

The Standard Imaging Pipeline

Generic pipeline

MSSS

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Outline

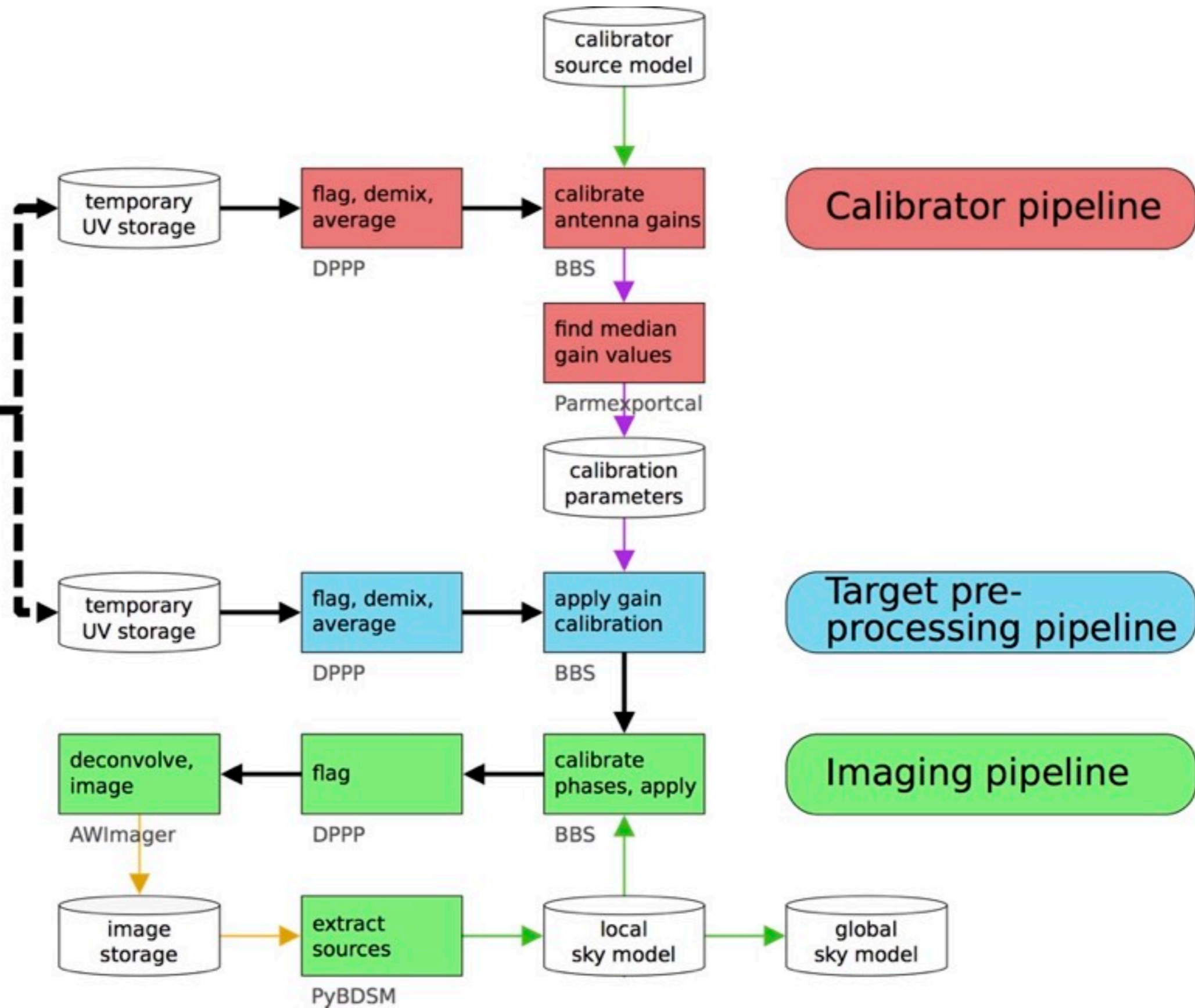
- RO standard imaging pipeline
- MSSS the survey and products
- Generic pipeline and its applications (Pre-factor FACTOR)
- RO planning for the future

Standard Imaging Pipeline

- An automatic pipeline, RO can run for users
- Preprocessing, calibrate, image, long baseline pre-processing (see Moldon lecture), PSR
- used for MSSS as testbed
- now outdated new pipelines coming soon

Calibrator

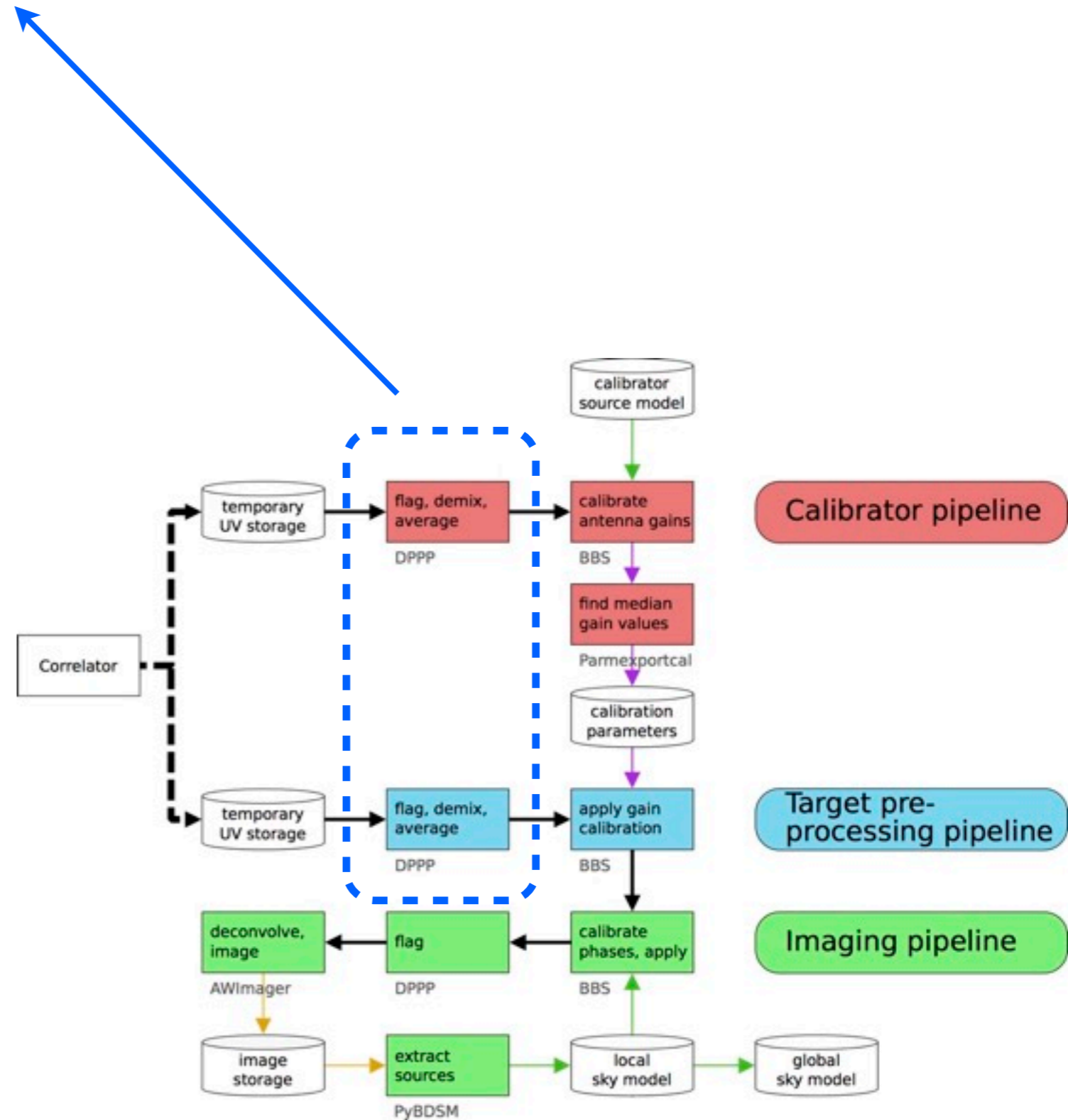
Target



Pre-processing pipeline

- Flags the data in time and frequency
- flags the autocorrelations
- flags the first and last two channels
- optionally “demix” subtraction of the contributions of the brightest sources in the sky (the so called "A-team
- Currently, users should specify if demixing is to be used, and which sources should be demixed.
- It is the pipeline most commonly used

