

Introduction to Low-Frequency Radio Astronomy

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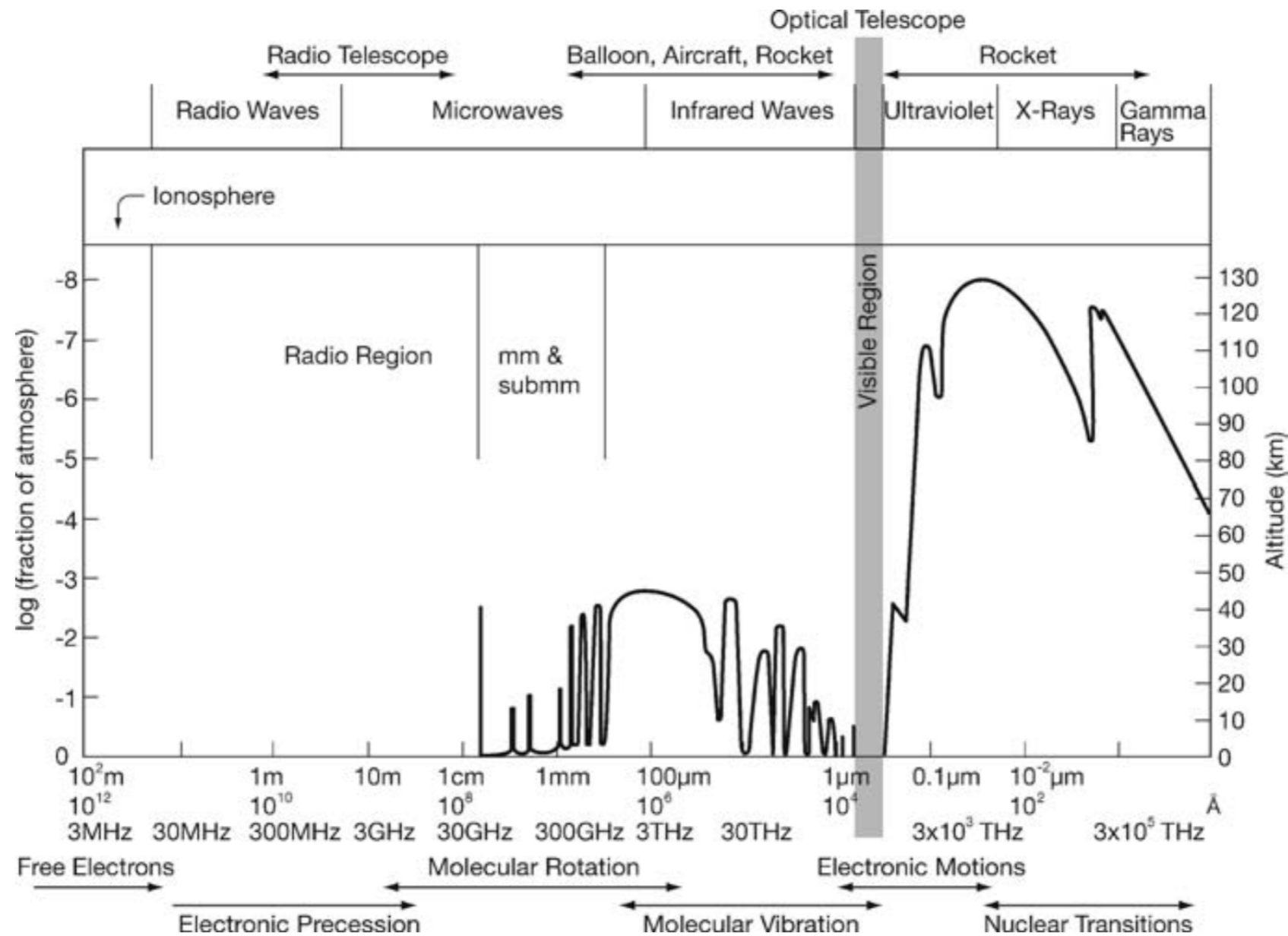
Preamble

- **AIM:** This lecture aims to give a general introduction to low frequency radio astronomy, focusing on the issues that you must consider and the differences with observations with other telescopes.
- **OUTLINE:**
 1. The radio sky and historical developments
 2. The response of a dipole antenna
 3. The response of an interferometer
 4. Low frequency radio telescopes



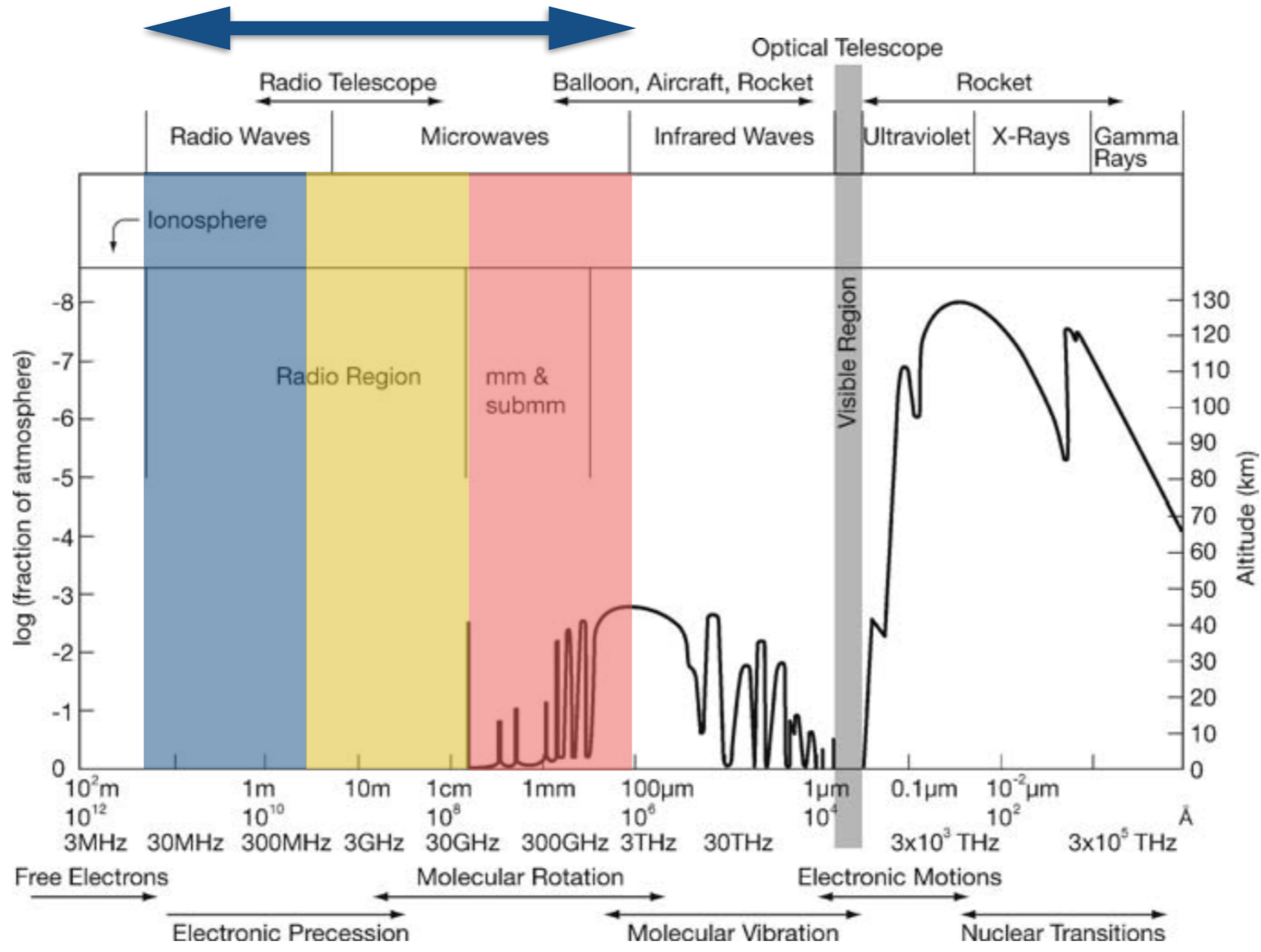
1.1 The Radio Window

- Radio Astronomy is the study of radiation from celestial sources at frequencies between $\nu \sim 10$ MHz to 1 THz (10^7 Hz to 10^{12} Hz).



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- The observing window is constrained by atmospheric absorption / emission and refraction.
 - 1) Charged particles in the ionosphere reflect radio waves back into space at < 10 MHz.
 - 2) Vibrational transitions of molecules have similar energy to infra-red photons and absorb the radiation at > 1 GHz (completely by ~300 GHz).

1.2 The low-frequency cut-off

- The ionosphere consists of a plasma of charged particles (conducting layers), that has an effective refractive index of,

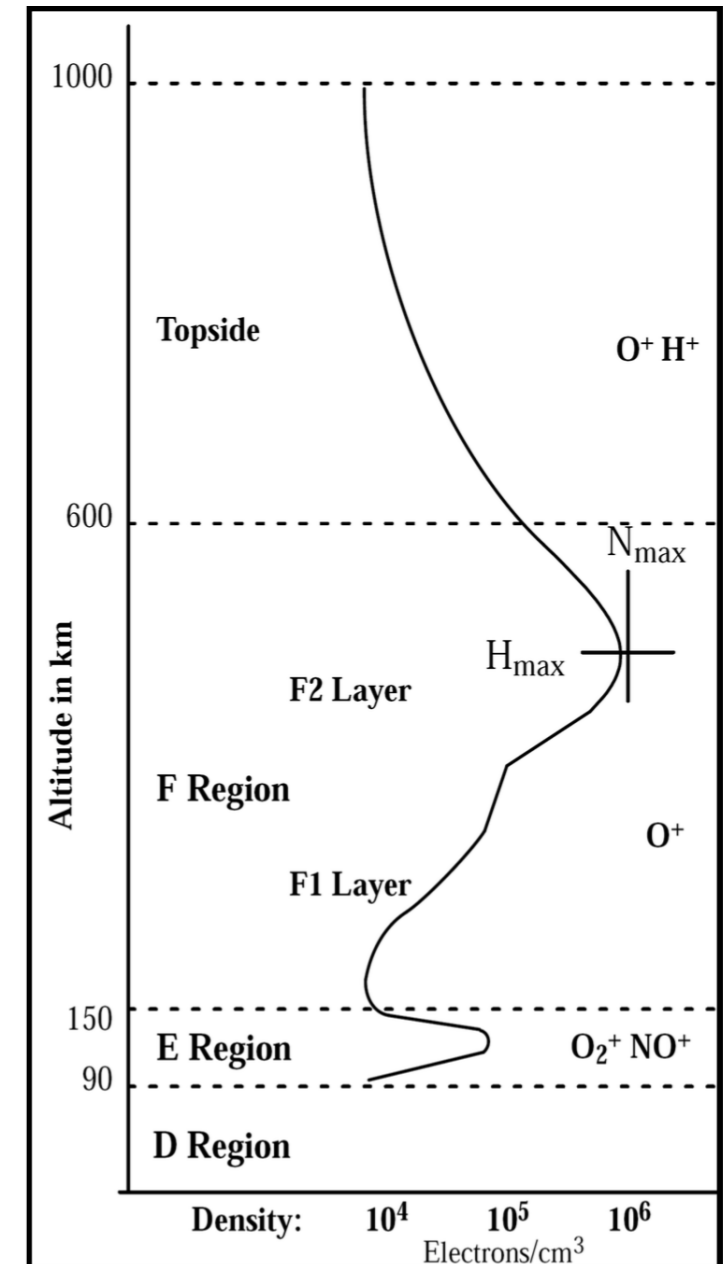
$$n^2 = 1 - \frac{\omega_p^2}{\omega^2} = 1 - \left(\frac{\lambda}{\lambda_p}\right)^2$$

where, the plasma frequency is defined as,

$$\nu_p [\text{Hz}] = \frac{\omega_p}{2\pi} = \left(\frac{N_e e^2}{4\pi^2 \epsilon_0 m}\right)^{1/2} = 8.97 \times 10^3 \sqrt{\frac{N_e}{[\text{cm}^{-3}]}}$$

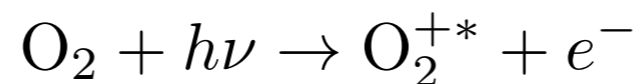
[see Calibration & Ionospheric lectures]

when $\omega < \omega_p$, there is no propagation, i.e. total reflection.



Worked example: What is the cut-off frequency for LOFAR observations carried out when the electron density is $N_e = 2.5 \times 10^5 \text{ cm}^{-3}$ (night time) and $N_e = 1.5 \times 10^6 \text{ cm}^{-3}$ (day time)?

- At frequencies,
 1. $\omega < \omega_p$: n^2 is **negative**, reflection ($\nu < 10 \text{ MHz}$),
 2. $\omega > \omega_p$: n^2 is **positive**, refraction ($10 \text{ MHz} < \nu < 10 \text{ GHz}$),
 3. $\omega \gg \omega_p$: n^2 is **unity** ($\nu > 10 \text{ GHz}$).
- The observing conditions are dependent on the electron density, i.e. the solar conditions (space weather), since the ionisation is due to the ultra-violet radiation field from the Sun,

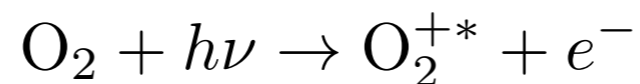


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$$\nu_p [\text{Hz}] = 8.97 \times 10^3 \sqrt{\frac{2.5 \times 10^5}{[\text{cm}^{-3}]}} = 4.5 \text{ MHz} \quad (\text{night time})$$

$$\nu_p [\text{Hz}] = 8.97 \times 10^3 \sqrt{\frac{1.5 \times 10^6}{[\text{cm}^{-3}]}} = 11 \text{ MHz} \quad (\text{day time})$$

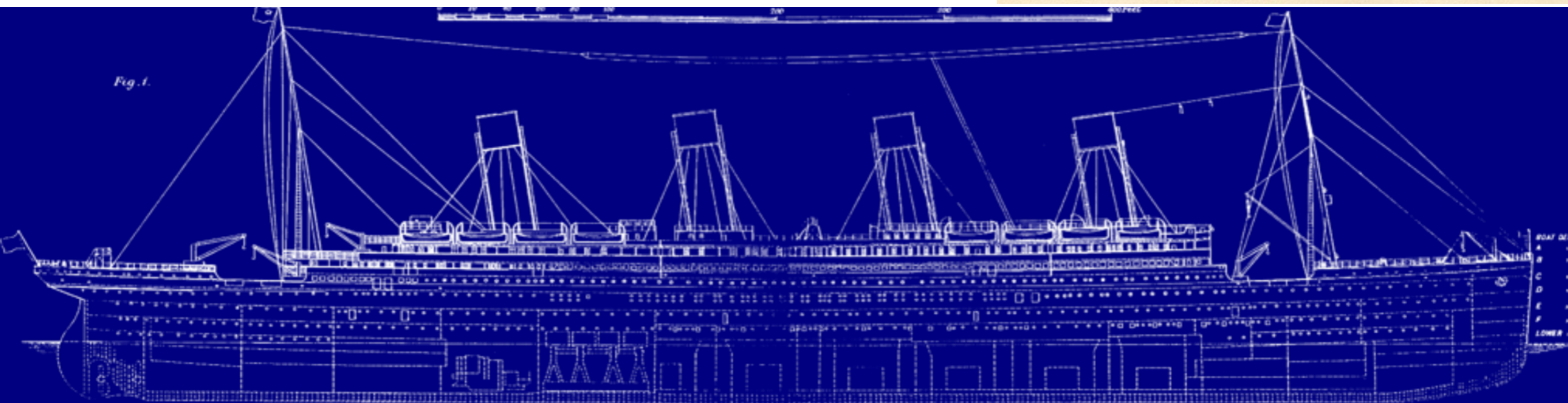
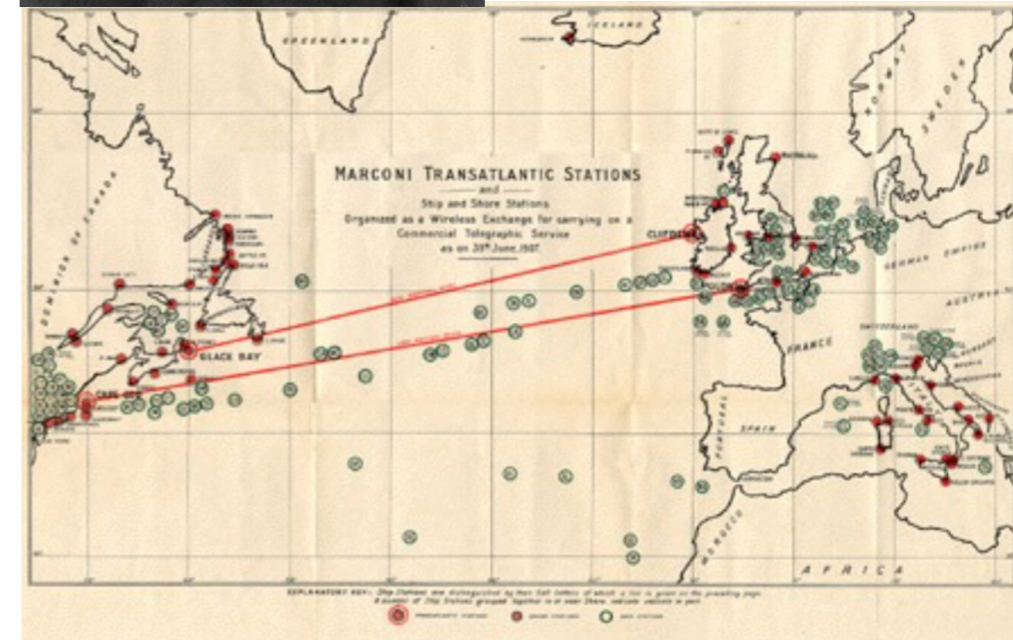
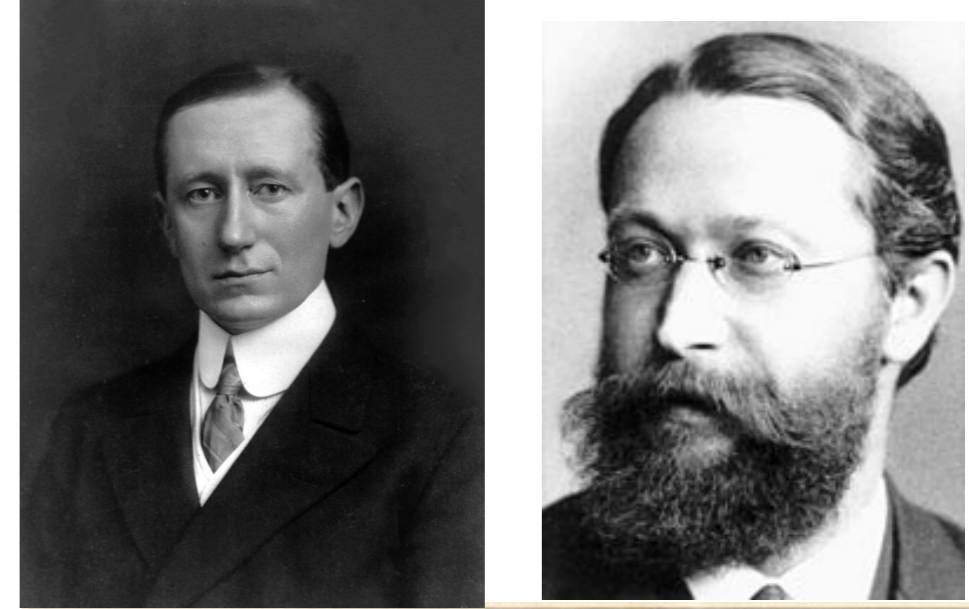
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- Long distance communication developed by Marconi & Ferdinand Braun - Nobel Prize 1909

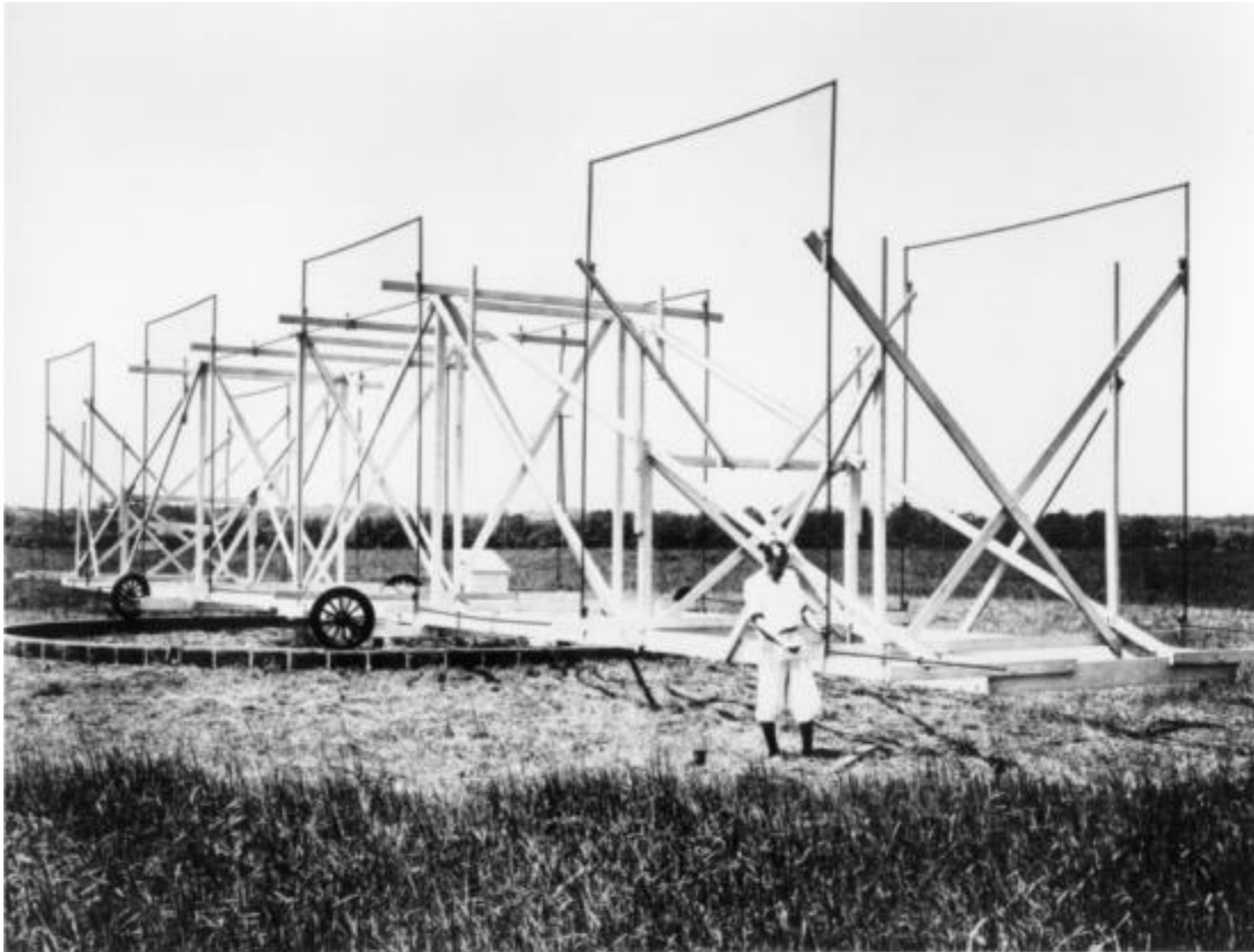
Evolution of frequency over the years

- pre-1920: <100 kHz.
- ca. 1920: shift to 1.5 MHz.
- post-1920: 10s of MHz (more voice channels, less effected by the ionosphere and thunderstorms).
- Research labs sprung up in early-1900s



