

## Introduction to Low-Frequency Radio Astronomy

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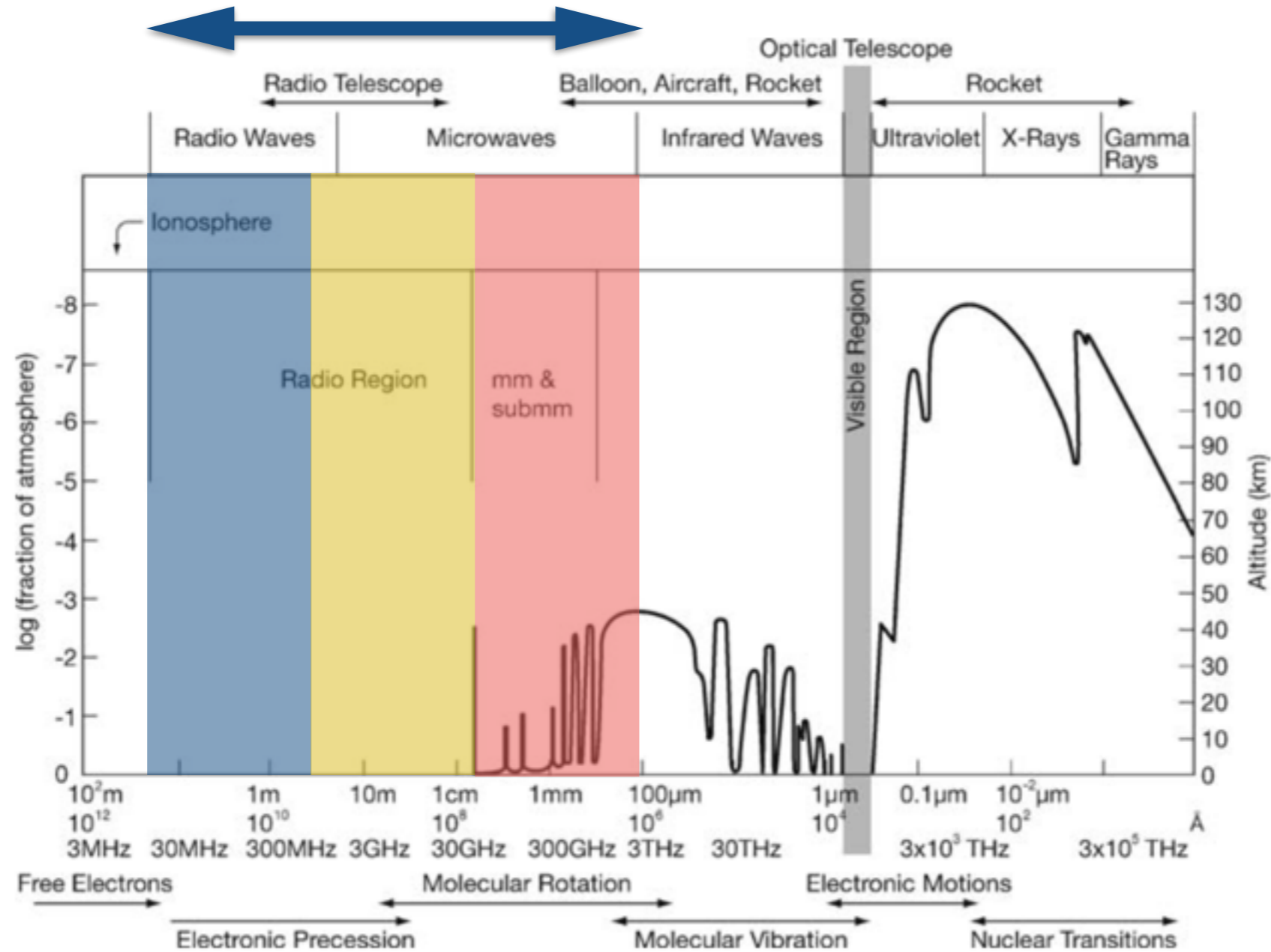
# Preamble

- **AIM:** This lecture aims to give a general introduction to low frequency radio astronomy, focusing on the issues that you must consider and the differences with observations with other telescopes.
- **OUTLINE:**
  1. The radio sky and historical developments
  2. The response of a dipole antenna
  3. The response of an interferometer
  4. Low frequency radio telescopes



# 1.1 The Radio Window

- Radio Astronomy is the study of radiation from celestial sources at frequencies between  $\nu \sim 10$  MHz to 1 THz ( $10^7$  Hz to  $10^{12}$  Hz).



- The observing window is constrained by atmospheric absorption / emission and refraction.
  - 1) Charged particles in the ionosphere reflects radio waves back into space at < 10 MHz.
  - 2) Vibrational transitions of molecules have similar energy to infra-red photons and absorb the radiation at > 1 GHz (completely by ~300 GHz).

## 1.2 The low-frequency cut-off

- The ionosphere consists of a plasma of charged particles (conducting layers), that has an effective refractive index of,

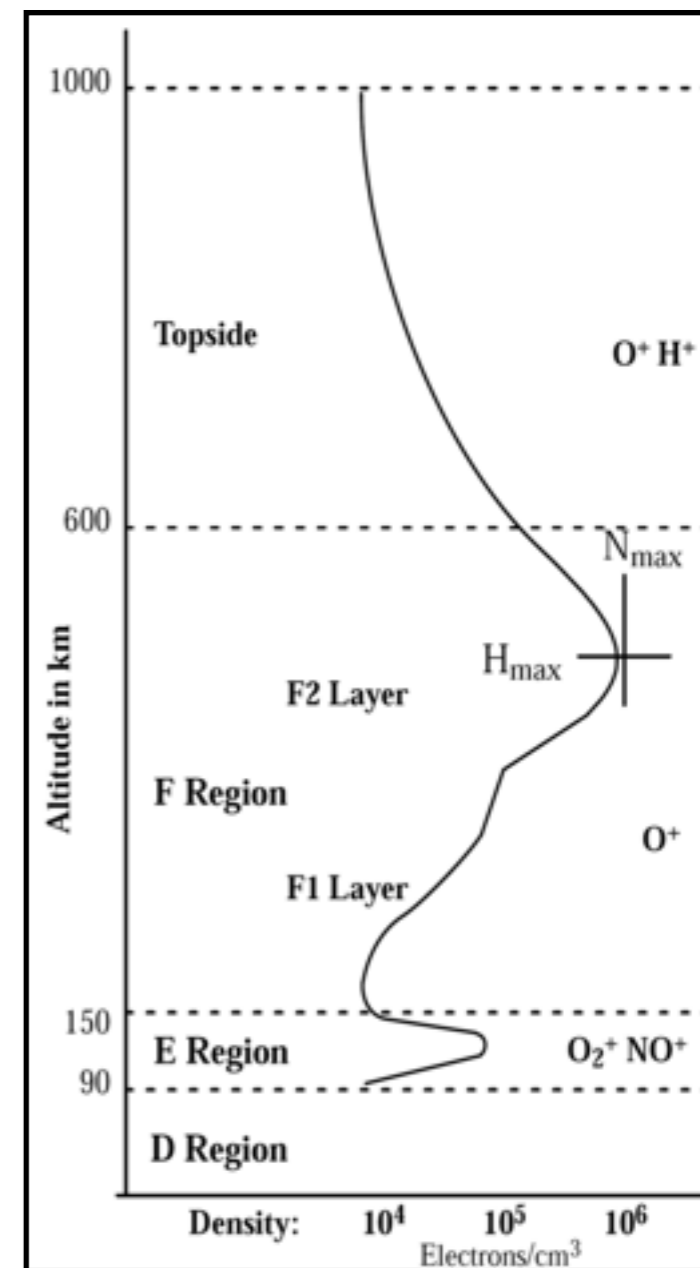
$$n^2 = 1 - \frac{\omega_p^2}{\omega^2} = 1 - \left( \frac{\lambda}{\lambda_p} \right)^2$$

where, the plasma frequency is defined as,

$$\nu_p [\text{Hz}] = \frac{\omega_p}{2\pi} = \left( \frac{N_e e^2}{4\pi^2 \epsilon_0 m} \right)^{1/2} = 8.97 \times 10^3 \sqrt{\frac{N_e}{[\text{cm}^{-3}]}}$$

[see Calibration & Ionospheric lectures]

when  $\omega < \omega_p$ , there is no propagation, i.e. total reflection.