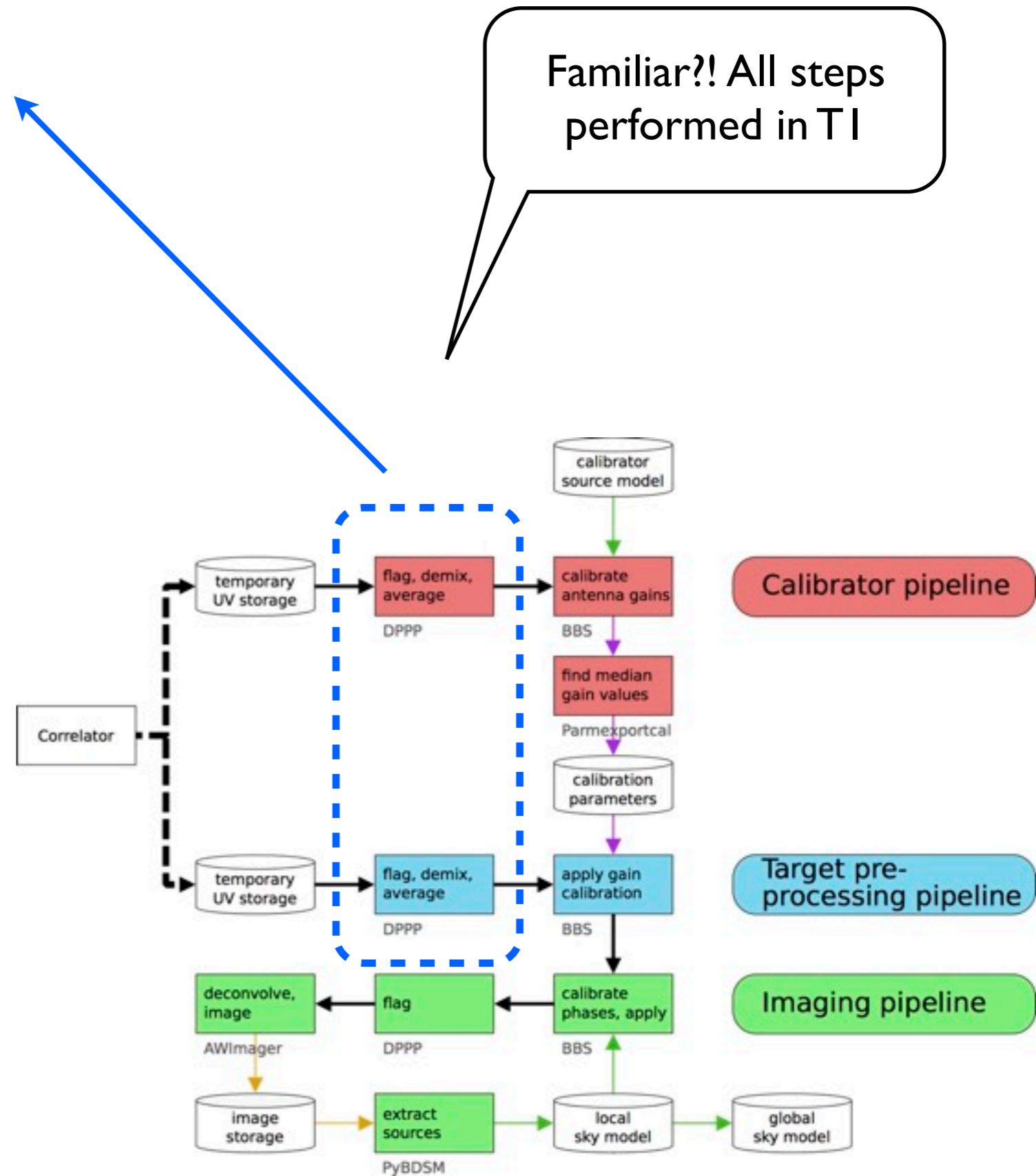
DATA PRODUCTS:
 For each observing beam a set of uncalibrated correlated visibilities is provided



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Calibrator pipeline

- Pre-processing
- Calibrate the calibrator The antenna gain solutions are estimated by BBS
- Solutions stored in a parmdb

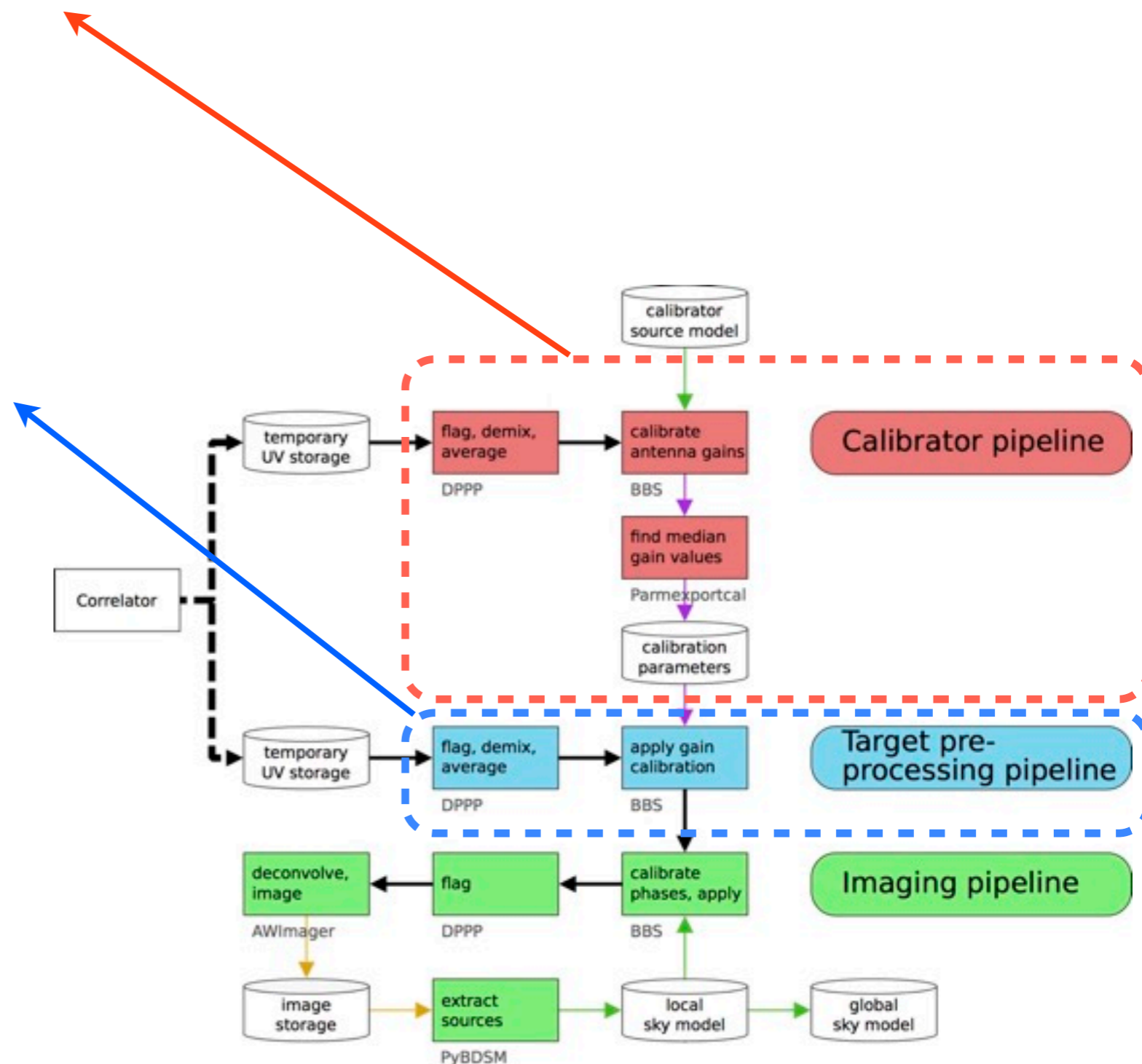
Target pipeline

- Pre-processing
- Applies the antenna gains (solutions) obtained in the calibrator pipeline

Used to calibrate MSSS

DATA PRODUCTS:

For the calibrator and target beams a set of uncalibrated and calibrated correlated visibilities are provided, written respectively in the DATA and CORRECT columns of the MS.



