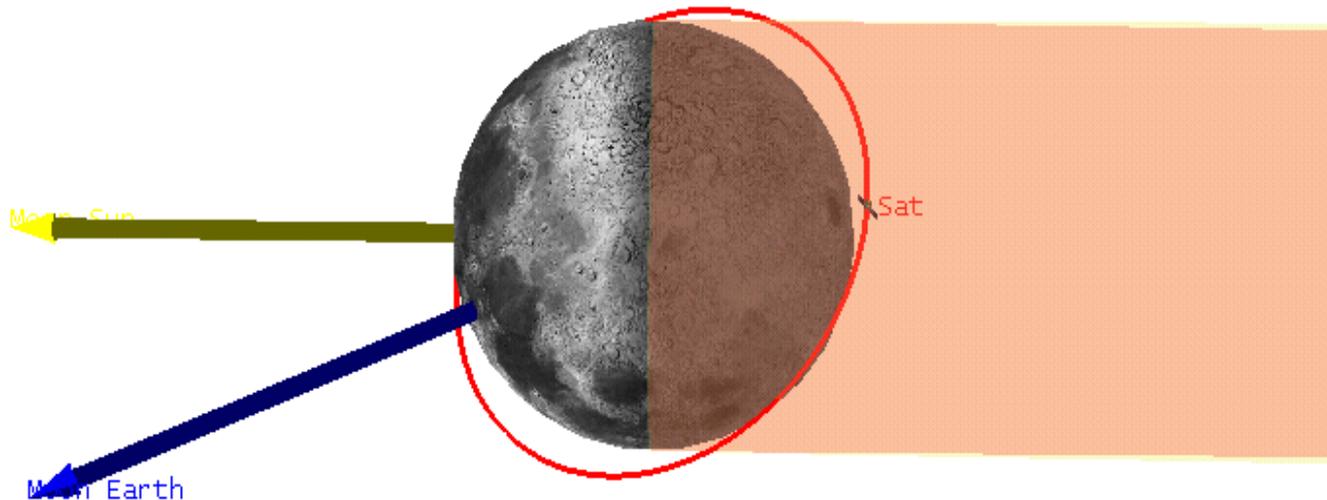
- 300km lunar orbit
- Linear formation flying.
- Active formation control
- Baselines coverage from 100km to 10m.



1. Satellites launch configuration.
2. Configuration in the transfer orbit from the Earth to the Moon.
3. Formation establishment.

