

LOFAR data:

error analysis

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(with thanks to E. Mahony, K. Chyzy and others who I have borrowed/stolen slides from)

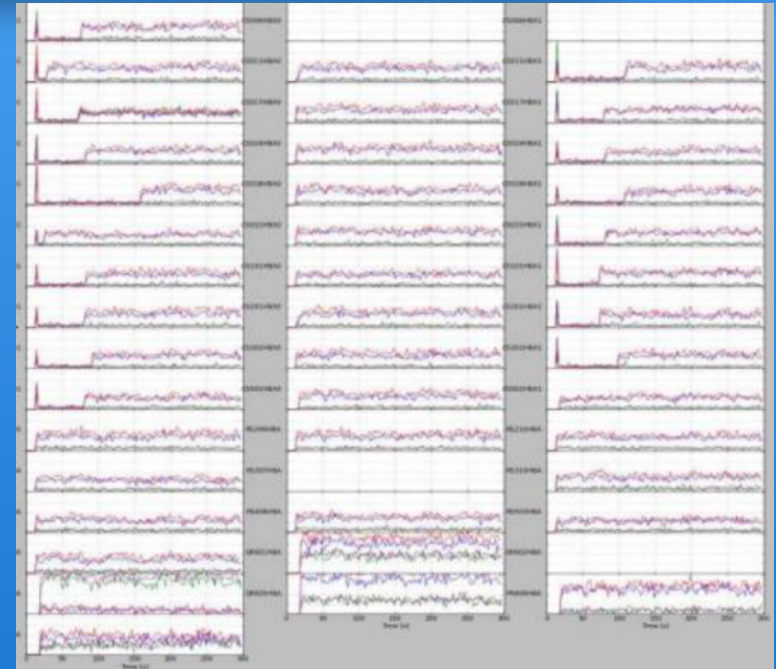
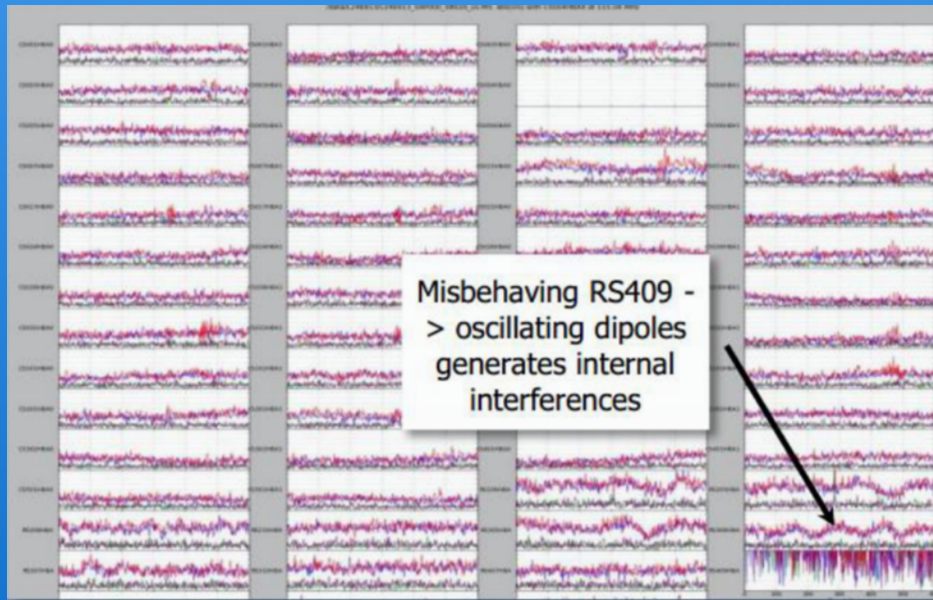
## PROBLEM

- Data Errors
- Calibration errors
- Image plane errors

## SOLUTION

- Use the observation log (report) to track big issues (ex. bad antennas). Inspect data, flag as warranted.
- Does the model fit the data? Ionosphere an issue?
- Deconvolution issues, residual data issues -> start at the top

# Data Errors: inspection plots



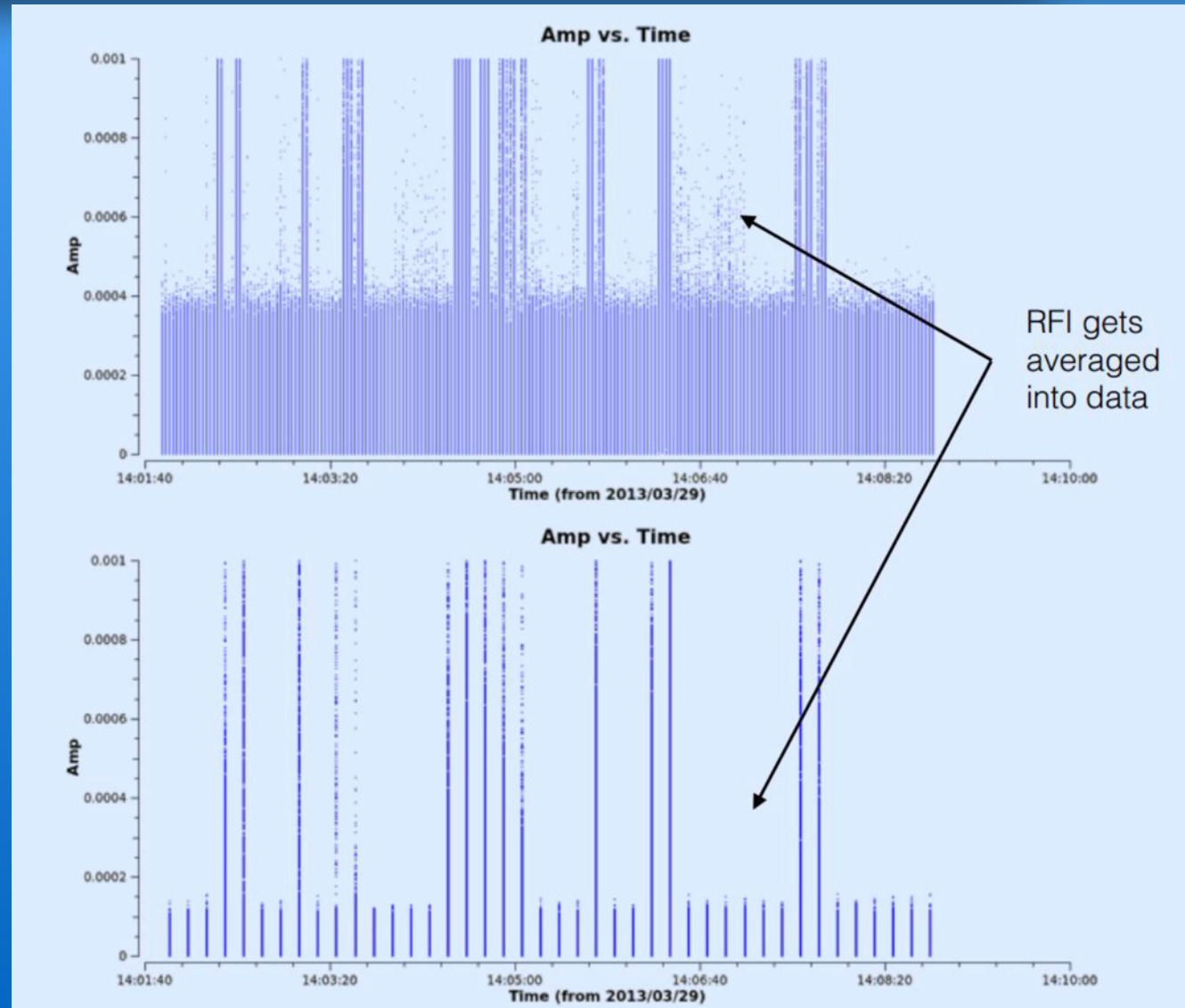
Connection problems at the start of the run

Learn more at: <http://www.astron.nl/radio-observatory/observing-capabilities/depth-technical-information/data-quality-inspection/data-qu>

# Data Errors: RFI

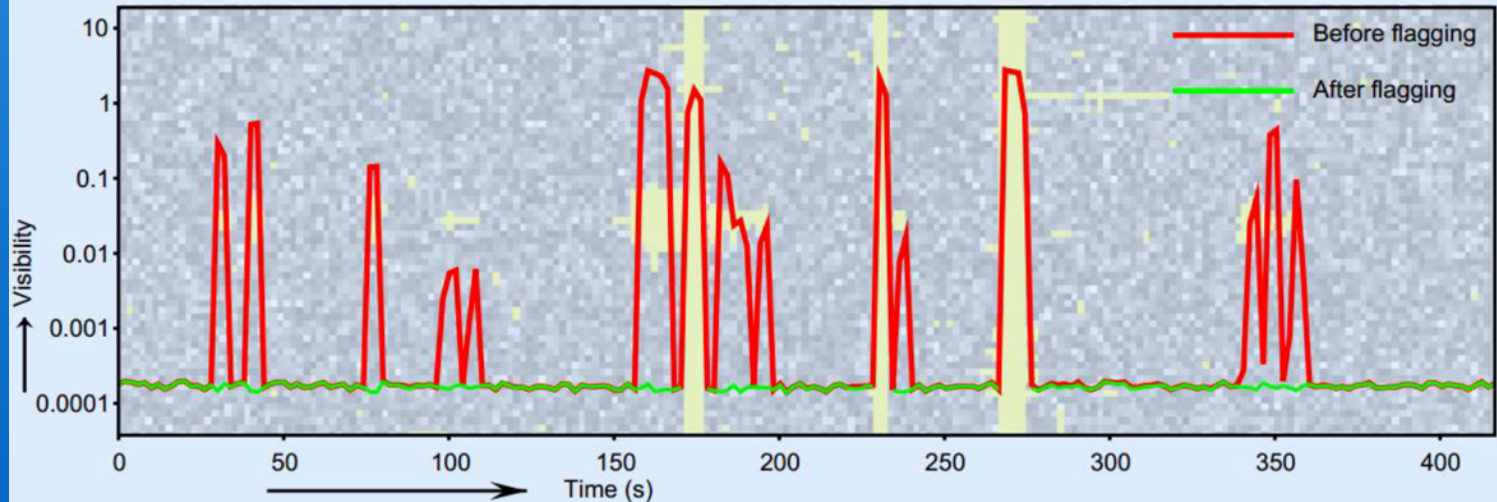
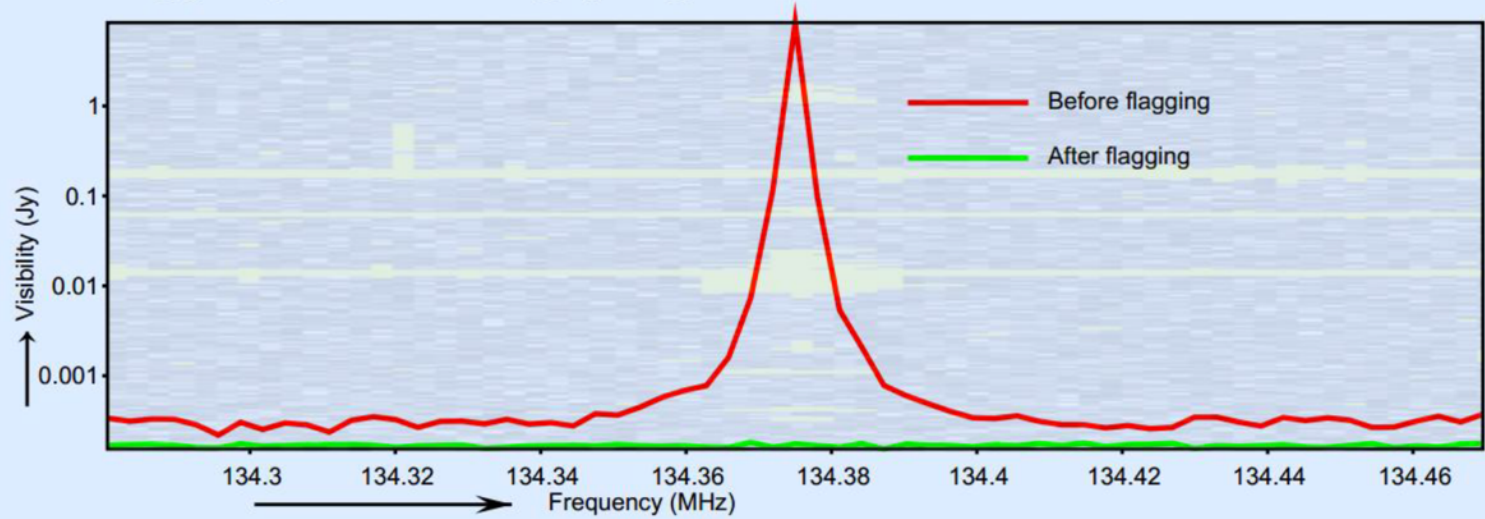
Flagging always  
the first step!