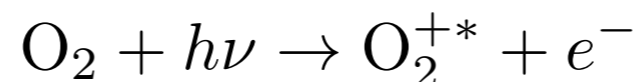


**Worked example:** What is the cut-off frequency for LOFAR observations carried out when the electron density is  $N_e = 2.5 \times 10^5 \text{ cm}^{-3}$  (night time) and  $N_e = 1.5 \times 10^6 \text{ cm}^{-3}$  (day time)?

$$\nu_p [\text{Hz}] = 8.97 \times 10^3 \sqrt{\frac{2.5 \times 10^5}{[\text{cm}^{-3}]}} = 4.5 \text{ MHz} \quad (\text{night time})$$

$$\nu_p [\text{Hz}] = 8.97 \times 10^3 \sqrt{\frac{1.5 \times 10^6}{[\text{cm}^{-3}]}} = 11 \text{ MHz} \quad (\text{day time})$$

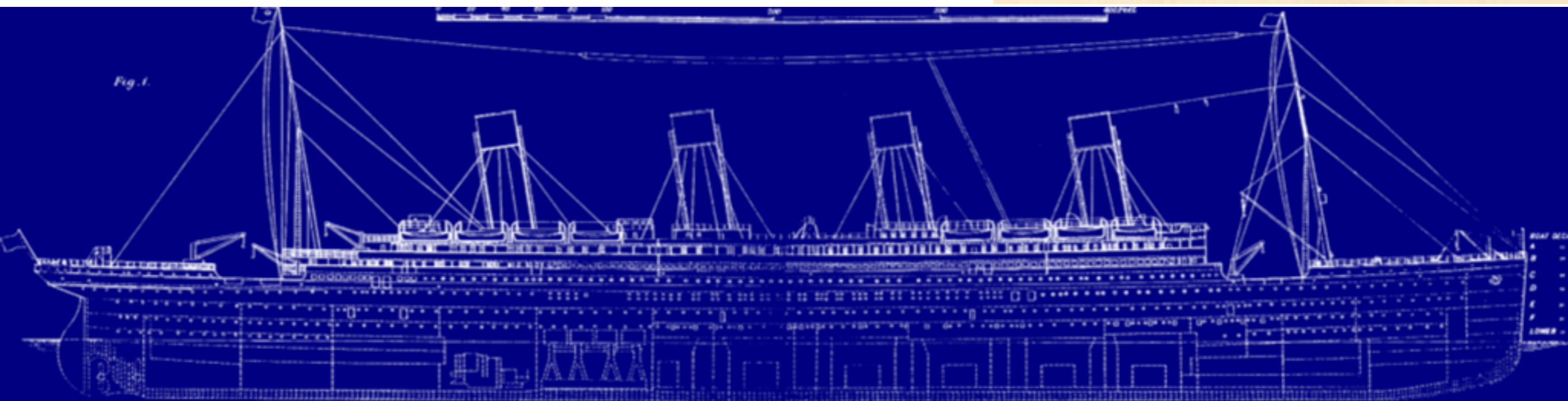
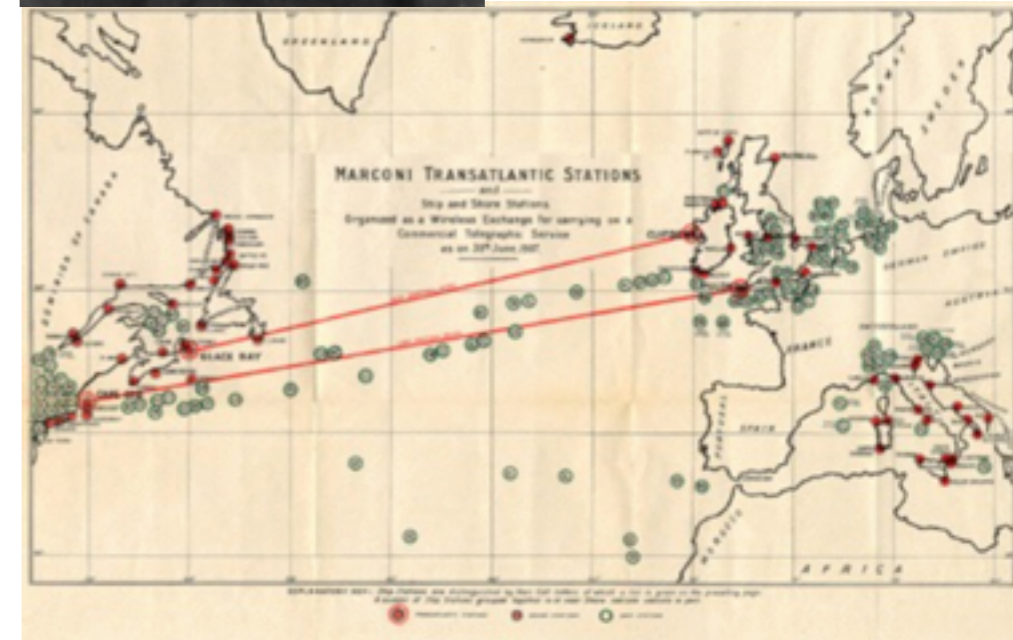
- At frequencies,
  1.  $\omega < \omega_p$ :  $n^2$  is **negative**, reflection ( $\nu < 10 \text{ MHz}$ ),
  2.  $\omega > \omega_p$ :  $n^2$  is **positive**, refraction ( $10 \text{ MHz} < \nu < 10 \text{ GHz}$ ),
  3.  $\omega \gg \omega_p$ :  $n^2$  is **unity** ( $\nu > 10 \text{ GHz}$ ).
- The observing conditions are dependent on the electron density, i.e. the solar conditions (space weather), since the ionisation is due to the ultra-violet radiation field from the Sun,



- Long distance communication developed by Marconi & Ferdinand Braun - Nobel Prize 1909