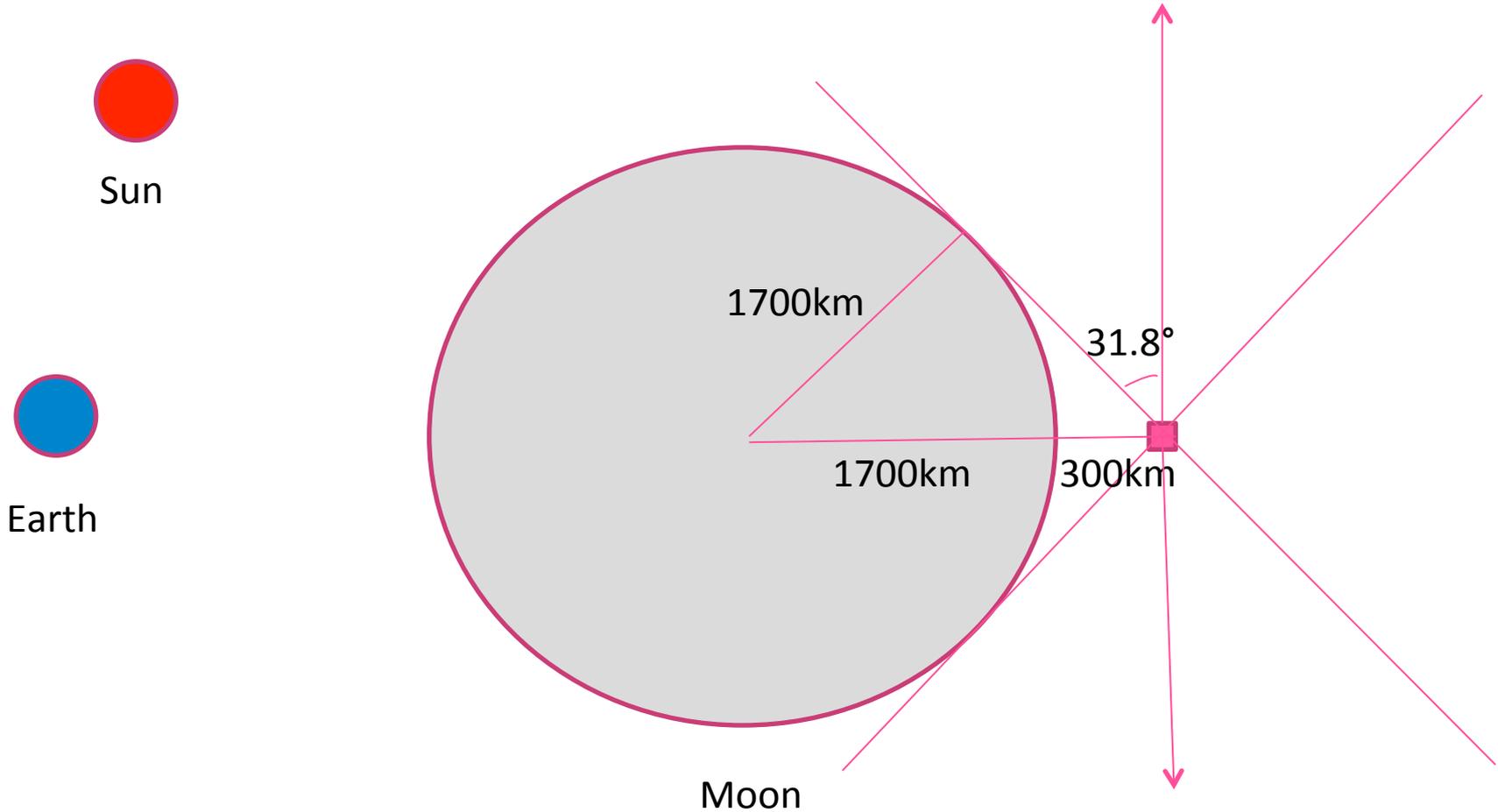
Target orbit analysis

- Perfect RFI free
- 1 or more strong sources will be blocked time to time, enabling diverse comparisons
- Orbit is stable, no crash will be happened
- Easier to avoid satellites collision