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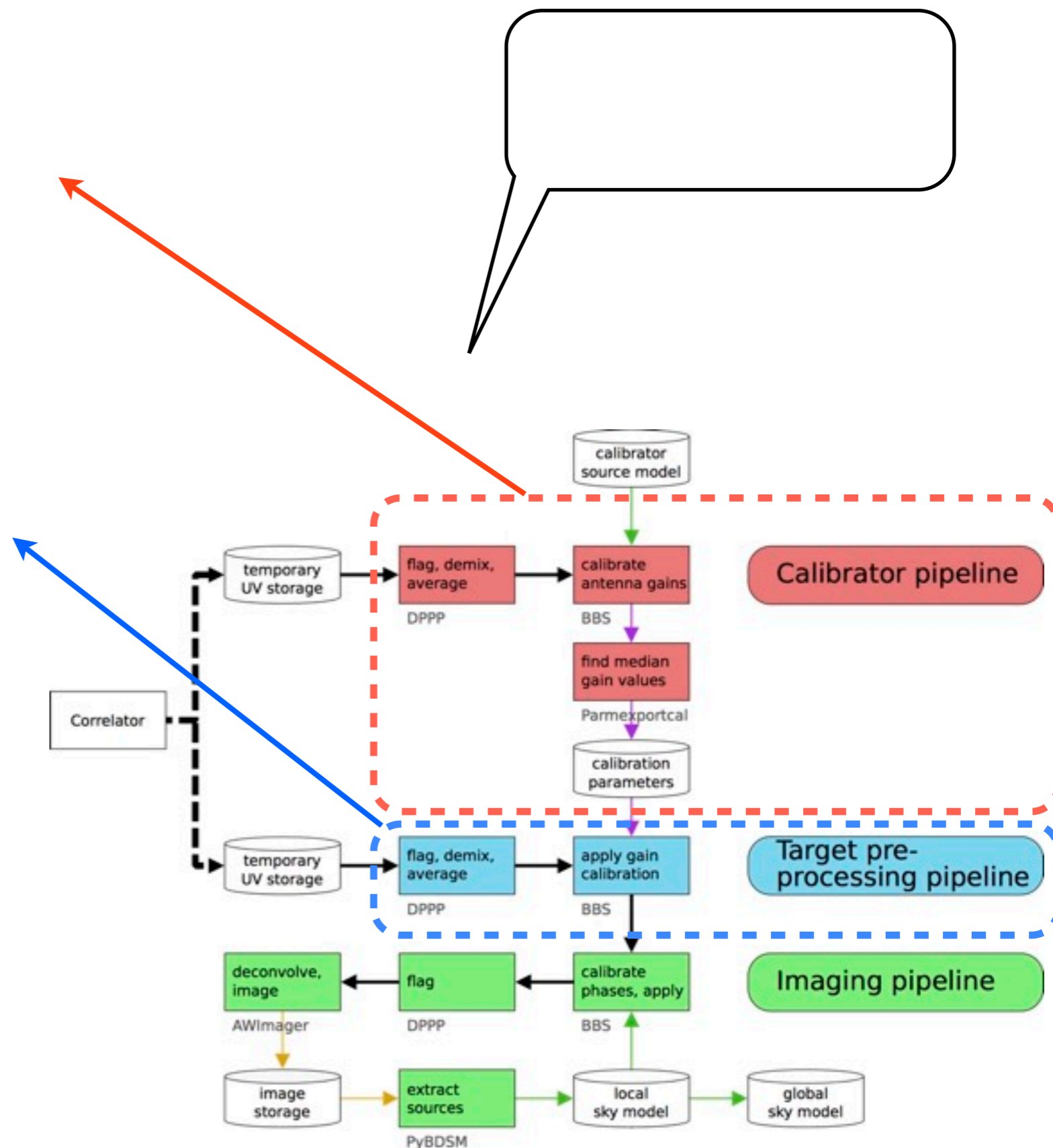
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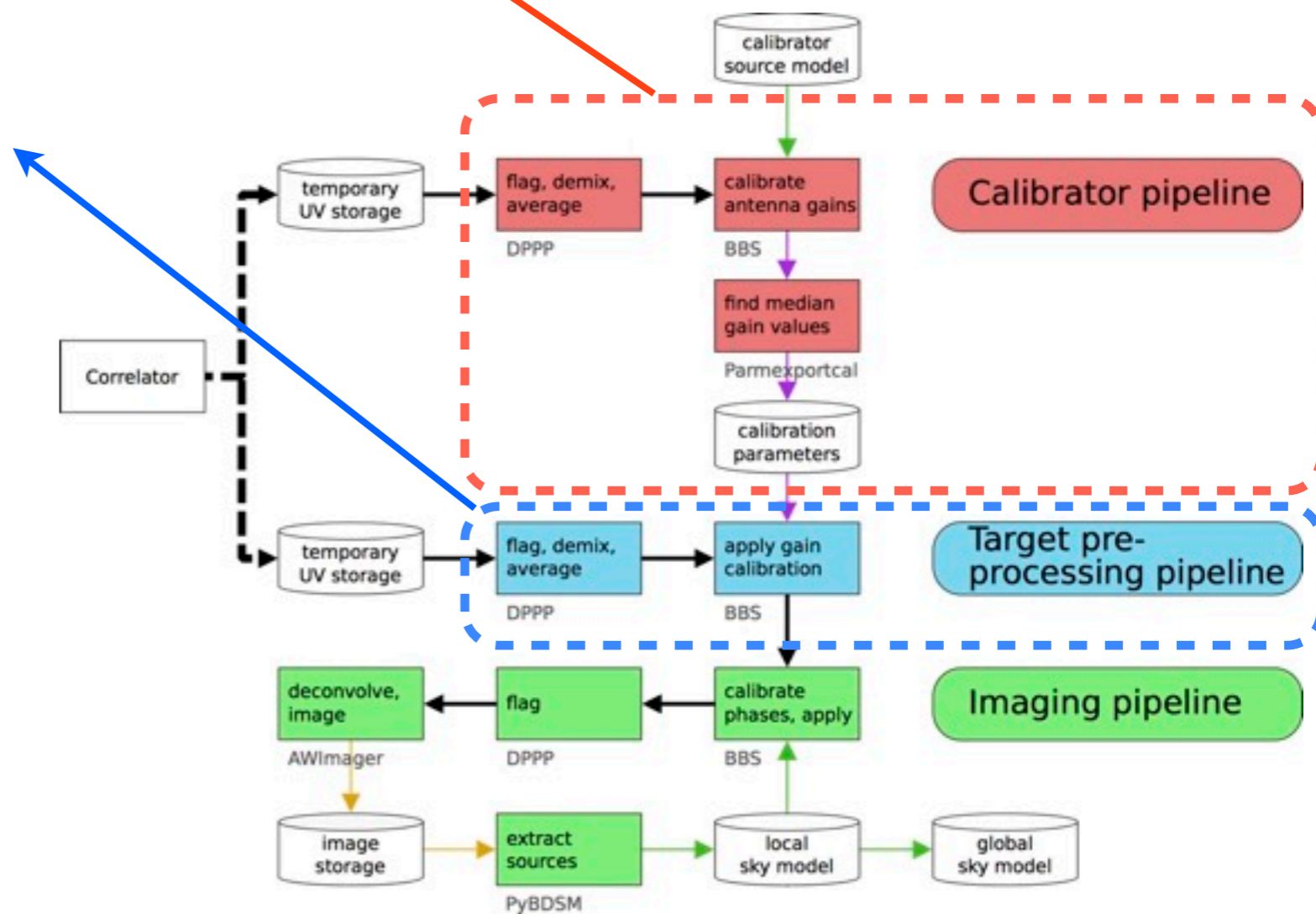
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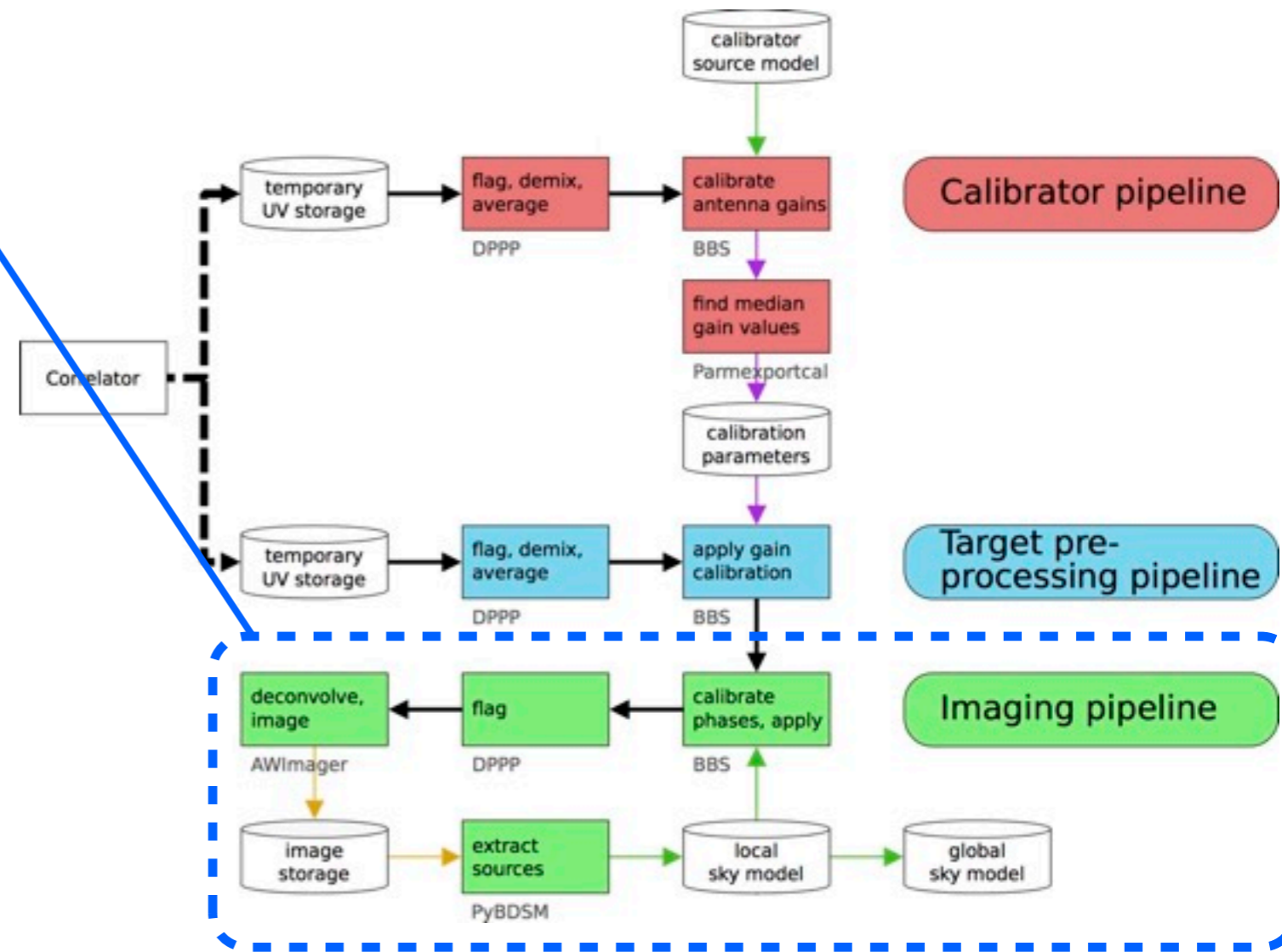
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Same concept will be used in T2 with different software