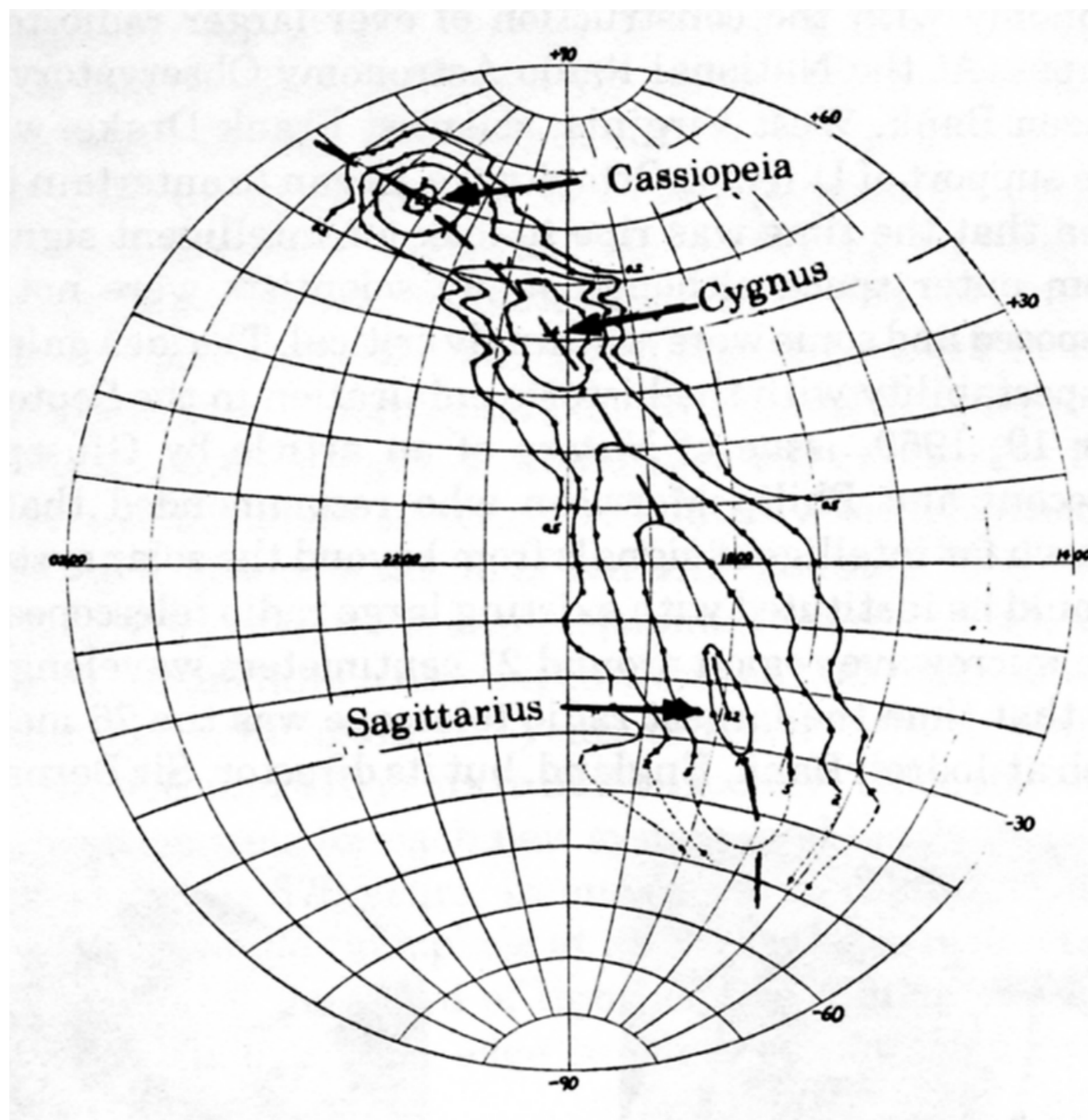
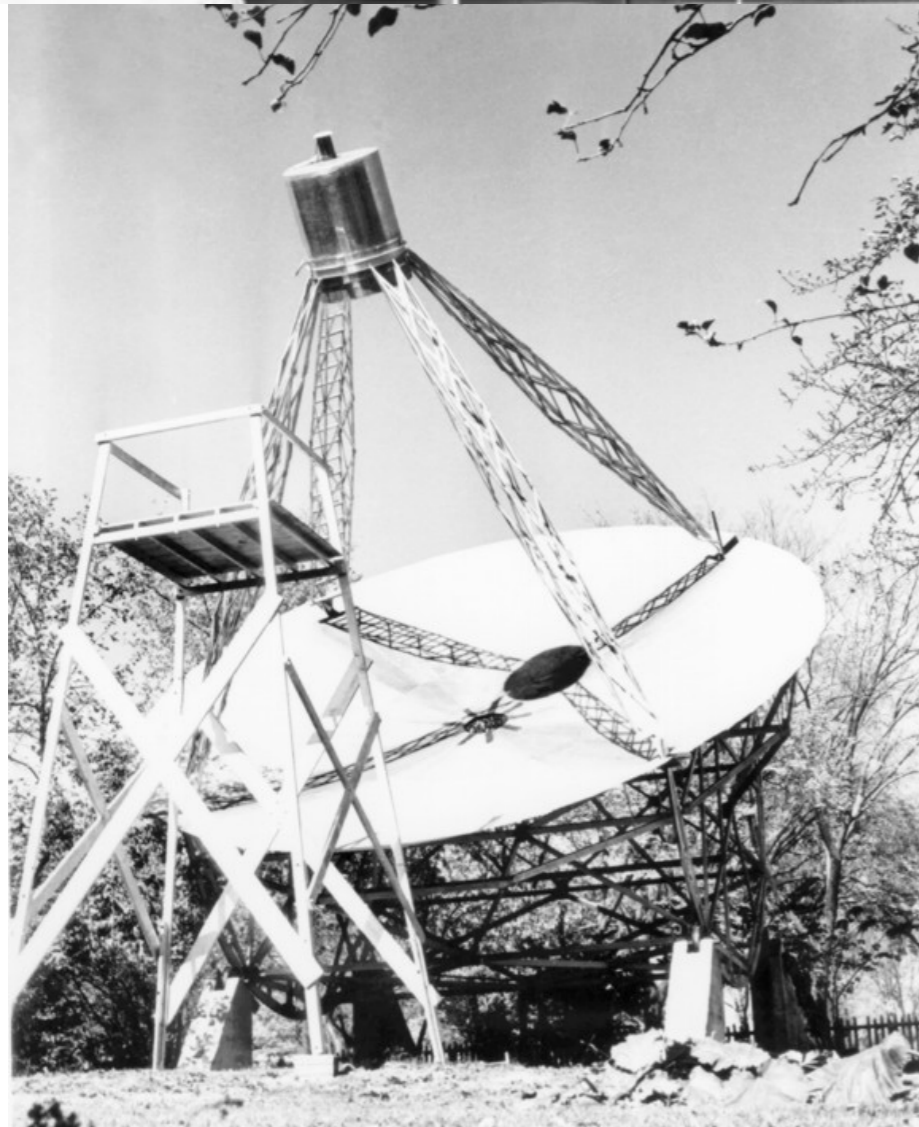
- Karl Jansky (1933, published) discovered a radio signal at 20.5 MHz that varied steady every 23 hours and 56 minutes (Sidereal day).

“The data give for the co-ordinates of the region from which the disturbance comes, a right ascension of 18 hours and declination -10 degrees.” He had detected the Galactic Centre.



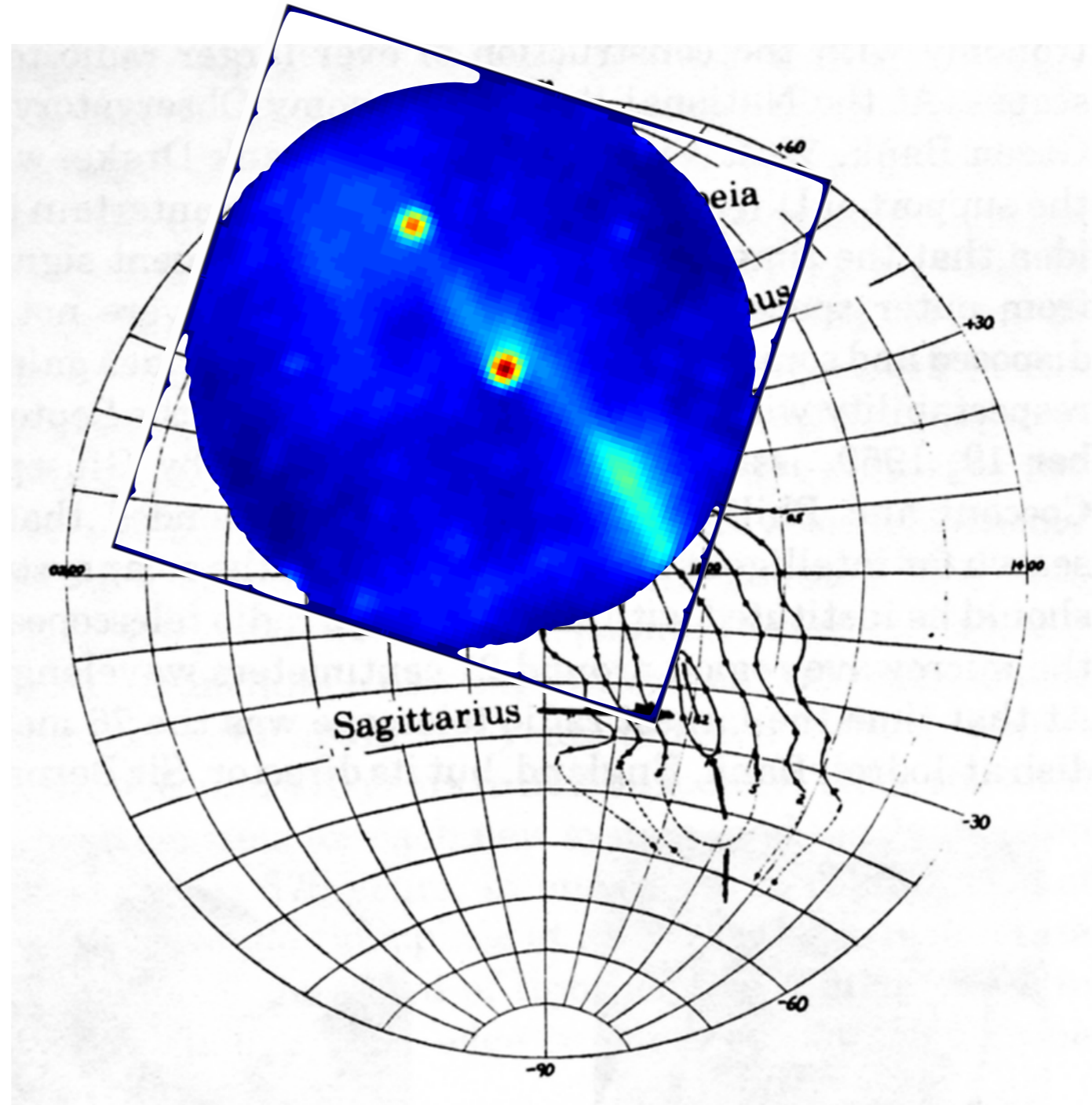
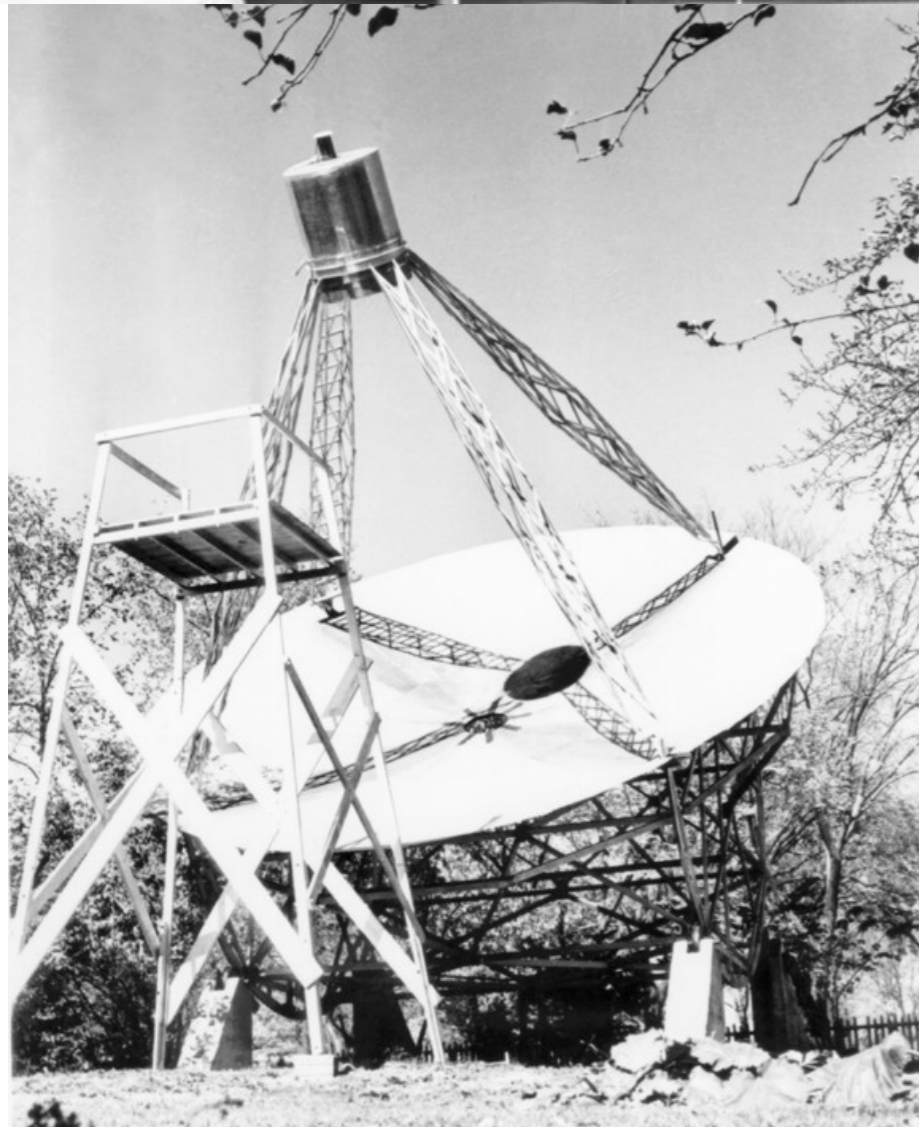


- Grote Reber (1937-39), using his own 10 m telescope, made no detection at 3300 and 910 MHz, ruling out a Planck spectrum ($B_\nu \propto \nu^2$).
- Detection made at 150 MHz, confirming Jansky's result and finding the spectrum must be non-thermal.



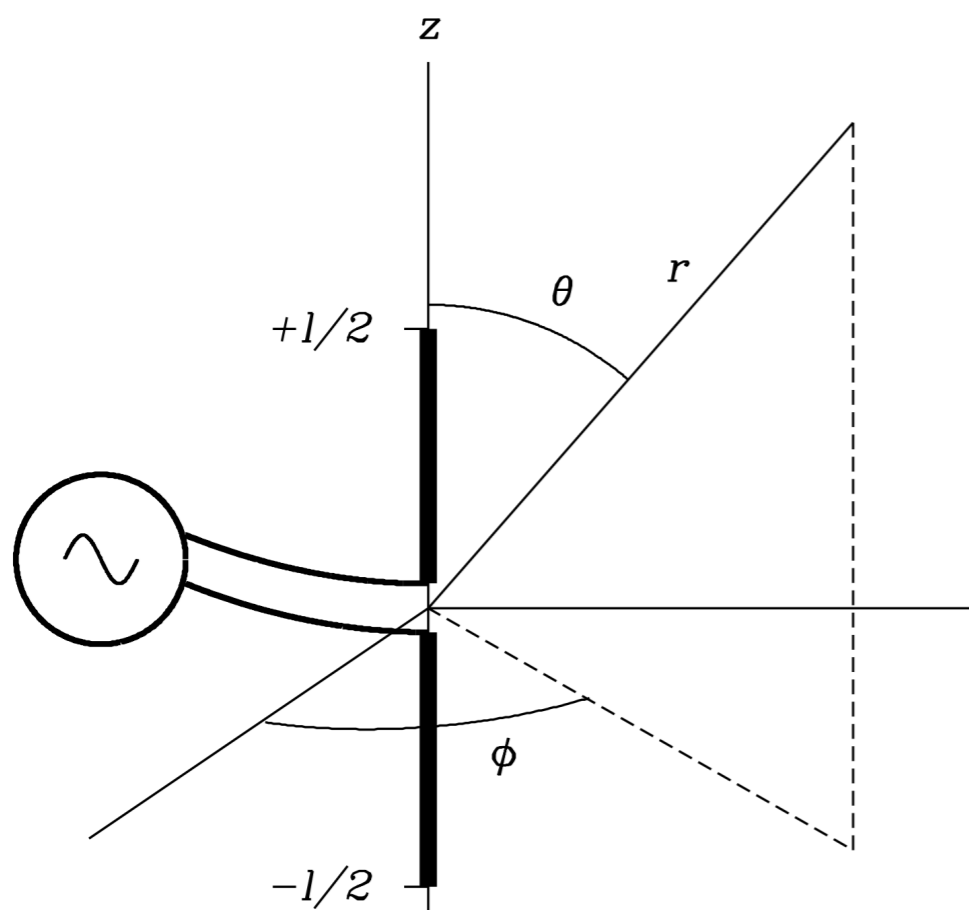


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2.1 Dipole antenna fundamentals

- **Antenna:** A device for converting electromagnetic radiation in space into electrical currents (transmitting and receiving).



Consider a Hertzian small ($l \ll \lambda$) dipole transmitter (same as for a receiving dipole, but easier to understand).

Two co-linear conductors (e.g. wires, conducting rods), driven by a current source at the gap. The driving current I is a time varying sinusoidally with angular frequency,

$$\omega = 2\pi\nu$$

$$I = I_0 \cos(\omega t) = I_0 e^{-i\omega t}$$

(Only consider the real part of $e^{-i\omega t} = \cos(\omega t) + i \sin(\omega t)$)

The time varying current density is defined as, $J = \frac{I}{q} = \frac{I_0}{q} e^{-i\omega t}$ inside the dipole,

and $J = 0$ outside the dipole.

- We want to measure the power radiated from such an antenna, so we calculate,
 1. The electromagnetic vector potential A ,
 2. The magnetic field induction B , and hence the magnetic field intensity H ,
 3. The electric field intensity E ,
 4. The Poynting flux S ,
 5. The total power radiated.

1. The electromagnetic vector potential

The induced magnetic field B is related to the vector potential by,

$$\vec{B} = \nabla \times \vec{A}$$

where,

$$\vec{A}(x) = \frac{\mu_0}{4\pi} \int \int \int \vec{J}(x) \frac{e^{ik|x-x'|}}{|x-x'|} d^3x'$$

i.e., the integral of the current density over the volume of the dipole ($dV = q dz$).

The current runs from $z = -\Delta l / 2$ and $z = +\Delta l / 2$ along the z -axis, thus

$$\begin{array}{l} \vec{J}_x = 0 \quad \text{and} \quad \vec{A}_x = 0 \\ \vec{J}_y = 0 \quad \text{and} \quad \vec{A}_y = 0 \end{array} \quad \text{only} \quad \vec{J}_z = \frac{I}{q} e^{-i\omega t} \quad \text{is non-zero.}$$

Therefore, our vector potential becomes,

$$\begin{aligned}\vec{A}_z &= \frac{\mu_0}{4\pi} \int_{-\Delta l/2}^{+\Delta l/2} \frac{I(z)}{q} e^{-i\omega t} \frac{e^{ikr}}{r} q dz \\ &= \frac{\mu_0}{4\pi} \frac{e^{-i(\omega t - kr)}}{r} \int_{-\Delta l/2}^{+\Delta l/2} I(z) dz\end{aligned}$$

If the current is constant,

$$\int_{-\Delta l/2}^{+\Delta l/2} I(z) dz = I [z]_{-\Delta l/2}^{+\Delta l/2} = I \Delta l$$

Therefore, our vector potential for a constant current is,

$$\vec{A}_z = \frac{\mu_0}{4\pi} \frac{e^{-i(\omega t - kr)}}{r} I \Delta l$$

2. The magnetic induction is related to the magnetic vector potential via,

$$\vec{B} = \nabla \times \vec{A}$$

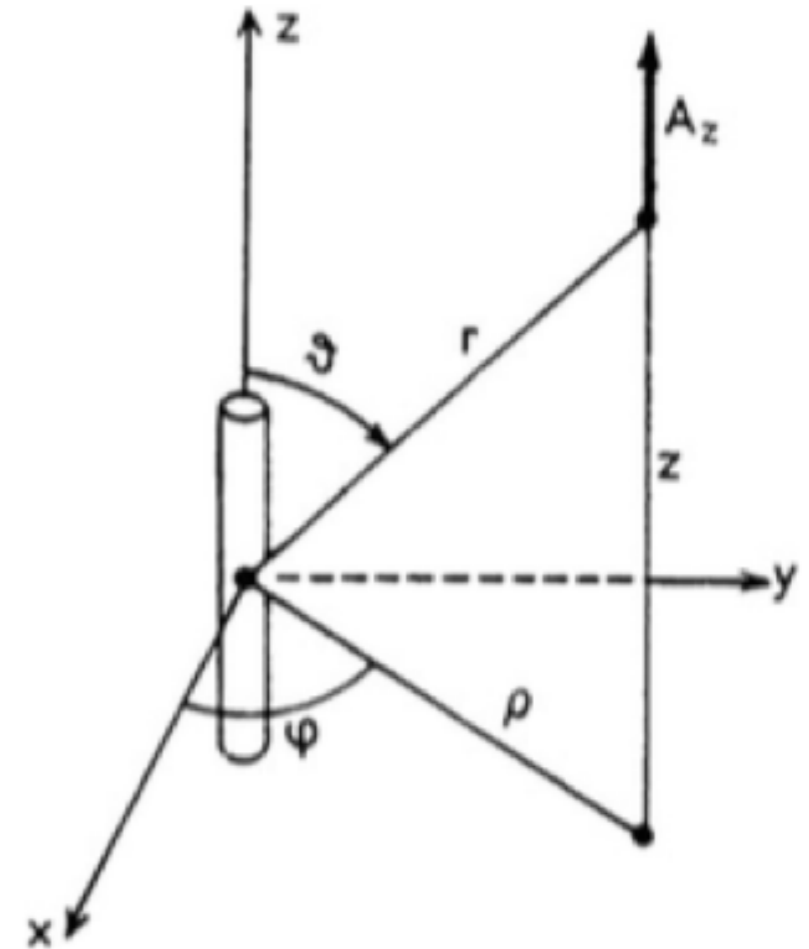
We can de-compose the curl of A into three orthogonal cylindrical co-ordinates (ρ, ψ, z) , using standard definitions,

$$(\nabla \times \vec{A})_{\rho} = \frac{1}{\rho} \frac{\partial A_z}{\partial \psi} - \frac{\partial A_{\psi}}{\partial z}$$

$$(\nabla \times \vec{A})_{\psi} = \frac{\partial A_{\rho}}{\partial z} - \frac{\partial A_z}{\partial \rho}$$

$$(\nabla \times \vec{A})_z = \frac{1}{\rho} \left(\frac{\partial(\rho A_{\psi})}{\partial \rho} - \frac{\partial A_{\rho}}{\partial \psi} \right)$$

As $A_{\rho} = A_{\psi} = 0$, the B-field must be perpendicular to the vector potential (A_z).