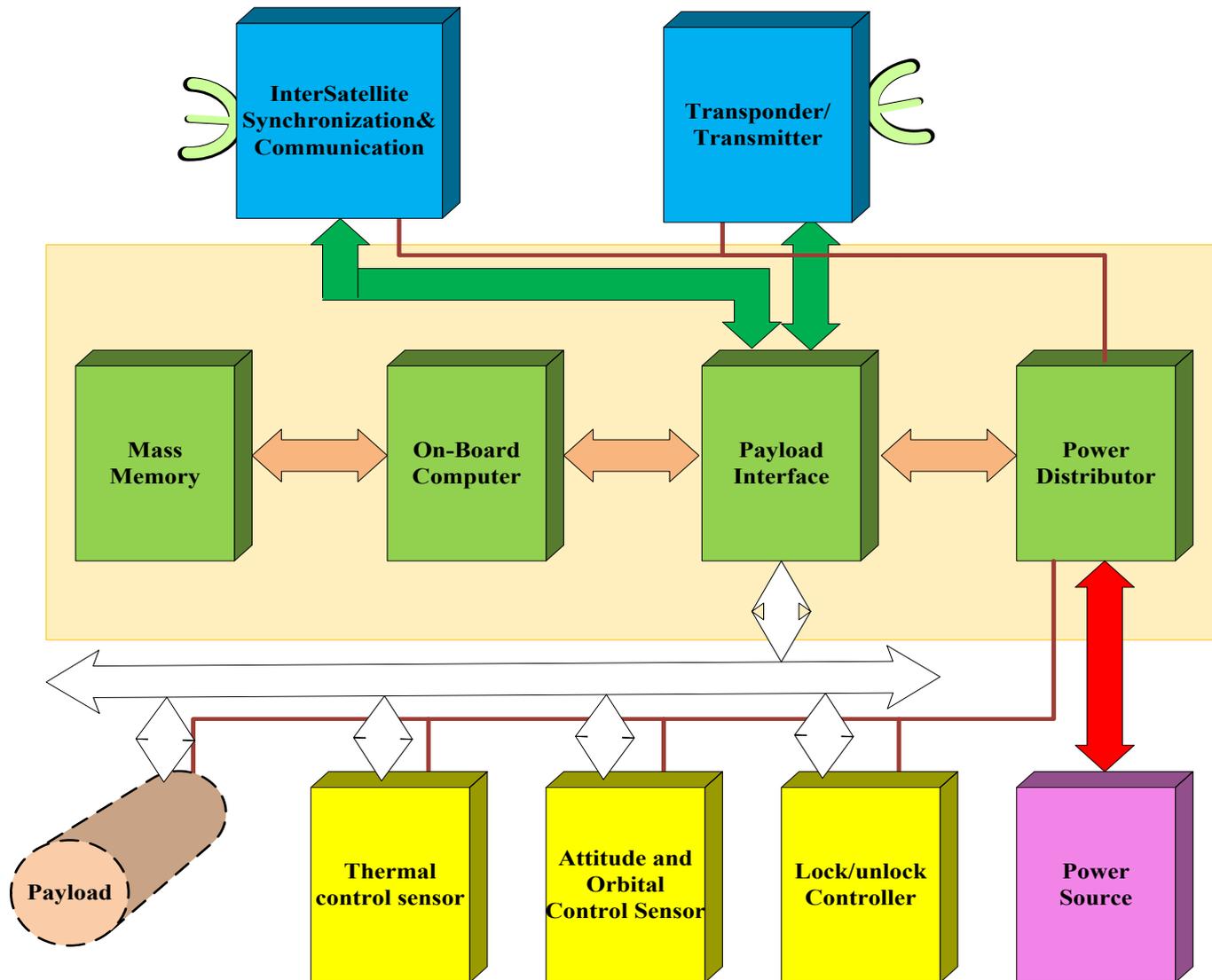


Orbit altitude: 300km
Sun/Earth free: 30%

Antenna field of view

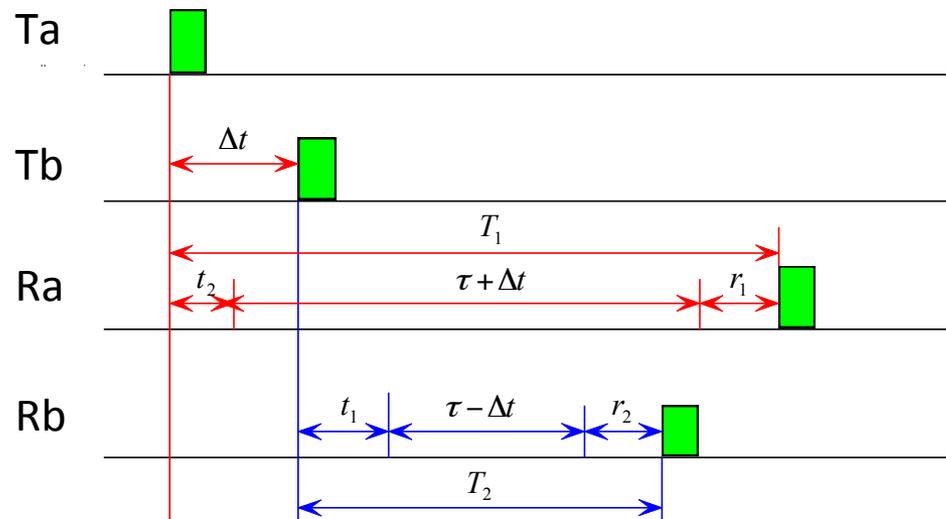


Integrated Electronic Subsystem(IES)



Communication, Ranging and Time Synchronization

Ranging Precision under Current Link Situation: 2cm



Time Synchronization

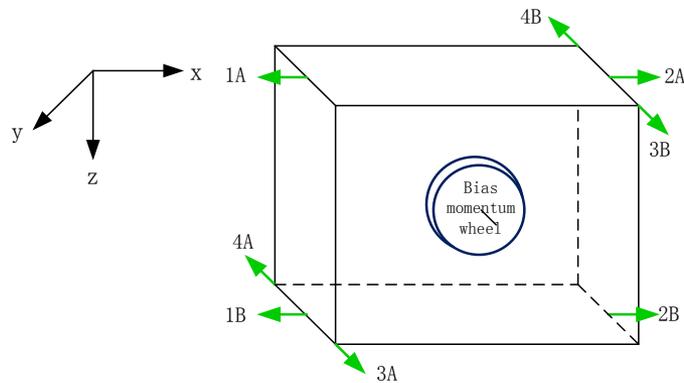
Dual One-way Ranging, DOR

$$D = \frac{1}{2} \cdot [(T_1 + T_2) - (t_1 + t_2) - (r_1 + r_2)] \cdot c$$

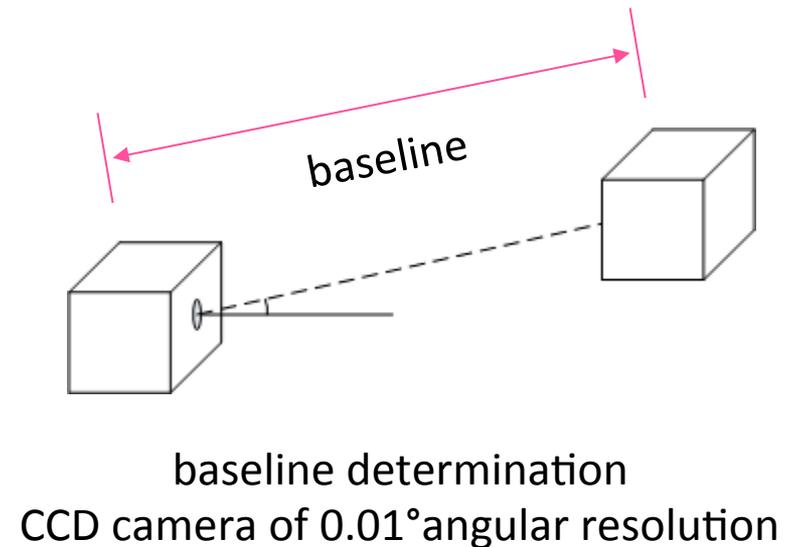
$$\Delta t = \frac{1}{2} \cdot [(T_1 - T_2) - (t_2 - t_1) - (r_1 - r_2)]$$