- flag at high resolution



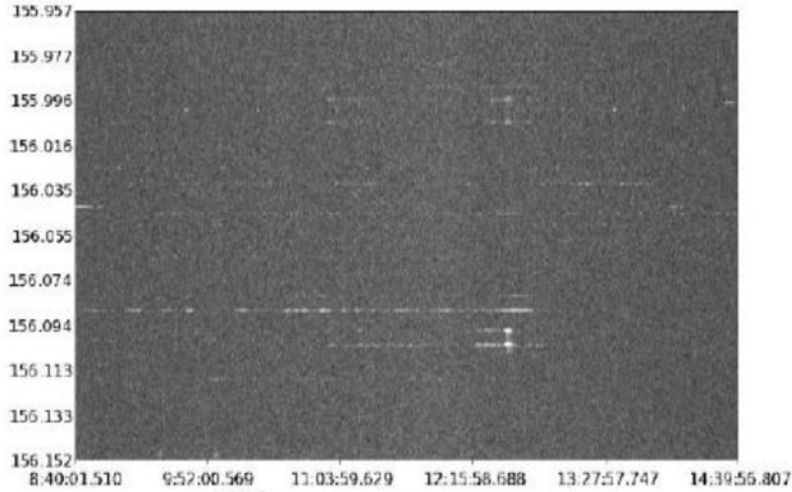
# Data Errors: RFI

AOFlagger (André Offringa) flags data based on statistics:

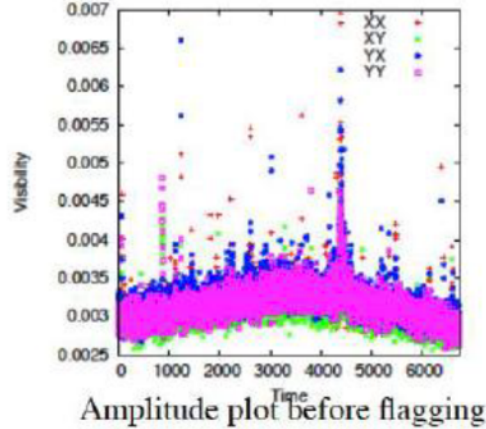
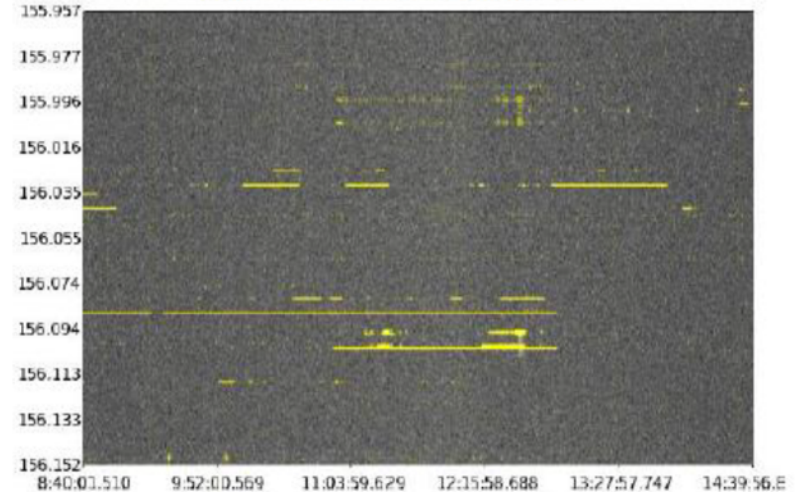


# Data Errors: RFI

Time-frequency before flagging

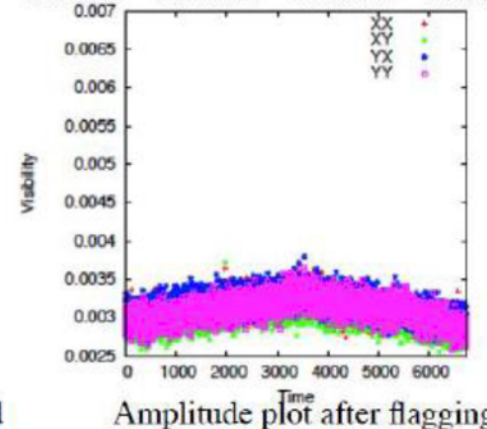


Time-frequency after flagging



Amplitude plot before flagging

156 MHz,  
1.8% data flagged



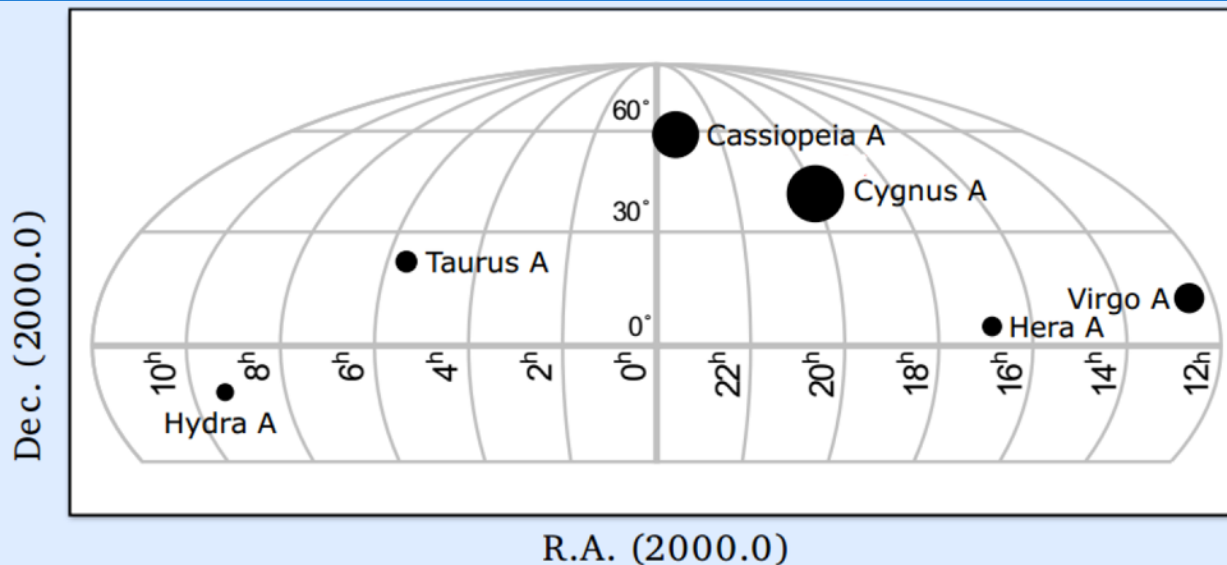
Amplitude plot after flagging

Offringa et al. (2010, 2012)

# Data (Errors): Demixing

At low frequencies, visibilities are affected by the brightest radio sources on the sky - CygA, CasA, VirA, TauA, HerA, HydA - the “A-team”

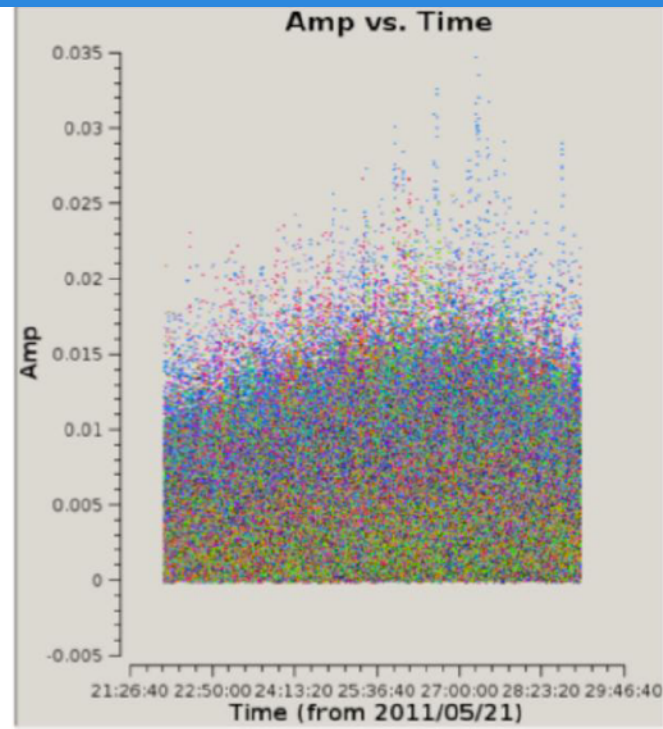
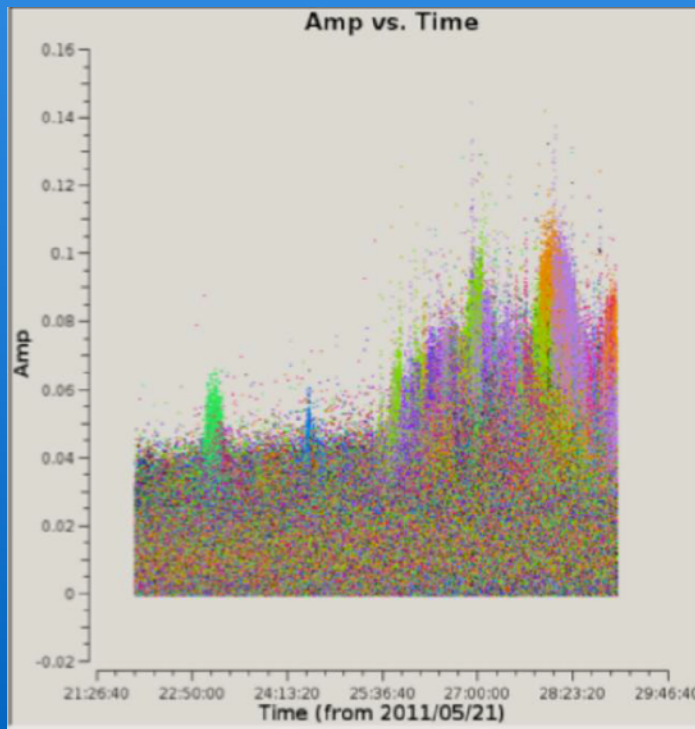
- LBA: data almost always affected by CygA, CasA at least
- HBA: data affected if phase centre within 30 deg. of an A-team source or if elevation of A-team high. To make sure, simulation is needed.



# Data (Errors): Demixing

A-team needs to be removed from the visibilities - “demixing”

- Use model to subtract A-team from visibilities  
Data needs to be at sufficient resolution for this to work.
- Clip of flag A- team contribution.