For simplicity lets evaluate,

$$B_{\psi} = (\nabla \times \vec{A})_{\psi} = \frac{\partial A_{\rho}}{\partial z} - \frac{\partial A_z}{\partial \rho} = -\frac{\partial A_z}{\partial \rho} = -\frac{\partial A_z}{\partial r} \frac{\partial r}{\partial \rho}$$

In the cylindrical system,

$$r^2 = \rho^2 + z^2 \quad r = (\rho^2 + z^2)^{1/2}$$

$$\frac{\partial r}{\partial \rho} = \frac{1}{2}(\rho^2 + z^2)^{-1/2} 2\rho = \frac{\rho}{r} = \sin \theta$$

Next,

$$\frac{\partial A_z}{\partial r} = \frac{\mu_0}{4\pi} I \Delta l e^{-i\omega t} \frac{\partial}{\partial r} \left[\frac{e^{ikr}}{r} \right]$$

We solve this using the quotient rule,

$$\left[\frac{u(r)}{v(r)} \right] = \frac{u'(r)v(r) - v'(r)u(r)}{v(r)^2} \quad \begin{array}{ll} u(r) = e^{ikr} & v(r) = r \\ u'(r) = ik e^{ikr} & v'(r) = 1 \end{array}$$

$$\frac{\partial}{\partial r} \left[\frac{e^{ikr}}{r} \right] = \frac{ik e^{ikr} \cdot r - 1 \cdot e^{ikr}}{r^2} = \frac{(ikr - 1)e^{ikr}}{r^2}$$

Therefore our B -field in the ψ direction becomes,

$$B_\psi = -\frac{\partial A_z}{\partial r} \frac{\partial r}{\partial \rho} = -ik \frac{\mu_0}{4\pi} I \Delta l \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

Since,

$$k = \frac{2\pi}{\lambda}$$

$$B_\psi = -i \mu_0 \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

which, from the materials equations, gives for the magnetic field intensity,

$$B = \mu_0 H \quad H_\psi = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

Again, the magnetic field intensity is perpendicular to the vector potential, that is, perpendicular to the element.

3. Now, let's consider the electric field intensity. From Maxwell's equations,

$$\nabla \times \vec{H} = \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

which, because we are away from the current element ($J = 0$), simplifies to,

$$\nabla \times \vec{H} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

We are dealing with harmonic waves of the form,

$$E(r, t) = E_0 e^{-i(\omega t - kr)}$$
$$\dot{E}(r, t) = E_0 e^{-i(\omega t - kr)} \cdot -i\omega = -i\omega E(r, t)$$

Therefore,

$$E = -\frac{1}{i\omega\epsilon_0} \nabla \times \vec{H}$$

To evaluate E , we must determine the curl of H , but as in the case of the B-field, only the H_ψ terms have non-zero entries.

From spherical co-ordinates, the only relevant term of the curl of H is,

$$(\nabla \times H)_\theta = -\frac{1}{r} \frac{\partial(rH_\psi)}{\partial r}$$

Note also, that the resulting E -field is in terms of θ and is perpendicular to the H -field, as expected for electromagnetic plane waves.

$$rH_\psi = -i \frac{I\Delta l}{2\lambda} \sin \theta \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

$$= -i \frac{I\Delta l}{2\lambda} \sin \theta e^{-i\omega t} \left(e^{ikr} - \frac{e^{ikr}}{ikr} \right)$$

$$\frac{\partial(rH_\psi)}{\partial r} = -i \frac{I\Delta l}{2\lambda} \sin \theta e^{-i\omega t} \frac{\partial}{\partial r} \left(e^{ikr} - \frac{e^{ikr}}{ikr} \right)$$

We solve this using the quotient rule,

$$\left[\frac{u(r)}{v(r)} \right] = \frac{u'(r)v(r) - v'(r)u(r)}{v(r)^2}$$

$$\begin{aligned} u(r) &= e^{ikr} & v(r) &= ikr \\ u'(r) &= ik e^{ikr} & v'(r) &= ik \end{aligned}$$

$$\begin{aligned} \frac{\partial}{\partial r} \left(e^{ikr} - \frac{e^{ikr}}{ikr} \right) &= ik e^{ikr} - \left(\frac{ik e^{ikr} \cdot ikr - ik \cdot e^{ikr}}{(ikr)^2} \right) \\ &= ik e^{ikr} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) \end{aligned}$$

so,

$$\frac{\partial(rH_\psi)}{\partial r} = -i \frac{I\Delta l}{2\lambda} \sin\theta e^{-i\omega t} ik e^{ikr} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right)$$

and,

$$-\frac{1}{r} \frac{\partial(rH_\psi)}{\partial r} = i^2 k \frac{I\Delta l}{2\lambda} \frac{\sin\theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

we find,

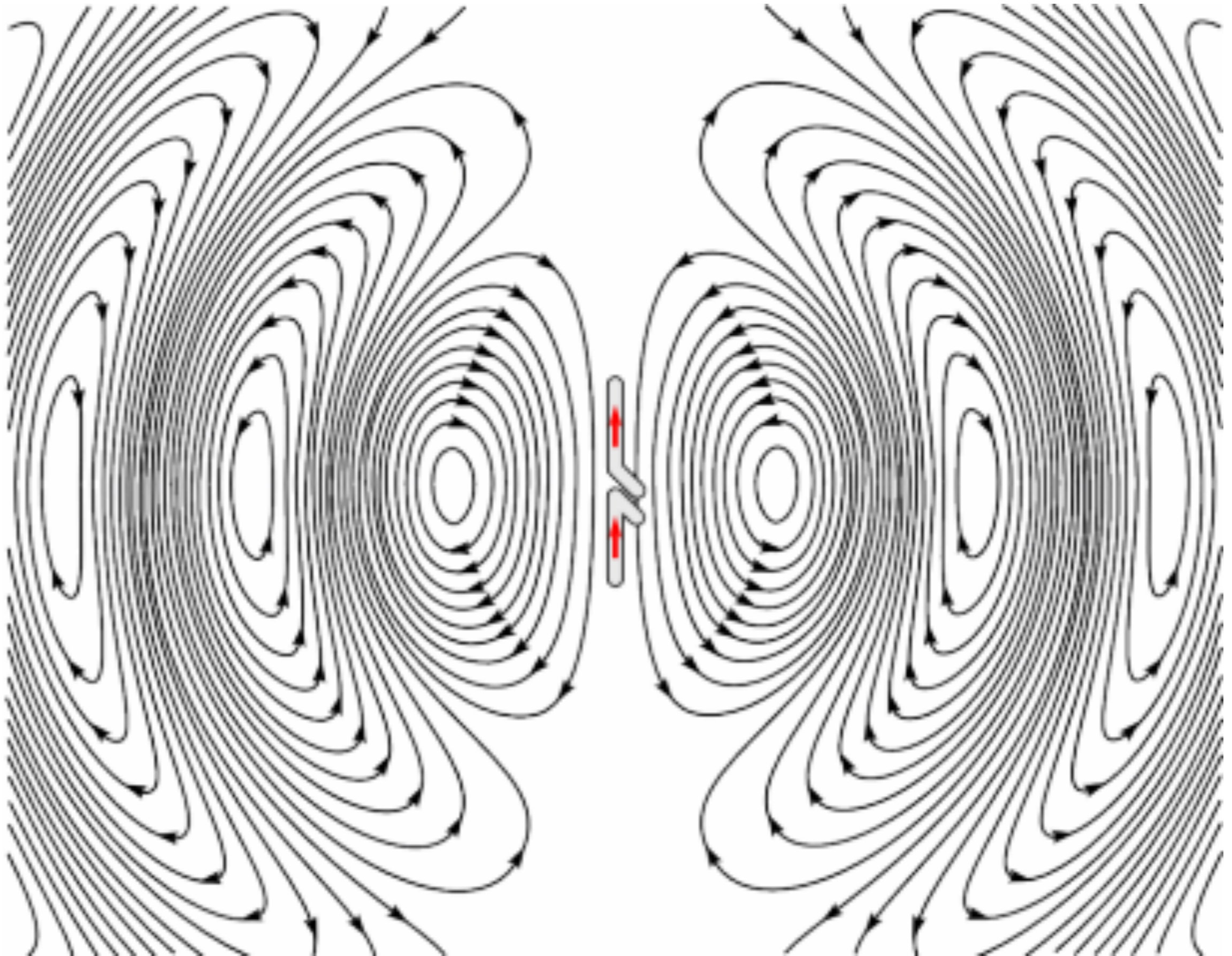
$$k = \frac{\omega}{c}$$

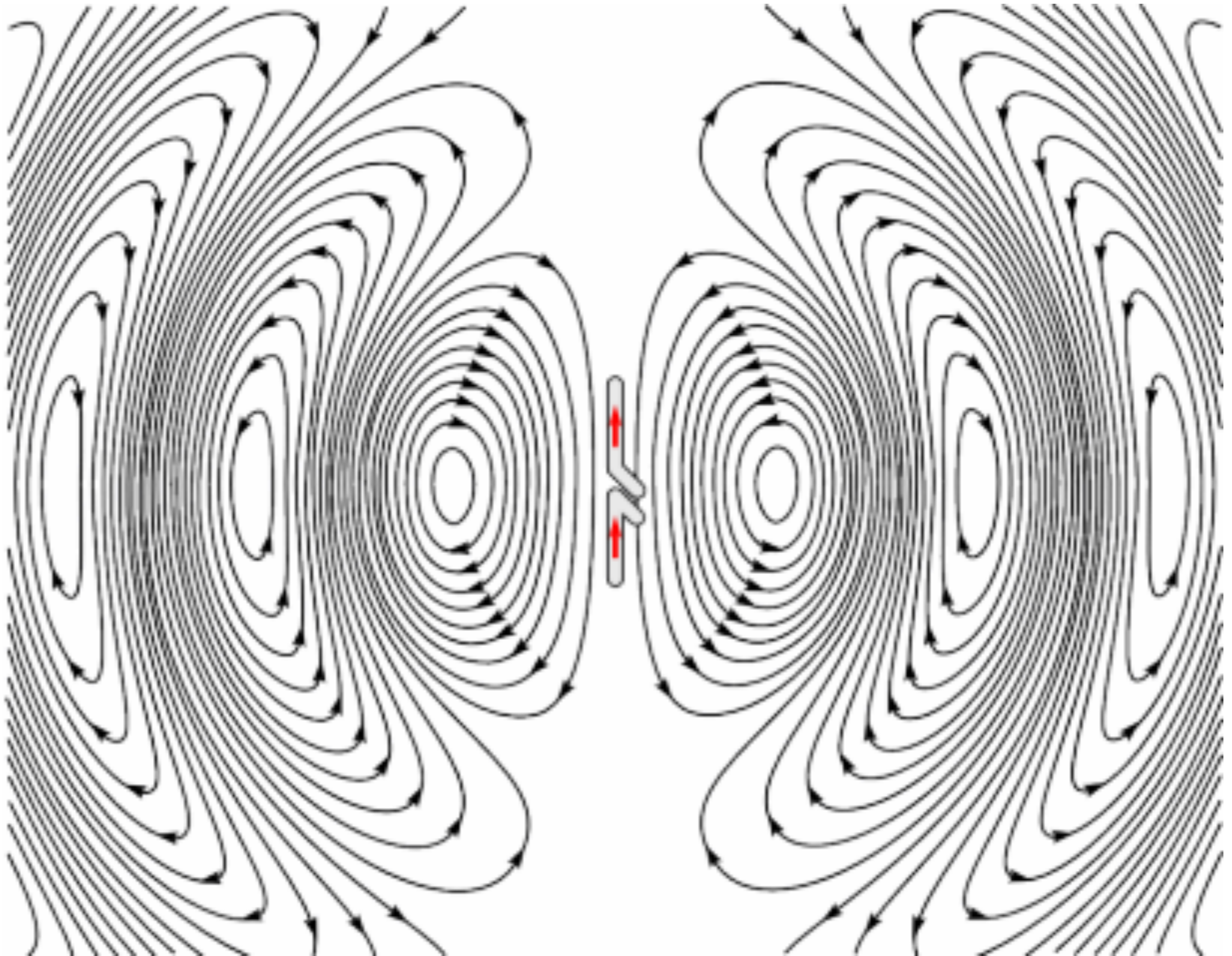
$$E_\theta = -i \frac{1}{c\epsilon_0} \frac{I\Delta l}{2\lambda} \frac{\sin\theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

So the E-field can also be expressed as,

$$c = \frac{1}{\sqrt{\mu_0\epsilon_0}}$$

$$E_\theta = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I\Delta l}{2\lambda} \frac{\sin\theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$





So, our electric and magnetic fields are,

$$H_{\psi} = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

$$E_{\theta} = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left(1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

There are several factors that depend on the power of the distance r from the antenna,

1. $1/r$: The radiation field (dominates at large $r \gg \Delta l$).
2. $1/r^2$: The induction field
3. $1/r^3$: The static field (of the E-field).

To calculate the near-field properties, all factors must be evaluated, but in the far-field, where we measure the radiation from the antennas, the $1/r$ term dominates.

$$H_{\psi} = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} e^{-i(\omega t - kr)}$$

$$E_{\theta} = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} e^{-i(\omega t - kr)}$$

Note that,

$$\frac{|E|}{|H|} = \sqrt{\frac{\mu_0}{\epsilon_0}} = 1$$

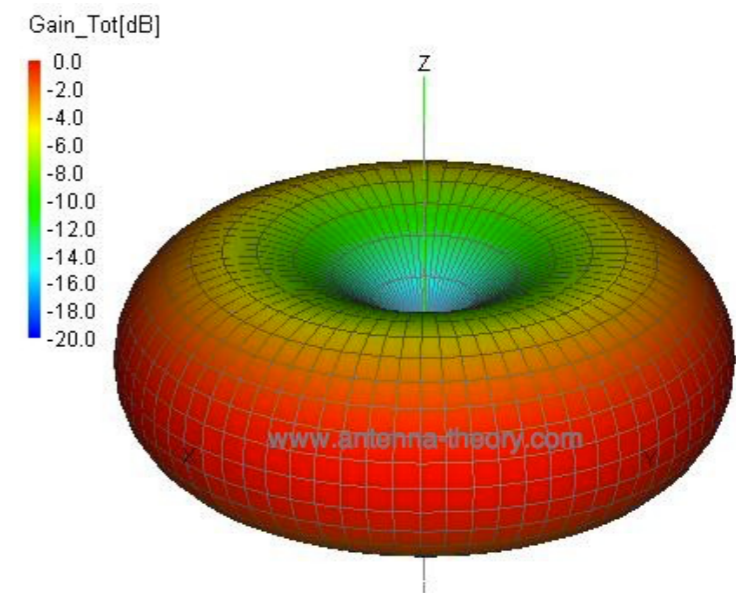
in cgs units

4. We can now determine the directional power per unit area in the far-field by calculating the time-averaged Poynting vector.

$$\begin{aligned}\langle \vec{S} \rangle &= \frac{1}{\mu_0} |\operatorname{Re} \vec{E} \times \vec{B}^*| = |\operatorname{Re} \vec{E} \times \vec{H}^*| \\ &= \sqrt{\frac{\mu_0}{\epsilon_0}} \left(\frac{I \Delta l}{2\lambda} \right)^2 \frac{\sin^2 \theta}{r^2} \left(\frac{1}{2} \right)\end{aligned}$$

where $\langle \cos^2(\omega t) \rangle = \frac{1}{2}$

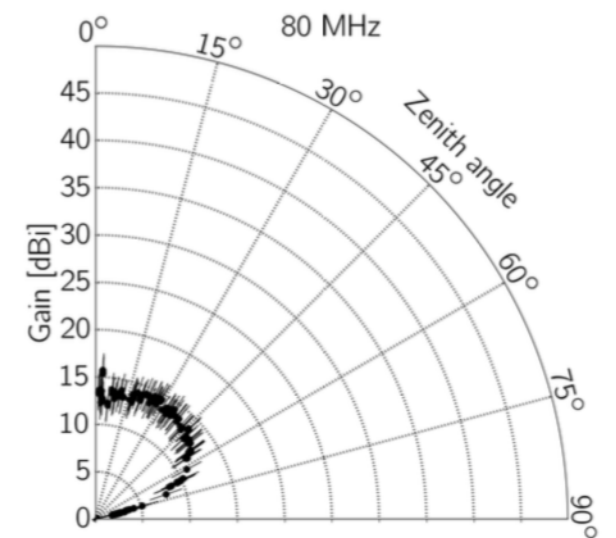
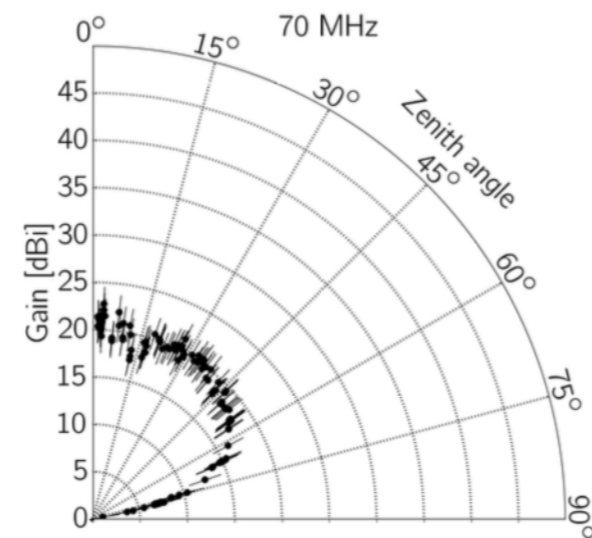
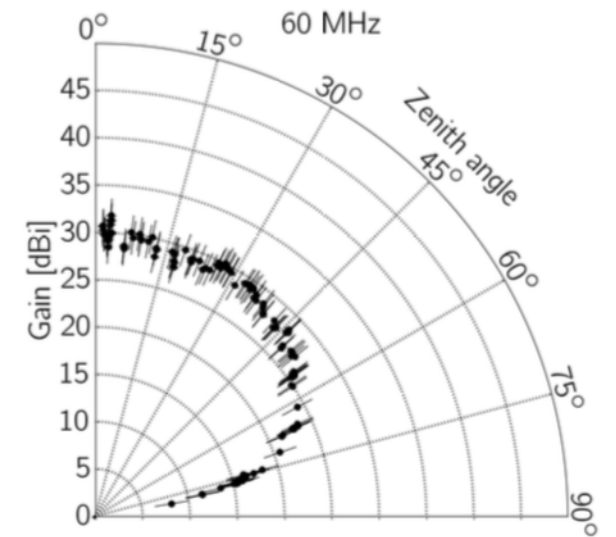
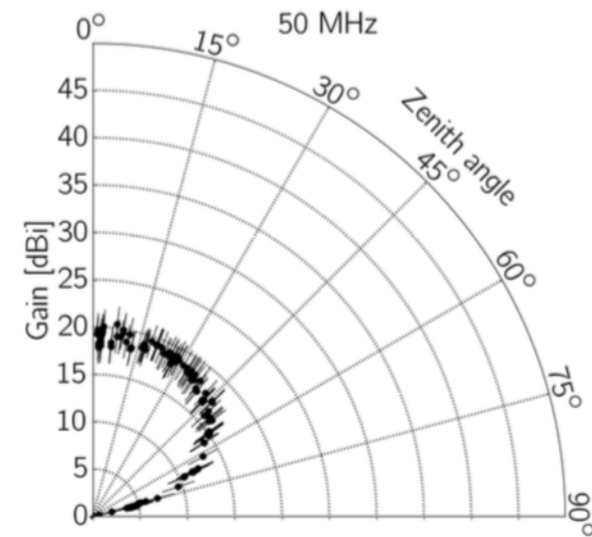
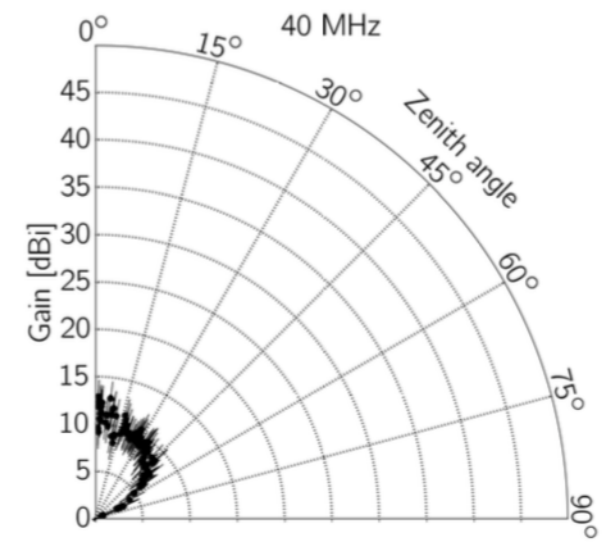
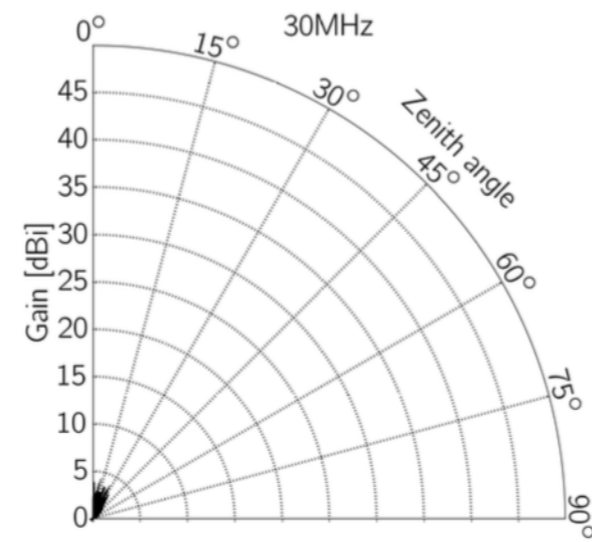
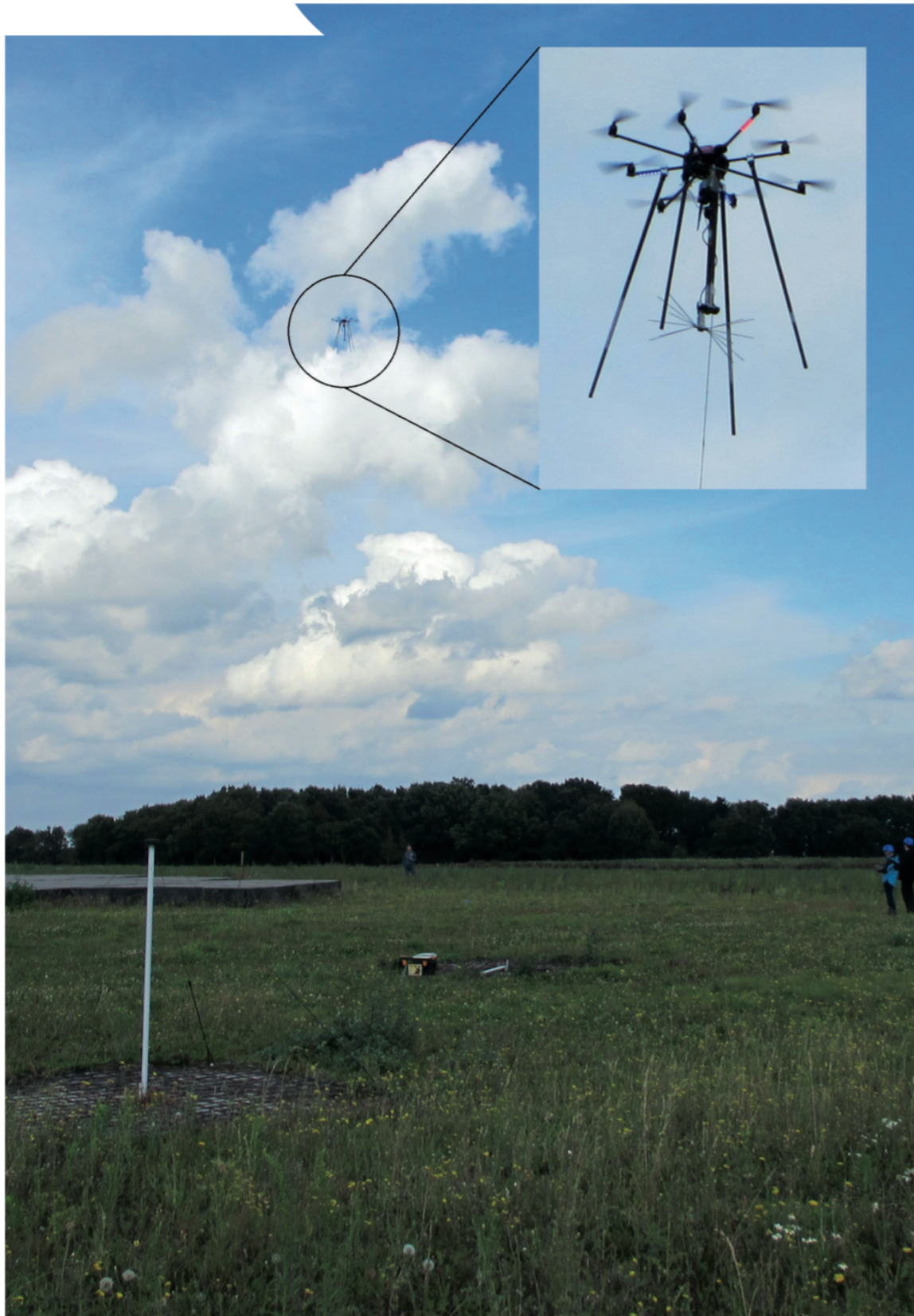
The radiation has doughnut shaped power pattern (angular distribution of radiated power) due to dependence on $\sin^2 \theta$.