Attitude control and baseline determination

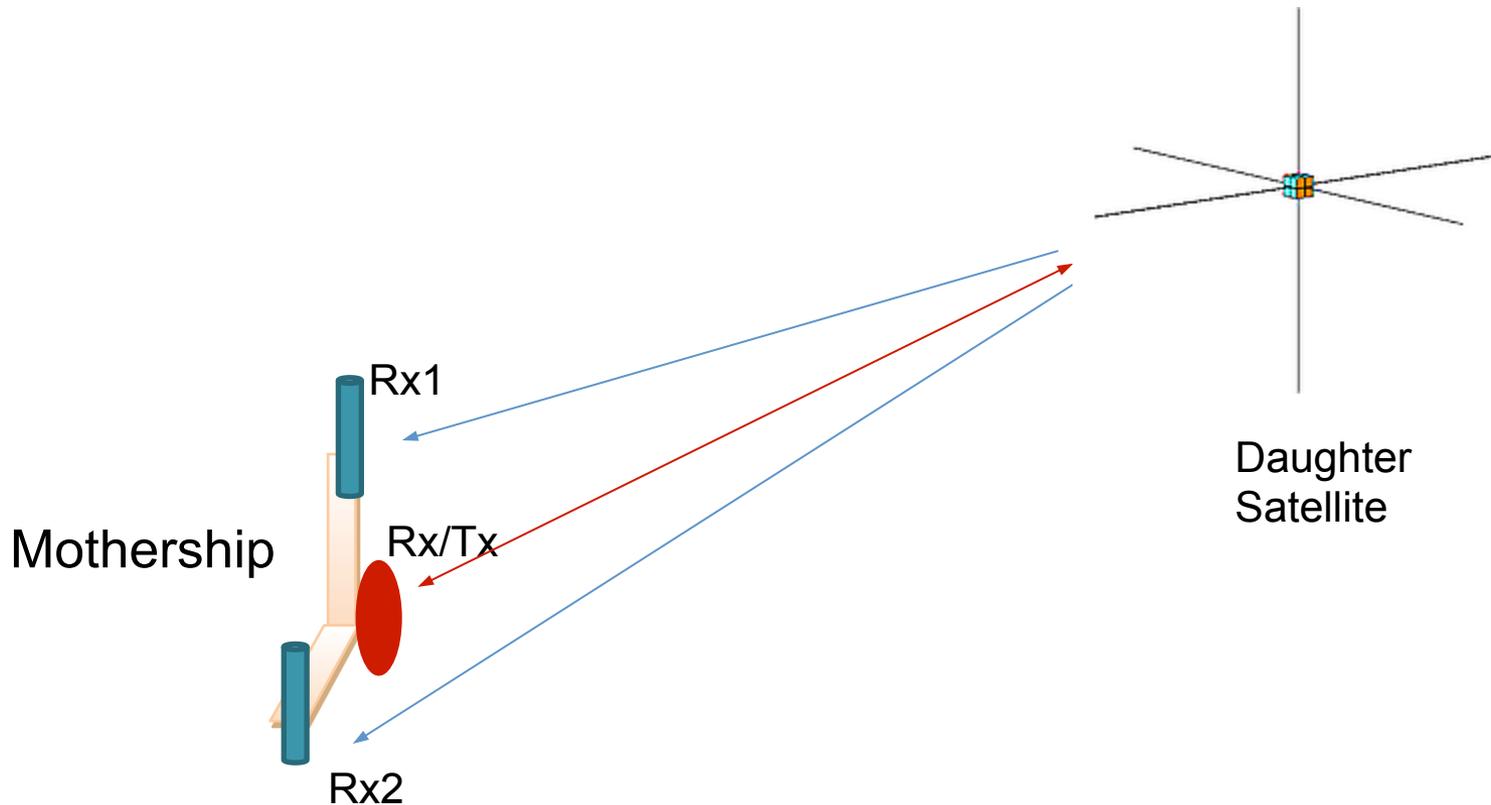
- Mother sat
 - 1 orbit control thruster, 12 attitude control thrusters and 4 momentum wheels.
- Daughter cubesat
 - 1 bias momentum wheel and 8 attitude control thruster.