Imaging pipeline

- Sub-bands are concatenated in frequency. Bandwidth size set according to user specification
- flag of outliers
- A run of phase calibration with BBS is performed using a GSM model.
- Sub-bands are concatenated in time when observations are performed in snapshot
- Images are produced in hdf5 format (using awimager)
- Source finding software is used to identify the sources detected in the image, and generate an updated local sky model.



DATA PRODUCTS:

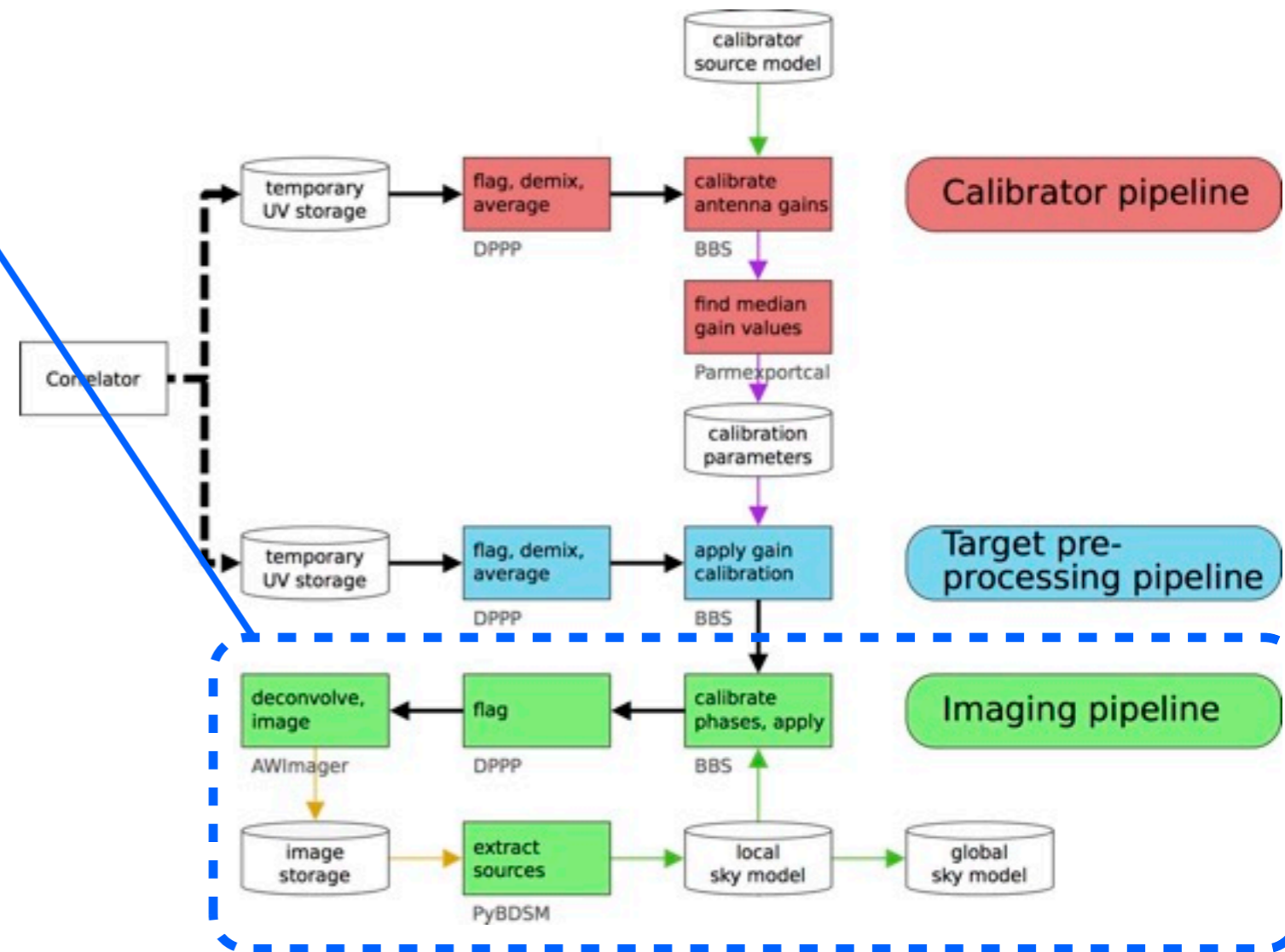
Calibrated images.