5. The time-average power radiated is then the integral of the Poynting vector over a whole sphere.

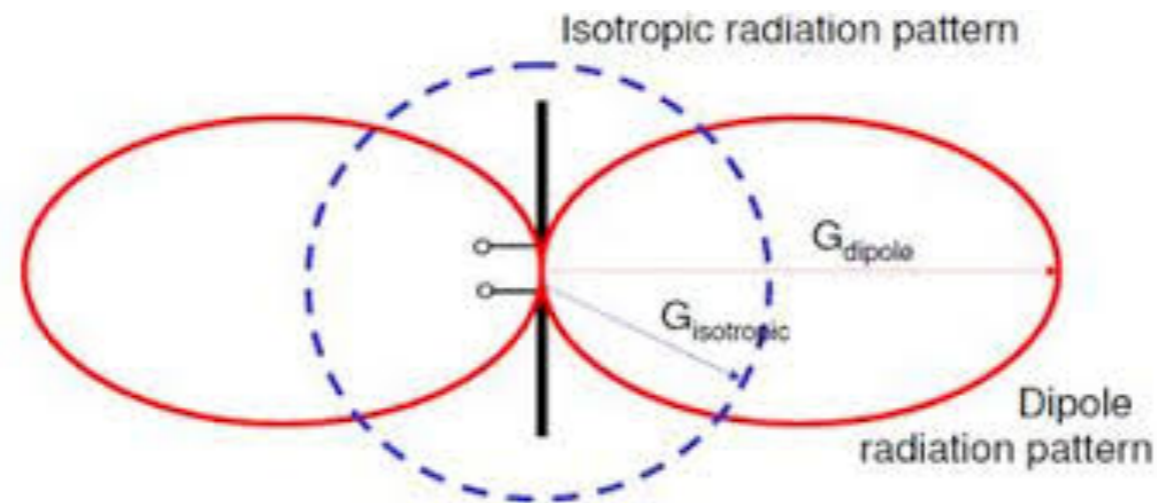
$$\begin{aligned}\langle P \rangle &= \int_{\text{sphere}} \langle S \rangle dA = \sqrt{\frac{\mu_0}{\epsilon_0}} \left(\frac{I \Delta l}{2\lambda} \right)^2 \left(\frac{1}{2} \right) \int_{\phi=0}^{\phi=2\pi} \int_{\theta=0}^{\theta=\pi} \frac{\sin^2 \theta}{r^2} r^2 \sin \theta d\theta d\phi \\ \langle P \rangle &= \frac{\pi}{3 c \epsilon_0} \left(\frac{I \Delta l}{\lambda} \right)^2\end{aligned}$$

2.2 Response of the LOFAR antenna:



2.3 Power gain:

$G(\theta, \phi)$ is the power transmitted per unit solid angle in direction (θ, ϕ) divided by the power transmitted per unit solid angle from an isotropic antenna with the same total power.



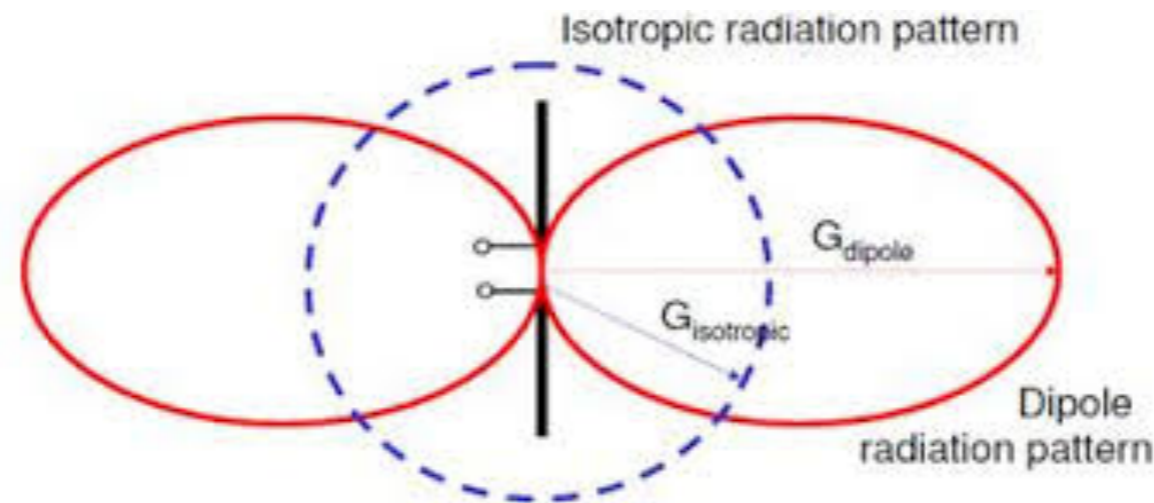
- The power or gain are often expressed in logarithmic units of decibels (dB):

$$G(\text{dB}) \equiv 10 \times \log_{10}(G)$$

Worked example: What is the maximum and half power of a normalised power pattern in decibels?

2.3 Power gain:

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$$G(\text{dB}) \equiv 10 \times \log_{10}(G)$$

Worked example: What is the maximum and half power of a normalised power pattern in decibels?

Maximum power of a normalised power pattern is $P_n = 1$

$$P_n(1) = 10 \times \log_{10}(1) = 0 \text{ dB}$$

Half power of a normalised power pattern is $P_n = 0.5$

$$P_n(0.5) = 10 \times \log_{10}(0.5) = -3 \text{ dB}$$

For a lossless isotropic antenna, conservation of energy requires the directive gain averaged over all directions be,

$$\langle G \rangle \equiv \frac{\int_{\text{sphere}} G d\Omega}{\int_{\text{sphere}} d\Omega} = 1$$

Therefore, for an isotropic lossless antenna,

$$\int_{\text{sphere}} G d\Omega = \int_{\text{sphere}} d\Omega = 4\pi \quad \text{and} \quad G = 1$$

- Lossless antennas may radiate with different directional patterns, but they cannot alter the total amount of power radiated —> the gain of a lossless antenna depends only on the angular distribution of radiation from that antenna.

Key Concept: Higher the gain, the narrower the radiation pattern (directivity).

$$\Delta\Omega \approx \frac{4\pi}{G_{\text{max}}}$$

2.4 Effective collecting area

- The receiving counterpart of the transmitting gain is the effective collecting area, defined as the product of the geometric area and the incident spectral power per unit area (S_ν , the flux-density),

$$A_e \equiv \frac{P_\nu}{S_{(\text{matched})}}$$

Effective area (m²) Spectral power (W Hz⁻¹)
Flux-density (W m⁻² Hz⁻¹)

We can relate the effective area with the geometric area via the aperture efficiency,

$$A_e = \eta_A A_g$$

Any antenna with a single output measures only one polarisation. Electric fields perpendicular to the antenna wires does not produce currents in the antenna. A pair of crossed dipoles are need to collect the power from both polarisations.

- For an unpolarised source (e.g. like a black body),

$$S_{(\text{matched})} = \frac{S}{2}$$

- The total spectral power from all directions collected by the antenna is,

$$P_\nu = A_e S_{(\text{matched})} = A_e \frac{S}{2} = \int_{4\pi} A_e(\theta, \phi) \frac{B_\nu}{2} d\Omega = kT$$

(must equal the Nyquist spectral power). From the R-J equation,

$$B_\nu = \frac{2kT}{\lambda^2} \quad P_\nu = \frac{2kT}{2\lambda^2} \int_{4\pi} A_e(\theta, \phi) d\Omega = kT$$

$$\int_{4\pi} A_e(\theta, \phi) d\Omega = \lambda^2$$

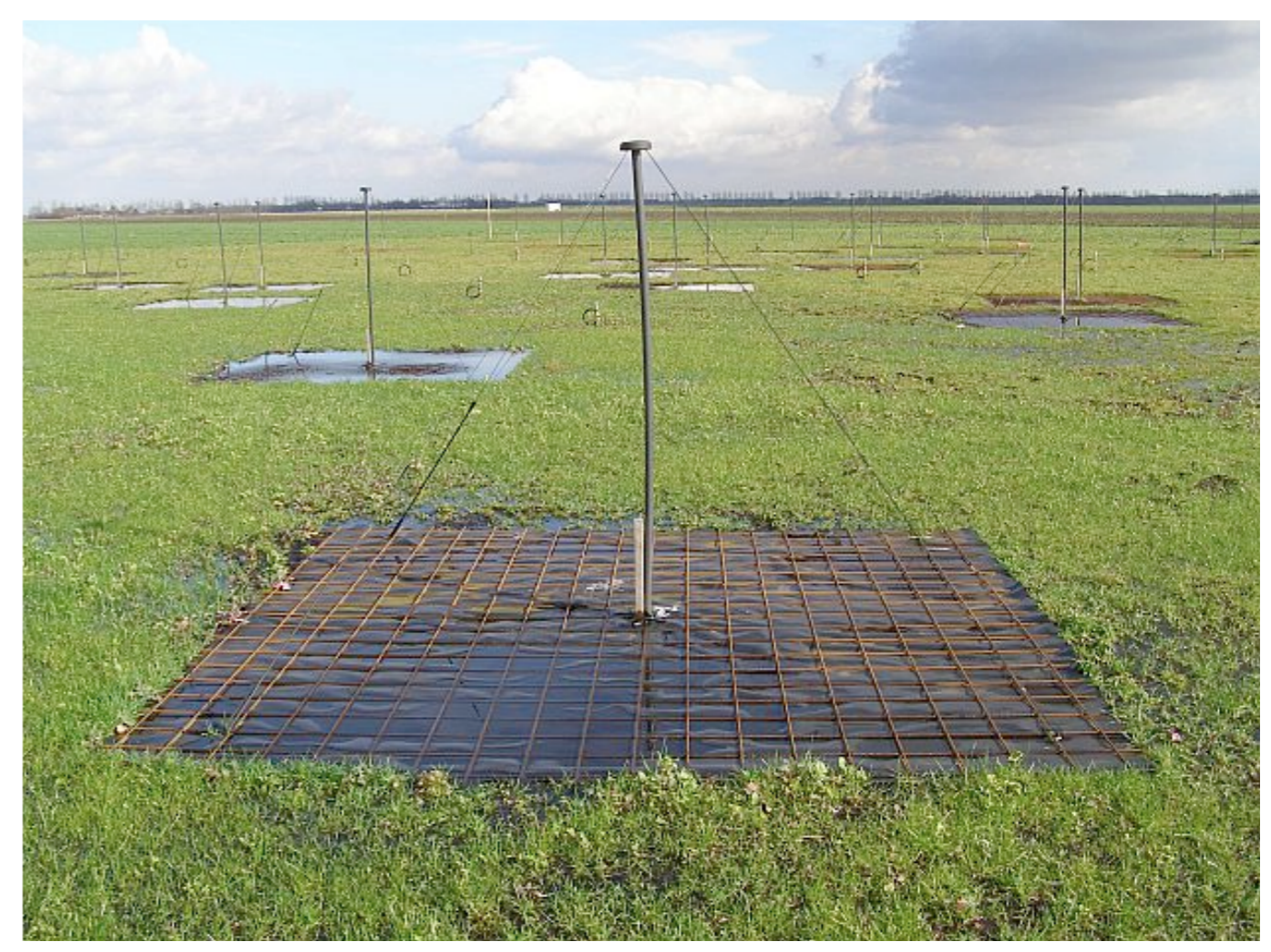
- The average collecting area is defined as

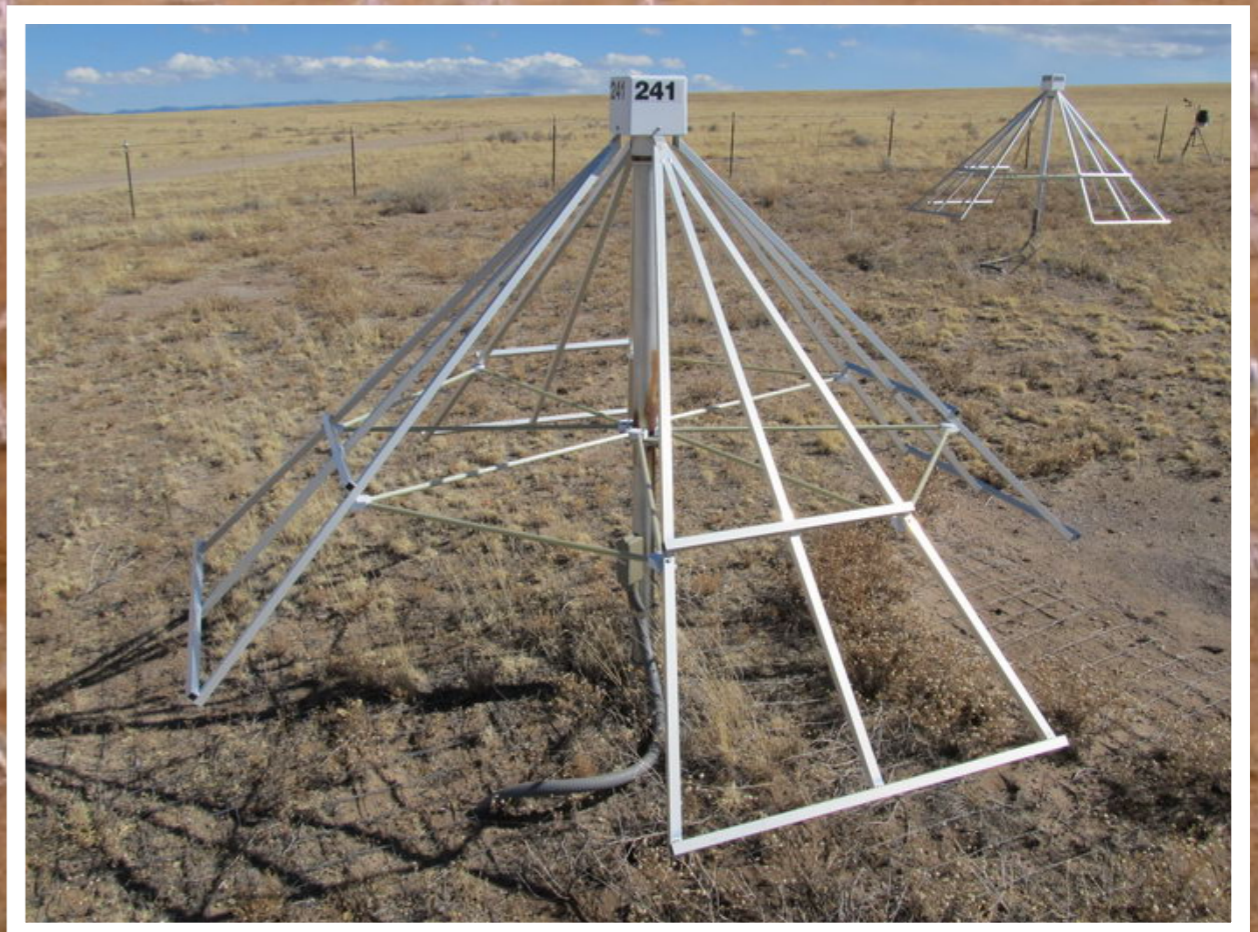
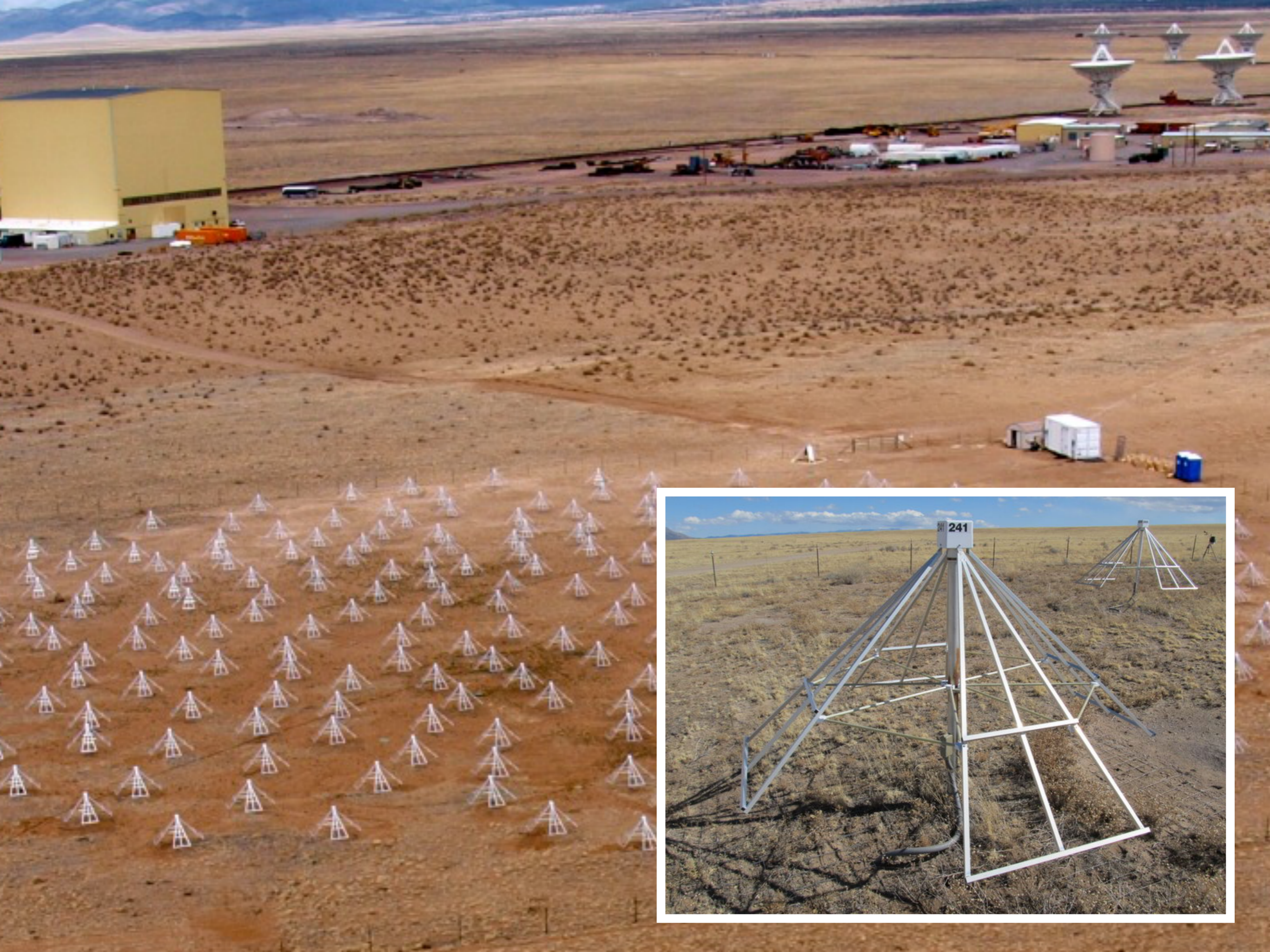
$$\langle A_e \rangle = \frac{\int_{4\pi} A_e(\theta, \phi) d\Omega}{\int_{4\pi} d\Omega}$$

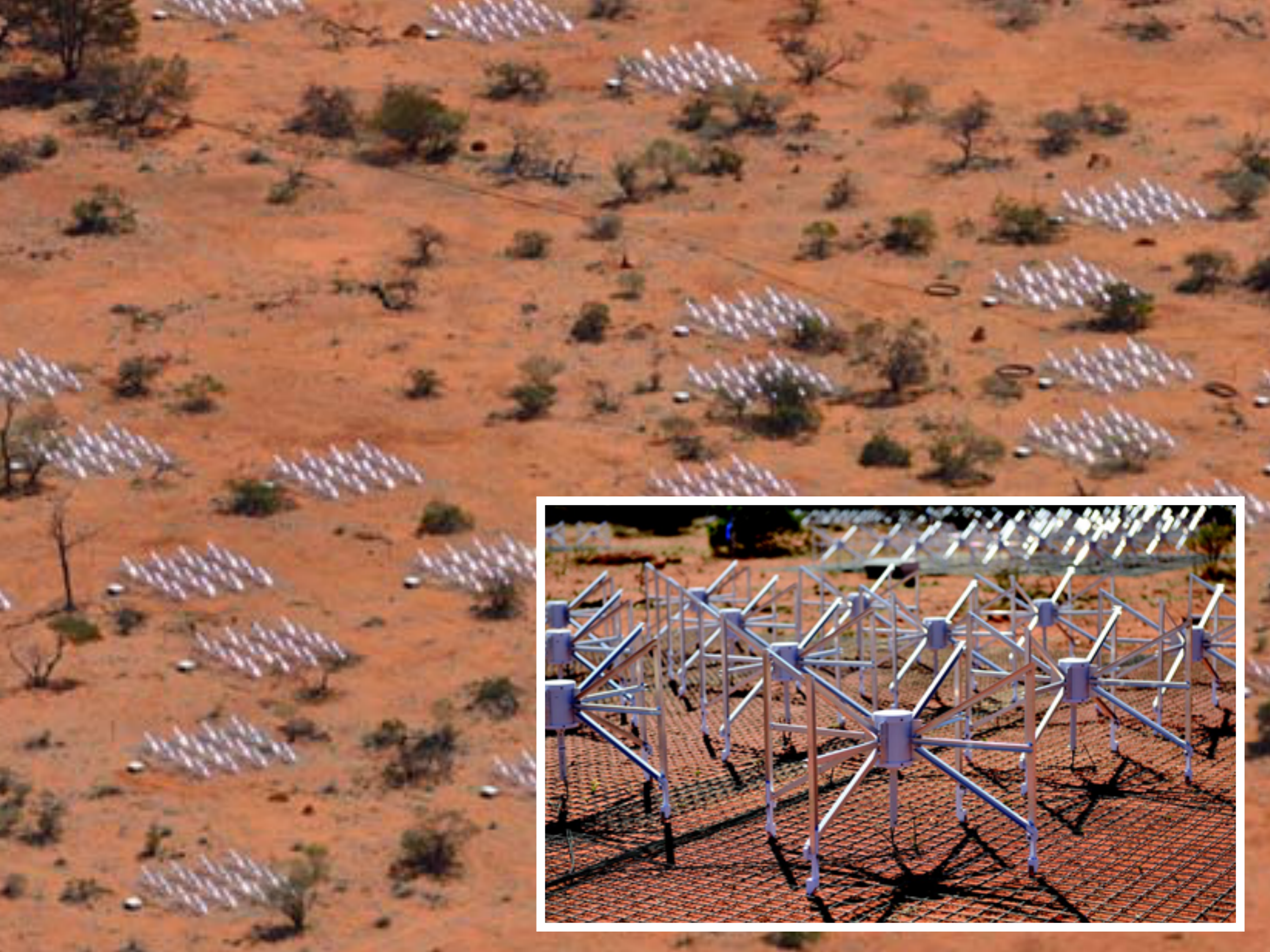
The effective collecting area is independent of the antenna environment, so this relation is valid for any type of radiation (not just black body radiation).