Attitude control

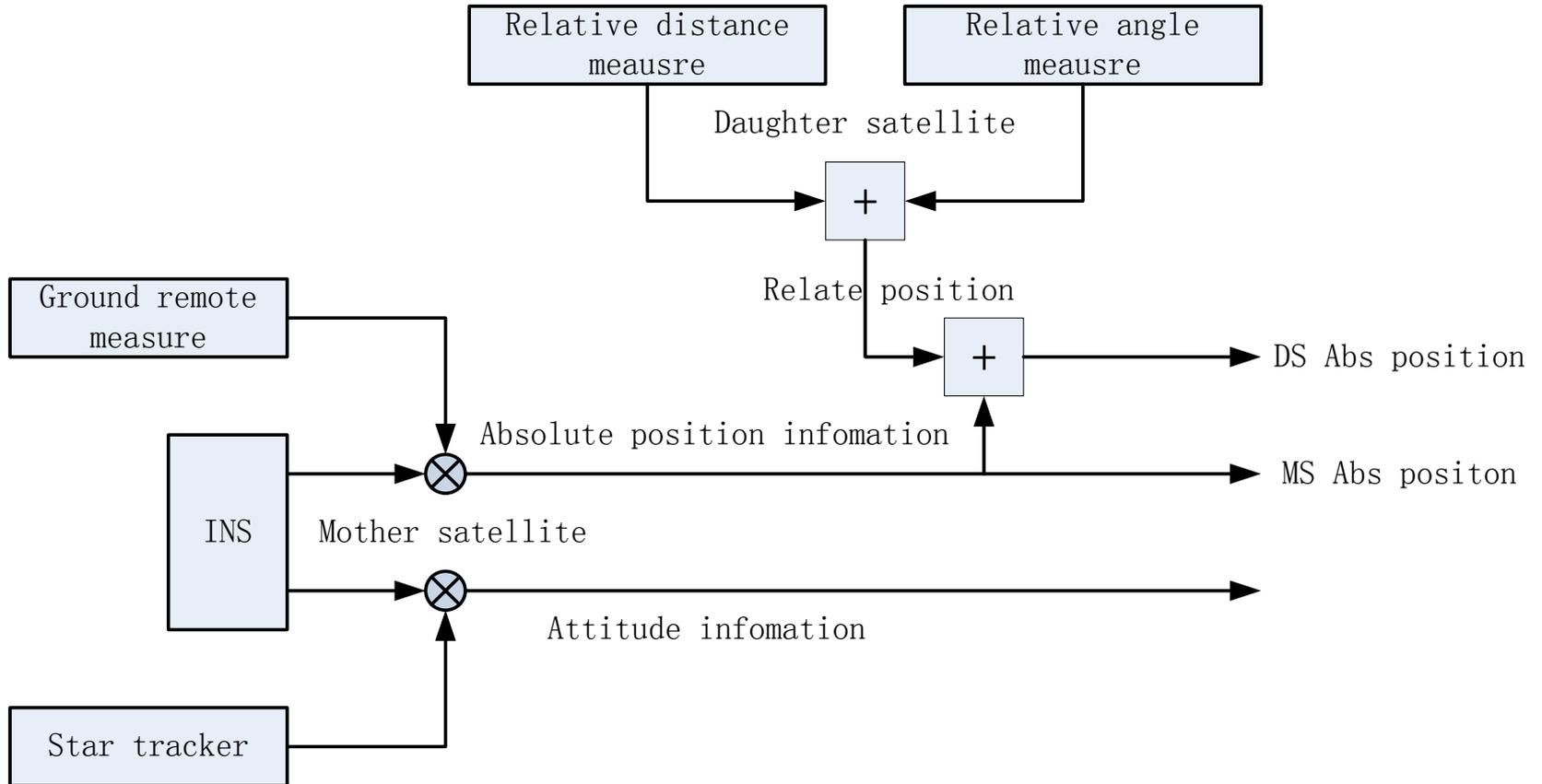


Radio interferometry



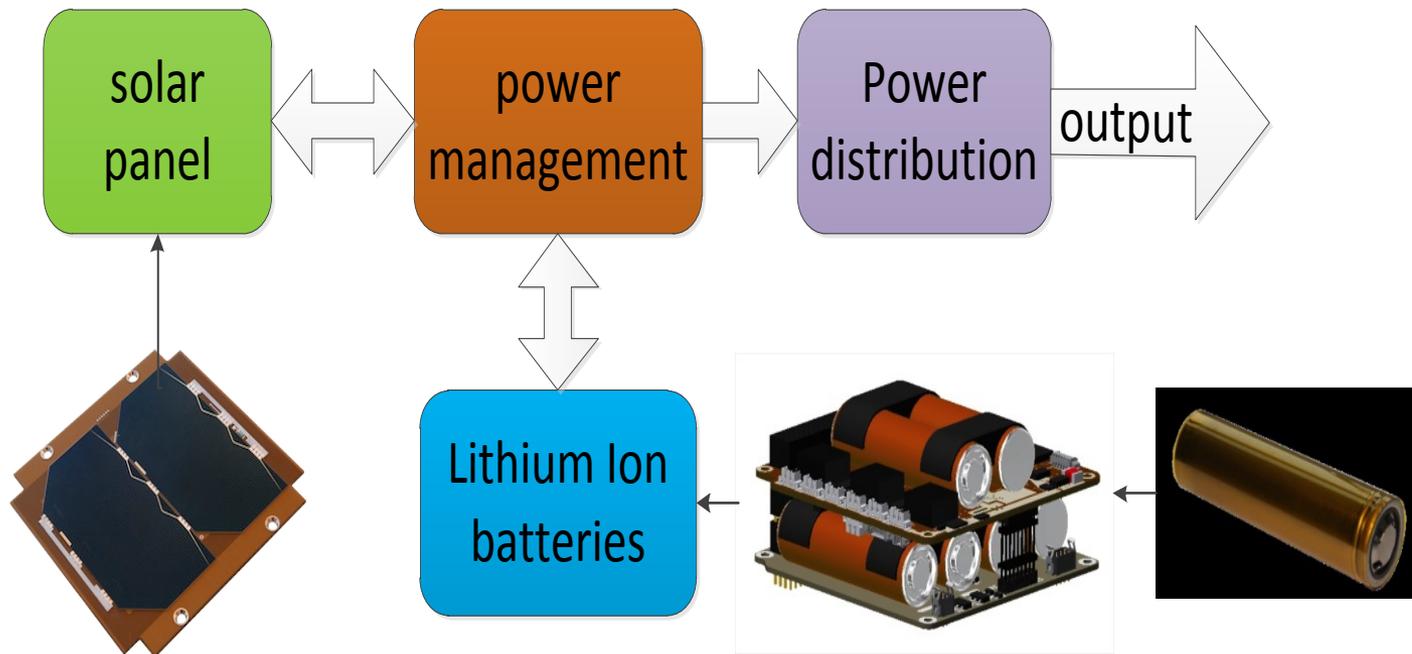
One main and two sub antennas is mounted on the Mothership. The angle of arrival (AOA) is measured by interferometry between antennas.

Navigation



Power Subsystem

- Power subsystem component