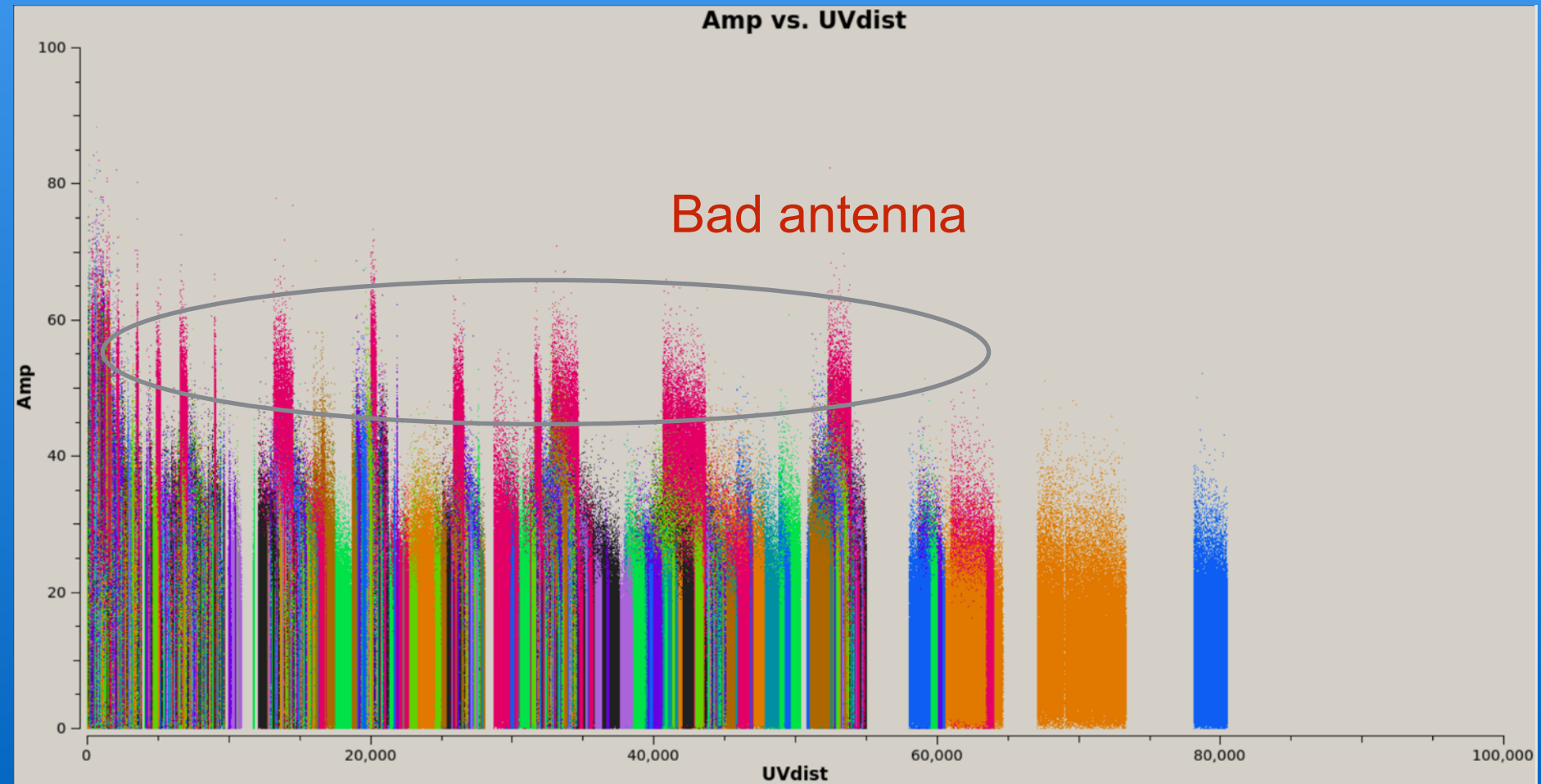




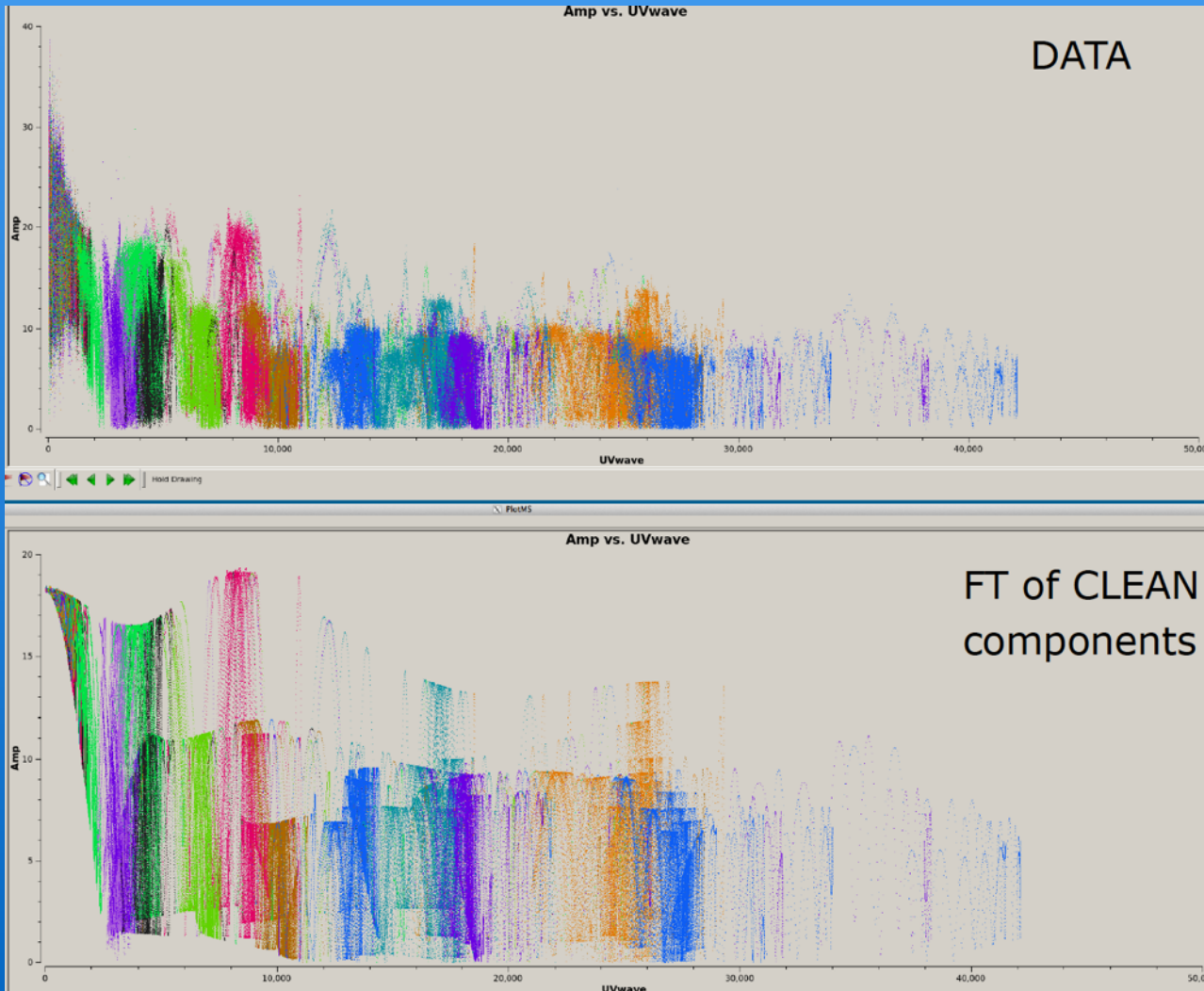
# Data Errors: visibilities

Amp vs. UVdist

Bad antenna



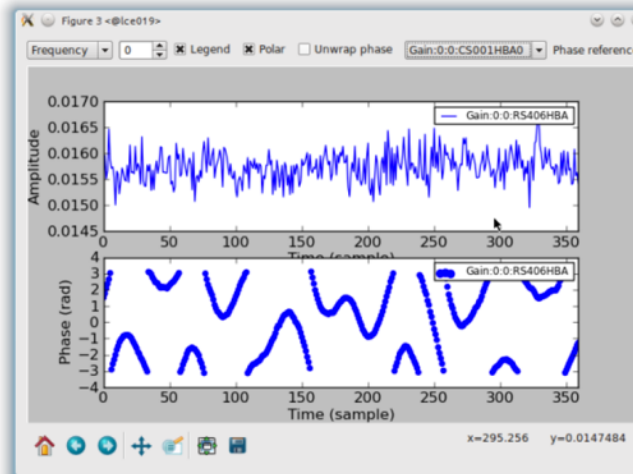
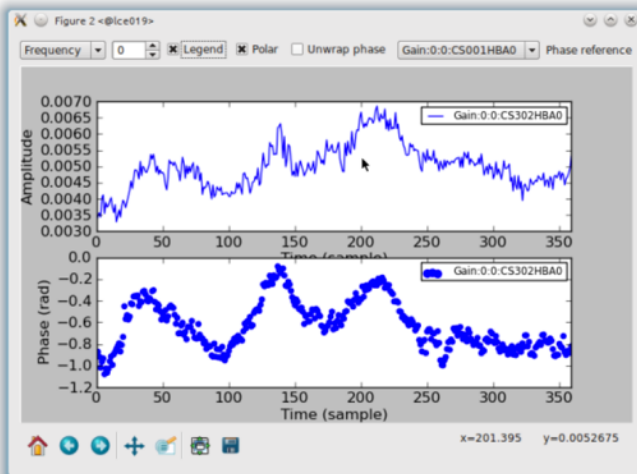
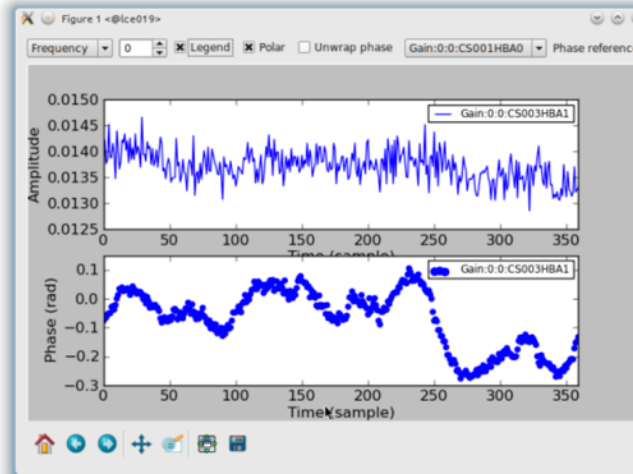
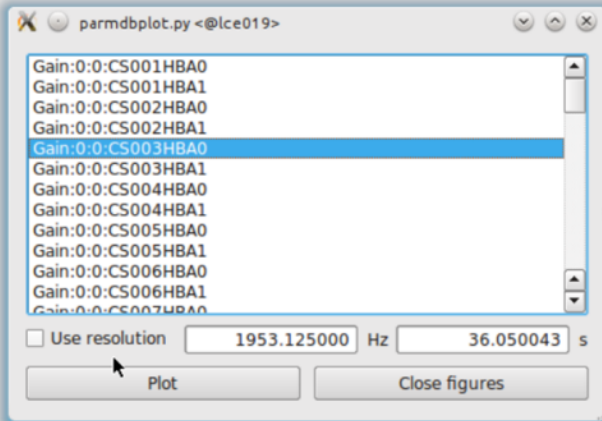
# Calibration



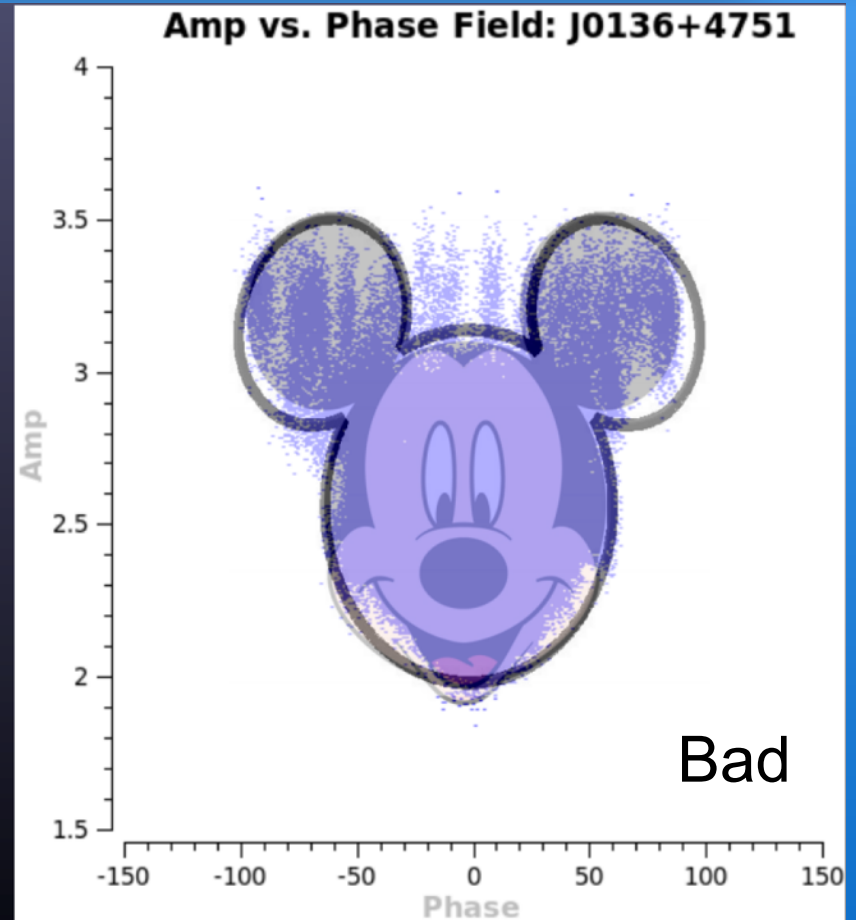
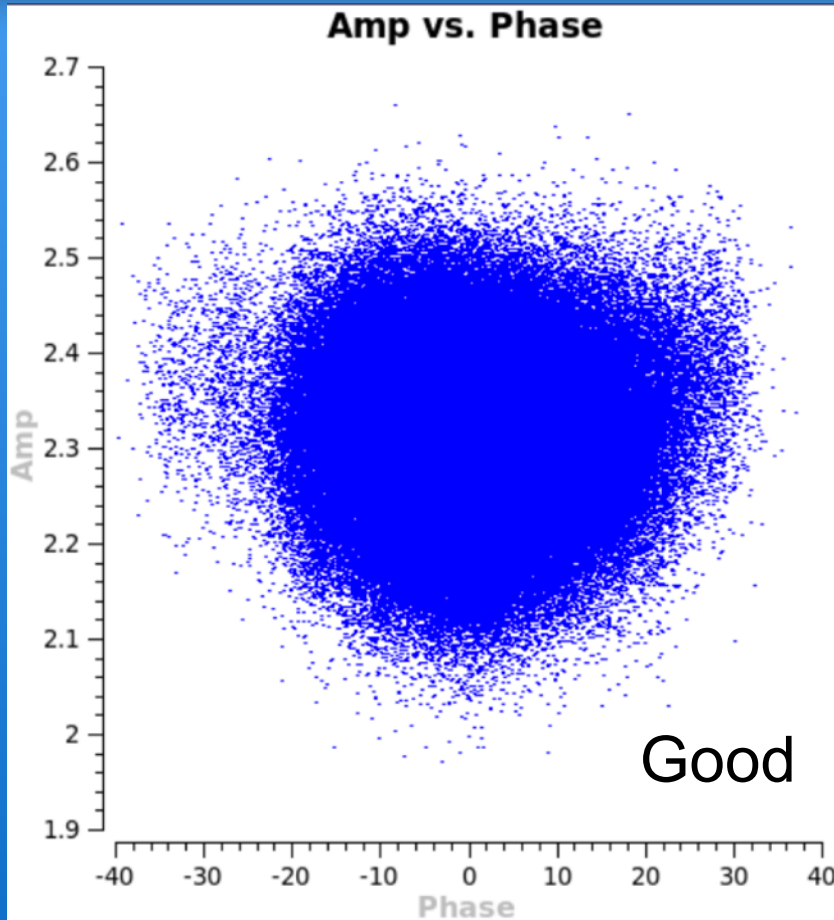
Model fits the data?

Model errors can be absorbed in the calibration process!