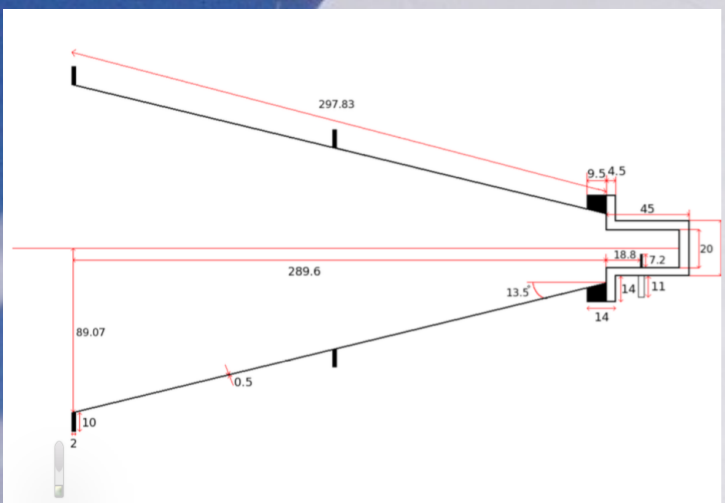
Key concept: Any antenna has the same average collecting area $\langle A_e \rangle$ that depends only on the wavelength of the radiation.

$$\langle A_e \rangle = \frac{\lambda^2}{4\pi}$$









- **Beam solid angle:** The beam area Ω_A is the solid angle through which all of the power radiated by the antenna would stream if $P(\theta, \phi)$ maintained its maximum value over Ω_A and zero everywhere else.

$$\Omega_A \equiv \int_{4\pi} P_n(\theta, \phi) d\Omega$$

Beam solid angle (sr) points to Ω_A .
 Normalised power pattern points to $P_n(\theta, \phi)$.
 sky area ($r^2 \sin \theta d\theta d\phi$) points to $d\Omega$.

The power (and temperature) received is also a function of the power pattern of the antenna. Therefore, the true antenna temperature is,

$$T_A = \frac{A_e}{2k} \int \int I_\nu(\theta, \phi) P_n(\theta, \phi) d\Omega$$

where $P_n(\theta, \phi)$ is the power pattern normalised to unity maximum,

$$P_n = \frac{G(\theta, \phi)}{G_{\max}}$$

- **Main beam solid angle:** The area containing the principle response out to the first zero.
- **Side-lobes:** Areas outside the principle response that are non-zero.

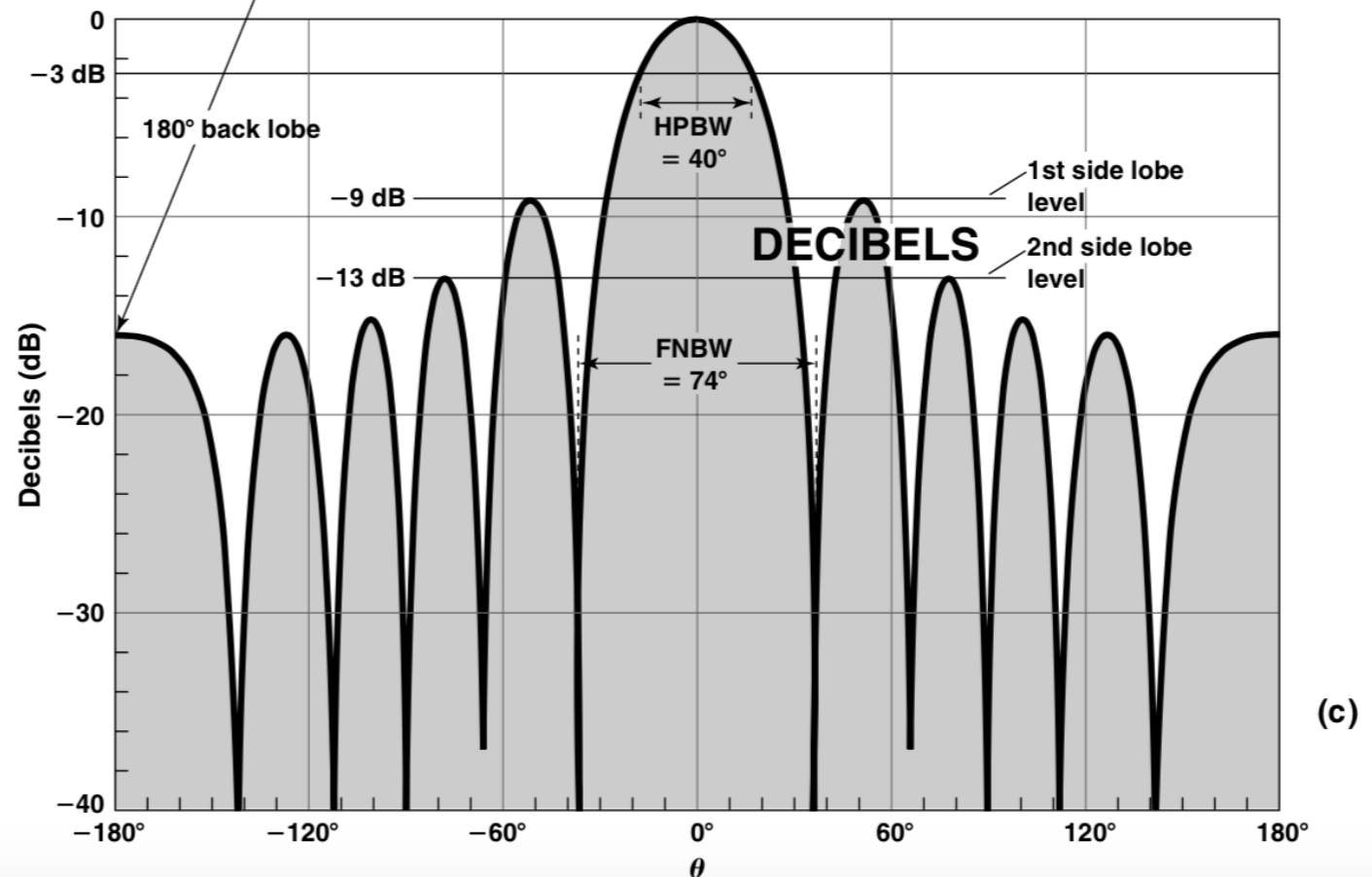
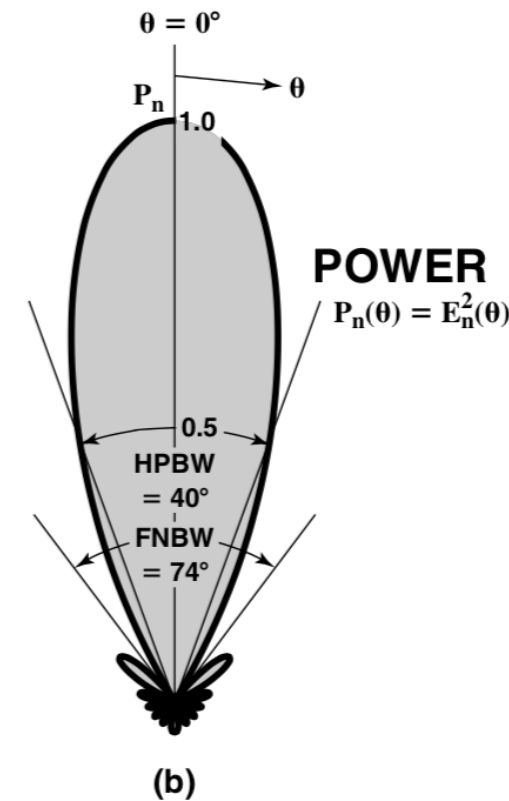
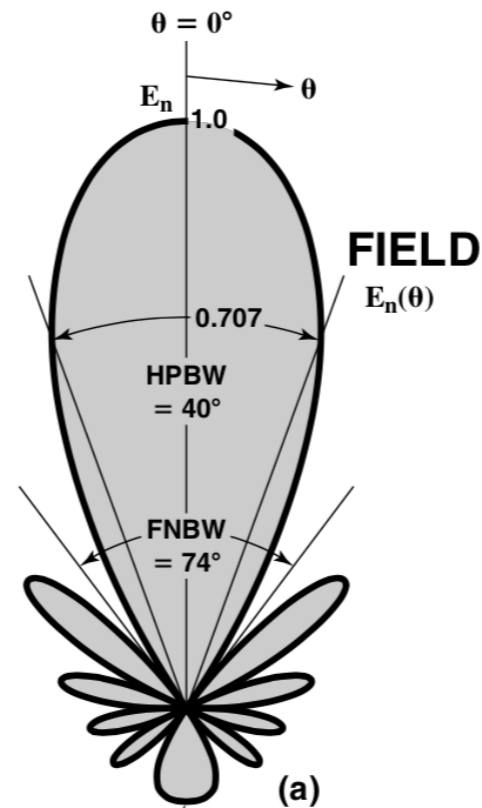
$$\Omega_{\text{MB}} \equiv \int_{\text{MB}} P_n(\theta, \phi) d\Omega$$

Main beam solid angle (sr)

- **Main beam efficiency:** The fraction of the total beam solid angle inside the main beam

$$\eta_B \equiv \frac{\Omega_{\text{MB}}}{\Omega_A}$$

Main beam efficiency



3.1 Interferometers

Combined telescopes

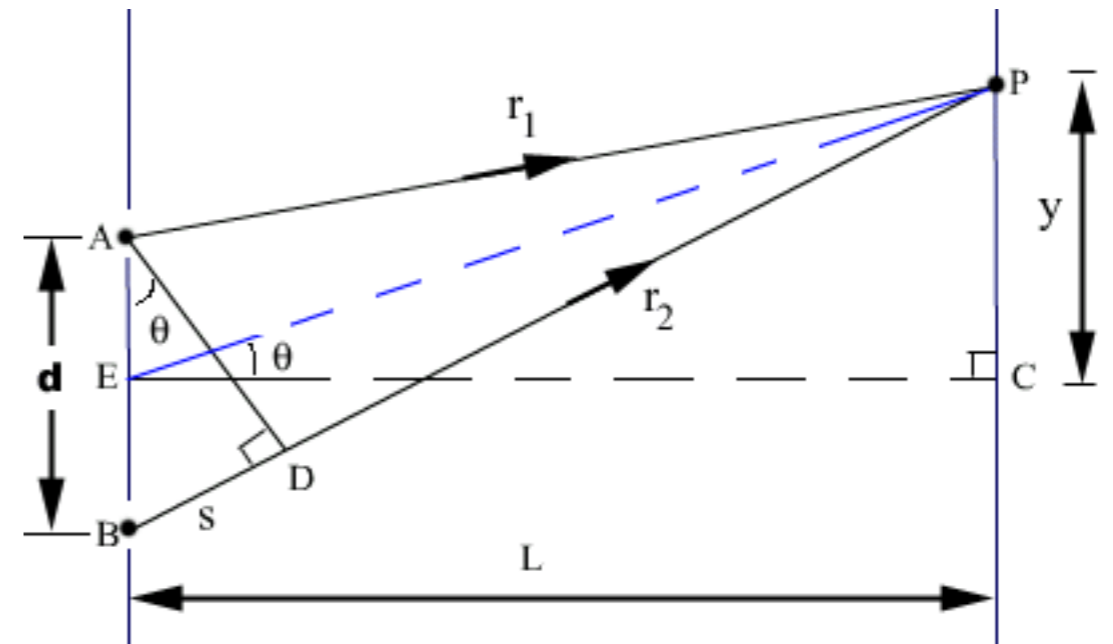
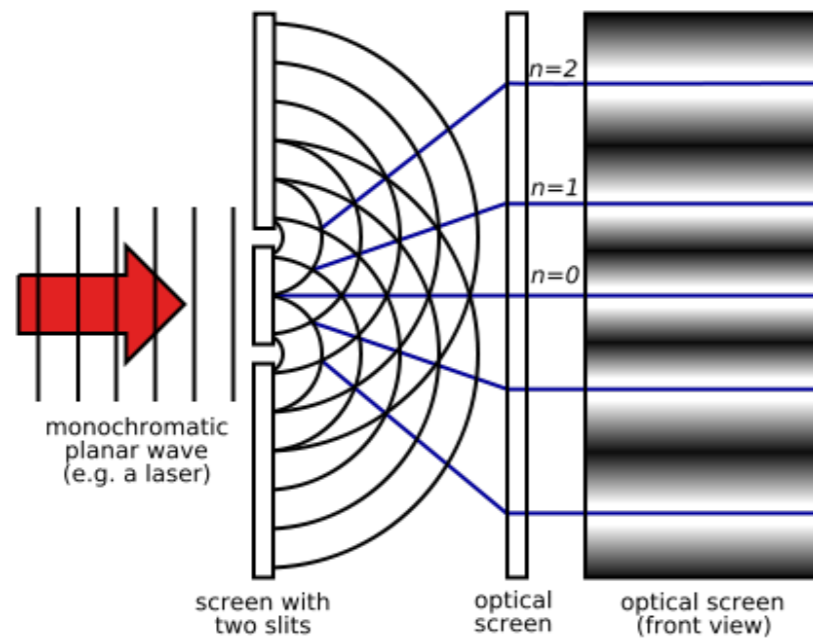
$$\theta_{\text{res}} \sim \frac{\lambda}{B}$$

Individual telescope

$$\theta_{\text{res}} \sim \frac{\lambda}{D}$$

- We can overcome this problem by correlating the signals from different telescopes to effectively increase D to an arbitrarily large value by increasing the distance between the telescopes, called the baseline length B . Now, $\theta \sim \lambda / B$.
 1. High angular resolution (down to < 1 mas; best in astronomy), e.g. VLBI.
 2. Better sensitivity (Area = $N\pi D^2 / 4$, N is number of telescopes), e.g. LOFAR, JVLA, ALMA.
 3. Large field-of-view (10s deg²) in the case of phased array feeds, e.g. WSRT-Aperitif.

3.2 Young's double slit experiment



Constructive interference **fringes** occur when the path difference is an integer number wavelengths, i.e.

$$d \sin \theta = n\lambda \quad \text{and for destructive interference,} \quad d \sin \theta = (n + 1/2)\lambda$$

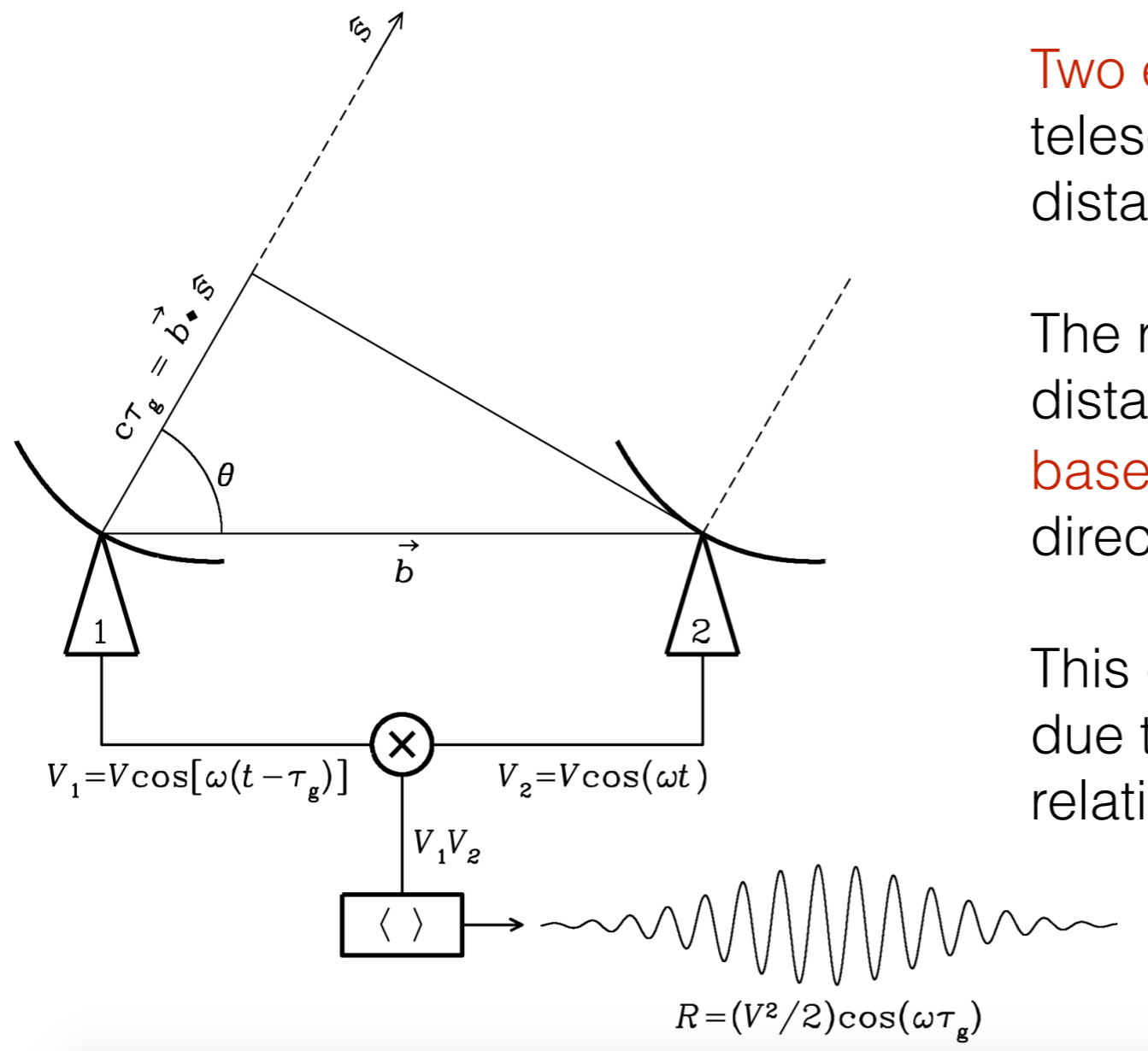
when $y \ll L$, we can approximate $\sin \theta = y / L$ and the positions of the maxima and minima are,

$$y_c = \frac{n\lambda L}{d} \quad \text{and} \quad y_d = \frac{(n + 1/2)\lambda L}{d}$$

and the spacing between successive fringes is,

$$\Delta y = \frac{\lambda L}{d} \quad \text{or, expressed as an angular size,} \quad \theta \sim \frac{\lambda}{d}$$

3.3 A simple two-element interferometer



Two element interferometer: Two identical telescopes observe the electric field of some distant source (c.f. Young's double slit).

The radiation to antenna 1 travels an extra distance $\vec{b} \cdot \hat{s} = b \cos \theta$, where \vec{b} is the vector **baseline** length and \hat{s} a unit vector in the direction of the source.

This can be expressed as a **geometric delay** due to the projected position of the source, relative to the baseline of the antennas.

$$\tau_g = \vec{b} \cdot \hat{s} / c$$

For a **quasi-monochromatic** interferometer (responds to a narrow frequency range $\nu = 2\pi / \lambda$), the output voltages over time t from the two antennas are,

$$V_1 = V \cos[\omega(t - \tau_g)] \quad \text{and} \quad V_2 = V \cos(\omega t)$$

The **correlator** multiplies the voltages from the two antennas together to give,

$$V_1 V_2 = V^2 \cos[\omega(t - \tau_g)] \cos(\omega t) = \left(\frac{V^2}{2}\right) [\cos[2\omega t - \omega\tau_g] + \cos(\omega\tau_g)]$$

and then a time average $[\Delta t \gg (2\omega)^{-1}]$ to remove the high frequency component to give,

$$R = \langle V_1 V_2 \rangle = \left(\frac{V^2}{2}\right) \cos(\omega\tau_g)$$

Uncorrelated noise from gain variations within the receivers, the atmosphere and radio frequency interference does not correlate (advantage over single dish measurements).