 - Solar panel
 - Lithium Ion batteries
 - power management and distribution system



The block diagram of power subsystem

Down link requirement

$$\tau(f) = \eta \frac{c}{f} \frac{T_0}{2\pi L}$$

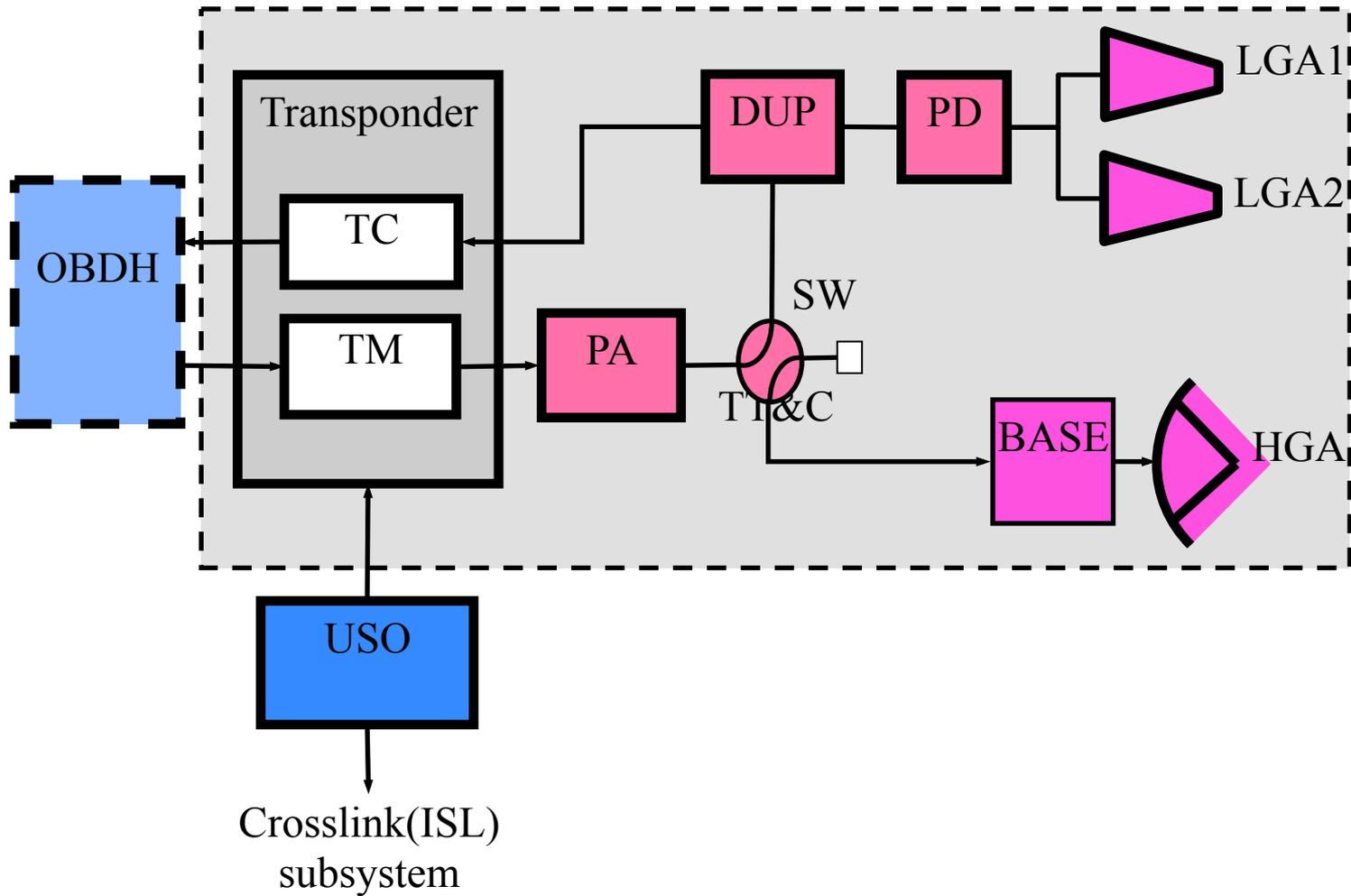
$$data_rate_{1s} = T_{\text{rfi-free}} \sum_{f=f_0:f_m} \frac{p_n^2 \cdot W_l}{\tau(f)}$$