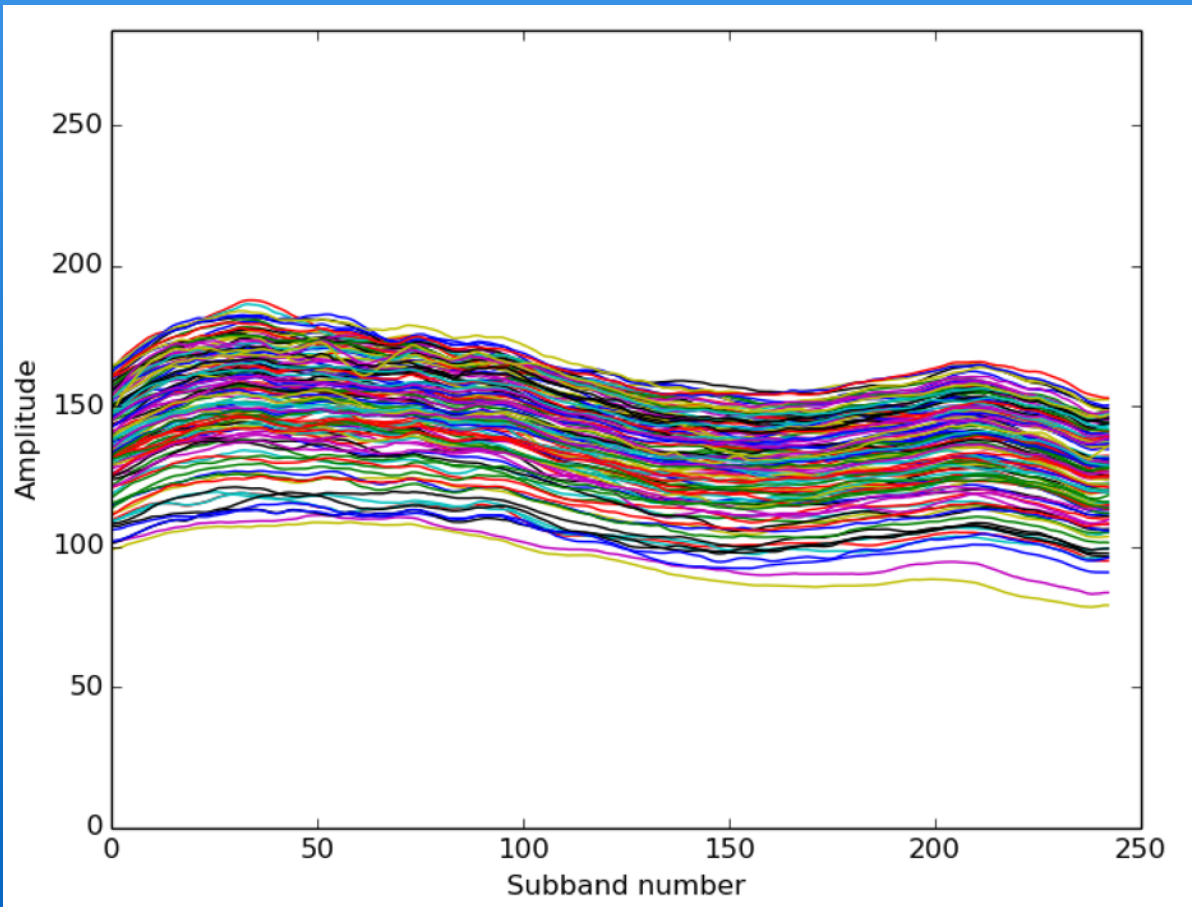
# Calibration



Inspect solution behaviour



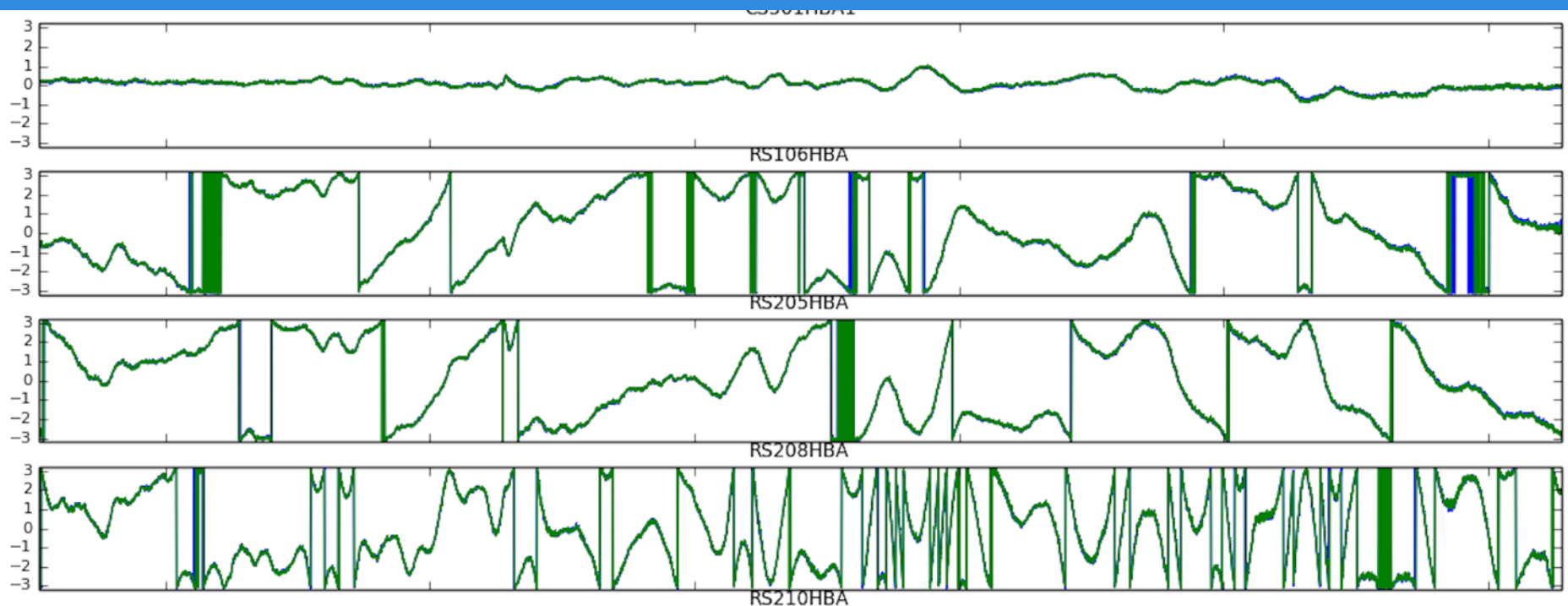
Asymmetry in amplitude-phase plots indicates bad data



Amplitude solutions - stable and at expected value

# Calibration

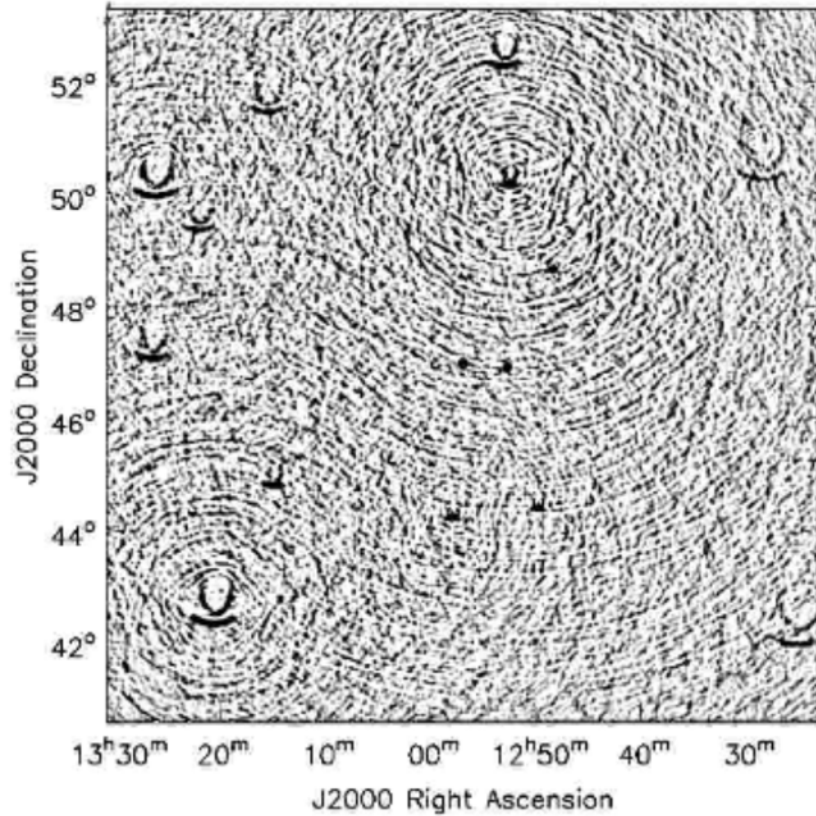
Phase solutions should track well  
Longest baselines can lose coherence at times due to the ionosphere



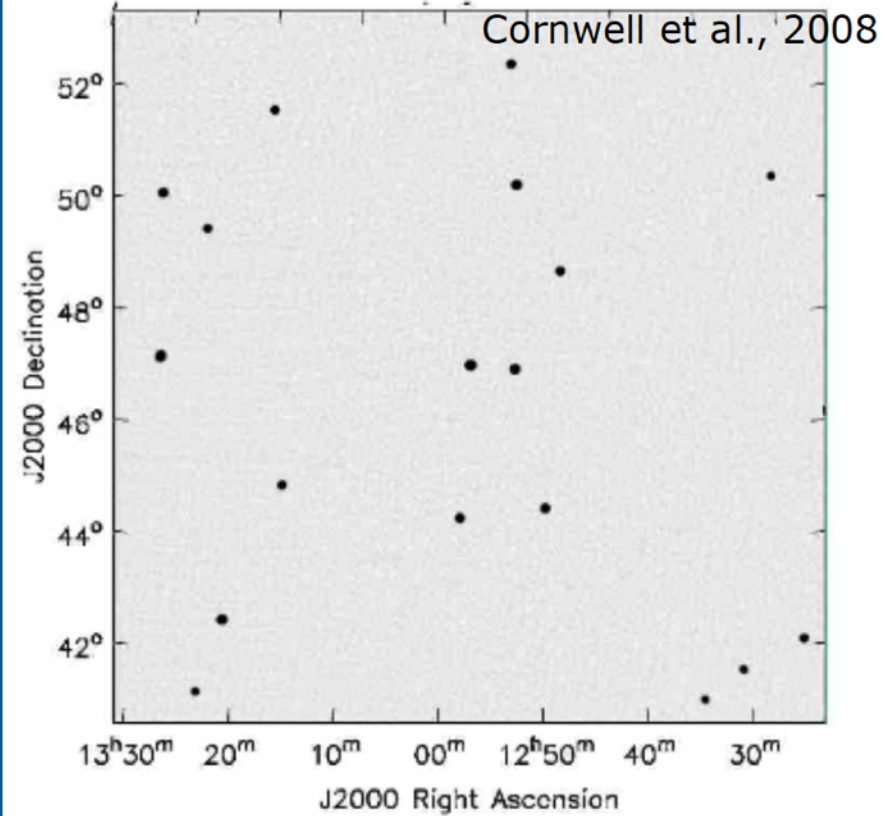
LOFAR - (very) large FoV ( $< 9\text{deg}$  across in LBA)

- 2D approximation no longer valid - W projection
- Beam constantly changes - A projection
- Wide bandwidth - BW and time averaging smearing an issue
- Ionosphere no longer iso-planatic - direction dependent effects
- Bright sources in the FoV a nuisance - peeling

# Imaging: W projection



(a) standard Fourier transform

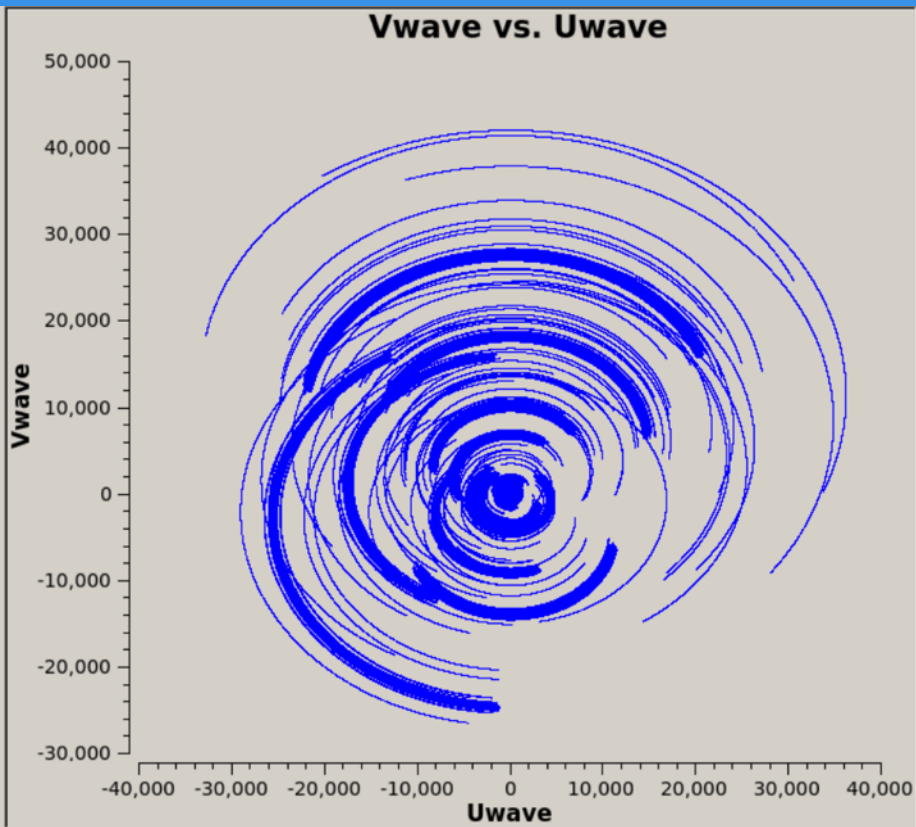


(c) W-projection (128  $\tilde{G}_T$  planes)

