Polarization in Interferometry

A basic introduction

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European Radio Interferometry School Dwingeloo (October 2017)









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Goals of this lecture



- Get familiar with some basics of polarimetry.
 - The different states of polarization.
 - The Stokes parameters.
- Understand radioastronomical polarizers.
 - Linear dipoles and quarter waveplates.
 - Polarization in interferometry: the Measurement Equation.
- Learn the basic calibration procedures.
 - Calibration with the Measurement Equation.
 - The effects of cross-delay (phase), amplitude, and leakage.
- Calibrate and process real observations (Tutorial: ALMA Band 5).

"Ordering" photons:

The polarization of light

Light polarization in the Universe.



Photons are produced at different source locations and under different conditions. As a result, light can have two components: one with deterministic \vec{E} directions and another with a "stochastic" variability.

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Light polarization in the Universe.





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Light polarization in the Universe.





"Ordered" light comes from large-scale structures with consistent properties (e.g., \vec{B})

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A random orientation of \vec{E}



 \vec{E} as seen on the wave-front plane

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 \vec{E} as seen on the wave-front plane

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Polarization modes



LINEAR



• ELLIPTIC (i.e., LINEAR + CIRCULAR)

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• We need four quantities to fully describe the polarization state:

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 - How much polarized vs. unpolarized light do we have?
 - What is the strength and direction of the linear polarization?
 - How much circular polarization do we have?



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Polarizers in Radio Astronomy

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Detecting source polarization



• The Stokes parameters describe the polarization state of light. But how do we measure them?

Detecting source polarization



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- Polarizing receivers (polarizers). The signal is split coherently into two orthogonal polarization states.

Detecting source polarization



- The Stokes parameters describe the polarization state of light. But how do we measure them?
- Polarizing receivers (polarizers). The signal is split coherently into two orthogonal polarization states.
 - Linear polarizers (horizontal / vertical linear polarization).
 - Circular polarizers (left / right circular polarization).





Decomposing linear pol. with linear polarizers (no phase offset)

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Decomposing circular pol. (left) with linear polarizers (90° offset)

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Decomposing circular pol. (right) with linear polarizers (270° offset)

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Decomposing elliptical pol. (right) with linear polarizers (generic phase offset)

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- $I = |E_x|^2 + |E_y|^2$
- $Q = |E_x|^2 |E_y|^2$
- $U = 2 \operatorname{Re}(E_x E_y^*)$
- $V = 2 Im(E_x E_y^*)$

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Decomposing linear pol. with circular polarizers (phase offset gives inclination)

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Decomposing elliptical pol. with circular polarizers (R/L amplitude difference)

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- $I = |E_I|^2 + |E_r|^2$
- $V = |E_I|^2 |E_r|^2$
- $Q = 2 \operatorname{Re}(E_l^* E_r)$
- $U = -2 Im(E_l^* E_r)$

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Advanced formulation: The Measurement Equation

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The classical formalism



$$V_{obs}^{AB} = G_A G_B^* \int_{\alpha,\delta} I(\alpha,\delta) e^{-\frac{2\pi j}{\lambda}(u\,\alpha+v\,\delta)} \frac{d\alpha\,d\delta}{z}$$

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Image: Image

• Electric field seen by antenna A: $\vec{E^A}$.



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- Electric field seen by antenna A: $\vec{E^A}$.
- For baseline *AB*, the coherency matrix is $E^{AB} = \vec{E^A} (\vec{E^B})^H$

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- Electric field seen by antenna A: $\vec{E^A}$.
- For baseline AB, the coherency matrix is $E^{AB} = \vec{E^A} (\vec{E^B})^H$
- In the x-y polarization basis, the coherency matrix for baseline AB is:

$$E^{AB} = \begin{pmatrix} \left\langle E_x^A \left(E_x^B \right)^* \right\rangle & \left\langle E_x^A \left(E_y^B \right)^* \right\rangle \\ \left\langle E_y^A \left(E_x^B \right)^* \right\rangle & \left\langle E_y^A \left(E_y^B \right)^* \right\rangle \end{pmatrix}$$



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• We also define the brightness matrix, S. For x-y polarizers, it is

$$S = \begin{pmatrix} I + Q & U + j V \\ U - j V & I - Q \end{pmatrix}$$



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The coherency matrix is related to the Fourier transform of the brightness matrix!

$$E^{AB} = \mathcal{F}[S]|_{(u,v)}$$

Coherency matrix and Visibility matrix.



• Voltage for antenna A with an x-y polarizer is: $\vec{v^A} = J^A \vec{E^A}$, where $\vec{E^A}$ is the electric field in the x-y base and J^A is the Jones matrix that calibrates antenna A.

Coherency matrix and Visibility matrix.