Assumption:

correlate 30MHz bandwidth at the same time (not possible for ISL)

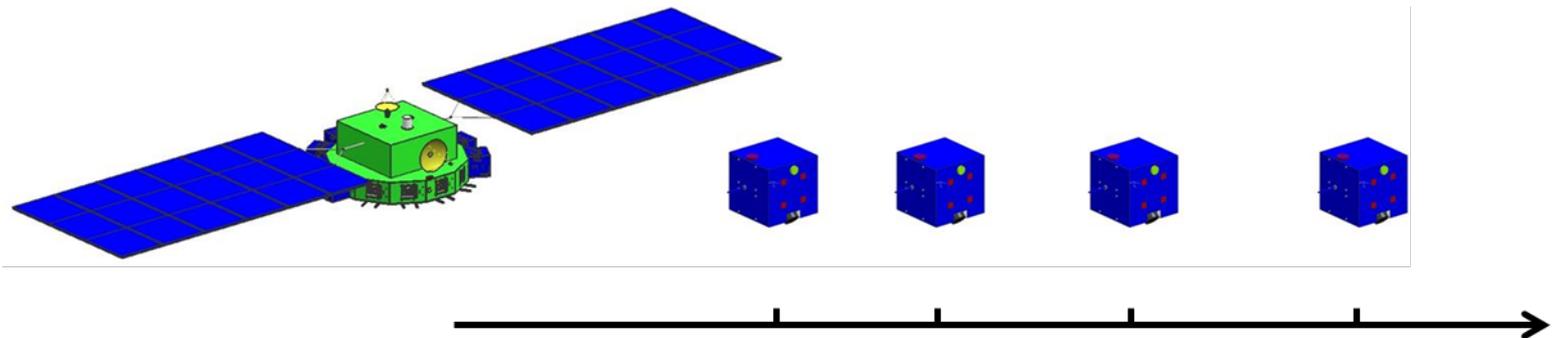
- 13.2Mbps
- 6.6Mbps (far side observation, near side download)
- High gain antenna is mandatory

TT&C Solution



In orbit calibration

- Relative amplitude calibration by cosmic background radiation
- Relative amplitude and phase calibration by calibration signal from Mother
- Absolute amplitude calibration by matched load and cosmic background
- Mothership is difficult to be used as a part of the array



High speed downlink (optional)

Phased array antenna— no moving parts

Reflector antenna- light and easier



Space engineering solution

Launch

- Launch into lunar orbit by LM-2D or Vega plus an upper stage

Wireless bus

- CCSDS Proximity-1
- SOIS

Relative distance

- Dual One-way Ranging, DOR

Time synchronization

- Dual time comparison

Relative positioning

- Relative distance
- Relative spatial angle

Attitude measurement

- Star tracker

Payload

- Space-borne radio synthetic aperture radiometer with 12 nano-satellites

Preliminary specifications

Mission:

- **Orbit:** 300 km
- **Number of satellites:** 13 (1 mother + 12 daughters)
- **Mass:** 300kg
Mother: 180kg
Daughters: 10kg*12
- **Power:** 15W*12 + 1200W
- **Downlink rate:** <20Mbps (onboard correlation);
>100 Mbps (raw data, HGA)
- **Life time:** 3 years

Payload

- **Frequency range:** 0.3 ÷ 30 MHz
- **Polarization:** Full-pol (circular pol)
- **Antenna:** Cross dipole, 2.5 m each stick
- **Baseline:** 100 m to 100 km
- **Angular resolution:** 6' @ 1 MHz, 12" @ 30 MHz
- **Visibilities:** ≈ 54K (half orbit), 59M (20 days)

Mass and Power consumption

- Mother satellite mass and power consumption

Subsystem	Subsystem Mass(kg)	Subsystem Power(W)
ADCS	3.87	6.6
Power	40.00	0.0
Propulsion	65.00	1100.0
Structure	50.00	0.0
Thermal	6.00	8.0
Communications	7.86	97.0
Payload	4.00	25.0
Data Handling	1.40	9.0
Total	178.13	1229.6

The mass of mother satellite is **178.13kg**, and power is **1229.6W**.