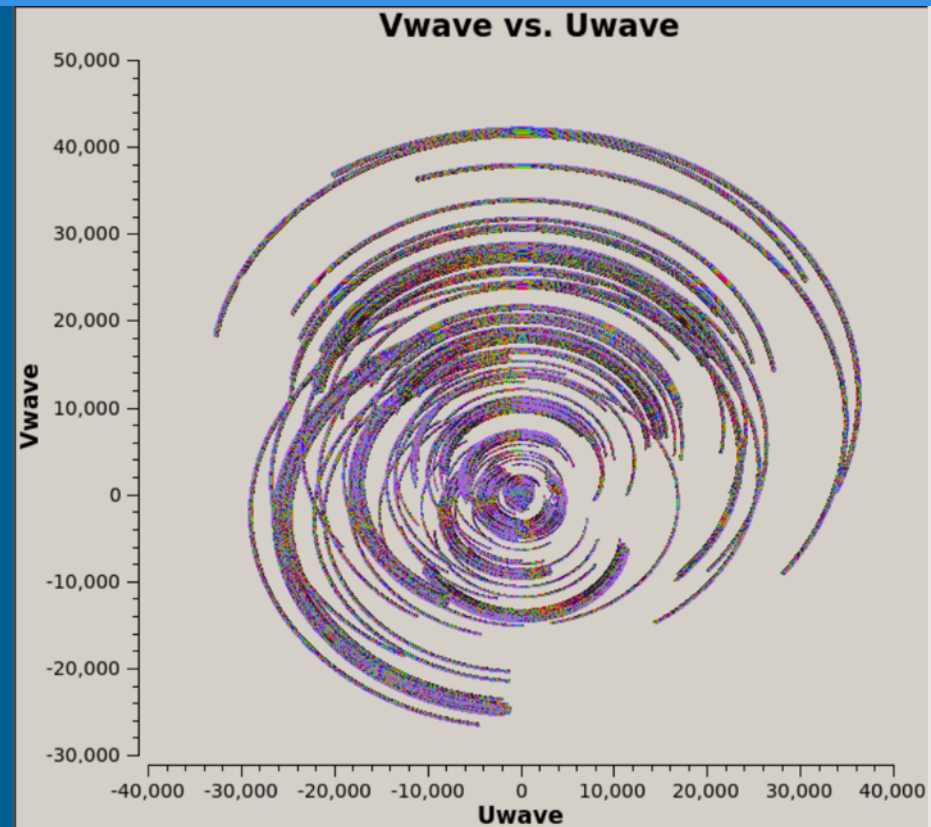


# Imaging: BW issues

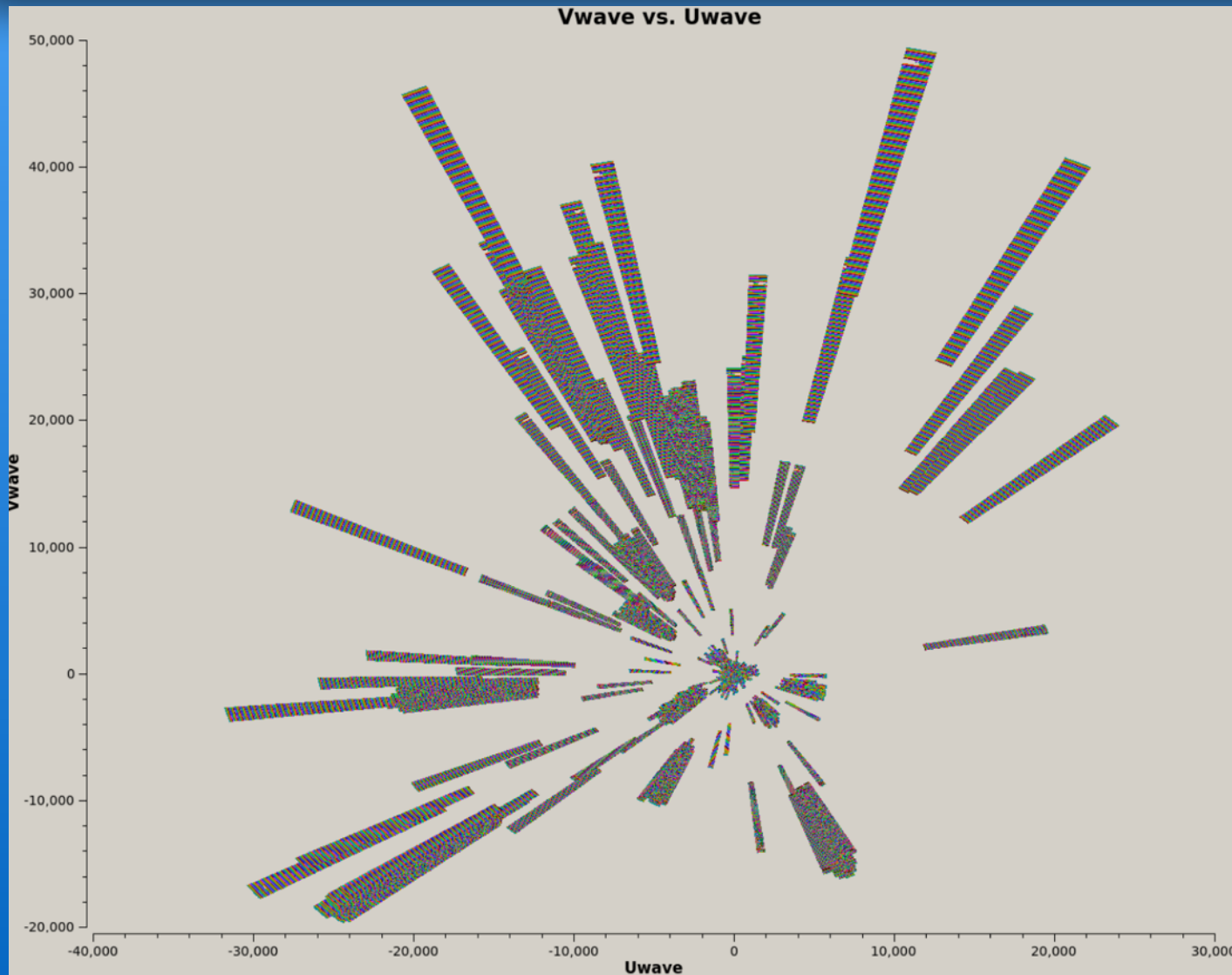
1 SB - 0.2 MHz



10 SBs - 2 MHz



# Imaging: BW issues



70 MHz  
10 minutes

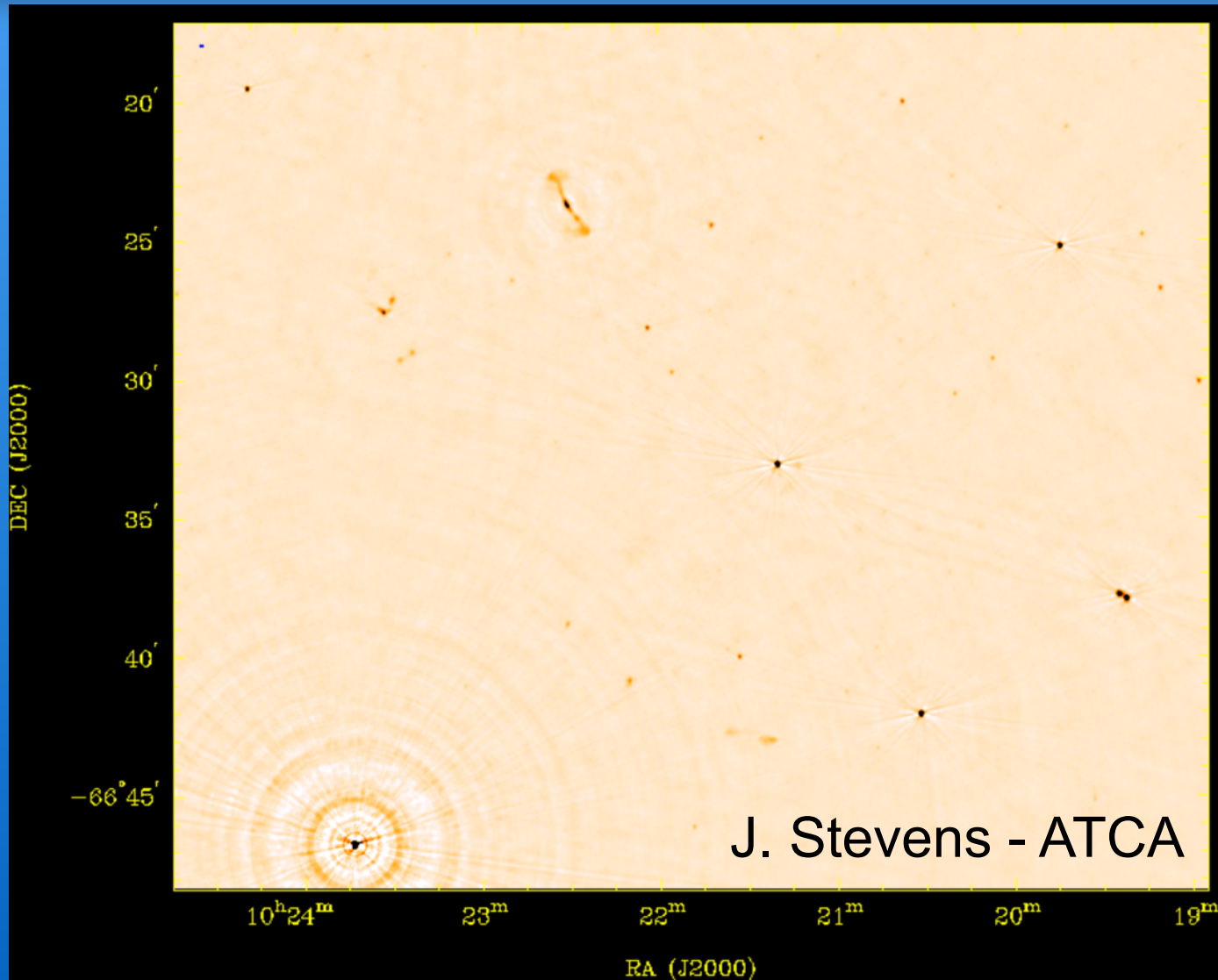
Visibilities gridded as if they were monochromatic (in case MFS imaging is not used)

If too much averaging in time/frequency is applied, smearing results

Effect is larger the further one goes from the phase centre - so especially important for LOFAR

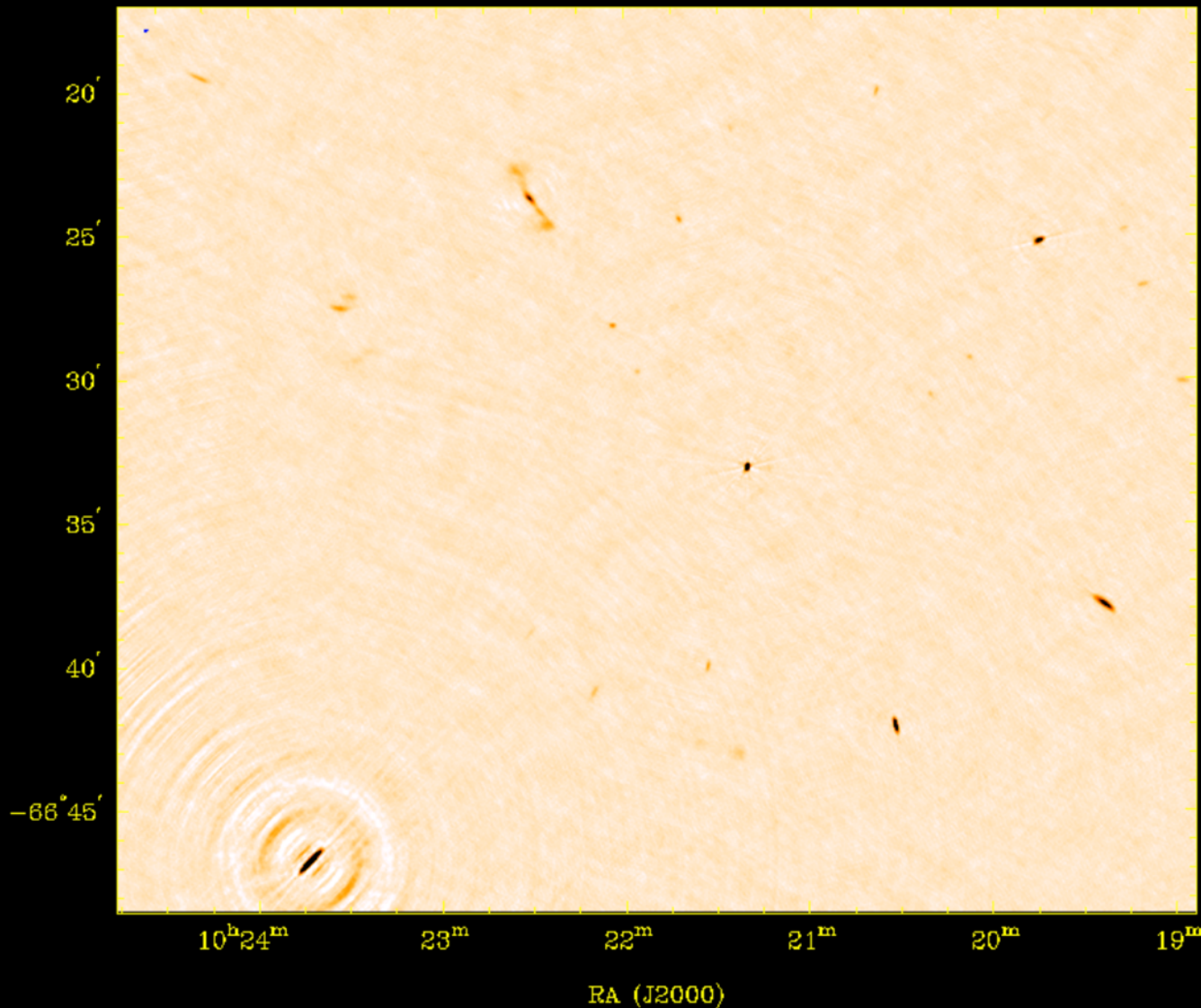
The need to mitigate these effects causes large LOFAR data sizes

# Imaging: BW issues



2048ch x 1MHz  
2GHz BW

# Imaging: BW issues



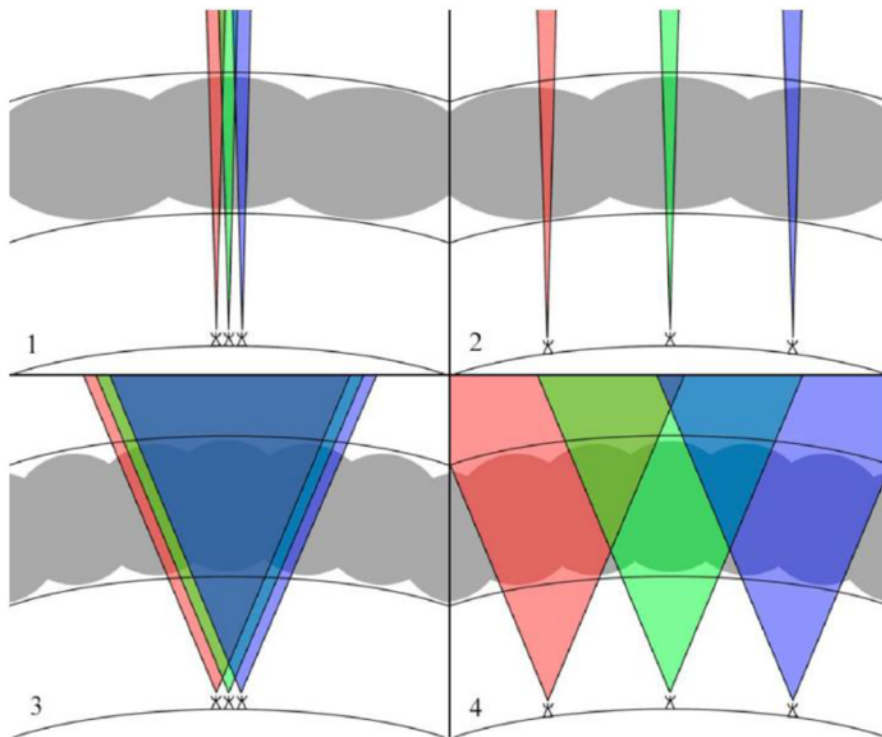
32ch x 64MHz  
2GHz BW

## Direction independent effects – DIE

$$G_i(t)$$

## Direction dependent effects - DDE

$$G_i(t, \alpha, \delta)$$



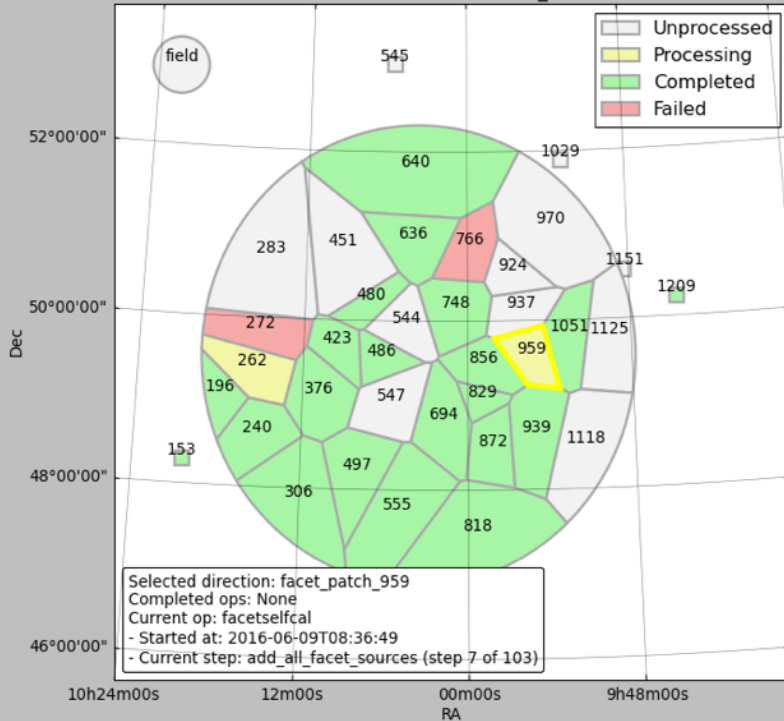
Intema et al. (2009)

1 and 2 - ionospheric phase error has no FoV dependence - self cal applicable

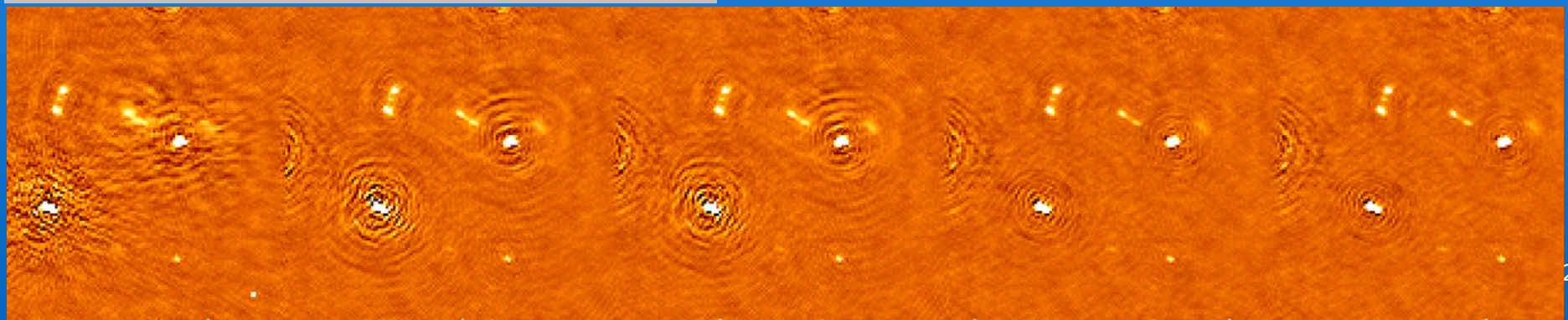
3 and 4 ionospheric phase error varies across the FoV  
DDE important