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Same concept will be used in T2 - T3 with different software

Multifrequency Snapshot Sky Survey

Goals: obtain broadband sky model, shakedown LOFAR operations

MSSS-LBA



Frequency: 30-75 MHz
(8 x 2 MHz bands)

Resolution: ≤ 100 arcsec

Sensitivity: ≤ 15 mJy/beam

Area: 20,000 square degrees

Number of Fields: 660

Simultaneous $\sim 10^\circ$ beams: 5

Test observations resuming

MSSS-HBA



Frequency: 120-160 MHz
(8 x 2 MHz bands)

Resolution: ≤ 120 arcsec

Sensitivity: ≤ 5 mJy/beam

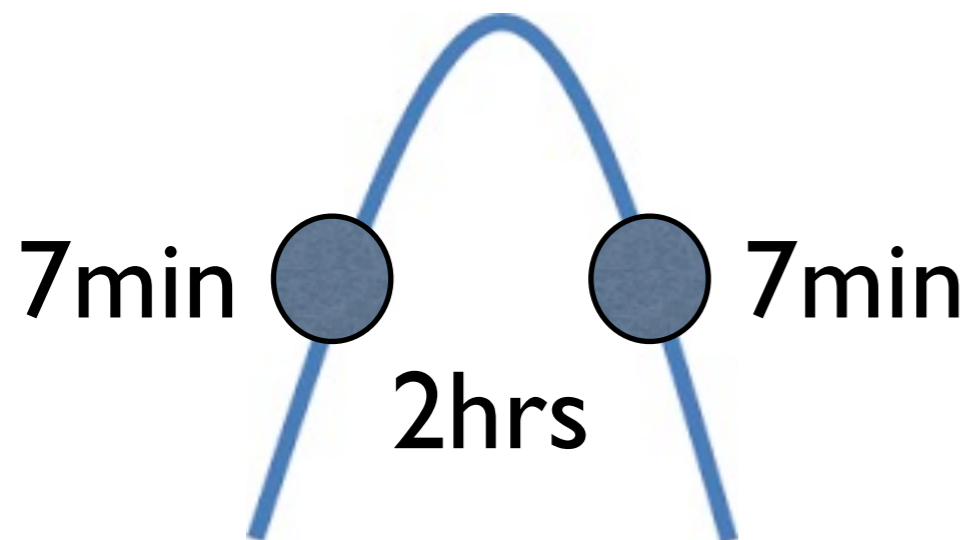
Area: 20,000 square degrees

Number of Fields: 3616

Simultaneous $\sim 4^\circ$ beams: 6

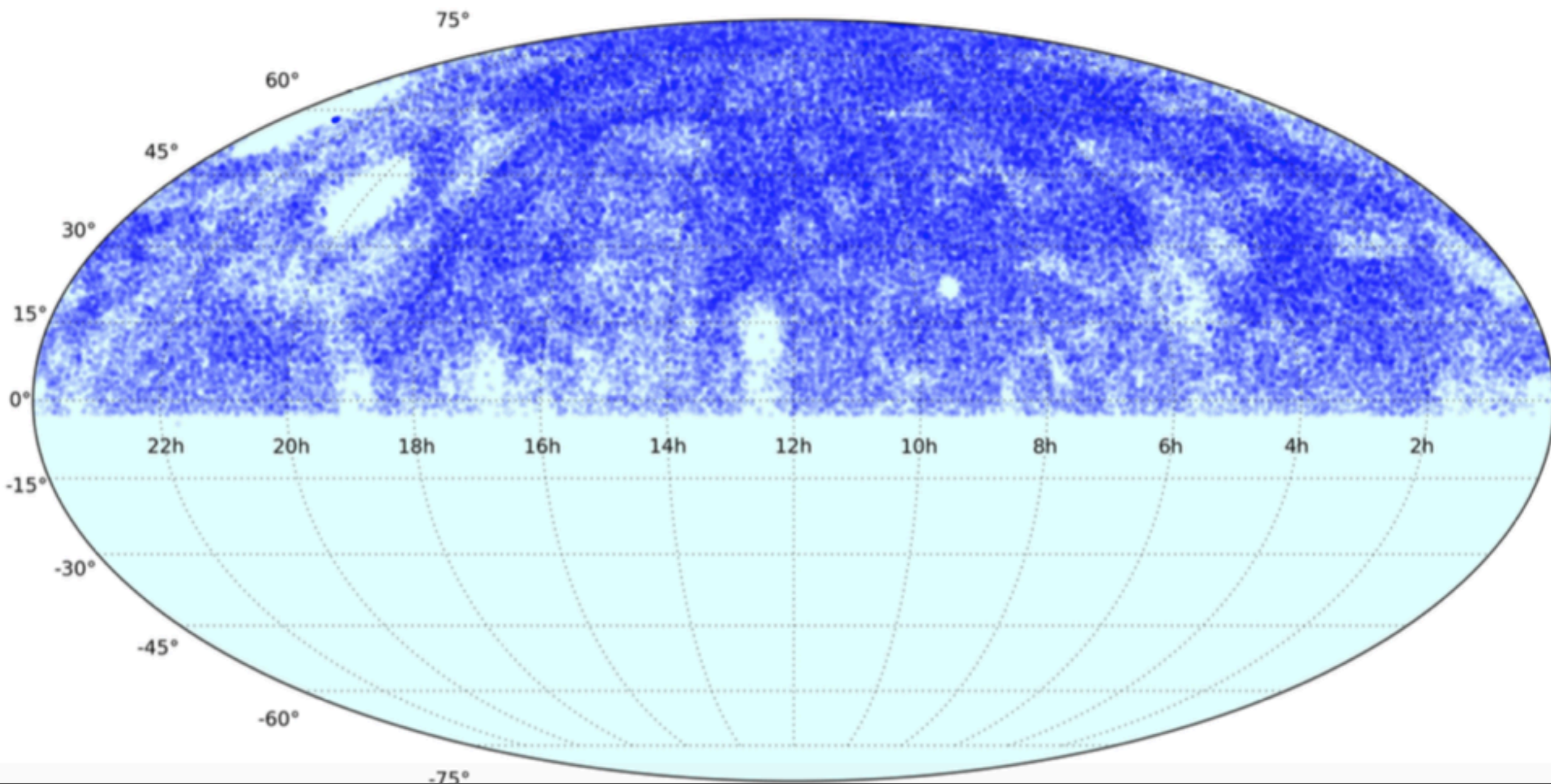
Observations 100% complete

Observations



Processing RO SIP

+ Script analogue to
imaging pipeline



MSSS-HBA catalog (v0.1): 130000 sources

- Final catalog still under development (need flux correction..)
- All fields and catalog loaded into MSSS VO server for use by initial science and checks.
- group of testers (active MSSS participants) ... identifying bugs in system. MSSS Forum being used to collect issues.
- Data products are password-protected before data release

More info verification field paper: *Heald et al. 2015, A&A, 582, A123*

Generic pipeline

- The Pipeline Framework is used by RO for automated processing on the CEP cluster systems (e.g. SIP). Writing these pipelines is complicated and requires a lot of knowledge of the framework itself and some programming skills.
- The generic pipeline is a pipeline based on that system. It is a simplified layer of software that helps users with the design and execution of their own workflow without the need to understand the underlying system.
- For a pipeline the user should organize the work into building blocks e.g. preprocessing-calibration-imaging....
- Parameters can be reduced to a minimum with different sets of default parsets for every step. Integration of other peoples steps and reusing existing work are one of the primary goals of the generic pipeline.
- A users pipeline can run on a single workstation and in a cluster environment without the need to change the pipeline parset or to program process management.
- Steps and arguments to the steps are defined in a parset file.
- This parset is then the argument for the genericpipeline.py.
- The pipelines name will be the first part of the parsets name mypipeline.parset. Log files will be tracked under that name

Parset

```
pipeline.steps    = [step1,step2,step3,...]
pipeline.pluginpath = plugins                # optional
pipeline.mapfile  = /path/to/your_data.mapfile # optional
```