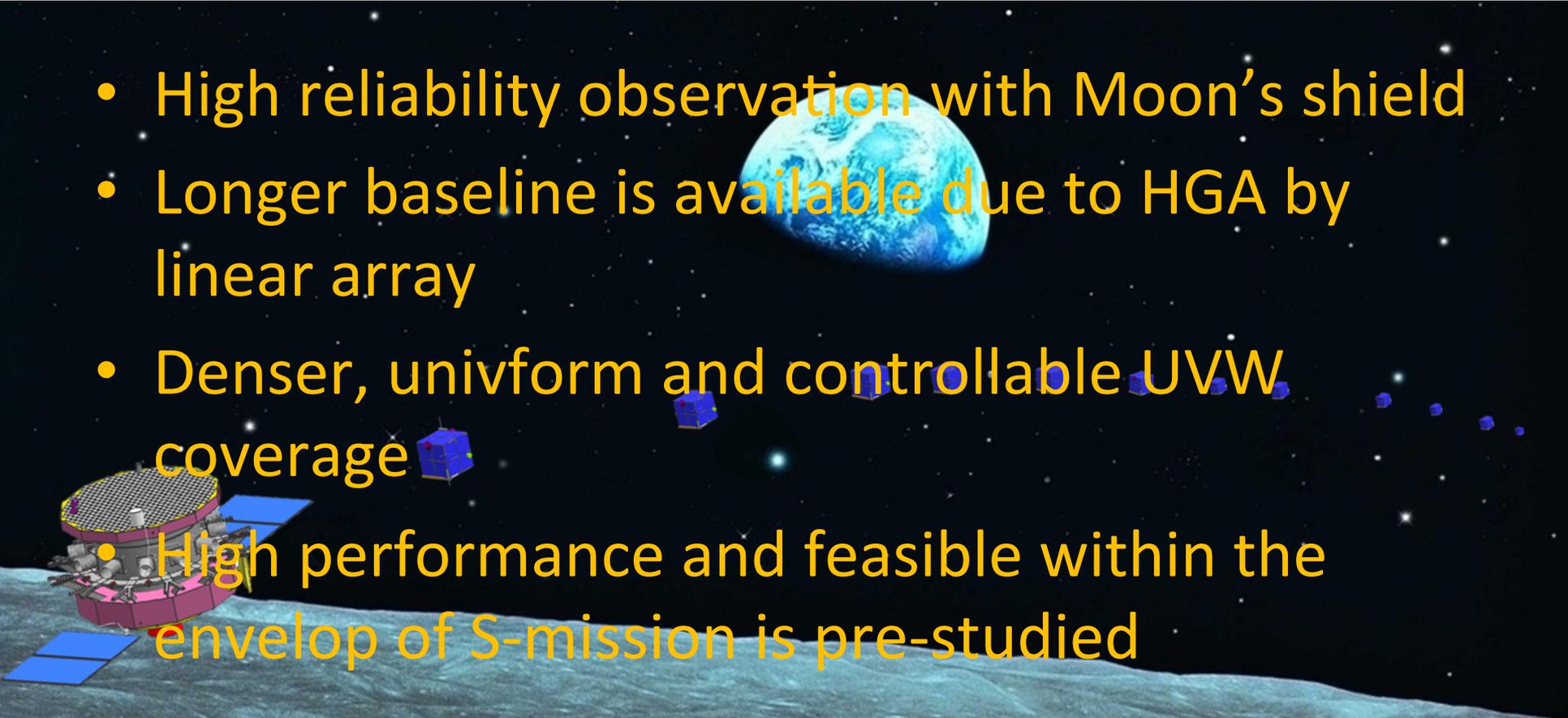
Mass and Power Consumption

- Daughter satellite mass and power

Subsystem	Subsystem Mass(kg)	Subsystem Power(W)
ADCS	1.08	2.3
Power	1.55	0.0
Propulsion	0.60	2.0
Structure	2.00	0.0
Thermal	1.00	1.0
Communications	0.50	6.0
Payload	2.00	1.5
Data Handling	0.60	3.0
Total	9.33	15.8

The mass of daughter satellite is **9.33kg**, and power is **15.8W**.

Summary

- High reliability observation with Moon's shield
 - Longer baseline is available due to HGA by linear array
 - Denser, uniform and controllable UVW coverage
 - High performance and feasible within the envelop of S-mission is pre-studied
- 
- A 3D rendering of a lunar lander on the moon's surface. The lander is a pinkish-red structure with a large, circular, grid-like antenna array on top and two blue solar panels extending from the sides. In the background, a large, blue and white Earth is visible in the sky, surrounded by a field of stars. Several small, blue, cube-shaped satellites are scattered in the space between the lander and the Earth.