# Imaging: Ionosphere

Overview of FACTOR run in  
/data/scratch/shulevski/P150\_50/Factor



Facet calibration - FACTOR  
van Weeren+ 2016, Williams+ 2016



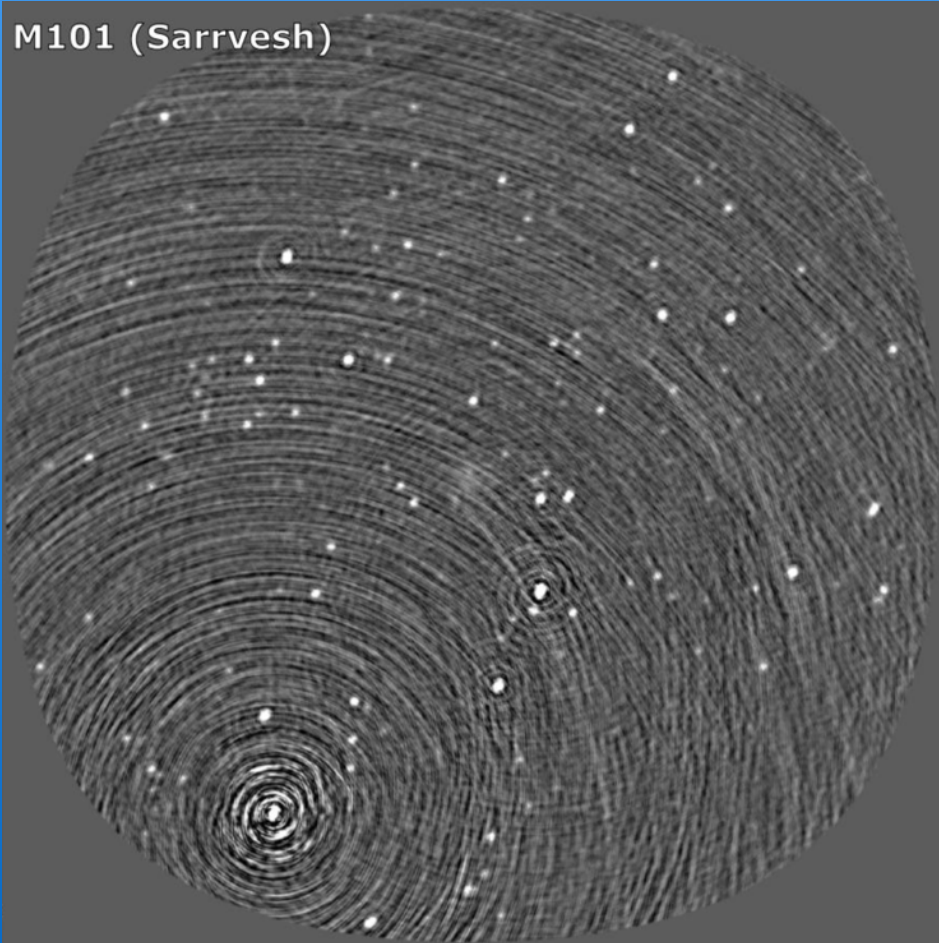
# Imaging: Peeling

Imaging beyond first  
null of beam  
lots of bright annoying  
sources



# Imaging: Peeling

M101 (Sarrvesh)



M101 (Sarrvesh)



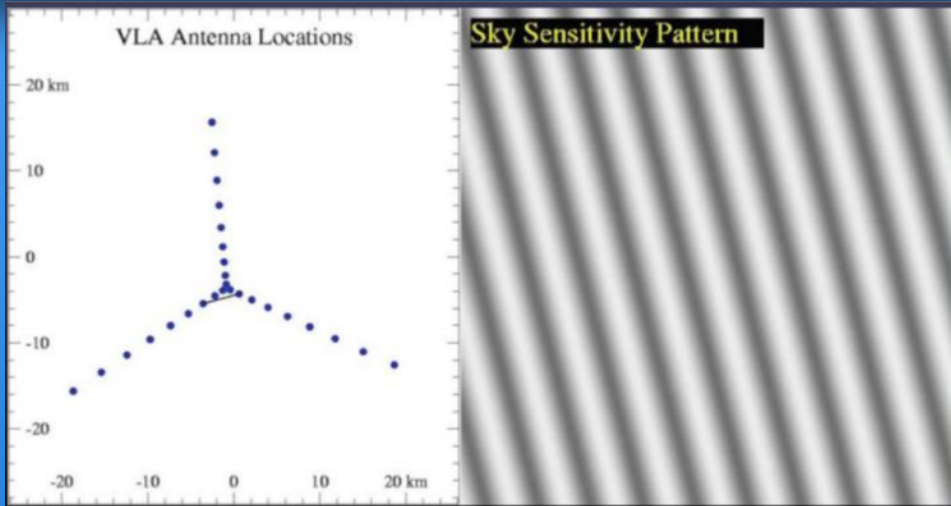
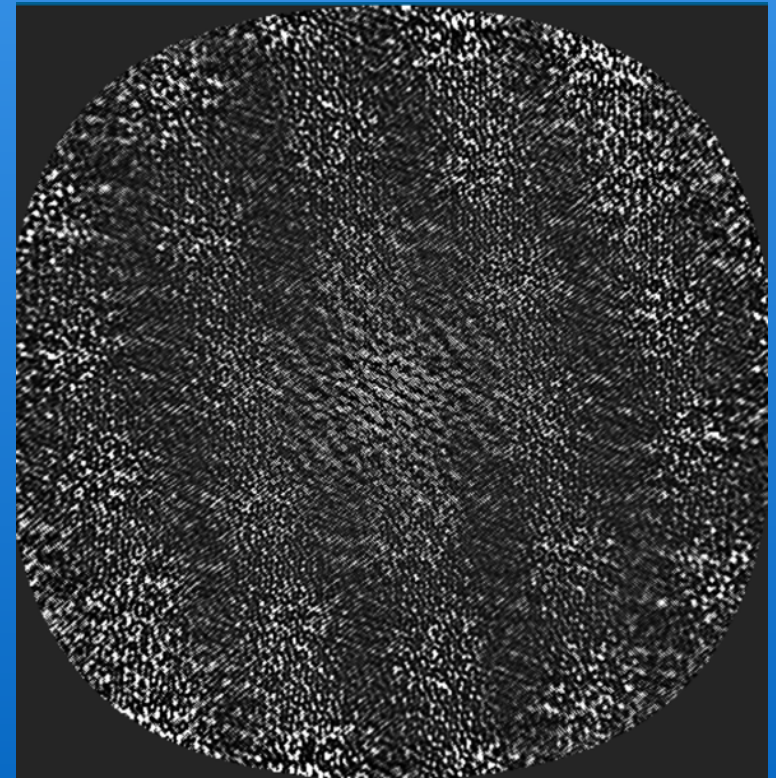
# Calibration / bad data effects in image plane

Can easily identify large errors in the  $u,v$  plane, but it's often difficult to find smaller errors

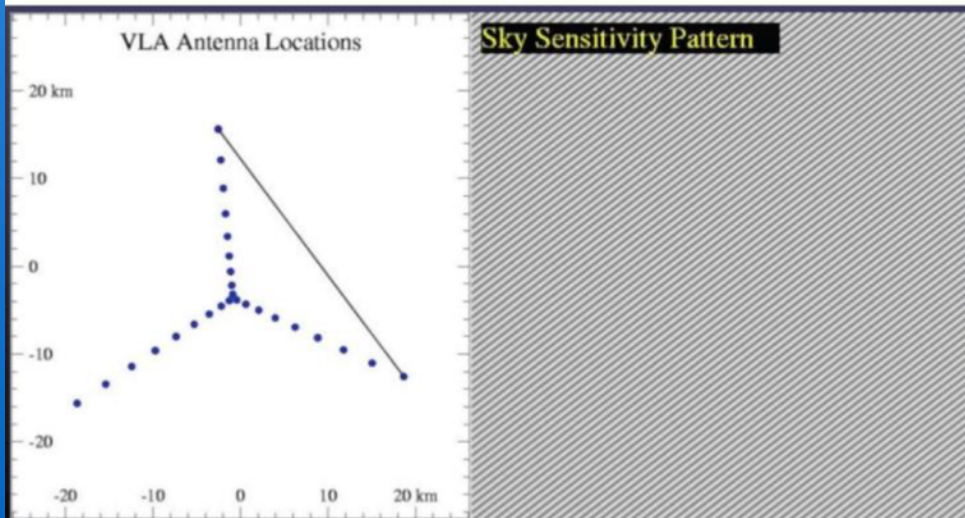
- Particularly true with LOFAR where many sources in the field of view make interpreting  $uv$ dist plots difficult!
- Remember: errors also obey the Fourier transform relation
- Large errors in the  $u,v$  plane can be virtually insignificant in the image plane
- Likewise, small undetectable defects in the  $u,v$  plane can be very obvious in the image plane

# Calibration / bad data effects in image plane

- Can use our knowledge of Fourier transform pairs to our advantage
- Look for patterns/symmetries



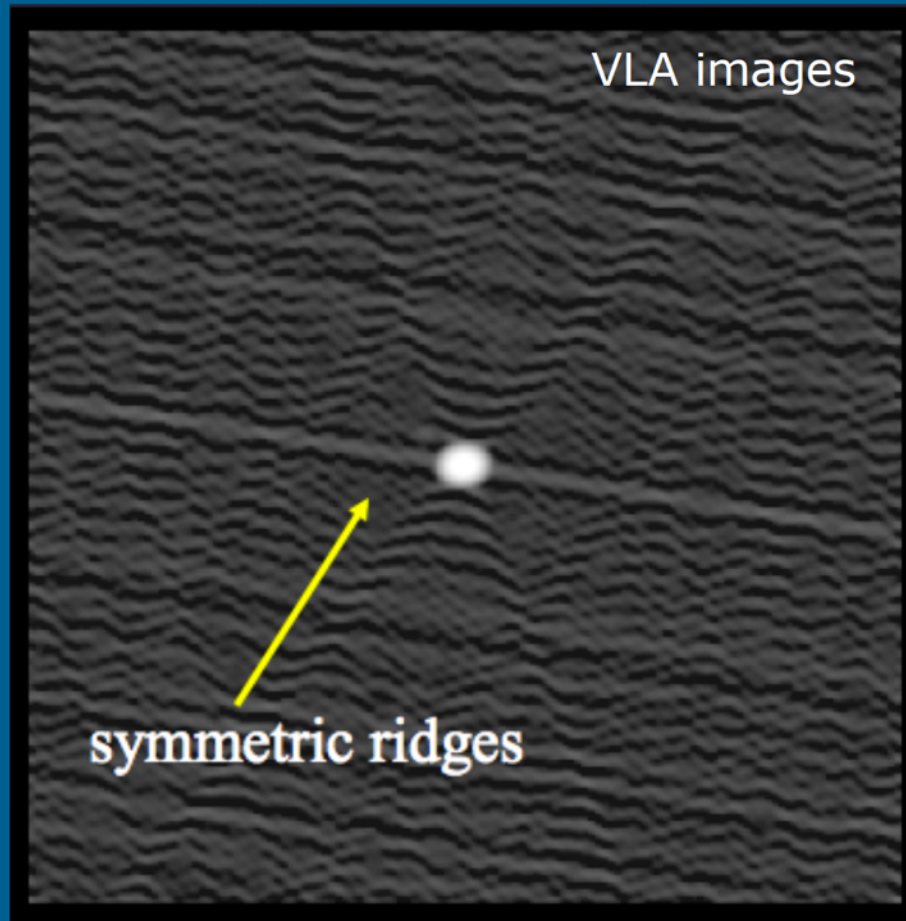
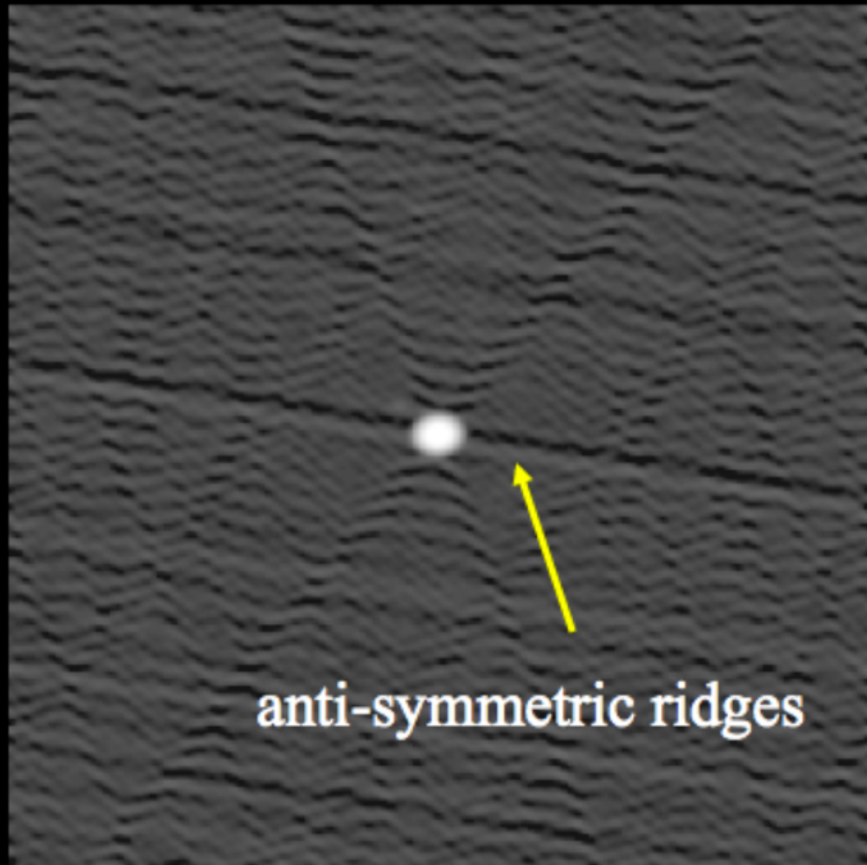
Fringes projected on to the sky for a short VLA baseline