## Evolution of frequency over the years

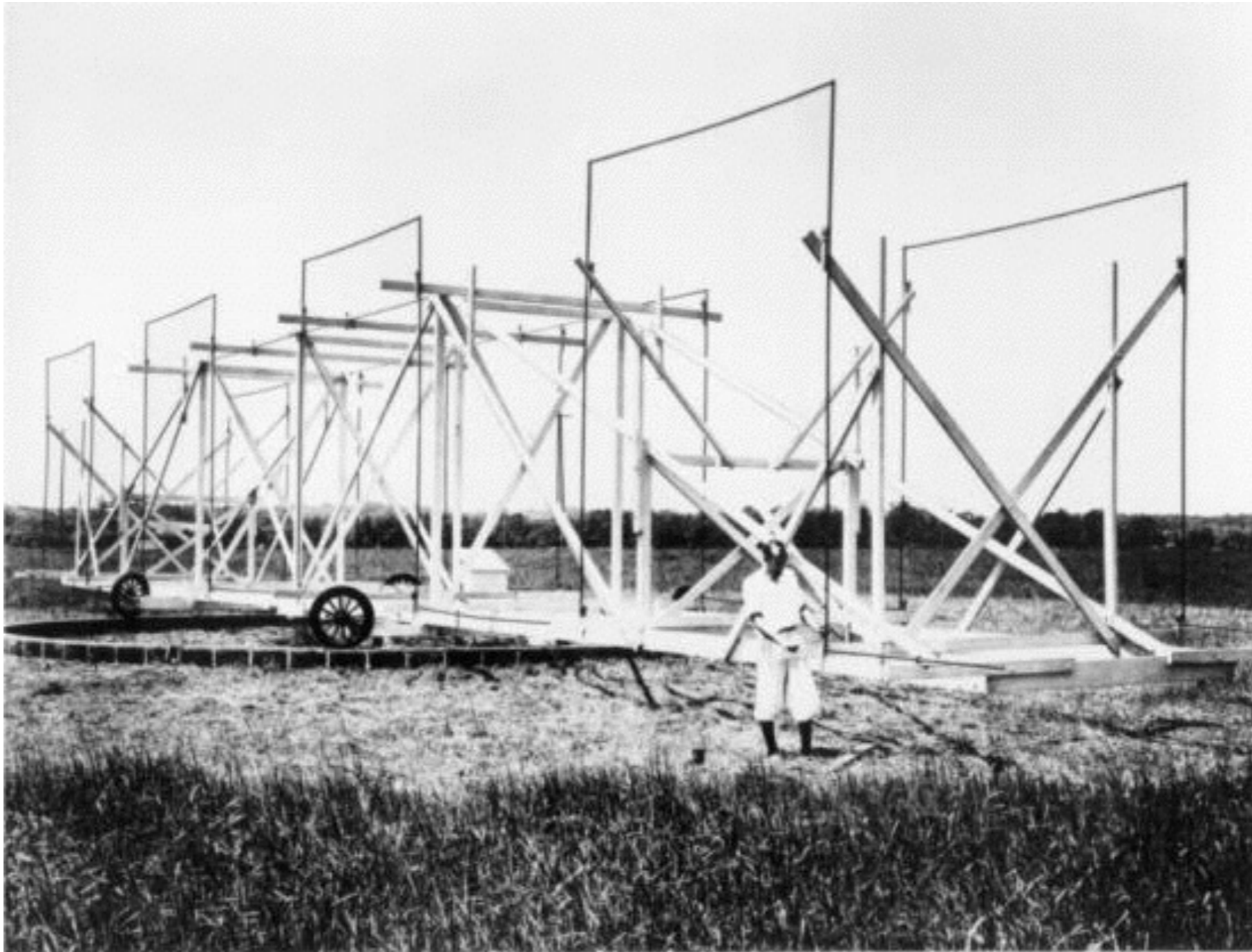
- pre-1920: <100 kHz.
- ca. 1920: shift to 1.5 MHz.
- post-1920: 10s of MHz (more voice channels, less effected by the ionosphere and thunderstorms).
- Research labs sprung up in early-1900s





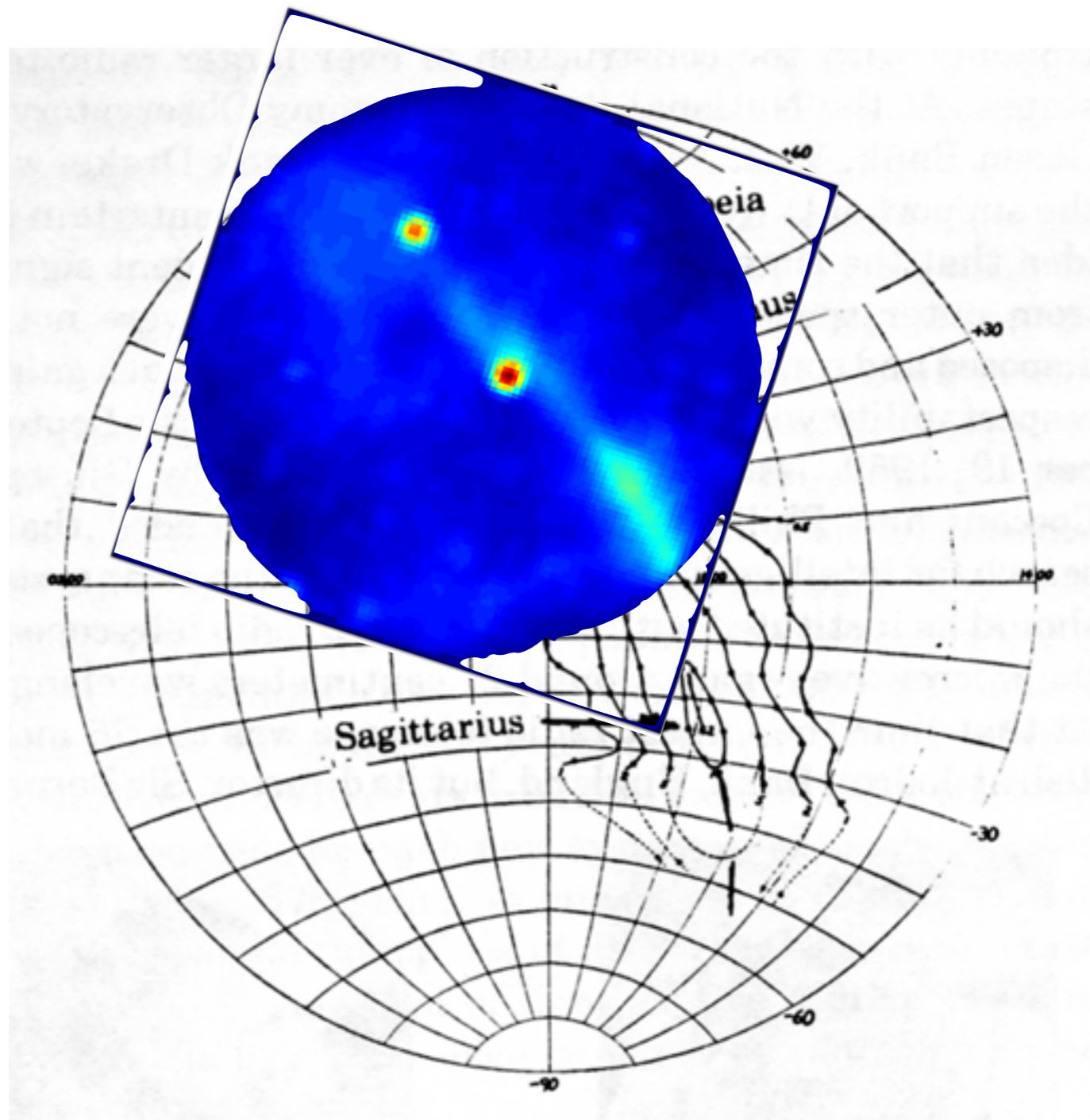
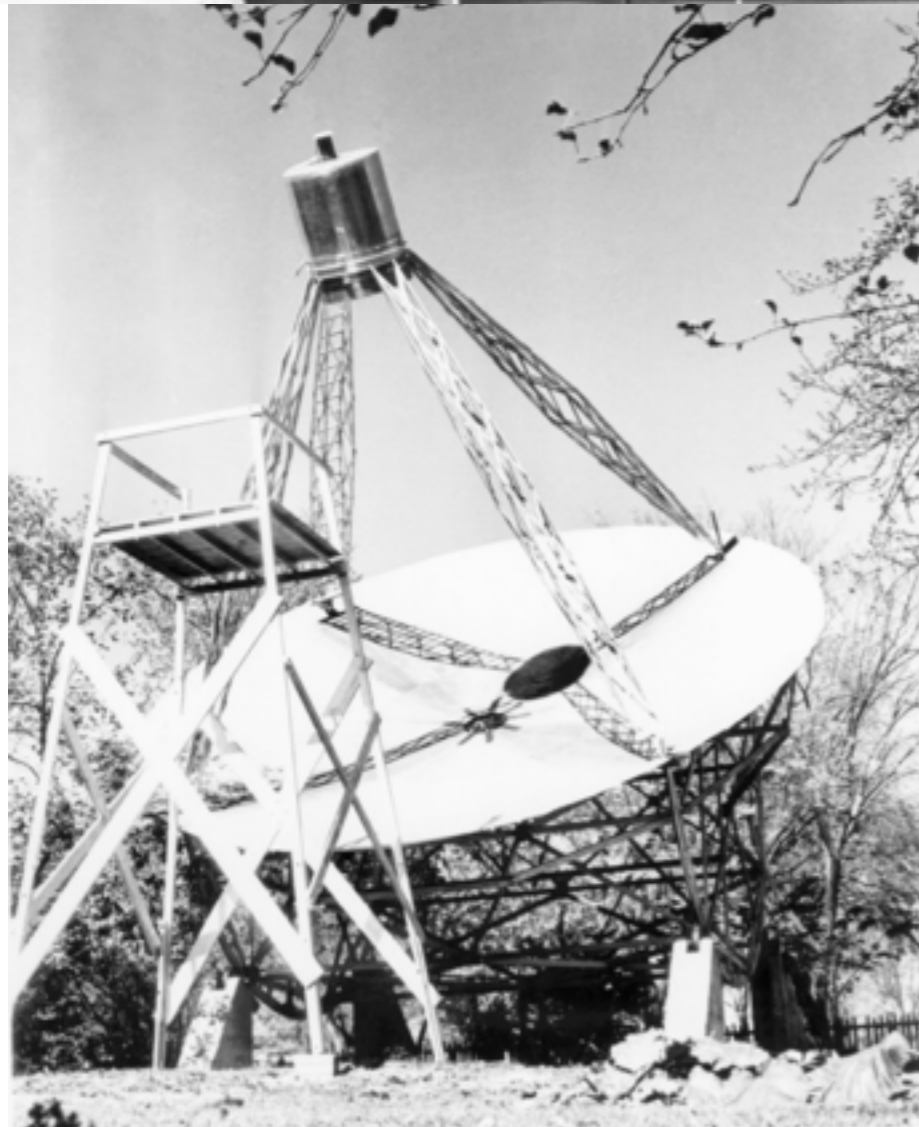
- Karl Jansky (1933, published) discovered a radio signal at 20.5 MHz that varied steady every 23 hours and 56 minutes (Sidereal day).