- The step list determines the order of execution.
- Optional path to a plugins directory
- Mapfiles are the data descriptors, the path to your input data

```
# Pipeline for running NDPPP on all files in a directory

#variable parameters
#path to the directory where we are looking for the input data
! input_path = /data/scratch/dummyuser/test-in
# path to the parset
! ndppp_parset = /home/dummyuser/parsets/NDPPP-preproc-parset.proto

pipeline.steps=[createmap,ndppp]

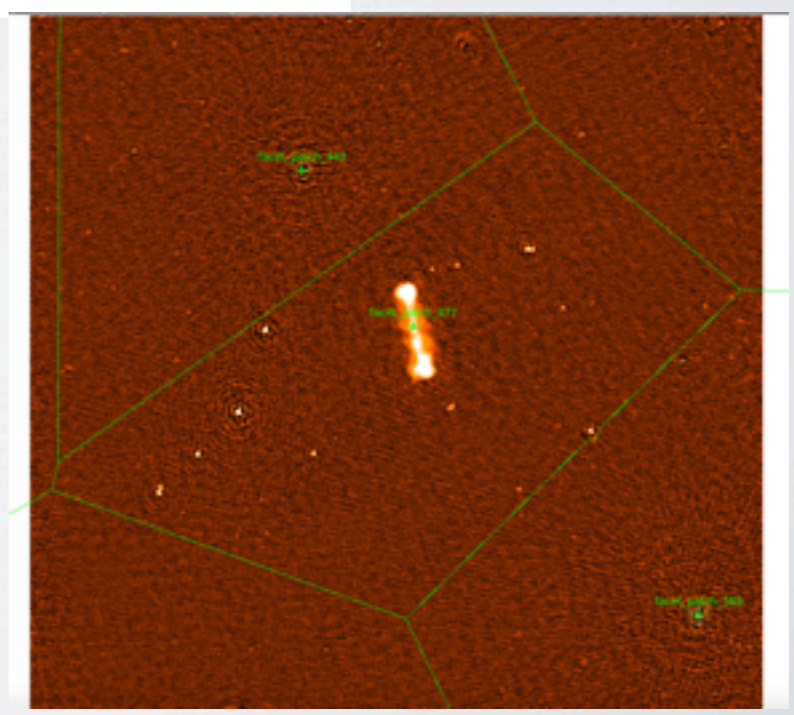
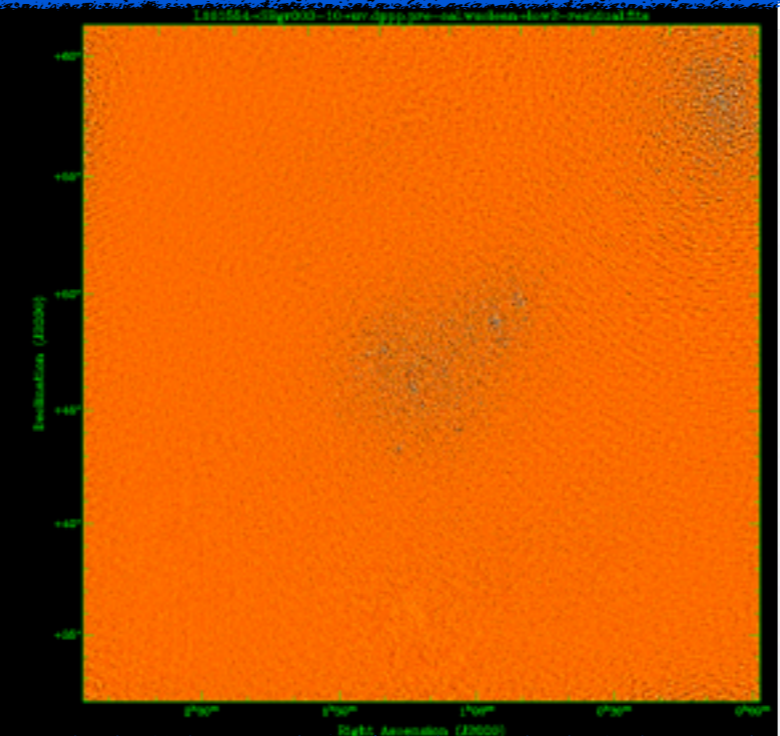
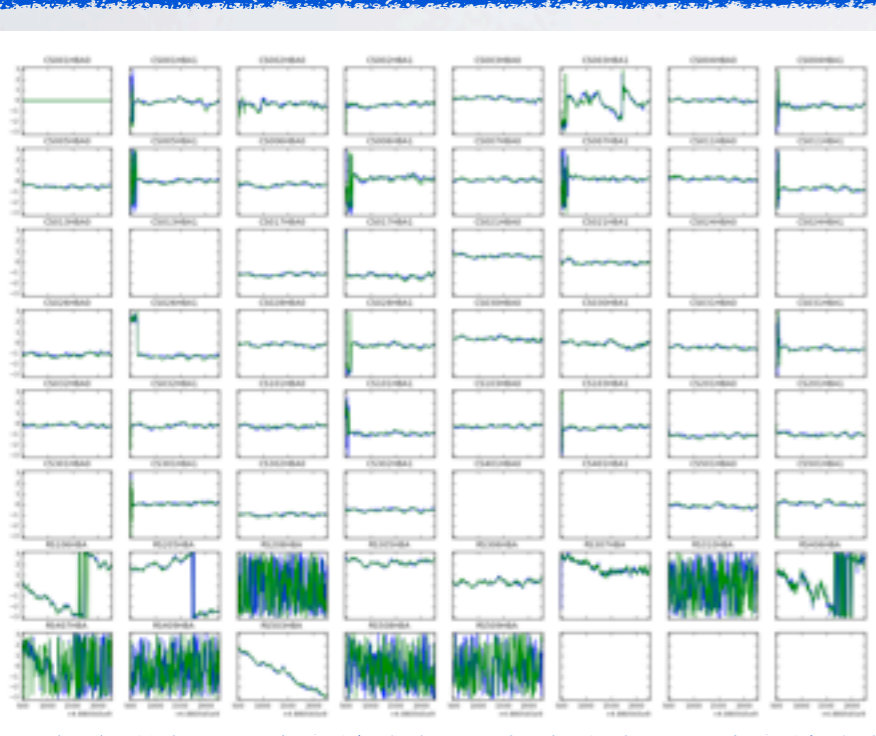
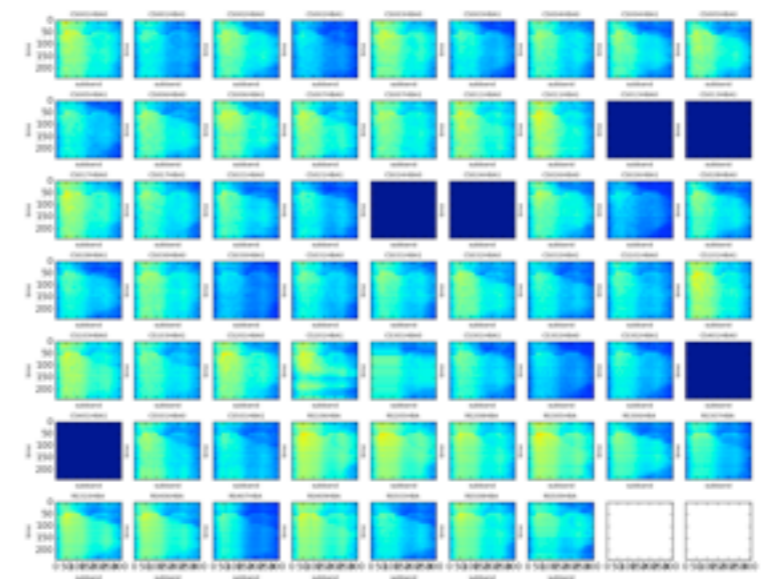
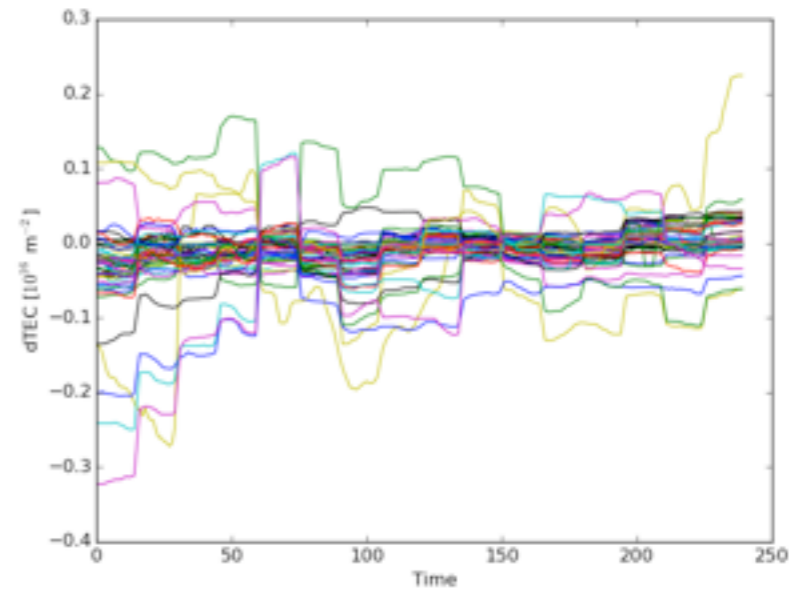
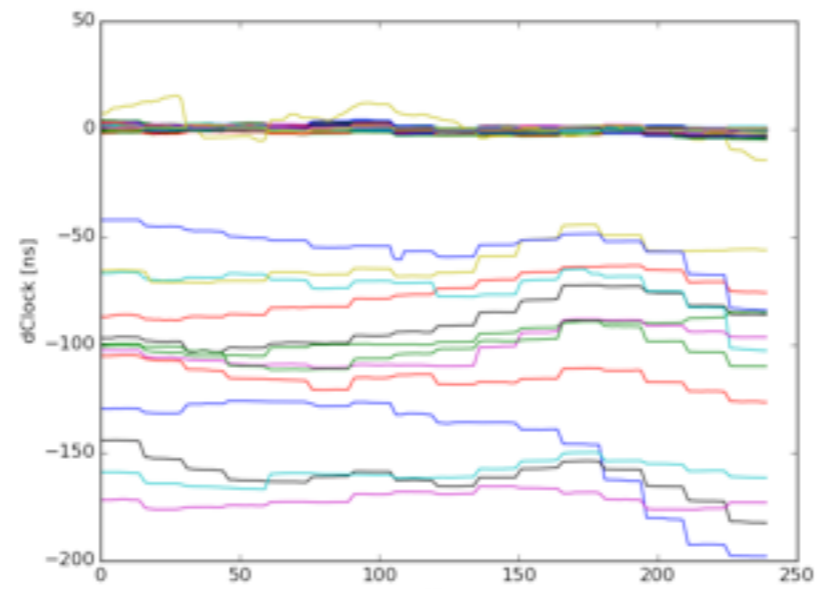
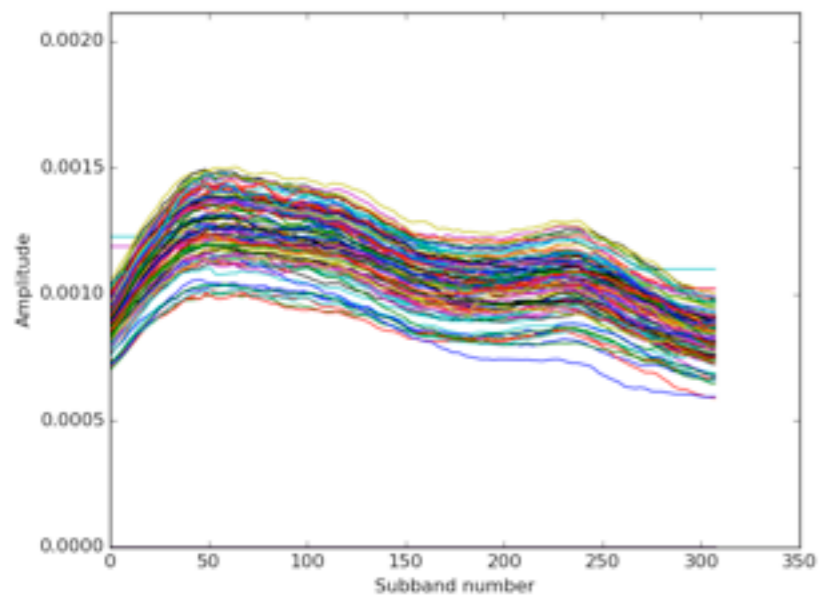
#Step 1: search for all measurement sets in one directory and generate a mapfile
createmap.control.kind          = plugin
createmap.control.type          = addMapfile
createmap.control.cmdline.create = mapfile_from_folder
createmap.control.mapfile_dir   = input.output.mapfile_dir #this is the name that the mapfile will have
createmap.control.filename     = input_data.mapfile
createmap.control.folder       = {{ input_path }}           #this references to the path we defined above

#Step 2: run NDPPP with a given parset on all files that the previous step found
ndppp.control.type              = dppp
ndppp.control.parset            = {{ ndppp_parset }}        #this references to the parset we defined above
ndppp.control.max_per_node     = 4                          #run 4 instances of NDPPP in parallel
ndppp.control.environment      = {OMP_NUM_THREADS: 6}      #tell NDPPP to use only 6 threads
ndppp.argument.msin            = createmap.output.mapfile
```