# Calibration / bad data effects in image plane

10 deg phase error for  
one antenna at one time

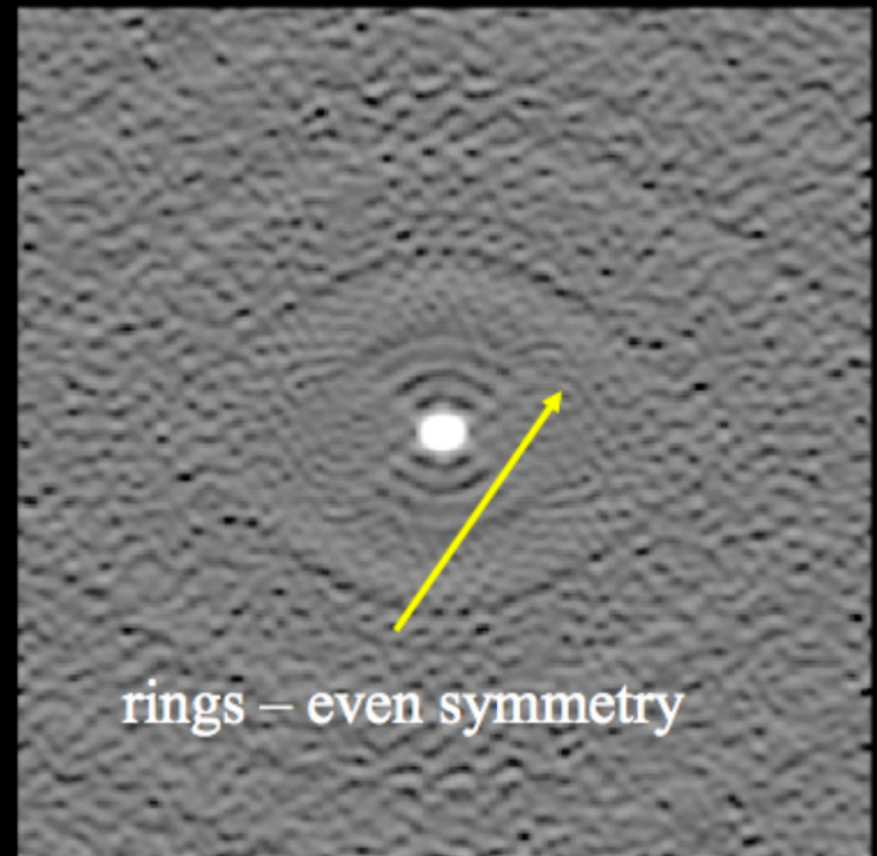
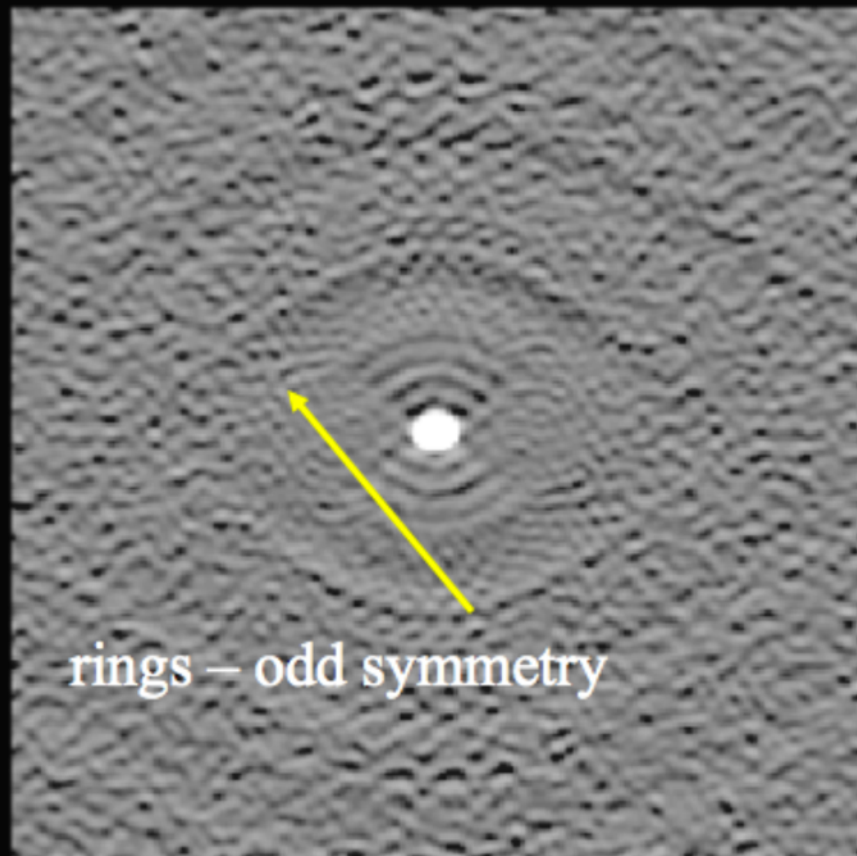
20% amplitude error for  
one antenna at one time



# Calibration / bad data effects in image plane

10 deg phase error for  
one antenna at all times

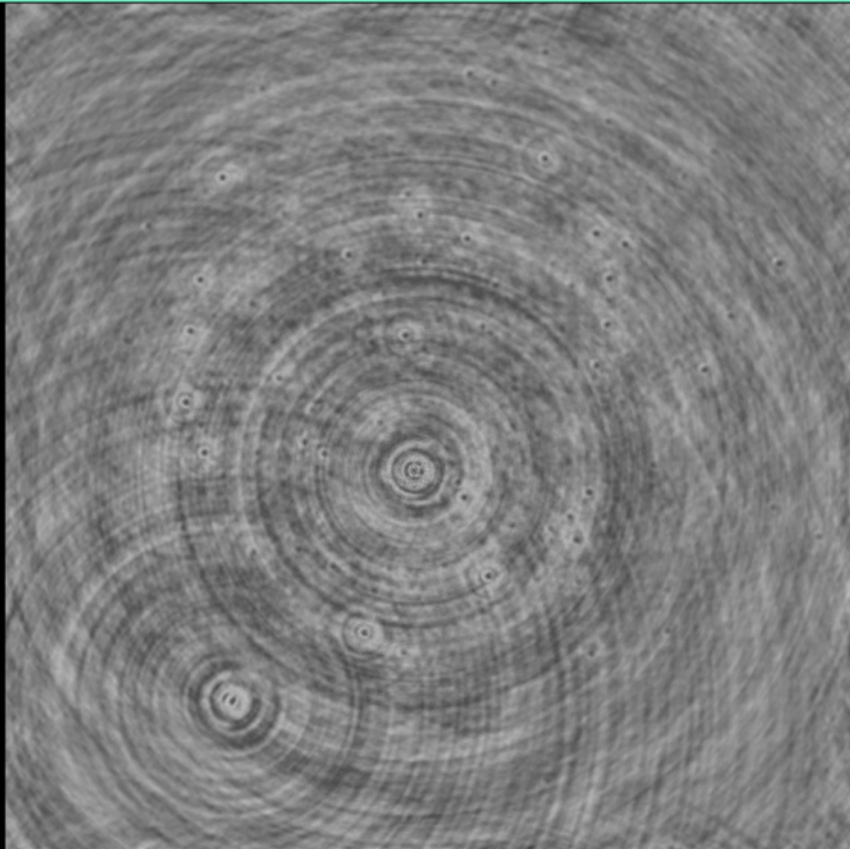
20% amplitude error for  
one antenna at all times



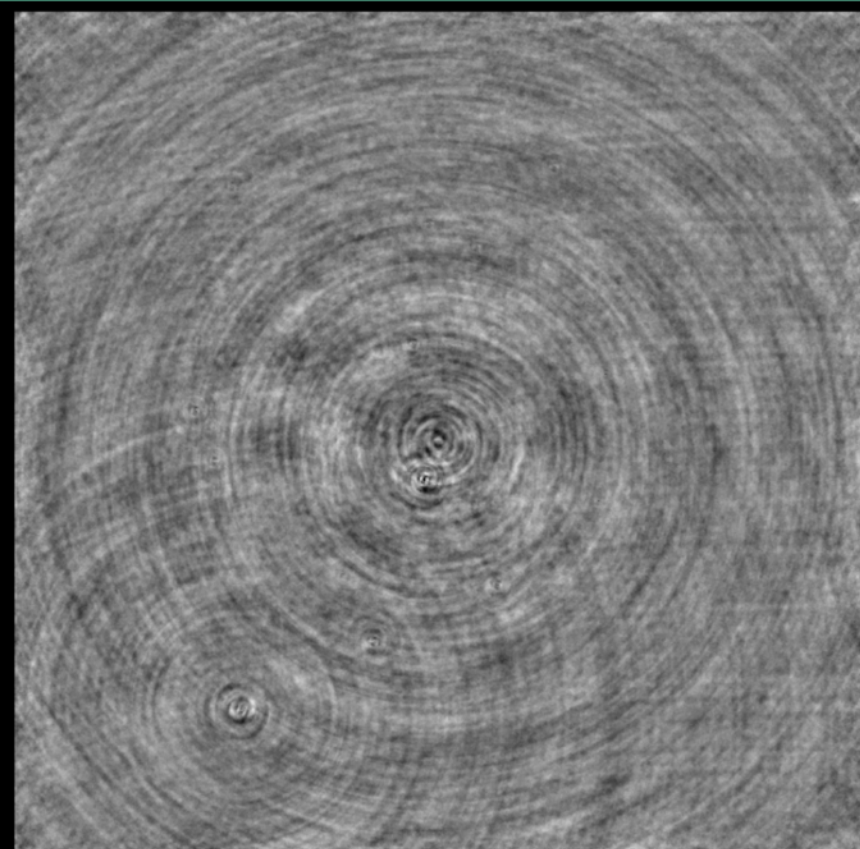
# Calibration / bad data effects in image plane

- Another example of RFI (NCP observations):

No RFI



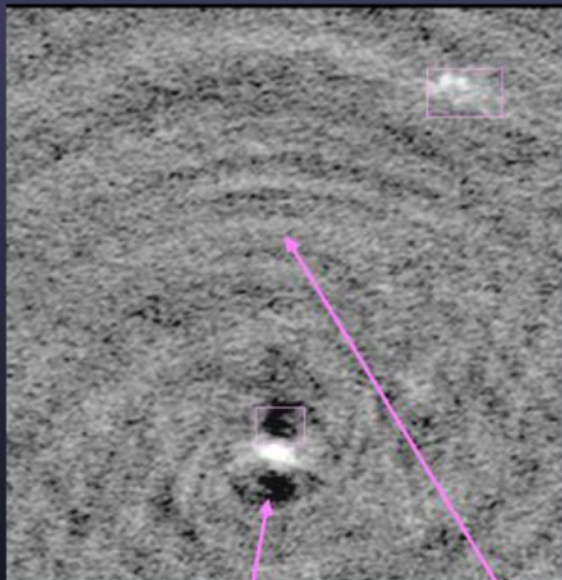
RFI centred at the pole



Images: A. Offringa (images have not been CLEANed)

# Imaging: how deep to clean?

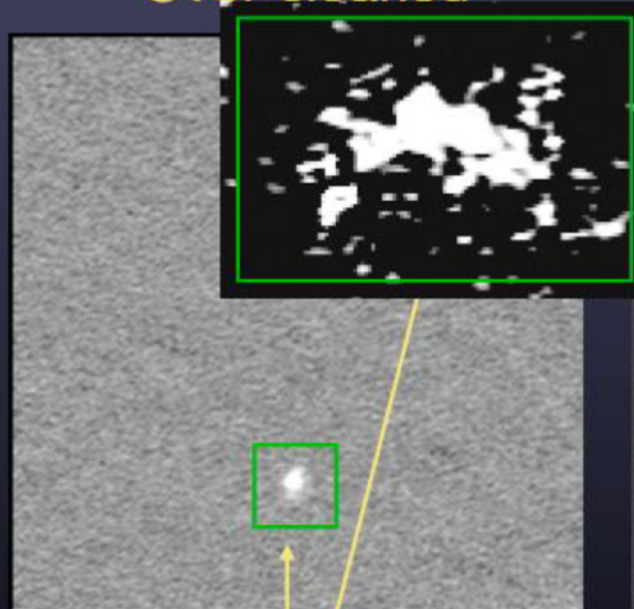
Under-cleaned



Residual sidelobes  
dominate the noise

Emission from  
second source sits  
atop a negative "bowl"

Over-cleaned



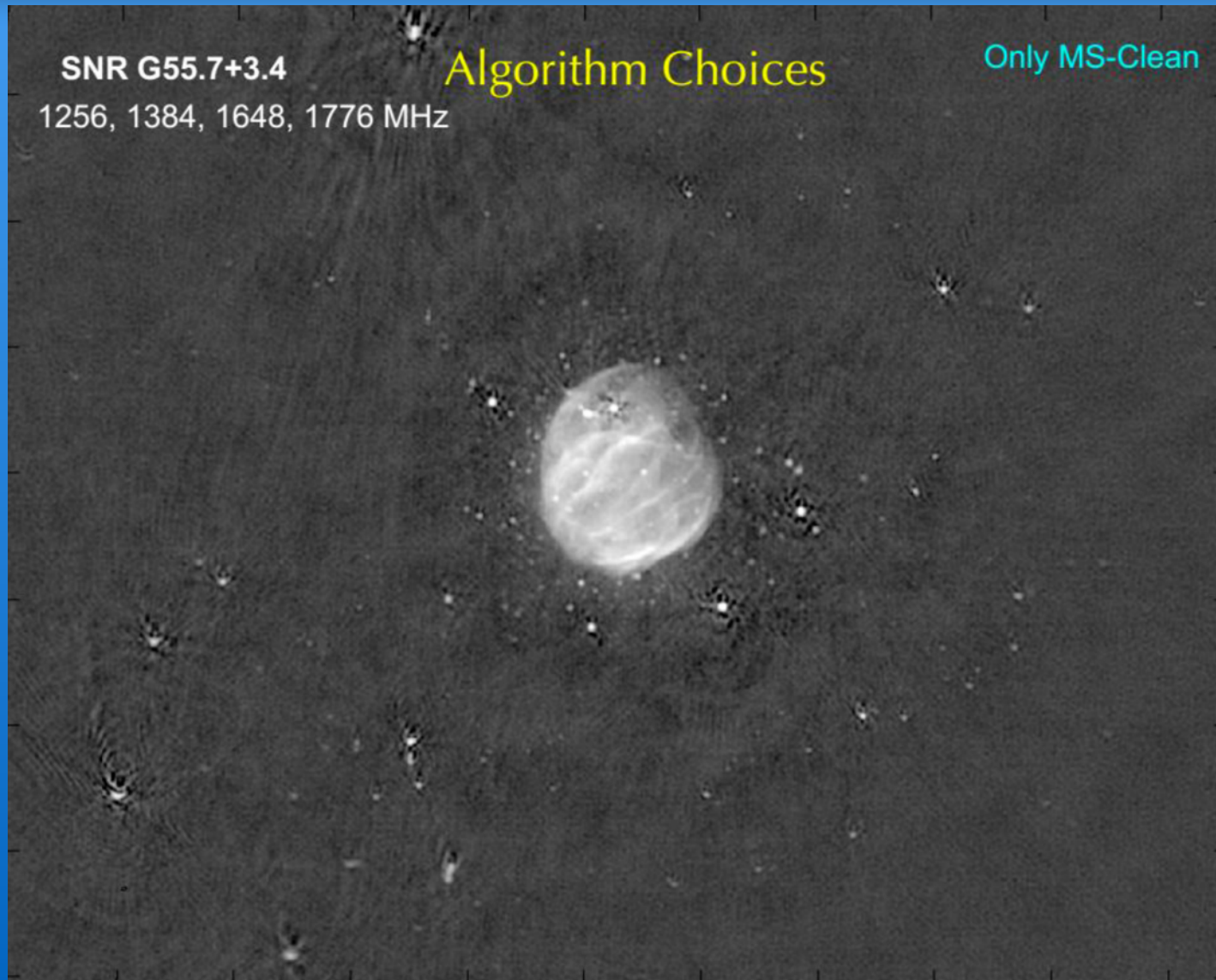
Regions within  
clean boxes  
appear "mottled"