“The data give for the co-ordinates of the region from which the disturbance comes, a right ascension of 18 hours and declination -10 degrees.” He had detected the Galactic Centre.





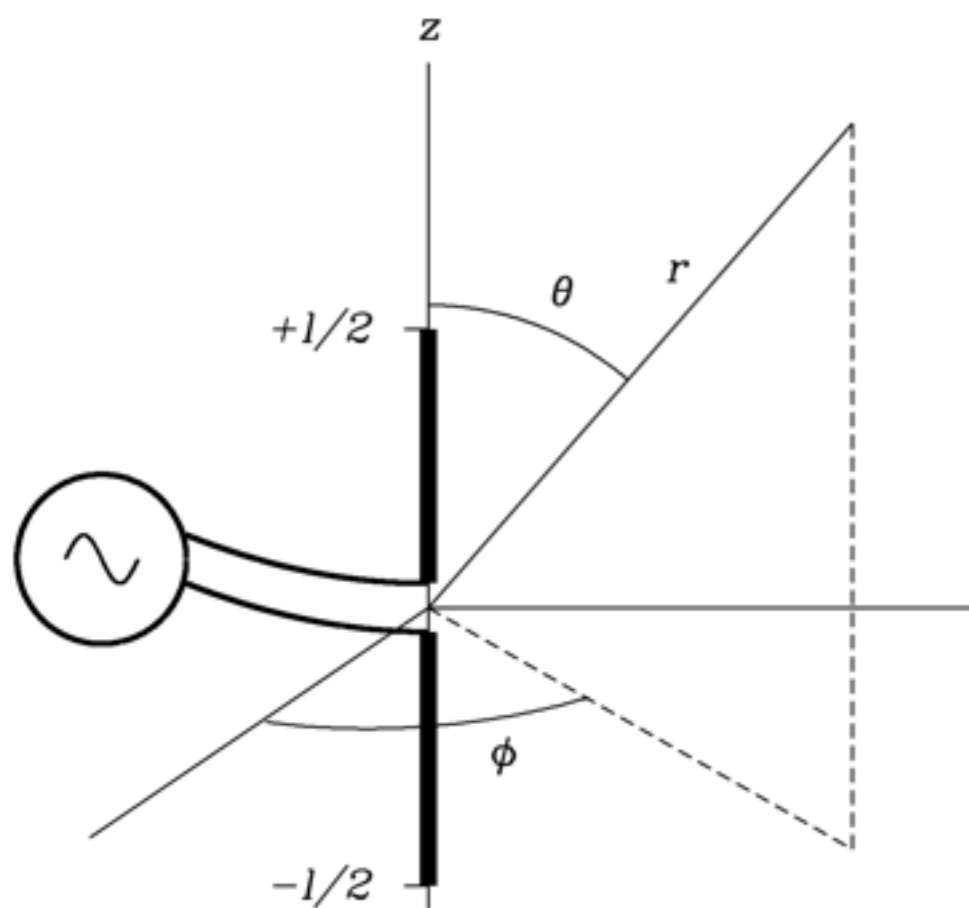
- Grote Reber (1937-39), using his own 10 m telescope, made no detection at 3300 and 910 MHz, ruling out a Planck spectrum ( $B_\nu \propto \nu^2$ ).
- Detection made at 150 MHz, confirming Jansky's result and finding the spectrum must be non-thermal.





## 2.1 Dipole antenna fundamentals

- **Antenna:** A device for converting electromagnetic radiation in space into electrical currents (transmitting and receiving).



Consider a Hertzian small ( $l \ll \lambda$ ) dipole transmitter (same as for a receiving dipole, but easier to understand).

Two co-linear conductors (e.g. wires, conducting rods), driven by a current source at the gap. The driving current  $I$  is a time varying sinusoidally with angular frequency,

$$\omega = 2\pi\nu$$

$$I = I_0 \cos(\omega t) = I_0 e^{-i\omega t}$$

(Only consider the real part of  $e^{-i\omega t} = \cos(\omega t) + i \sin(\omega t)$ )

The time varying current density is defined as,  $J = \frac{I}{q} = \frac{I_0}{q} e^{-i\omega t}$  inside the dipole,

and  $J = 0$  outside the dipole.