The output voltage R varies sinusoidally with the change of the source direction in the interferometer frame, i.e. the delay changes. These sinusoids are called **fringes**, and we can define the **fringe phase** as,

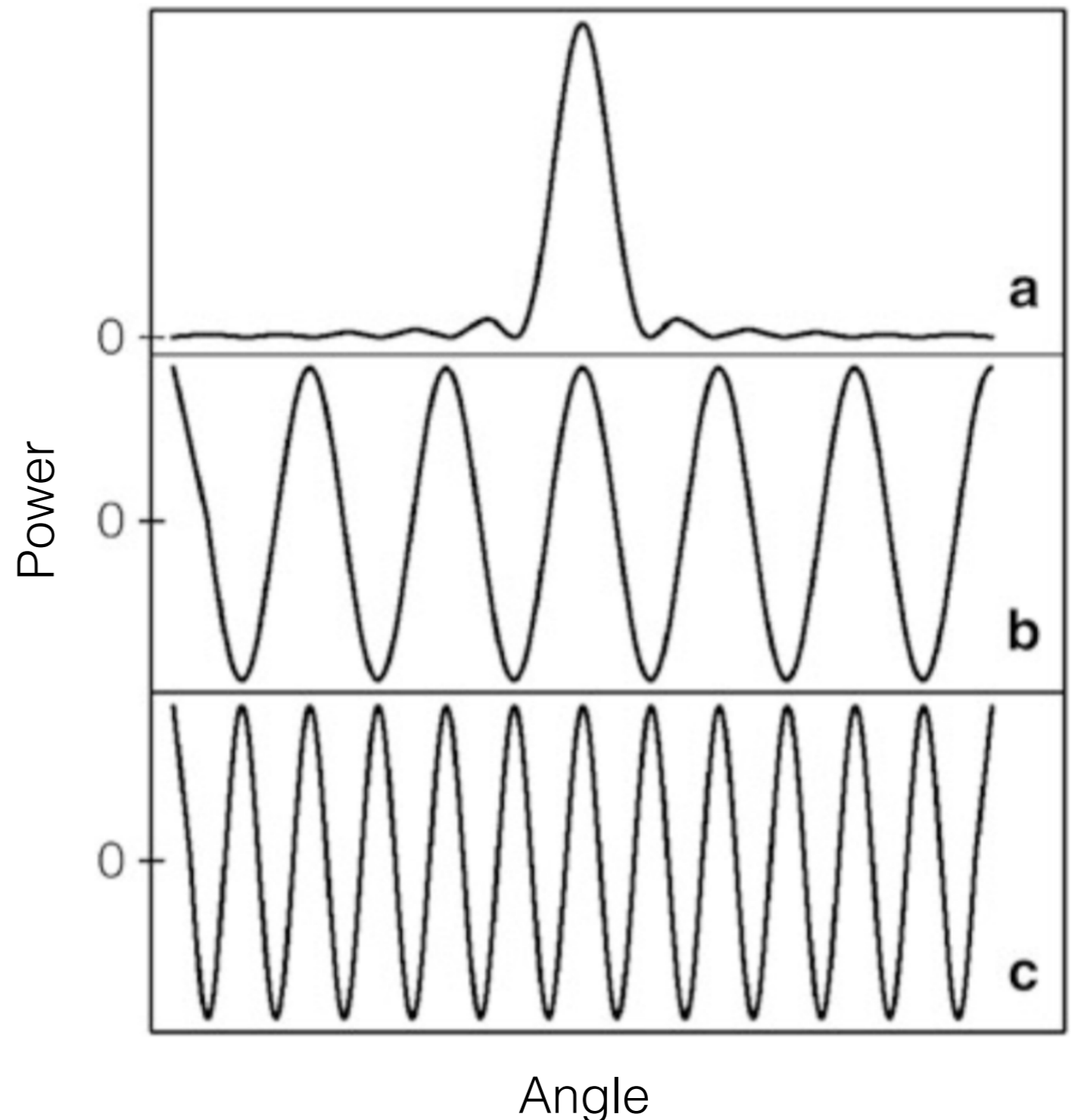
$$\phi = \omega\tau_g = \frac{\omega}{c} b \cos \theta \quad \text{and} \quad \frac{d\phi}{d\theta} = \frac{\omega}{c} b \sin \theta = 2\pi \left(\frac{b \sin \theta}{\lambda}\right)$$

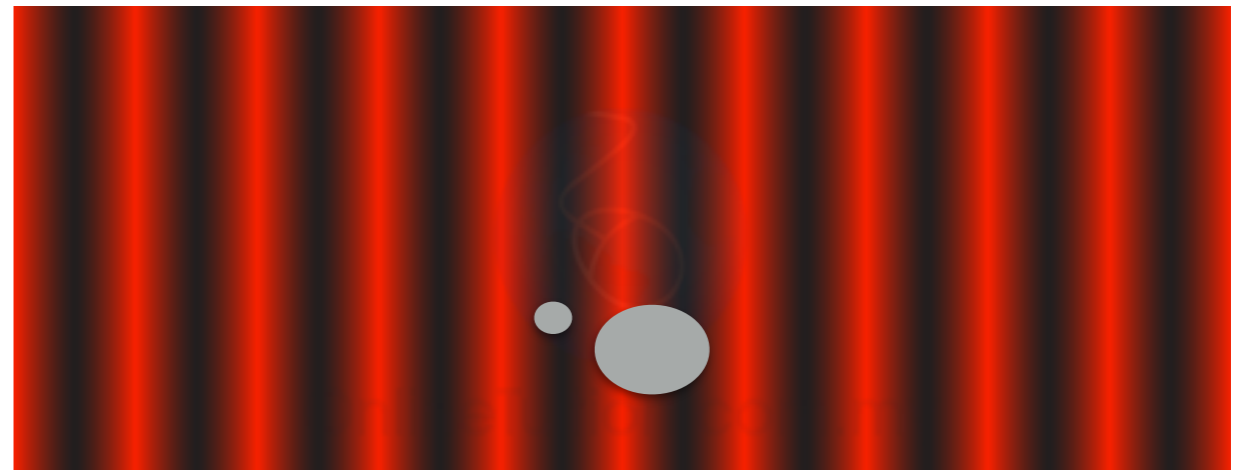
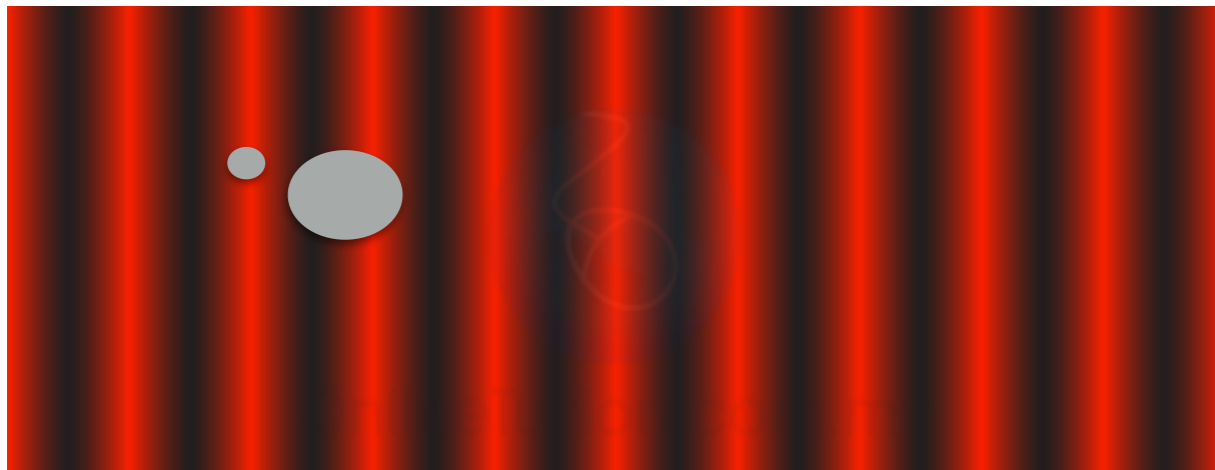
The fringe period ($\Delta\phi = 2\pi$) corresponds to an angular change of $\Delta\theta = \lambda / (b \sin \theta)$, and so, for large b , interferometers can measure very accurate positions of sources (typically $\sigma_\theta \sim 10^{-3}$ arcsec).

As the source(s) moves across the sky, the response of the interferometer changes because the geometric delay changes. The maximum in the fringe pattern occurs when $\tau_g c$ is an integral number of wavelengths (similar to the Young's double slit).

This effect of combining antennas changes the response of our instrument to the sky.

- a. The power pattern of a filled aperture of diameter D with a constant illumination pattern. The FWHM of the main beam is $\sim \lambda / D$.
- b. The power pattern of a two-element interferometer with 2 antennas of diameter d and separation D . The side-lobe level is constant and the power is centred on 0. The FWHM of the fringes is $\sim \lambda / D$.
- c. The power pattern of a two-element interferometer with 2 antennas of diameter d and separation $2D$. The FWHM of the fringes is now $\sim \lambda / 2D$.

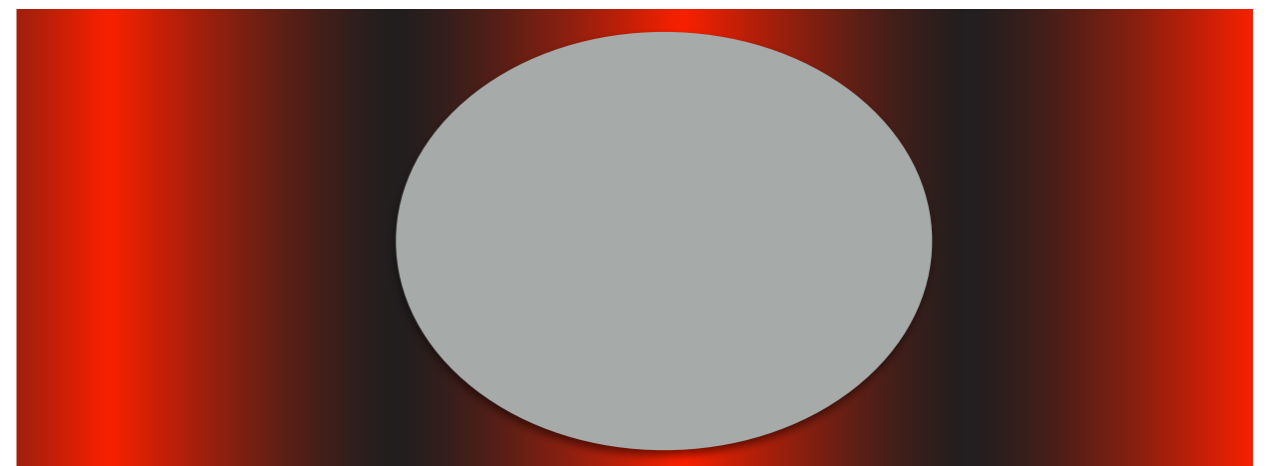
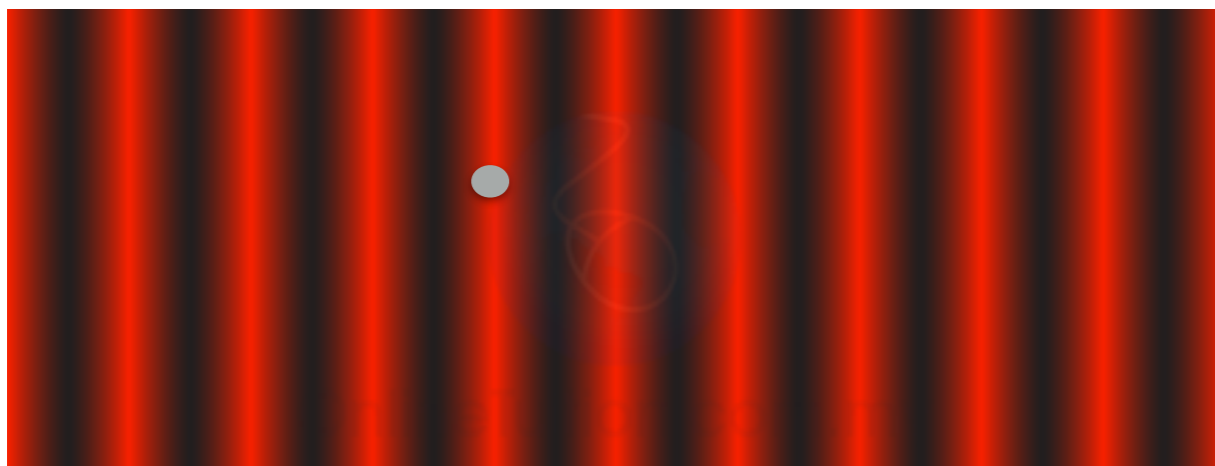




For sources much larger than adjacent positive and negative fringes, the source cancels itself out and the interferometer response does not vary.



Each set of antennas correspond to a finite set of angular frequencies centred on $(b \sin \theta / \lambda)$, small b is needed for extended objects and large b is needed for compact objects.



3.4 Extended sources

A spatially incoherent extended source with sky brightness $I_\nu(\hat{s})$ near frequency $\nu = \omega / 2\pi$ can be considered as the sum of independent point sources. The response of an interferometer is then,

$$R_c = \int I_\nu(\hat{s}) \cos(2\pi\nu\vec{b} \cdot \hat{s}/c) d\Omega = \int I_\nu(\hat{s}) \cos(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

Note that, the output from the correlator is a complex quantity and so far we have only considered the (real) cosine part of the signal. The (imaginary) sine component is found by inserting a 90° phase delay ($t - \tau_g - \pi/2$).

$$R_s = \int I_\nu(\hat{s}) \sin(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

It is convenient to express this in terms of complex exponentials,

$$e^{i\phi} = \cos \phi + i \sin \phi$$

Allowing us to define the **complex visibility** $V = R_c - iR_s$ as,

$$V = Ae^{-i\phi}$$

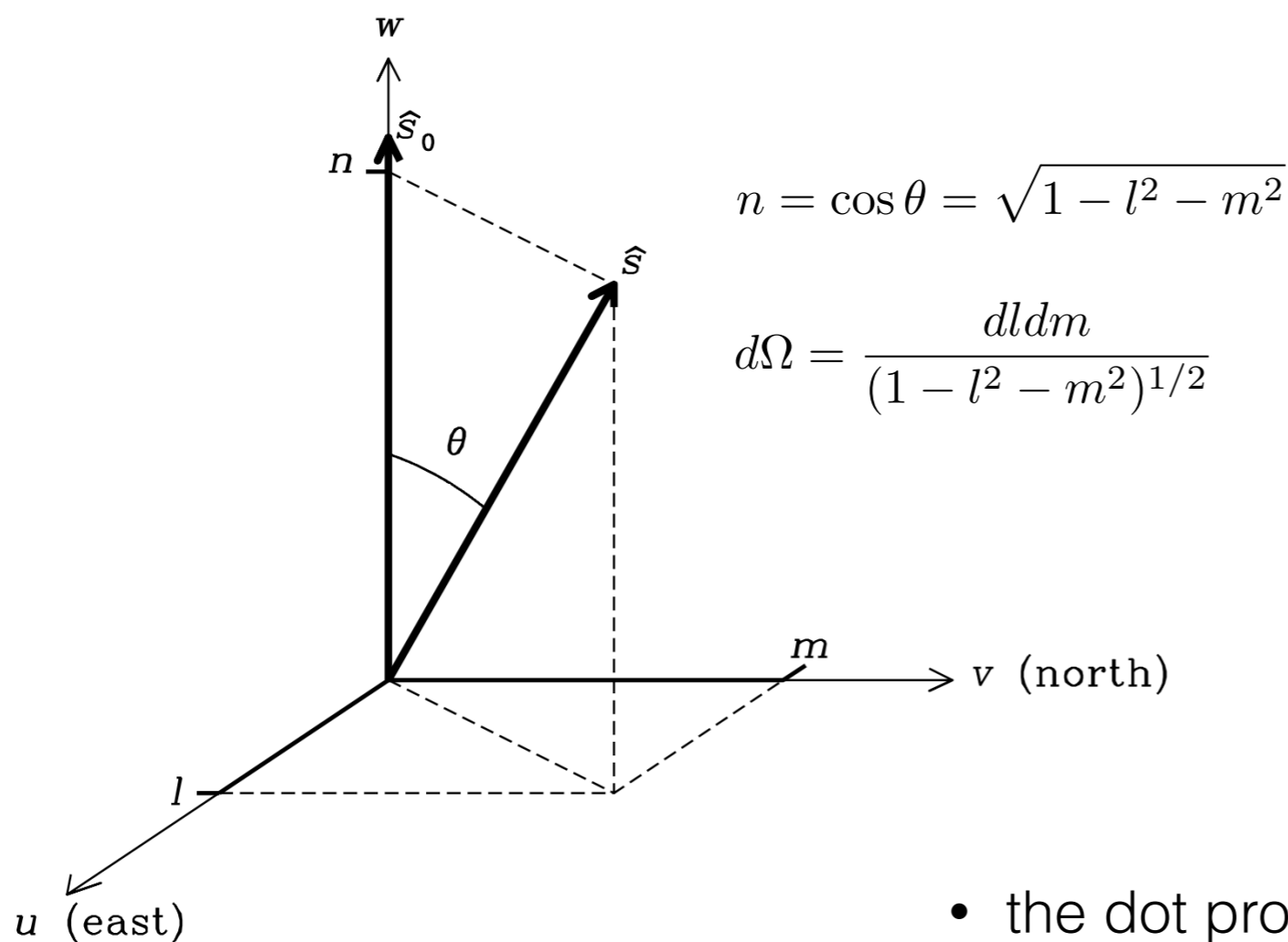
where the amplitude is, $A = (R_c^2 + R_s^2)^{1/2}$ and the phase is, $\phi = \tan^{-1}(R_s/R_c)$

So, we can write the response of a two element interferometer to an extended source with brightness distribution $I_\nu(\hat{s})$ as,

$$V_\nu = \int I_\nu(\hat{s}) \exp(-i2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

3.5 General response of an interferometer

First, we define our co-ordinate systems.



- baseline

$$\frac{\vec{b}}{\lambda} = (u, v, w)$$

North-South
 /
 East-West Up-Down

- source

$$\hat{s} = (l, m, \sqrt{1 - l^2 - m^2})$$

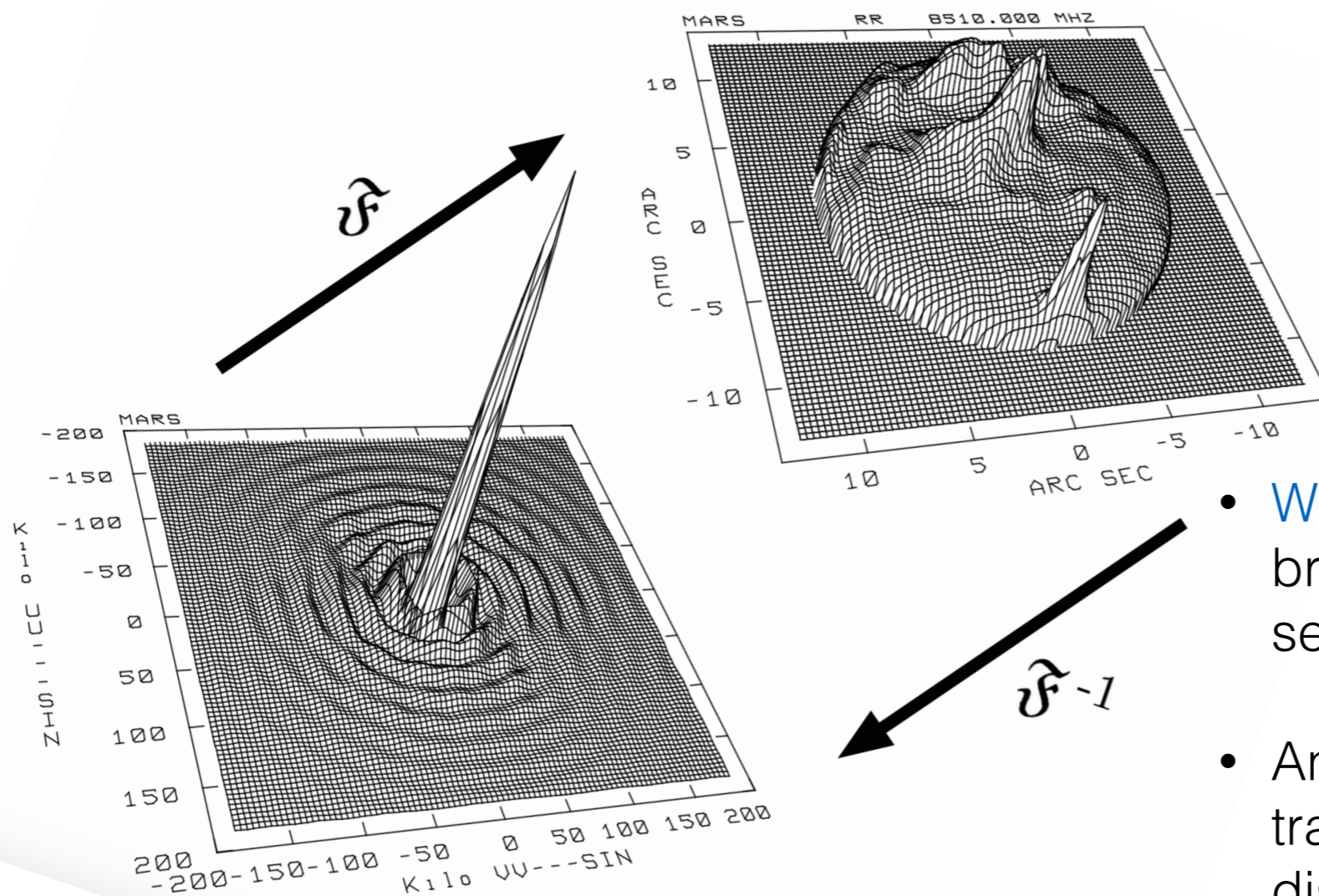
North-South
 /
 East-West Up-Down

- the dot product $\frac{\vec{b}}{\lambda} \cdot \hat{s} = ul + vm + w\sqrt{1 - l^2 - m^2}$

We can then describe the response of an interferometer to any position in the sky as,

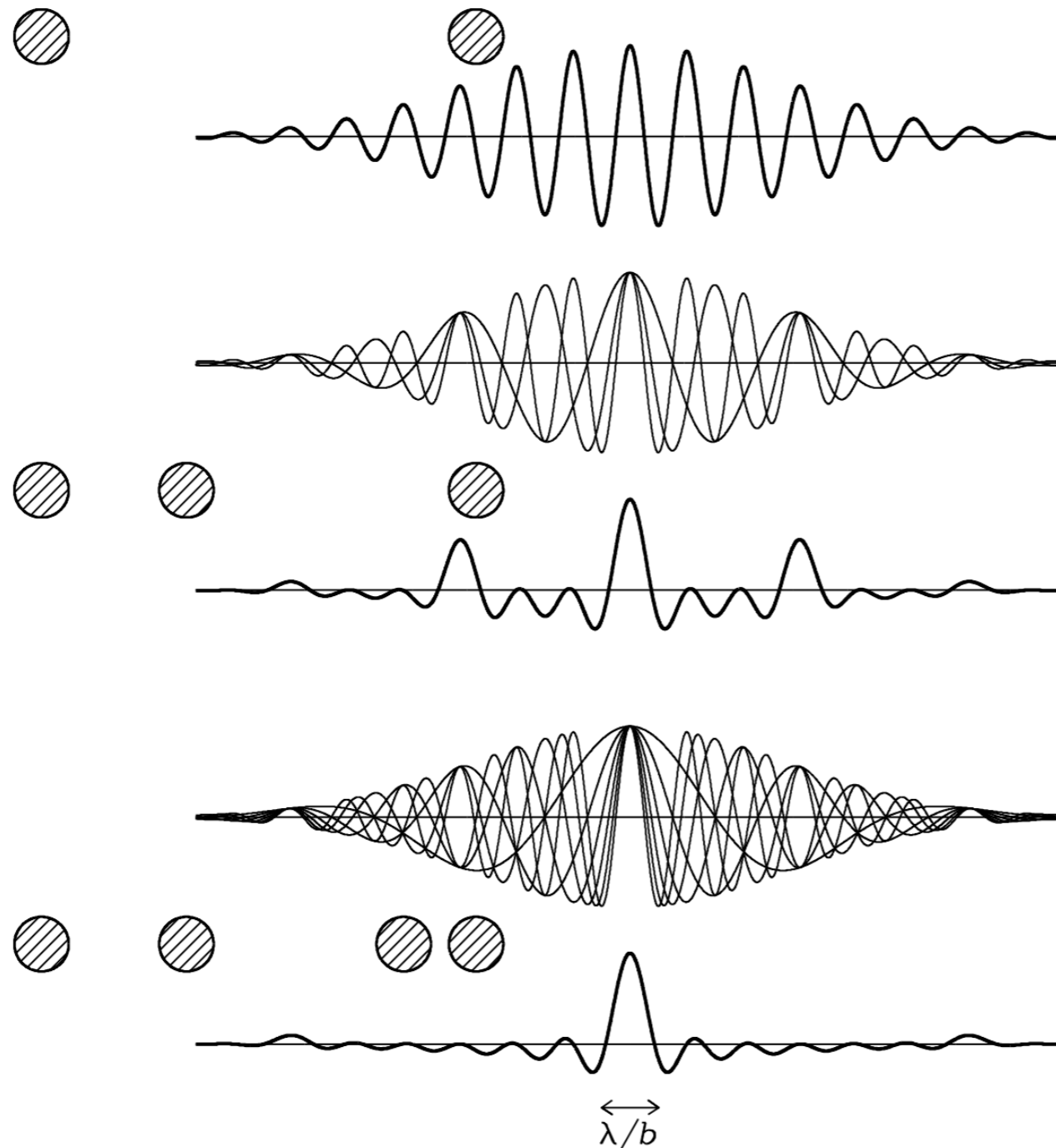
$$V_\nu(u, v, w) = \iint \frac{I_\nu(l, m)}{(1 - l^2 - m^2)^{1/2}} \exp[-i2\pi(ul + vm + wn)] dl dm$$

Key Concept: The response of an interferometer is the (inverse) Fourier transform of the (apparent) sky brightness distribution.