Properly cleaned

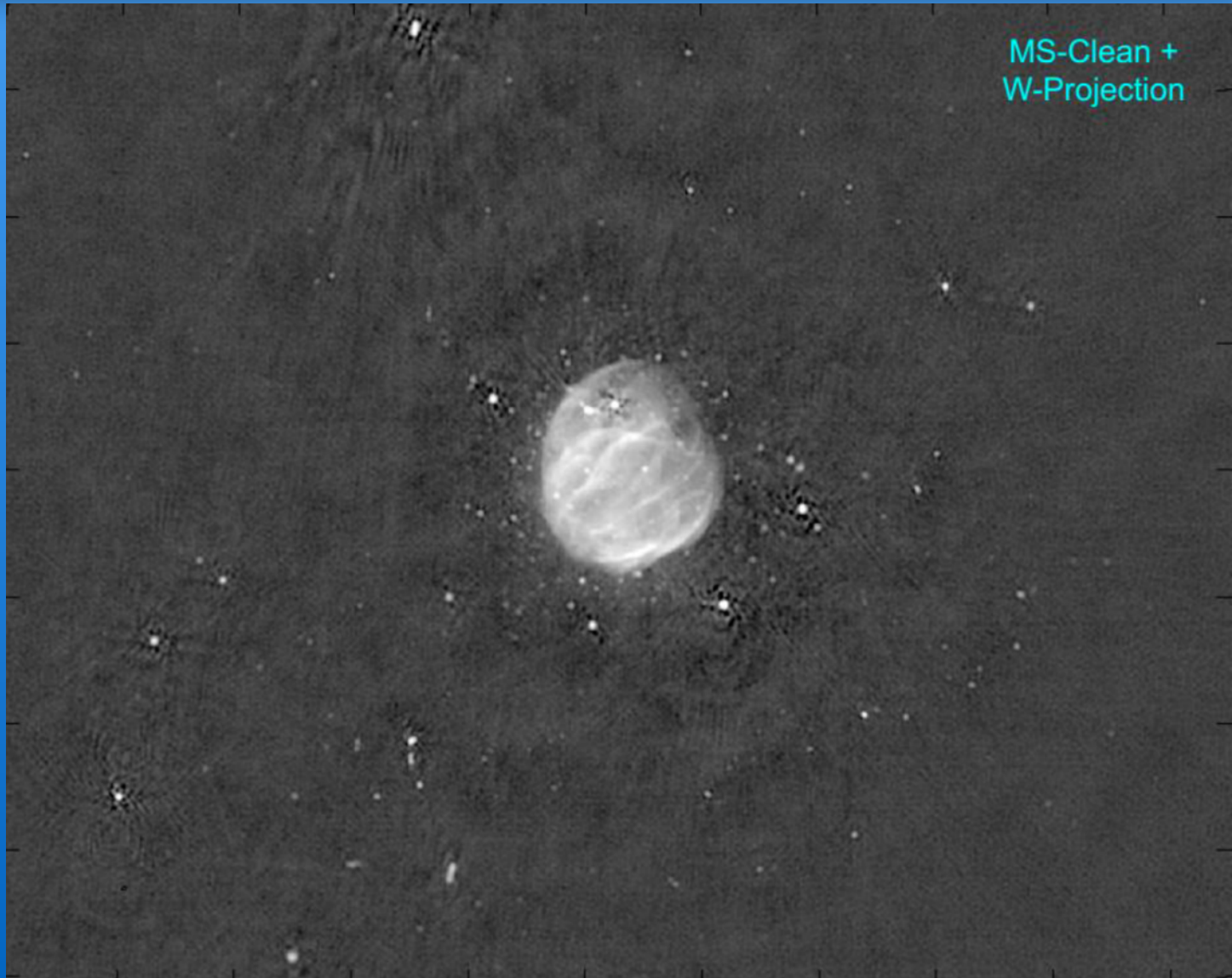


Background is thermal  
noise-dominated;  
no "bowls" around  
sources.

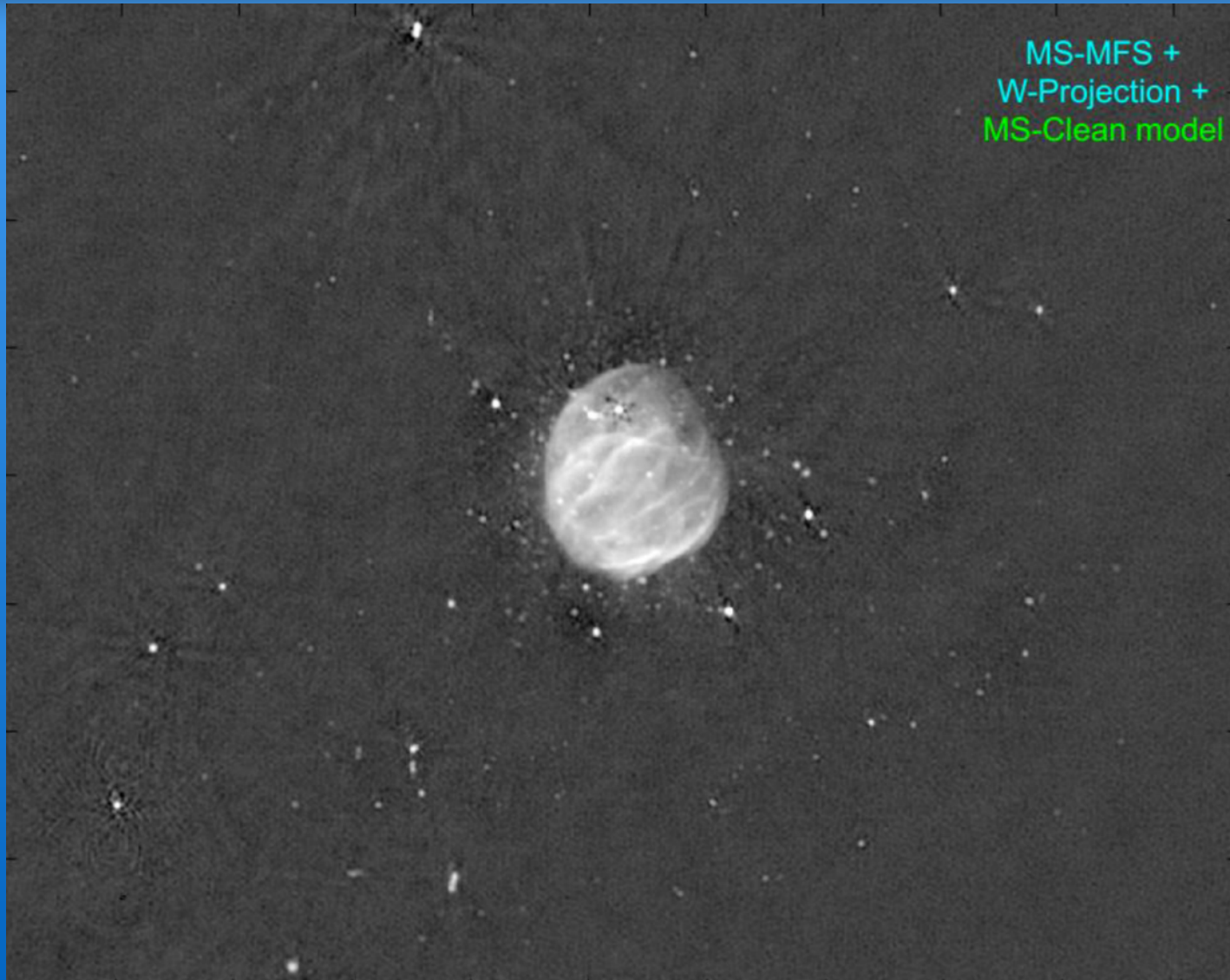
# Imaging: algorithms



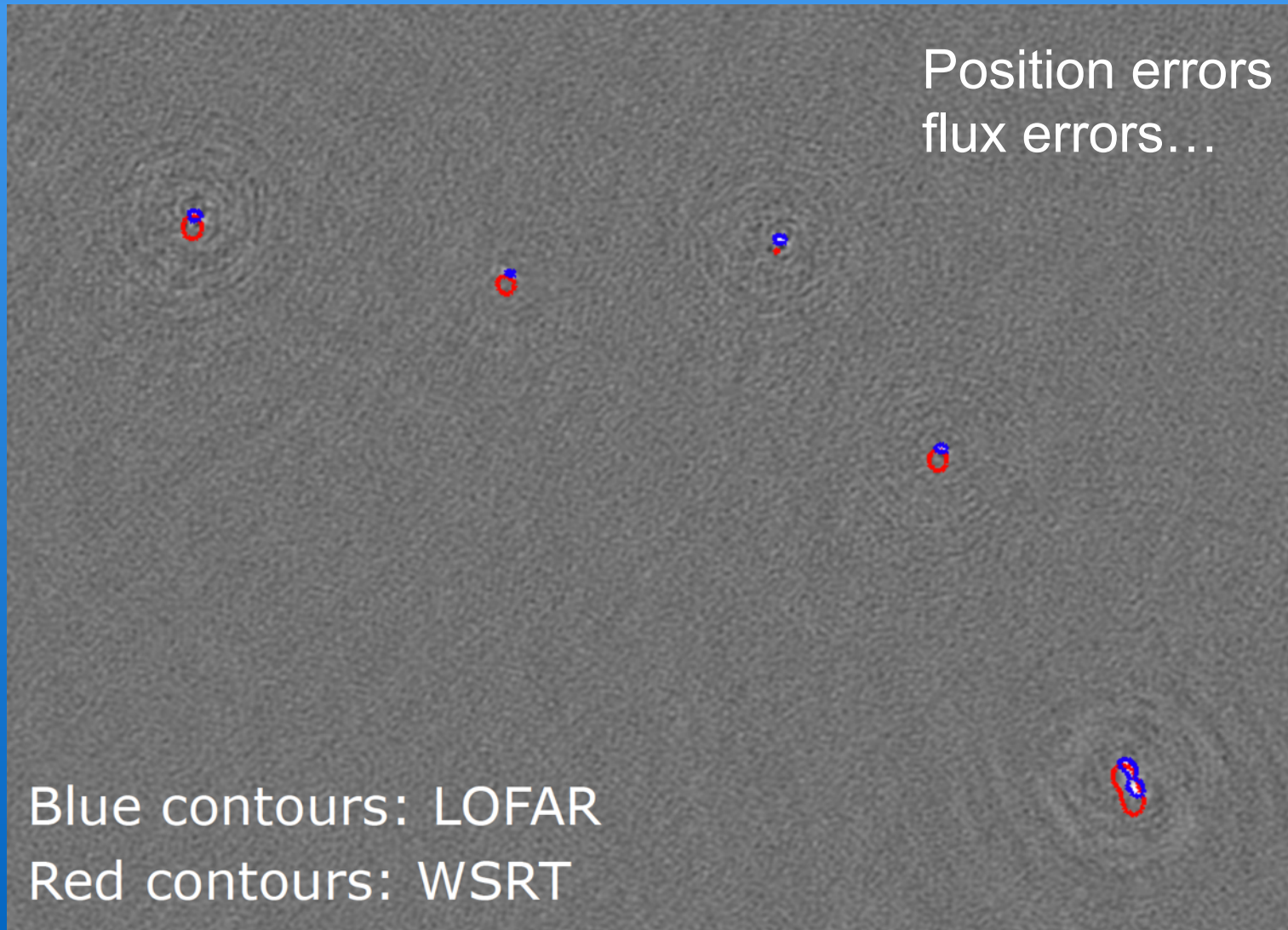




# Imaging: algorithms



# Is the imaging science-worthy?



- Errors obey Fourier transform relation – use this to your advantage!
- Image artifacts can either come from bad  $u,v$  data which needs to be flagged, OR due to the deconvolution algorithm used -> choose wisely
- If still in doubt, try FT back into visibility space to compare -> make sure you have the best skymodel possible

Beware of wide-field imaging effects:

- Need to use W-projection and A-projection
- Be careful not to average too heavily, can lead to bandwidth or time-smearing
- Direction dependent effects
- Are there any bright sources in the field you need to peel?

Can you do science with your image?

- Check the flux scale and source positions!

First flag obviously bad data in the  $u,v$  plane

- Make large, low resolution image first
- Identify potential issues (i.e. bright sources in the field)
- First check of flux scale (7C/VLSS/TGSS good catalogues to crossmatch with, in the future MSSS)
- Check that you have the best input skymodel possible

Start with a subset of data to reduce manually and work out the best strategy

VLA white book – Chapters 15, 18, 19

Lectures from previous synthesis imaging schools

- LOFAR data school 2014
- ERIS 2013 (<http://www.astron.nl/eris2013/lectures.php>)
- NRAO synthesis imaging workshop 2014 (<https://science.nrao.edu/science/meetings/2014/14th-synthesis-imagingworkshop/lectures>)
- CSIRO radio astronomy school (<http://www.atnf.csiro.au/research/radio-school/2014/index.html>)

Papers on w-projection and a-projection (Cornwell+ 2008; Bhatnagar+ 2008,2013; Offringa+ 2014)

Papers on direction-dependent calibration (Intema+ 2009,2014; van Weeren+ 2016; Williams+ 2016)

Thank you! Questions?

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