- We want to measure the power radiated from such an antenna, so we calculate,
  1. The electromagnetic vector potential  $A$ ,
  2. The magnetic field induction  $B$ , and hence the magnetic field intensity  $H$ ,
  3. The electric field intensity  $E$ ,
  4. The Poynting flux  $S$ ,

### 1. The electromagnetic vector potential

The induced magnetic field  $B$  is related to the vector potential by,

$$\vec{B} = \nabla \times \vec{A}$$

where,

$$\vec{A}(x) = \frac{\mu_0}{4\pi} \int \int \int \vec{J}(x) \frac{e^{ik|x-x'|}}{|x-x'|} d^3x'$$

i.e., the integral of the current density over the volume of the dipole ( $dV = q dz$ ).

The current runs from  $z = -\Delta l / 2$  and  $z = +\Delta l / 2$  along the z-axis, thus

$$\begin{array}{l} \vec{J}_x = 0 \quad \text{and} \quad \vec{A}_x = 0 \\ \vec{J}_y = 0 \quad \text{and} \quad \vec{A}_y = 0 \end{array} \quad \text{only} \quad \vec{J}_z = \frac{I}{q} e^{-i\omega t} \quad \text{is non-zero.}$$



Therefore, our vector potential becomes,

$$\begin{aligned}\vec{A}_z &= \frac{\mu_0}{4\pi} \int_{-\Delta l/2}^{+\Delta l/2} \frac{I(z)}{q} e^{-i\omega t} \frac{e^{ikr}}{r} q dz \\ &= \frac{\mu_0}{4\pi} \frac{e^{-i(\omega t - kr)}}{r} \int_{-\Delta l/2}^{+\Delta l/2} I(z) dz\end{aligned}$$

If the current is constant,

$$\int_{-\Delta l/2}^{+\Delta l/2} I(z) dz = I [z]_{-\Delta l/2}^{+\Delta l/2} = I \Delta l$$

Therefore, our vector potential for a constant current is,

$$\vec{A}_z = \frac{\mu_0}{4\pi} \frac{e^{-i(\omega t - kr)}}{r} I \Delta l$$

2. The magnetic induction is related to the magnetic vector potential via,

$$\vec{B} = \nabla \times \vec{A}$$

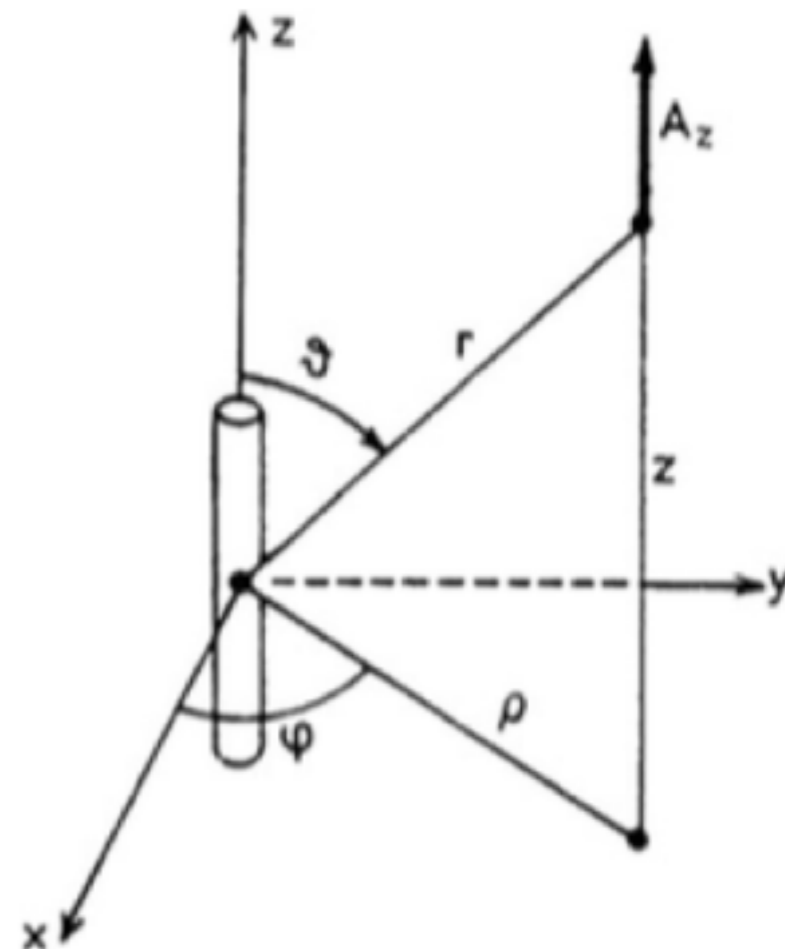
We can de-compose the curl of  $A$  into three orthogonal cylindrical co-ordinates  $(\rho, \psi, z)$ , using standard definitions,

$$(\nabla \times \vec{A})_\rho = \frac{1}{\rho} \frac{\partial A_z}{\partial \psi} - \frac{\partial A_\psi}{\partial z}$$

$$(\nabla \times \vec{A})_\psi = \frac{\partial A_\rho}{\partial z} - \frac{\partial A_z}{\partial \rho}$$

$$(\nabla \times \vec{A})_z = \frac{1}{\rho} \left( \frac{\partial(\rho A_\psi)}{\partial \rho} - \frac{\partial A_\rho}{\partial \psi} \right)$$

As  $A_\rho = A_\psi = 0$ , the B-field must be perpendicular to the vector potential ( $A_z$ ).



For simplicity lets evaluate,

$$B_\psi = (\nabla \times \vec{A})_\psi = \frac{\partial A_\rho}{\partial z} - \frac{\partial A_z}{\partial \rho} = -\frac{\partial A_z}{\partial \rho} = -\frac{\partial A_z}{\partial r} \frac{\partial r}{\partial \rho}$$

In the cylindrical system,

$$r^2 = \rho^2 + z^2 \quad r = (\rho^2 + z^2)^{1/2}$$

$$\frac{\partial r}{\partial \rho} = \frac{1}{2} (\rho^2 + z^2)^{-1/2} 2\rho = \frac{\rho}{r} = \sin \theta$$

Next,

$$\frac{\partial A_z}{\partial r} = \frac{\mu_0}{4\pi} I \Delta l e^{-i\omega t} \frac{\partial}{\partial r} \left[ \frac{e^{ikr}}{r} \right]$$

We solve this using the quotient rule,

$$\left[ \frac{u(r)}{v(r)} \right] = \frac{u'(r)v(r) - v'(r)u(r)}{v(r)^2} \quad \begin{array}{ll} u(r) = e^{ikr} & v(r) = r \\ u'(r) = ik e^{ikr} & v'(r) = 1 \end{array}$$

$$\frac{\partial}{\partial r} \left[ \frac{e^{ikr}}{r} \right] = \frac{ik e^{ikr} \cdot r - 1 \cdot e^{ikr}}{r^2} = \frac{(ikr - 1)e^{ikr}}{r^2}$$

Therefore our  $B$ -field in the  $\psi$  direction becomes,

$$B_\psi = -\frac{\partial A_z}{\partial r} \frac{\partial r}{\partial \rho} = -ik \frac{\mu_0}{4\pi} I \Delta l \frac{\sin \theta}{r} \left( 1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

Since,

$$k = \frac{2\pi}{\lambda}$$

$$B_\psi = -i \mu_0 \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left( 1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$



which, from the materials equations, gives for the magnetic field intensity,

$$B = \mu_0 H \quad H_\psi = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left( 1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

Again, the magnetic field intensity is perpendicular to the vector potential, that is, perpendicular to the element.