More info: <http://www.astron.nl/citt/genericpipeline/#>

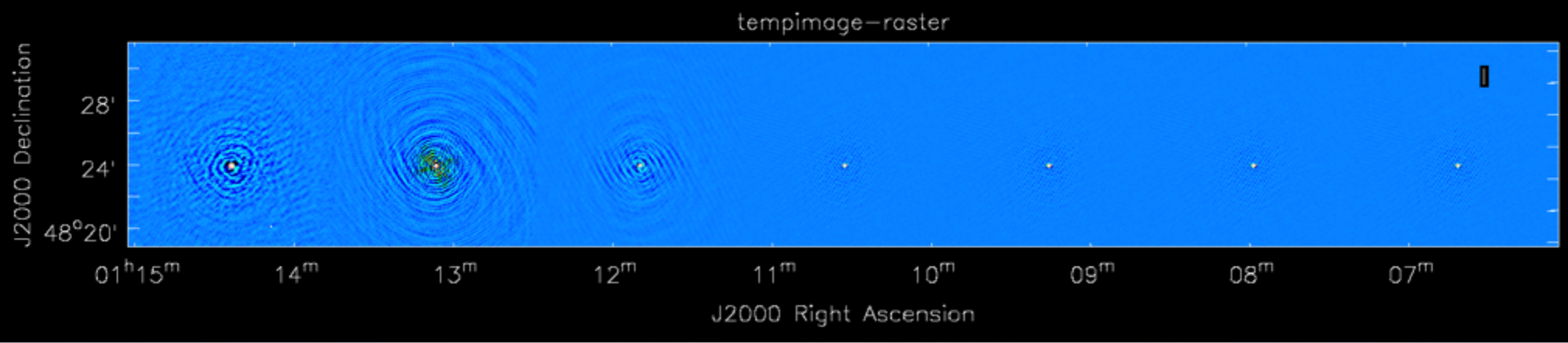
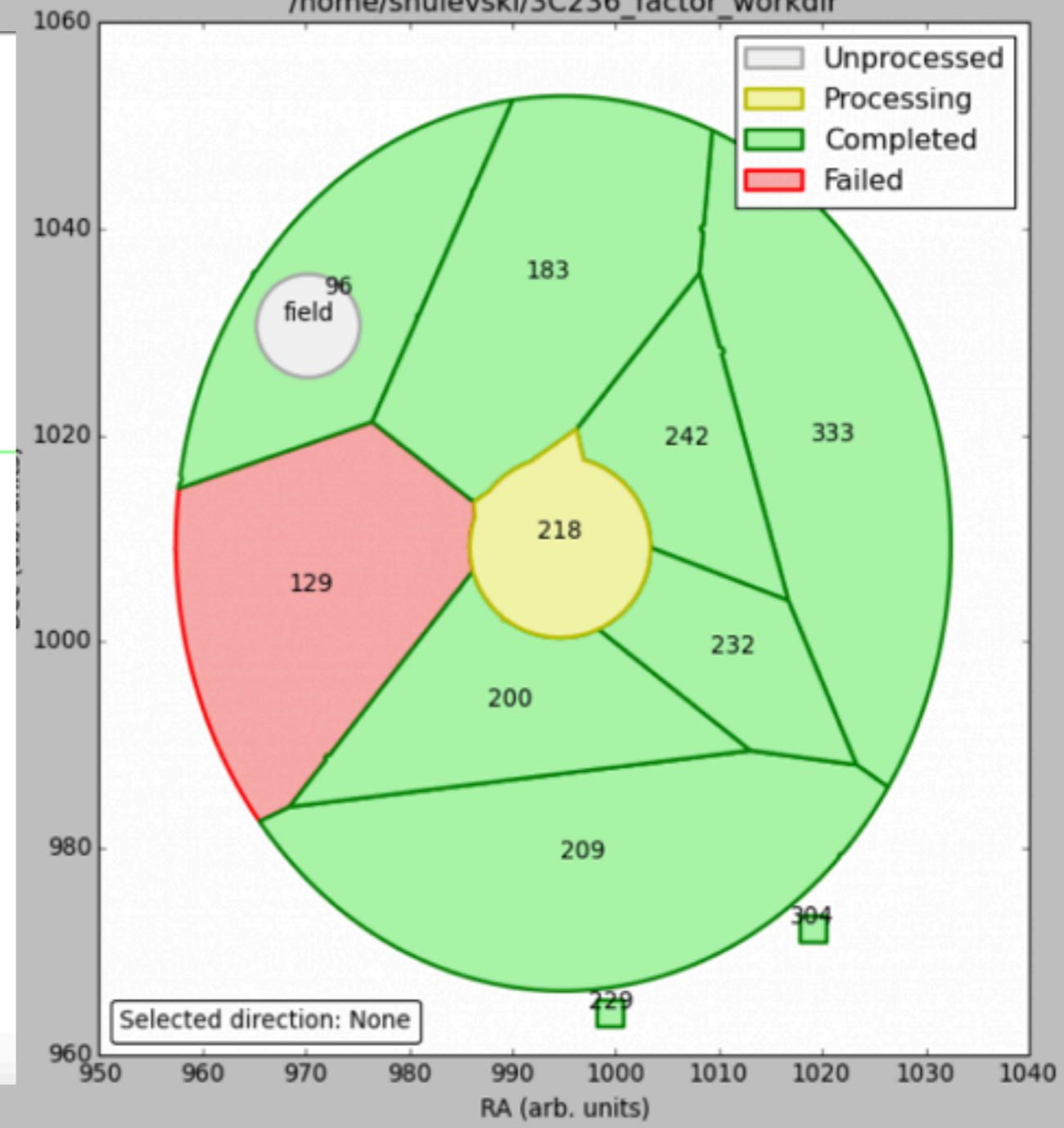
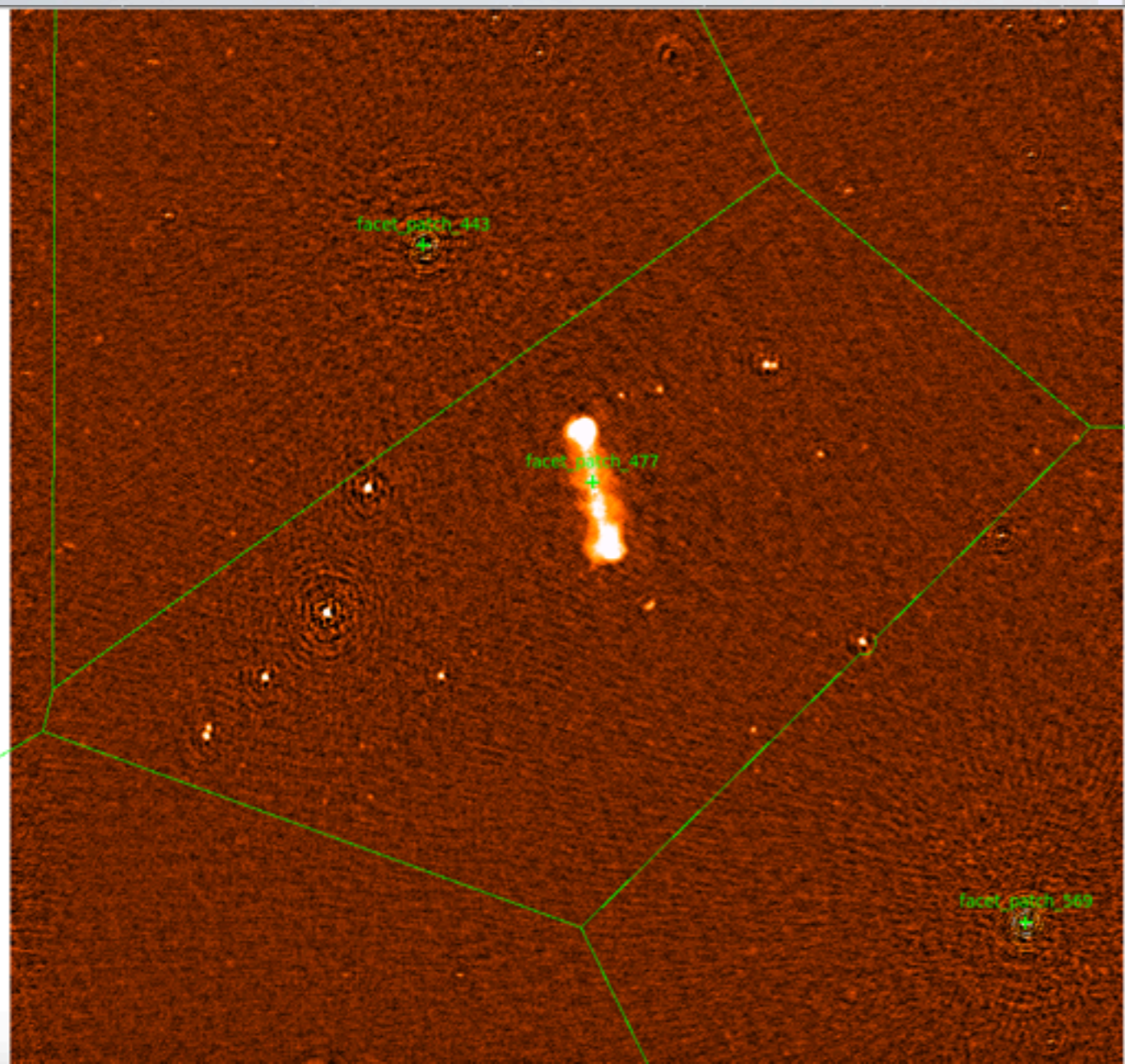
Pre-factor (new calibrator pipeline)

- In the calibrator field: solves for bandpass and separates the instrumental (clock) from the ionospheric (TEC) contribution to the phase delays.
- Transfers to the target field the bandpass, clock and phase offset.
- Combines SBs and image the blocks at high and low resolution. Produces residual images and MS to be fed to the FACTOR pipeline



FACTOR: facet self calibration pipeline

- By dividing up the field into many facets and solving for the direction-dependent corrections in each facet using the “peeling”
- phase calibration on short time scale >>
ionospheric effects amplitude calibration long time scale >> residual beam errors
- instrumental-noise limited images (~ 0.1 mJy/beam for an 8-hour observation), high-resolution images (~ 5 arcsec FWHM) and high-fidelity images
- designed to distribute of jobs over multiple nodes of a cluster and for the processing of facets in parallel.



future development

- RO plans to implement the generic pipeline and use it as platform for all the current pipelines -- highly flexible easy for users to provide different set up wrt the standard
- RO plans to substitute the calibrator, target and imaging pipeline with the pre-factor pipeline.
- FACTOR needs more automatization and performance optimization in order to be taken into account as part of the SIP.