- **Worked example:** Here is the surface brightness distribution of Mars, as seen at 3.6 cm.
- An interferometer will see the Fourier transform of this surface brightness distribution.

- Incomplete measurement of the Fourier plane results in significant structure in the point spread function response of the interferometer.



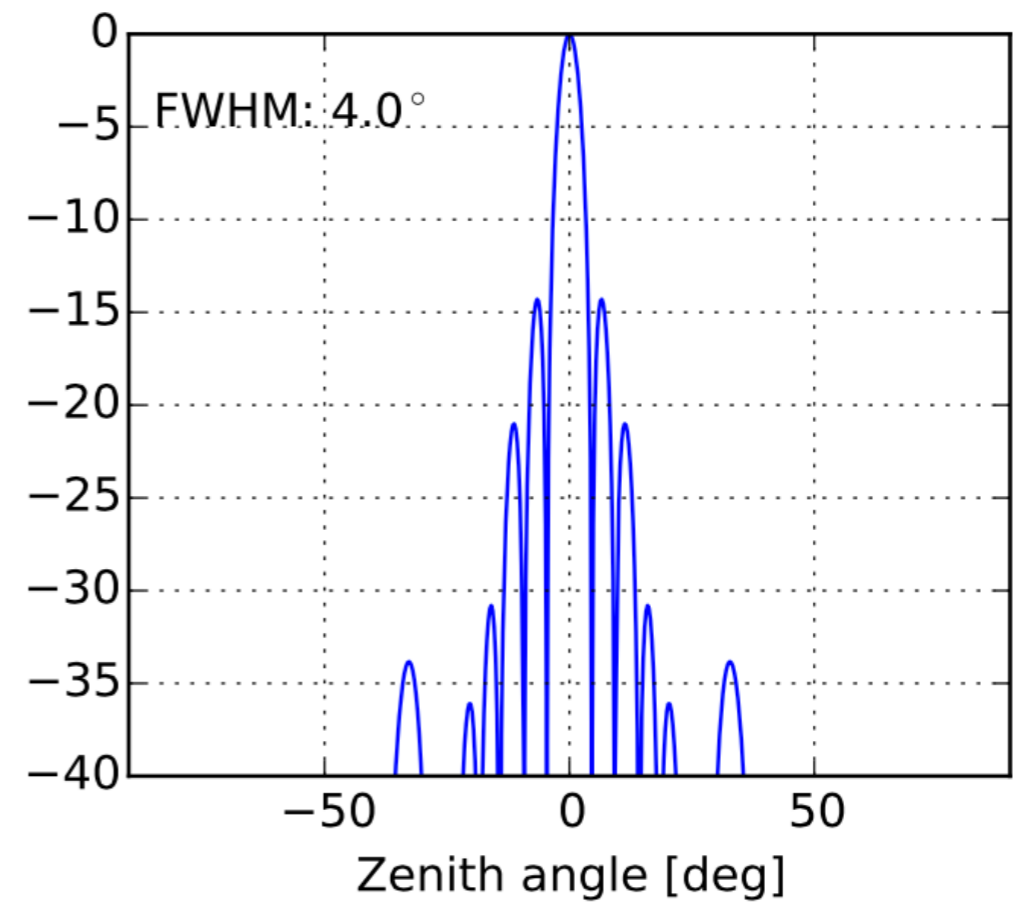
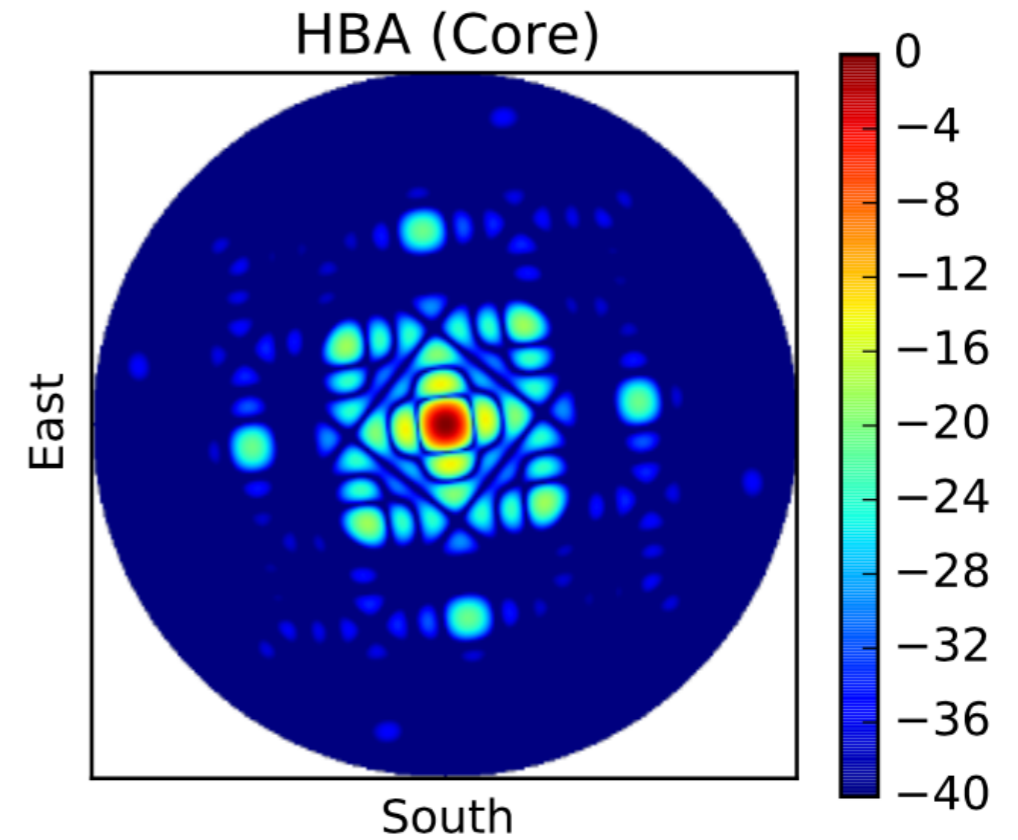
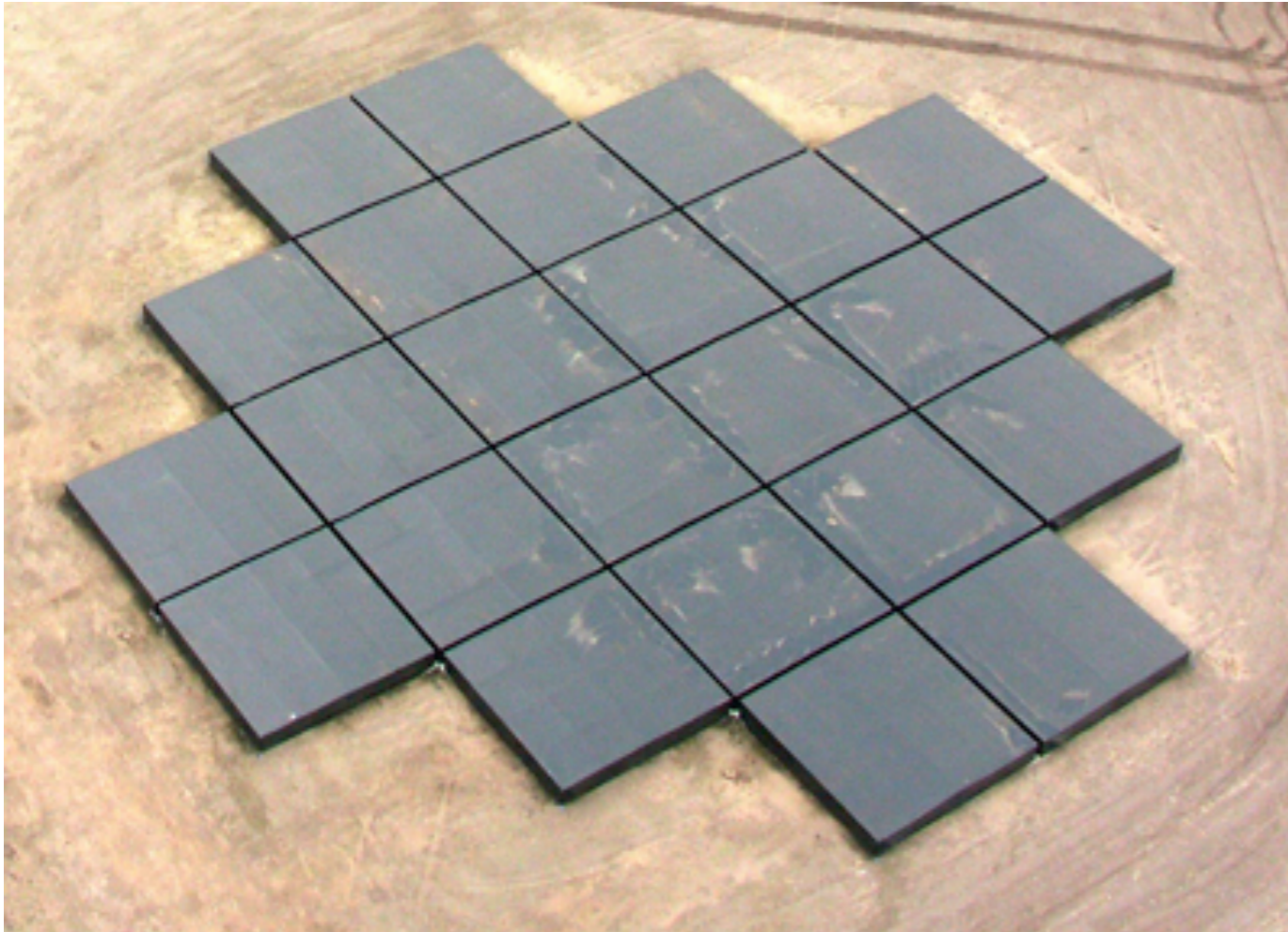
- Two antennas

- Three antennas

- Four antennas

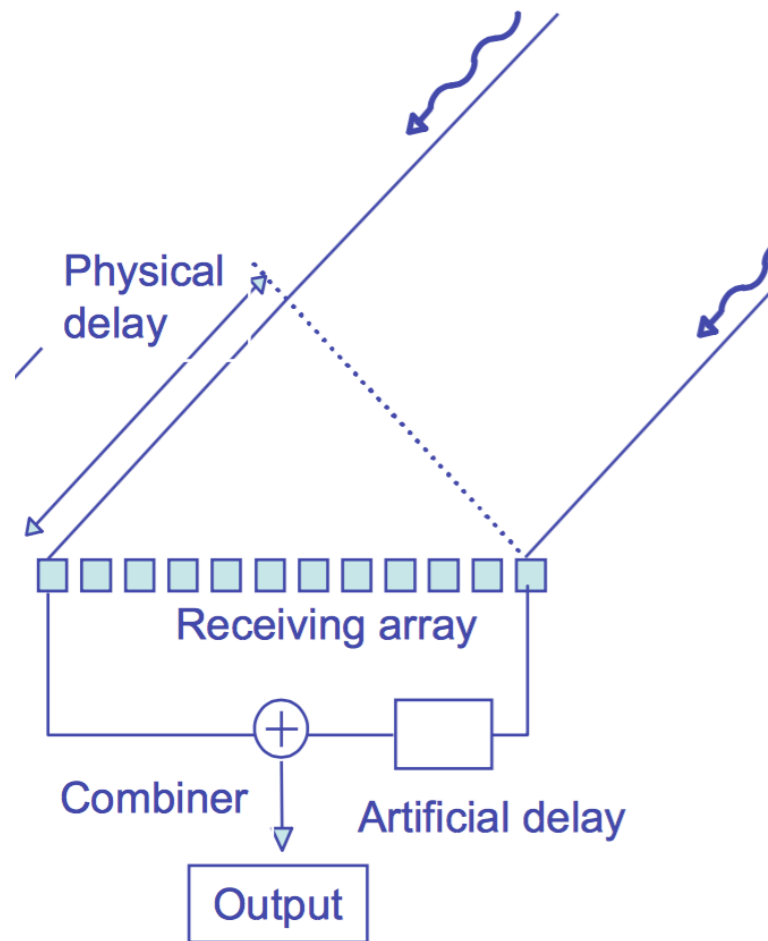
- Negative bowl around the centre is due to the lack of information at short spacings (b cannot be $< D$, the antenna diameter).

Worked example: The combined 24 tiles of a LOFAR High Band Antenna station (120-250 MHz) arranged in a regular grid.



3.6 Next generation interferometers

- We can also combine different antenna receiver elements together coherently to form an **aperture array** (e.g. LOFAR; MWA; LWA).

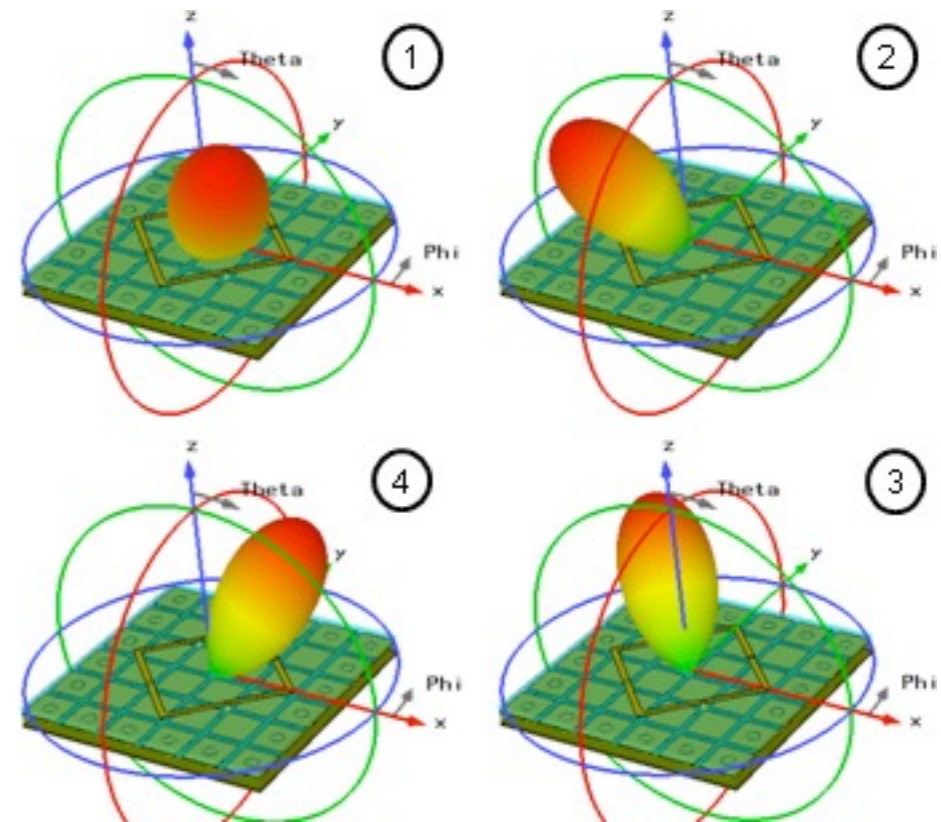
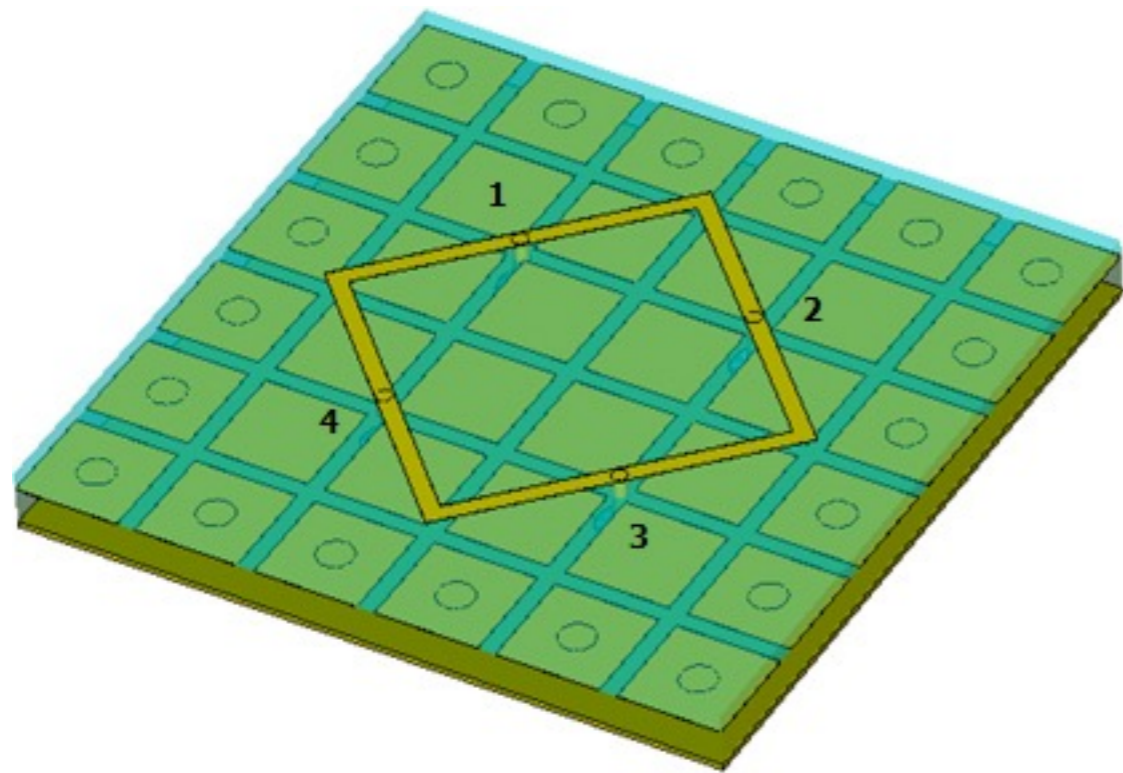
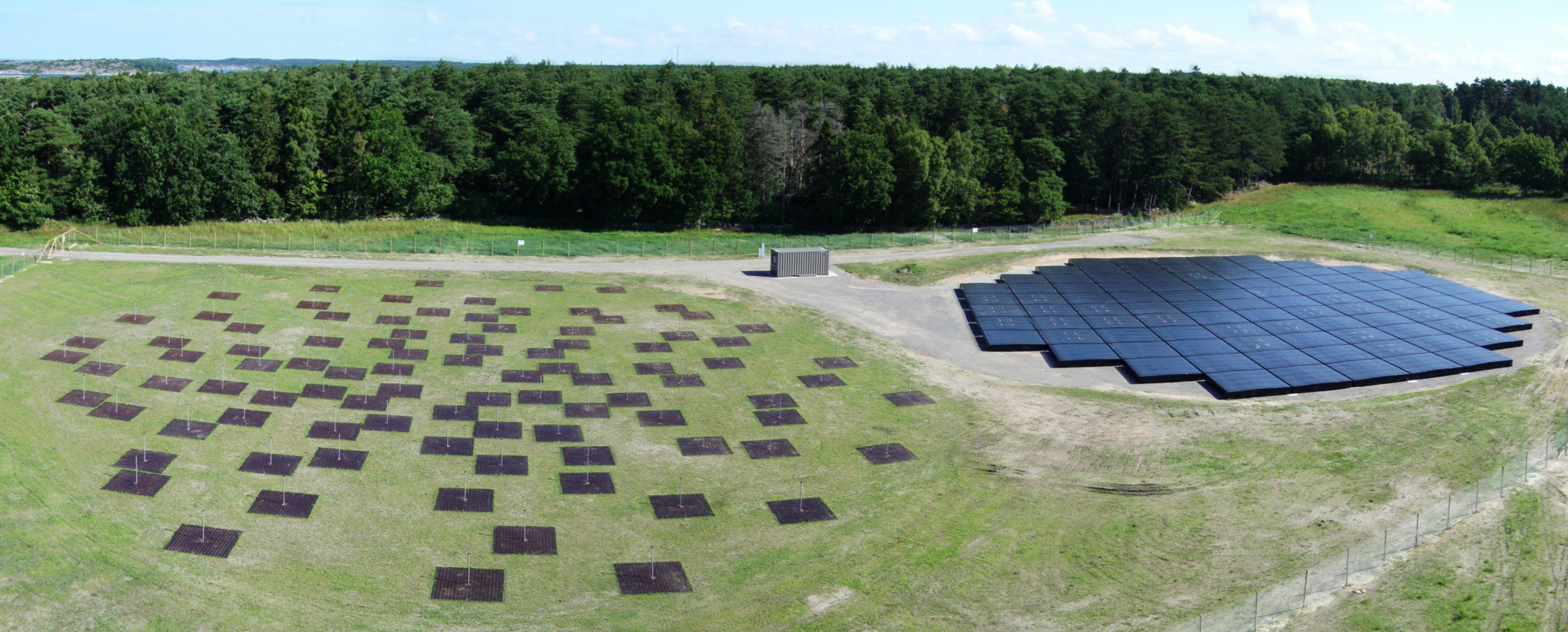


Tile

Station

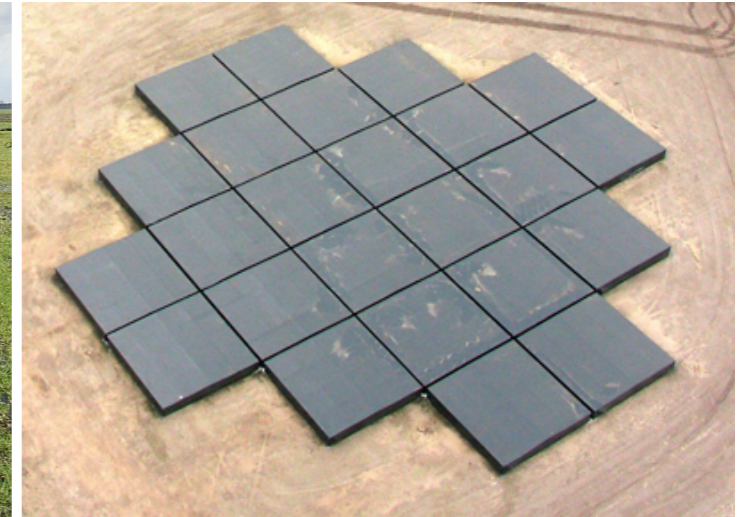
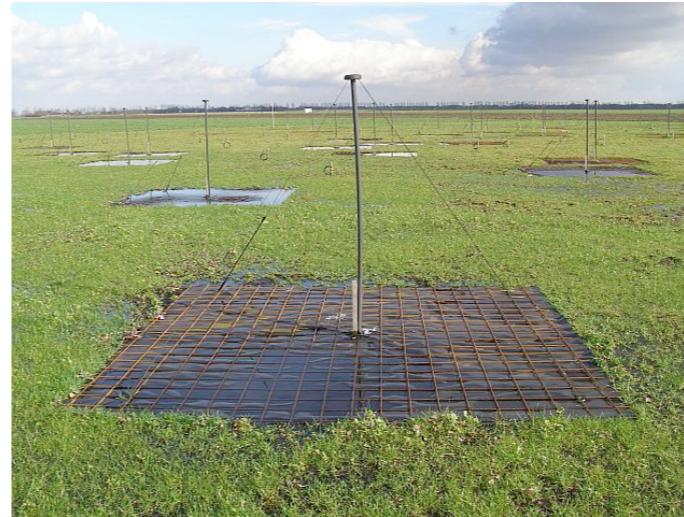
Core

- Aperture array**: In the same way that an interferometer works, the receiving elements are added together by taking into account the **delay** due to the waves arriving at different times, from **different directions**.
 - Low cost (no moving parts, dipole elements).
 - Better effective area at low radio frequencies.
 - Large fields-of-view and flexible electronic beam forming.