3. Now, let's consider the electric field intensity. From Maxwell's equations,

$$\nabla \times \vec{H} = \vec{J} + \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

which, because we are away from the current element ( $J = 0$ ), simplifies to,

$$\nabla \times \vec{H} = \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

We are dealing with harmonic waves of the form,

$$E(r, t) = E_0 e^{-i(\omega t - kr)}$$

$$\dot{E}(r, t) = E_0 e^{-i(\omega t - kr)} \cdot -i\omega = -i\omega E(r, t)$$

Therefore,

$$E = -\frac{1}{i\omega\epsilon_0} \nabla \times \vec{H}$$

To evaluate  $E$ , we must determine the curl of  $H$ , but as in the case of the B-field, only the  $H_\psi$  terms have non-zero entries.

From spherical co-ordinates, the only relevant term of the curl of  $H$  is,

$$(\nabla \times H)_\theta = -\frac{1}{r} \frac{\partial(rH_\psi)}{\partial r}$$

Note also, that the resulting  $E$ -field is in terms of  $\theta$  and is perpendicular to the  $H$ -field, as expected for electromagnetic plane waves.

$$\begin{aligned} rH_\psi &= -i \frac{I\Delta l}{2\lambda} \sin \theta \left( 1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)} \\ &= -i \frac{I\Delta l}{2\lambda} \sin \theta e^{-i\omega t} \left( e^{ikr} - \frac{e^{ikr}}{ikr} \right) \\ \frac{\partial(rH_\psi)}{\partial r} &= -i \frac{I\Delta l}{2\lambda} \sin \theta e^{-i\omega t} \frac{\partial}{\partial r} \left( e^{ikr} - \frac{e^{ikr}}{ikr} \right) \end{aligned}$$

We solve this using the quotient rule,

$$\left[ \frac{u(r)}{v(r)} \right] = \frac{u'(r)v(r) - v'(r)u(r)}{v(r)^2} \quad \begin{array}{ll} u(r) = e^{ikr} & v(r) = ikr \\ u'(r) = ik e^{ikr} & v'(r) = ik \end{array}$$

$$\begin{aligned} \frac{\partial}{\partial r} \left( e^{ikr} - \frac{e^{ikr}}{ikr} \right) &= ik e^{ikr} - \left( \frac{ik e^{ikr} \cdot ikr - ik \cdot e^{ikr}}{(ikr)^2} \right) \\ &= ik e^{ikr} \left( 1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) \end{aligned}$$

so,

$$\frac{\partial(rH_\psi)}{\partial r} = -i \frac{I\Delta l}{2\lambda} \sin\theta e^{-i\omega t} ik e^{ikr} \left( 1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right)$$

and,

$$-\frac{1}{r} \frac{\partial(rH_\psi)}{\partial r} = i^2 k \frac{I\Delta l}{2\lambda} \frac{\sin\theta}{r} \left( 1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

we find,

$$k = \frac{\omega}{c}$$

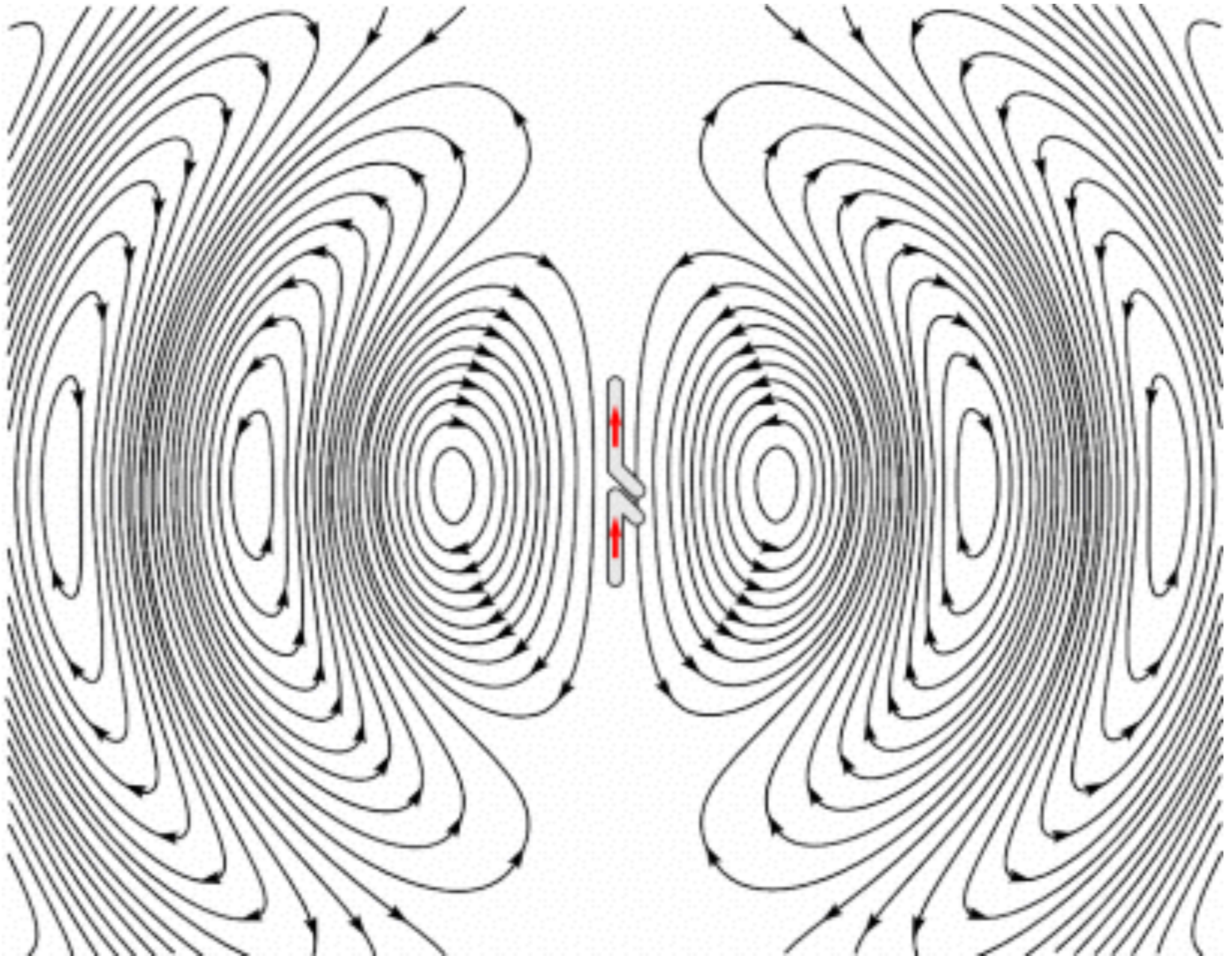
$$E_\theta = -i \frac{1}{c\epsilon_0} \frac{I\Delta l}{2\lambda} \frac{\sin\theta}{r} \left( 1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

So the E-field can also be expressed as,

$$c = \frac{1}{\sqrt{\mu_0\epsilon_0}}$$

$$E_\theta = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I\Delta l}{2\lambda} \frac{\sin\theta}{r} \left( 1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$





So, our electric and magnetic fields are,

$$H_{\psi} = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left( 1 - \frac{1}{ikr} \right) e^{-i(\omega t - kr)}$$

$$E_{\theta} = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} \left( 1 - \frac{1}{ikr} + \frac{1}{(ikr)^2} \right) e^{-i(\omega t - kr)}$$

There are several factors that depend on the power of the distance  $r$  from the antenna,

1.  $1/r$  : The radiation field (dominates at large  $r \gg \Delta l$ ).
2.  $1/r^2$ : The induction field
3.  $1/r^3$ : The static field (of the E-field).