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- The visibility matrix (i.e., voltage cross-correlations) is:

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• Since $\vec{v_i} = J_i \vec{E_i}$,

$$V^{AB} = J_{A}\vec{E_{A}}\left(\vec{E_{B}}\right)^{H}J_{B}^{H} = J_{A}\begin{pmatrix} \left\langle E_{x}^{A}\left(E_{x}^{B}\right)^{*}\right\rangle & \left\langle E_{x}^{A}\left(E_{y}^{B}\right)^{*}\right\rangle \\ \left\langle E_{y}^{A}\left(E_{x}^{B}\right)^{*}\right\rangle & \left\langle E_{y}^{A}\left(E_{y}^{B}\right)^{*}\right\rangle \end{pmatrix} J_{B}^{H}$$

The MEq. A full Stokes formalism



For a source with a generic structure, the visibility matrix for antennas A and B (with no direction-dependent calibration) will be

$$V_{AB}^{obs} = J_{A} \left[\int_{\alpha, \delta} S \, e^{-\frac{2\pi j}{\lambda} (u \, \alpha + v \, \delta)} \, \frac{d\alpha \, d\delta}{z} \right] \left(J_{B} \right)^{H}$$

where (α, δ) are the (normalized) sky coordinates in the source plane, and $z = \sqrt{1 - \alpha^2 - \delta^2}$.

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Let us remember the classical interferometer equation:

$$V_{AB}^{obs} = G_A G_B^* \int_{\alpha,\delta} I(\alpha,\delta) e^{-\frac{2\pi j}{\lambda}(u\,\alpha+v\,\delta)} \frac{d\alpha\,d\delta}{z}$$

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Jones calibration matrices. Examples



• Gain,
$$G = \begin{pmatrix} A_x(t) e^{j\phi_x(t)} & 0\\ 0 & A_y(t) e^{j\phi_y(t)} \end{pmatrix}$$

• Delay, $K = \begin{pmatrix} e^{j\tau_x(\nu-\nu_0)} & 0\\ 0 & e^{j\tau_y(\nu-\nu_0)} \end{pmatrix}$
• Bandpass, $B = \begin{pmatrix} A_x(\nu) e^{j\phi_x(\nu)} & 0\\ 0 & A_y(\nu) e^{j\phi_y(\nu)} \end{pmatrix}$

The Jones matrices are multiplicative, e.g.: $J = G \times B \times K$, but care must be taken, since matrices generally do not commute.



Polarization calibration

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Polarization calibration



- Parallactic angle.
- Polarization leakage.
- Cross-Delay/phase.
- Amplitude ratio.

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Pol. calibration I. Parallactic angle



$$P_{xy} = \begin{pmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{pmatrix} \qquad P_{rl} = \begin{pmatrix} e^{j\phi} & 0 \\ 0 & e^{-j\phi} \end{pmatrix}$$

- Is the rotation of the antenna mount axis w.r.t. the sky.
- Is deterministic. It's good to apply it before the phase (and delay/rate) calibration.
- It does not commute with the gains for linear polarizers.
- In VLBI, it also mixes V_{xx} and V_{yy} with V_{xy} and V_{yx} .

Pol. calibration II. Leakage



$$D_{xy} = egin{pmatrix} 1 & D_x(
u) \ D_y(
u) & 1 \end{pmatrix}$$

- Is caused by cross-talking between the polarizer channels
- Each leaked signal is modified by an amplitude and a phase.
- Introduces spurious ellipticity and linear polarization.

LIN. + LEAK CIRC. + LEAK

Pol. calibration III. Cross-hand delay/pha



$$\mathcal{K}_{m{c}} = egin{pmatrix} 1 & 0 \ 0 & e^{j(au_{m{c}}(
u-
u_0)+\phi_{m{c}})} \end{pmatrix},$$

- Is caused by a delay between the polarizer channels at the reference antenna.
- In linear polarizers, introduces ellipticity and spurious V.
- In circular polarizers, just rotates the PA of the linear polarization.

OFFSET: 0° OFFSET: 45°

LINEAR:

CIRCULAR:

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Pol. calibration IV. Amplitude ratio $G_a = \begin{pmatrix} 1 & 0 \\ 0 & A_c \end{pmatrix}$



- Is caused by different *T*_{sys}, gain and/or bandpass between polarizer channels.
- In linear polarizers, introduces spurious linear polarization.
- In circular polarizers, introduces spurious Stokes V.
- Not *explicitely* calibrated, but implicit in the gain calibration.



The right order for matrix product is: $J = (G_a K_c) \times D \times P$ i.e.: $V^{cal} = P^{-1} \times D^{-1} \times (G_a K_c)^{-1} \times V^{obs}$

 STEP 1 (optional): Calibrate the cross-delay using a strong polarized source.



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- STEP 1 (optional): Calibrate the cross-delay using a strong polarized source.
- STEP 2: Calibrate the leakage using an unpolarized source.
 - If all calibrators are polarized, solve for leakage and source polarization simultaneously.
 - Need good parallactic-angle coverage.



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• STEP 4: Image each Stokes parameter separately. Combine images: $(Q, U) \rightarrow (I_p, \theta)$.



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SUMMARY



- We have reviewed basic concepts of polarization.
 - Modes of polarization.
 - Stokes parameters.
- We have discussed about the different kinds of polarizers in radioastronomical receivers.
 - Linear polarizers (X-Y).
 - Circular polarizers (R-L).
- We have studied how to deal with polarization in interferometric observations.
 - The Measurement Equation.
 - The matrices for polarization calibration.
 - Calibration effects on X-Y vs. R-L polarizers.
 - Overview of calibration procedure.

RadioNet has received funding from the European Union's Horizon 2020 research and innovation programme under grant agreement No 730562

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THANKS

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