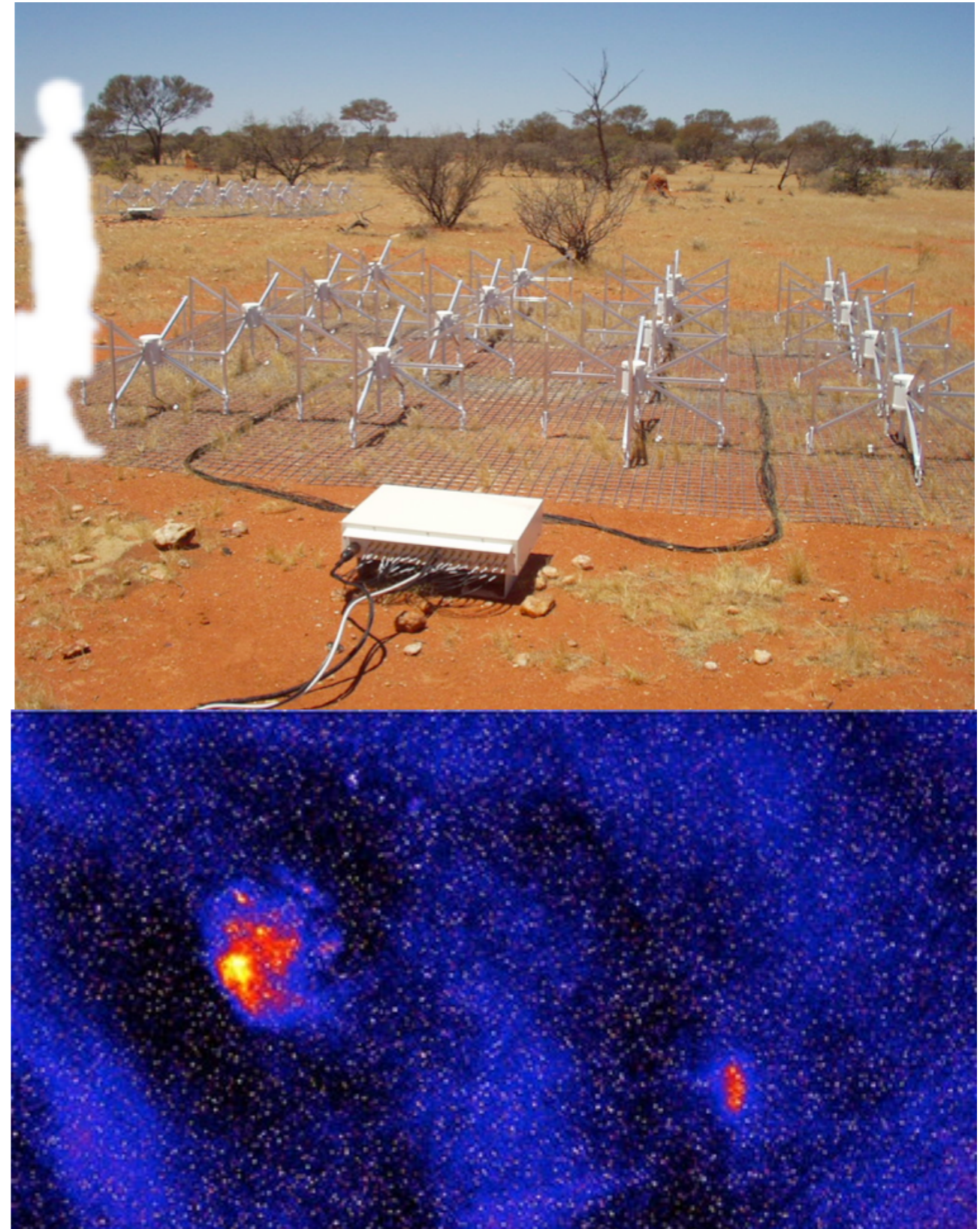
4.1 The Low Frequency Array

- International LOFAR Telescope being built by a consortium of institutes in the Netherlands, Germany, UK, France, Sweden, Poland and Ireland.
- Low Band Antenna (LBA; 10--90 MHz) - simple dipoles.
- High Band Antenna (110-180 MHz, 210-240 MHz) - tiled array.
- 96 MHz bandwidth.
- 50 Stations throughout Europe (~50 m to 1500 km baselines), resolution ~few degrees to sub-arcsec.



4.2 The Murchison Wide-Field Array

- Low frequency pathfinder based in Australia (quiet-site).
- 80--300 MHz frequency coverage, with 32 MHz instantaneous bandwidth.
- 128 tiles, with 4 x 4 dipoles (very like LOFAR).
- Max baseline to 3 km outriggers; most tiles (112) within 1.5 km.
- Wide field-of-view (15-45 degrees)
- Resolution of 2.5 to 8.5 arcmin



4.3 The Very Large Array

- Upgraded VLA, P-band (230-470 MHz).
- Receivers in place to sample down to 50 MHz.
- 27 x 25 m dish antennas with baselines up to 36 km in 4 configurations (A-D)



4.4 Long Wavelength Array

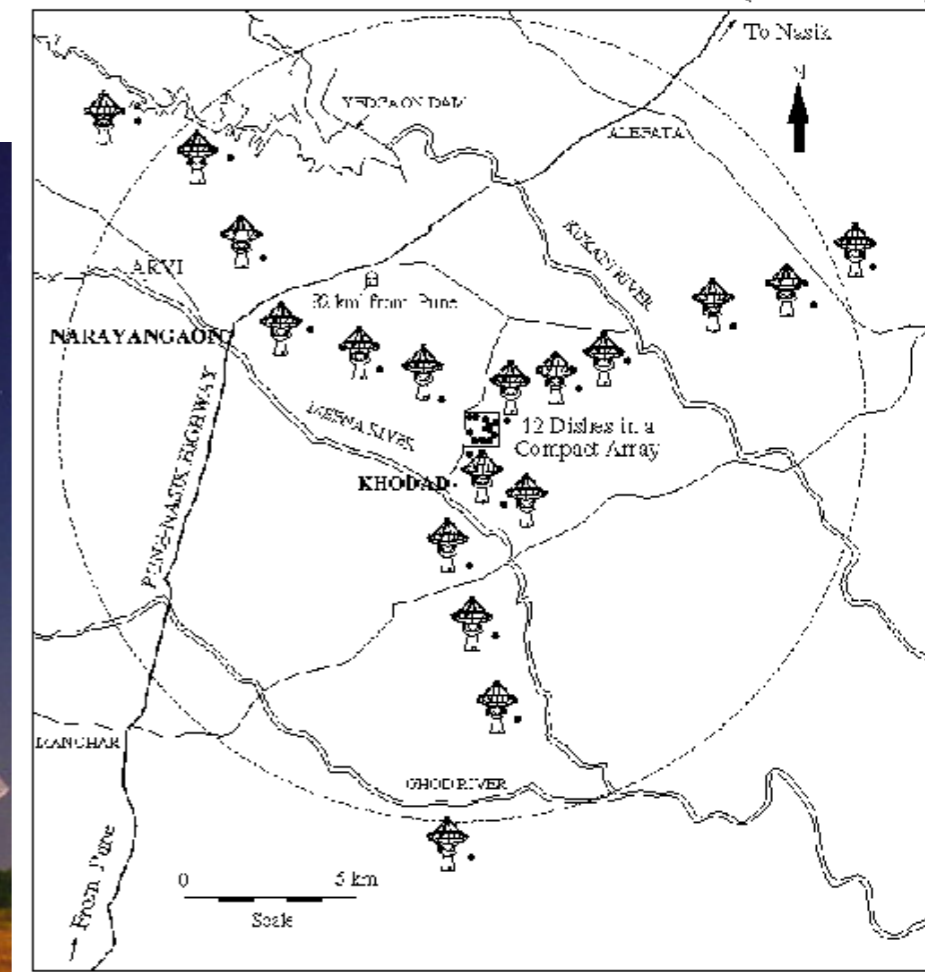


- 10-88 MHz; 4 simultaneous beam.
- LWA1 = 256 (+1) dual polarisation dipoles (100 x 110 m station)
- Full array; Ambitions to have baselines up to 400 km (~50 stations in NM; USA)
- LWA2 currently under construction (19 km baseline to LWA1)

4.5 Giant Metrewave Radio Telescope



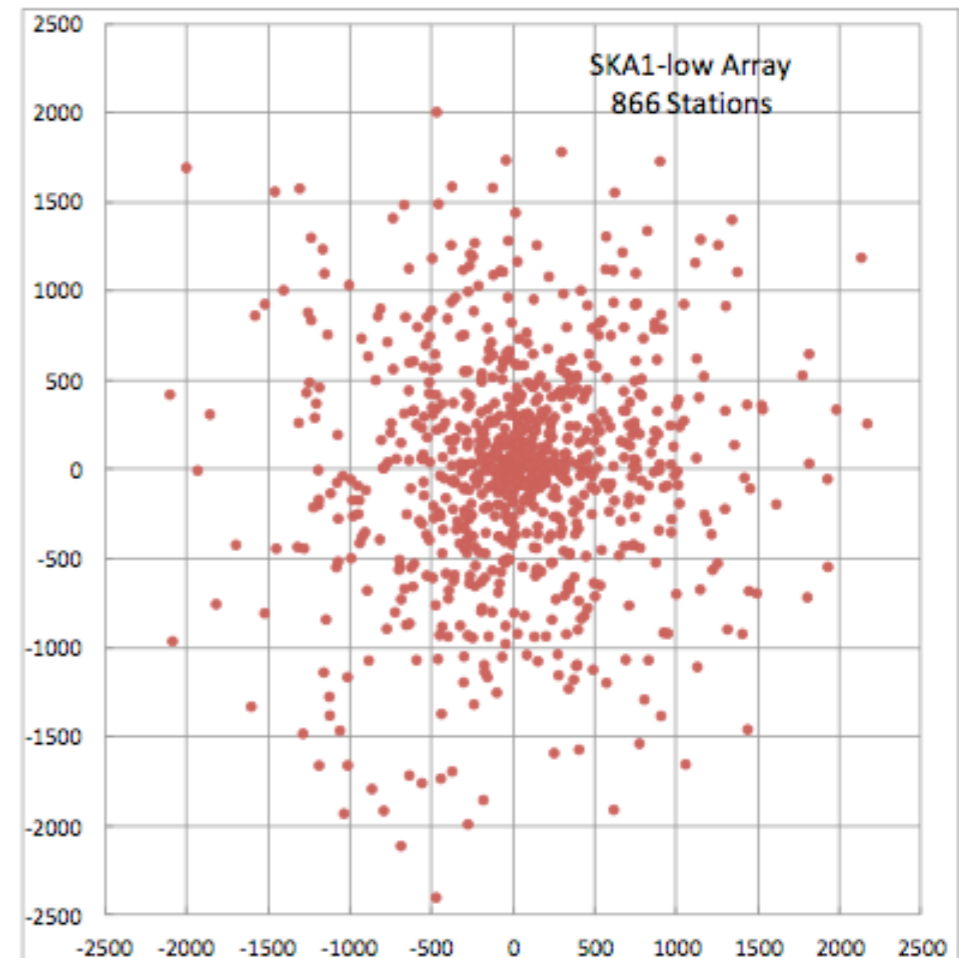
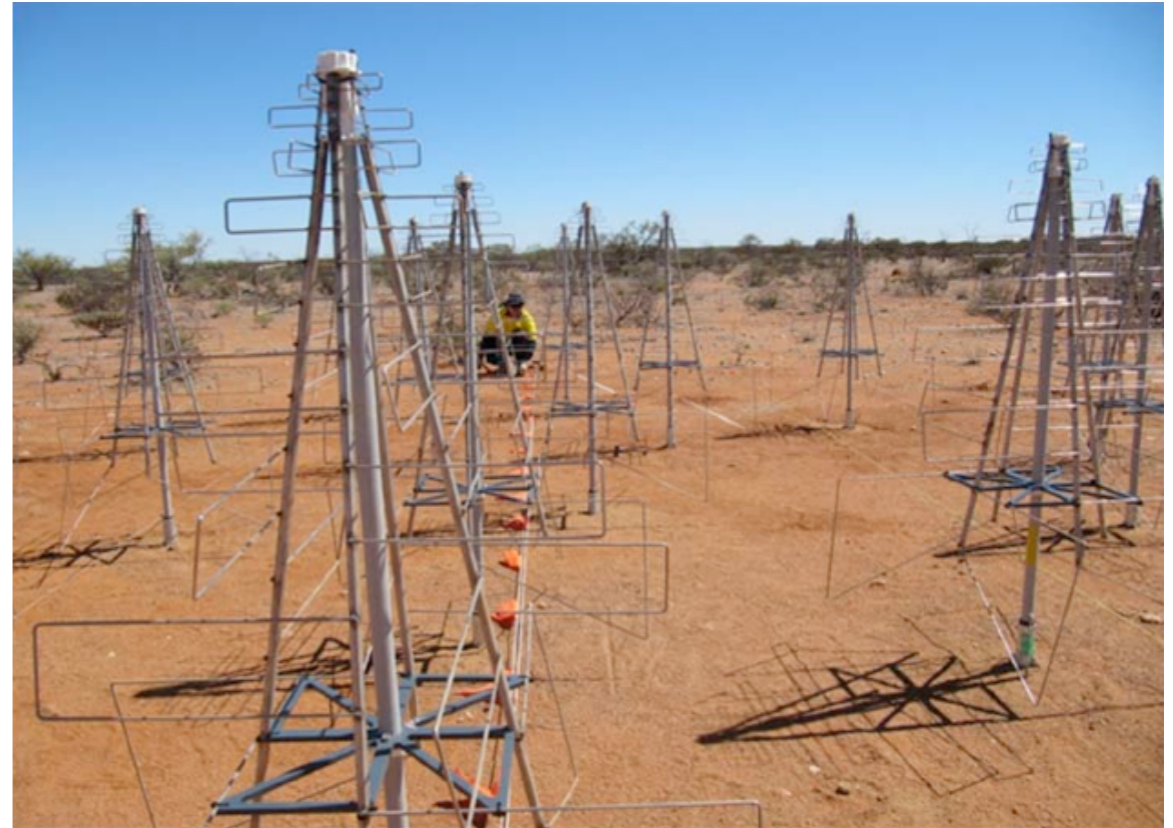
LOCATIONS OF GMRT ANTENNAS (30 dishes)



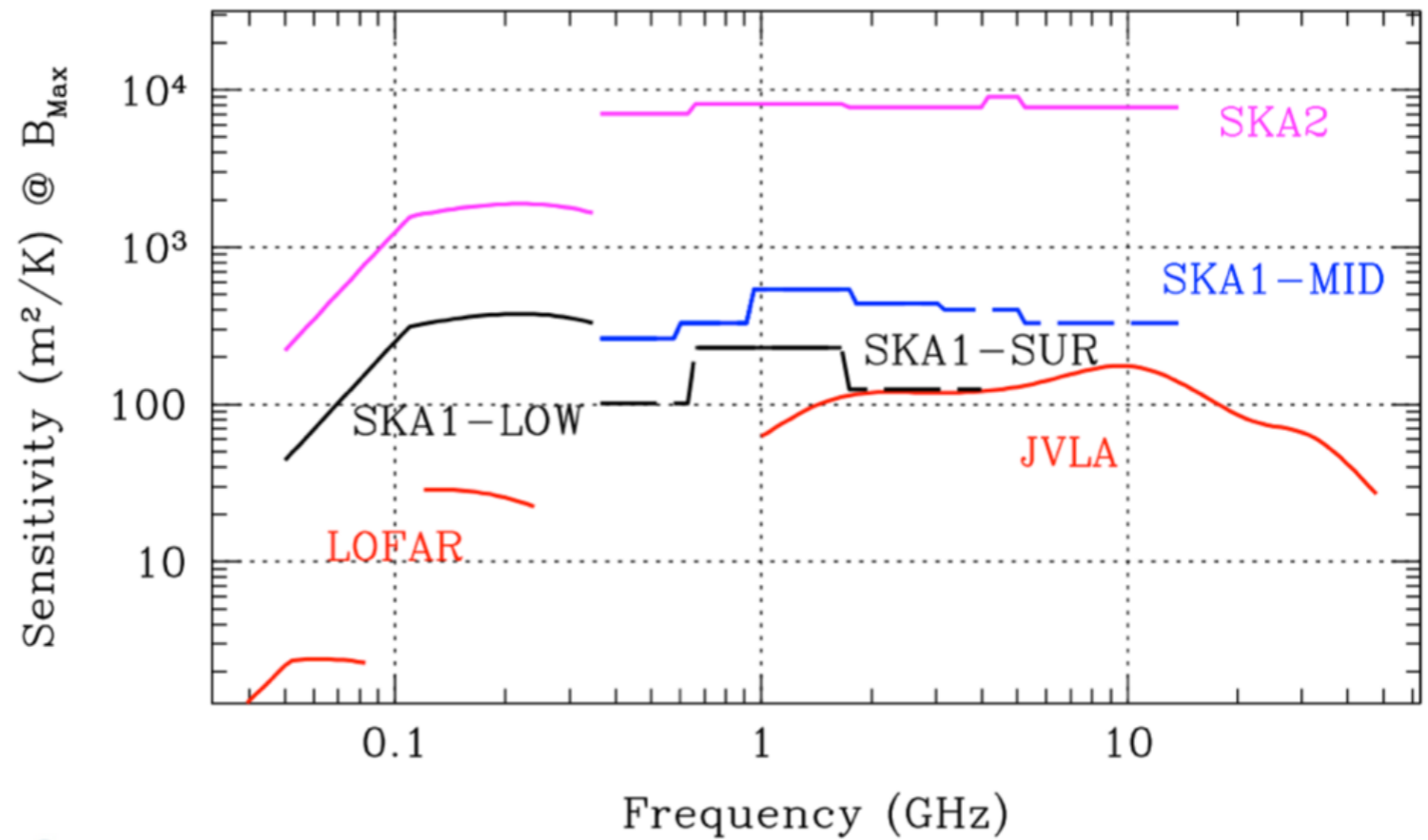
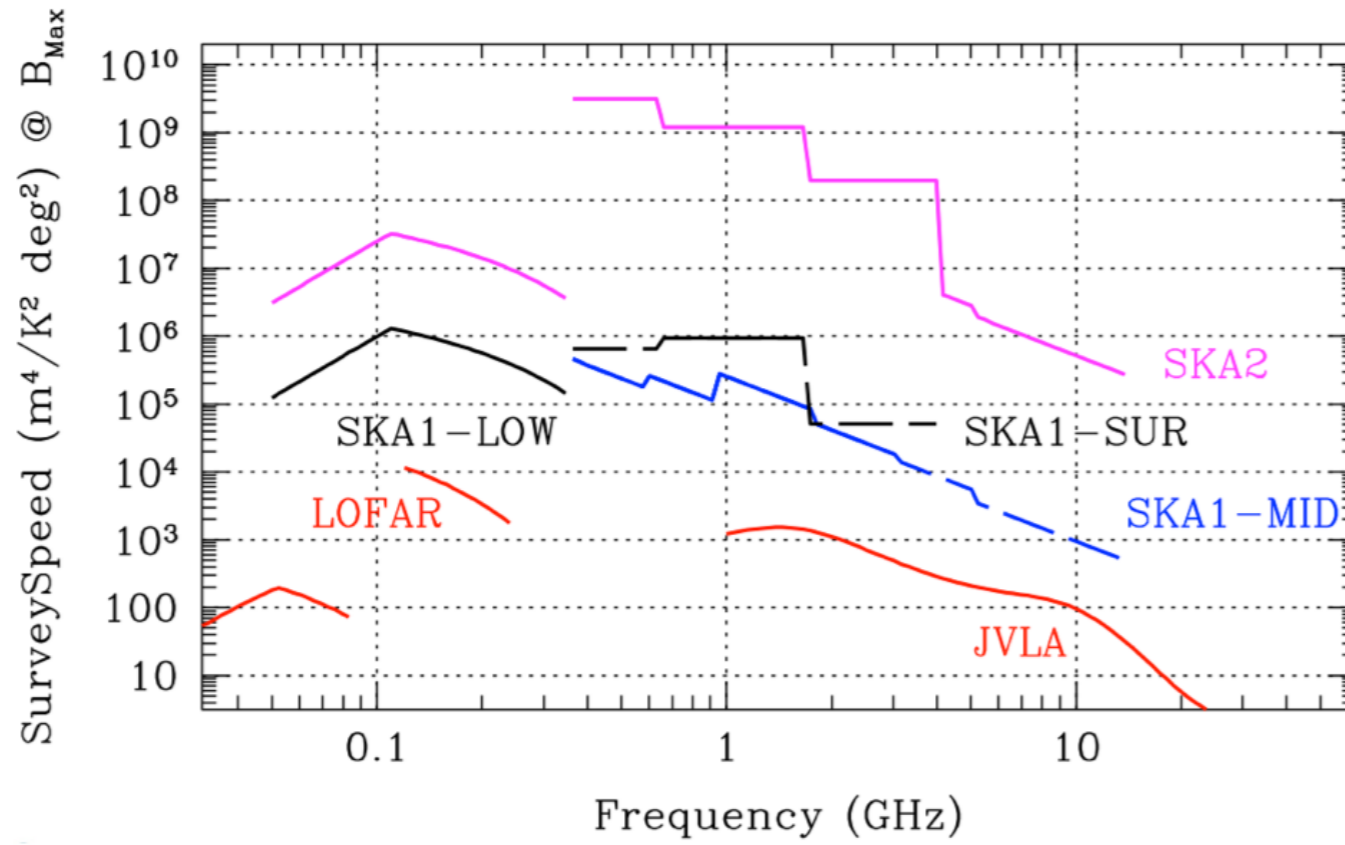
- Low frequency bands at 150, 235, 327 MHz (32 MHz bandwidth).
- 30 x 45 m antennas.
- Baselines up to 25 km
- Upgrade underway, providing contiguous 30-1500 MHz (400 MHz bandwidth).

4.6 Square Kilometre Array (SKA)

- Sparse dipoles (dual pol; similar to LOFAR).
- Freq: 50 to 350 MHz (300 MHz bandwidth).
- 130000 dipole antennas.
- 8 x more sensitive than LOFAR
- 50% collecting area at < 600 m, 75% at < 1 km.
- Spiral arms out to 50 km (100 km baselines), containing only ~4% of the collecting area.
- Dense core for EoR and Pulsar timing experiments (1 mK brightness temperature for 5 arcmin structures).
- $A_{\text{eff}} / T_{\text{sys}} \sim 1000 \text{ m}^2 / \text{K}$ (>100 MHz).



4.6 Square Kilometre Array (SKA)



Summary

1. Radio astronomy had its origins at low frequencies, and after a successful diversion to higher frequencies, attention is returning to < 350 MHz.
 - Modern dipoles still quite simple (cheap, easily replaced, large fields-of-view, large effective collecting area).
 - Need large computing power for correlation and data processing (see lecture on LOFAR Overview).
2. Interferometry is essential for competitive low frequency science.
 - Increases angular resolution and sensitivity at cost to filtering structure on large angular-scales and complicating the point-spread function.
 - Requires detailed calibration (see lectures on Calibration, Error Analysis and Ionosphere) and special wide-field, wide-bandwidth imaging techniques (see lectures on Imaging).
3. Several important low frequency radio telescopes available (LOFAR, LWA, GMRT, VLA, MWA) and upcoming (SKA).