To calculate the near-field properties, all factors must be evaluated, but in the far-field, where we measure the radiation from the antennas, the  $1/r$  term dominates.

$$H_{\psi} = -i \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} e^{-i(\omega t - kr)}$$

$$E_{\theta} = -i \sqrt{\frac{\mu_0}{\epsilon_0}} \frac{I \Delta l}{2\lambda} \frac{\sin \theta}{r} e^{-i(\omega t - kr)}$$

Note that,

$$\frac{|E|}{|H|} = \sqrt{\frac{\mu_0}{\epsilon_0}} = 1$$

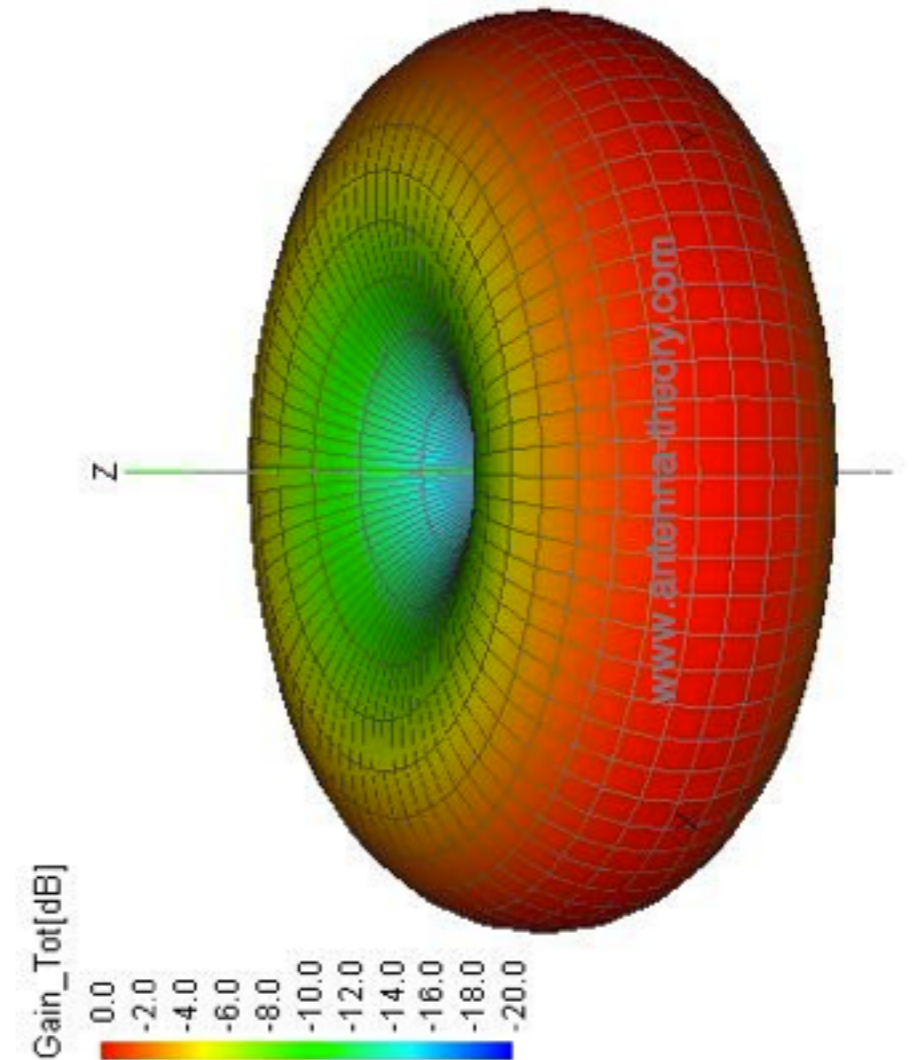
in cgs units

4. We can now determine the directional power per unit area in the far-field by calculating the time-averaged Poynting vector.

$$\begin{aligned} \langle \vec{S} \rangle &= \frac{1}{\mu_0} |\operatorname{Re} \vec{E} \times \vec{B}^*| = |\operatorname{Re} \vec{E} \times \vec{H}^*| \\ &= \sqrt{\frac{\mu_0}{\epsilon_0}} \left( \frac{I \Delta l}{2\lambda} \right)^2 \frac{\sin^2 \theta}{r^2} \left( \frac{1}{2} \right) \end{aligned}$$

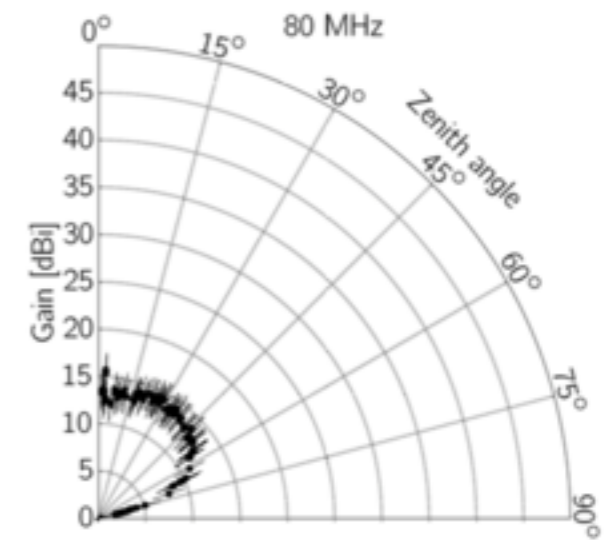
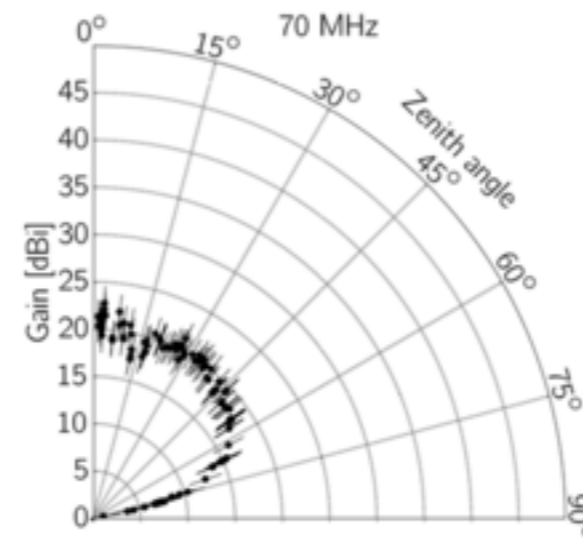
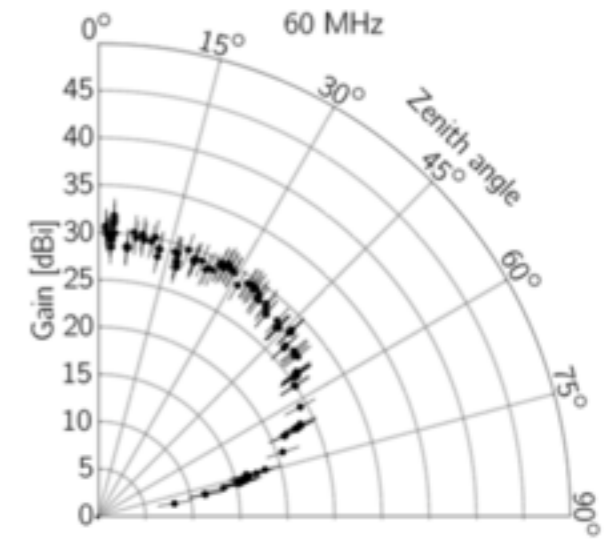
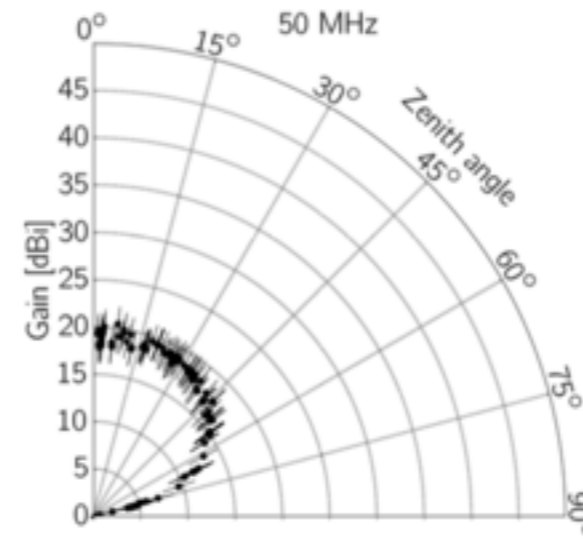
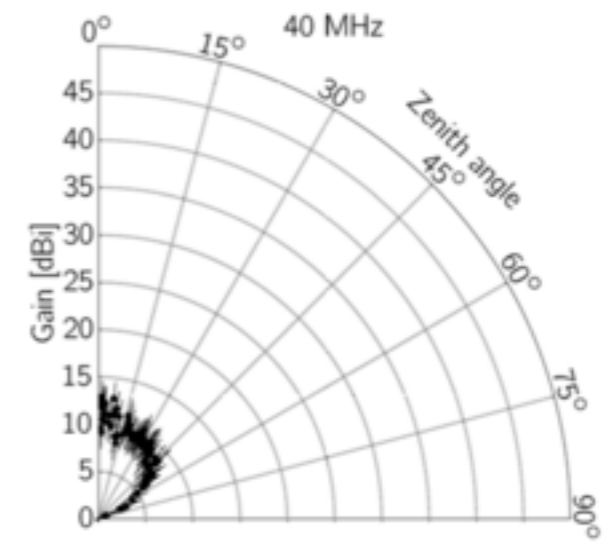
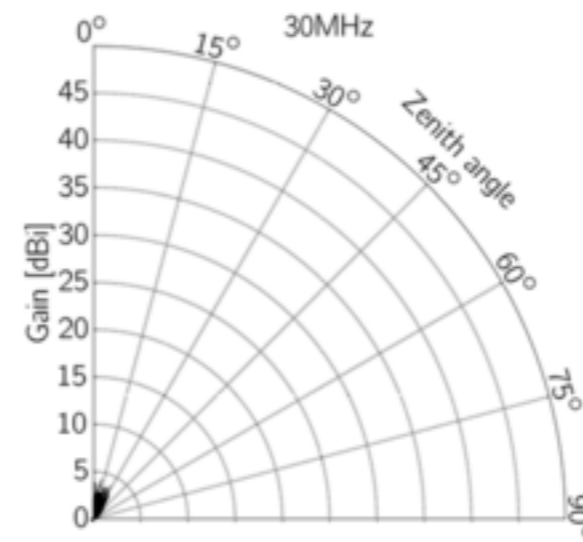
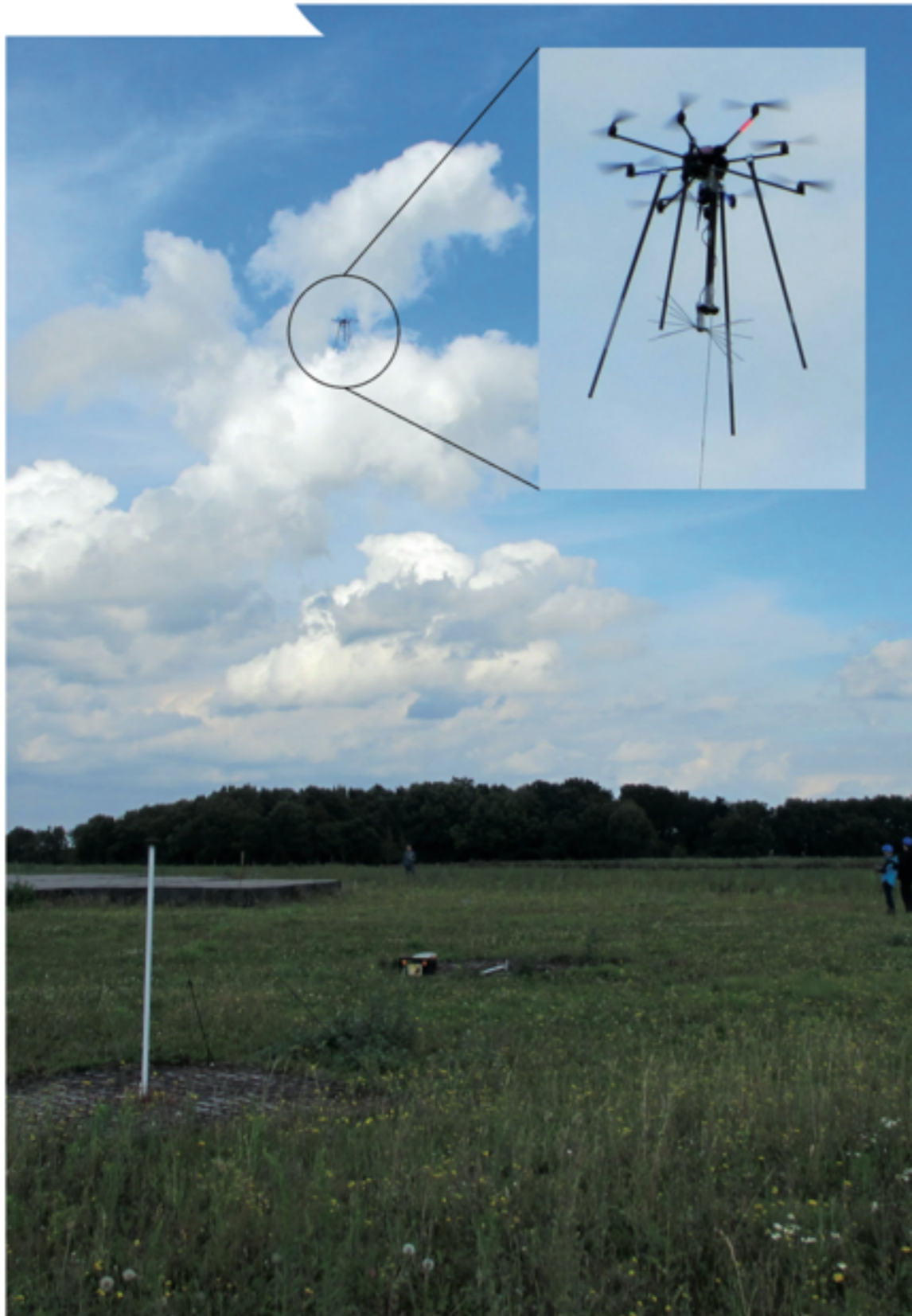
where  $\langle \cos^2(\omega t) \rangle = \frac{1}{2}$

The radiation has doughnut shaped power pattern (angular distribution of radiated power) due to dependence on  $\sin^2 \theta$ .



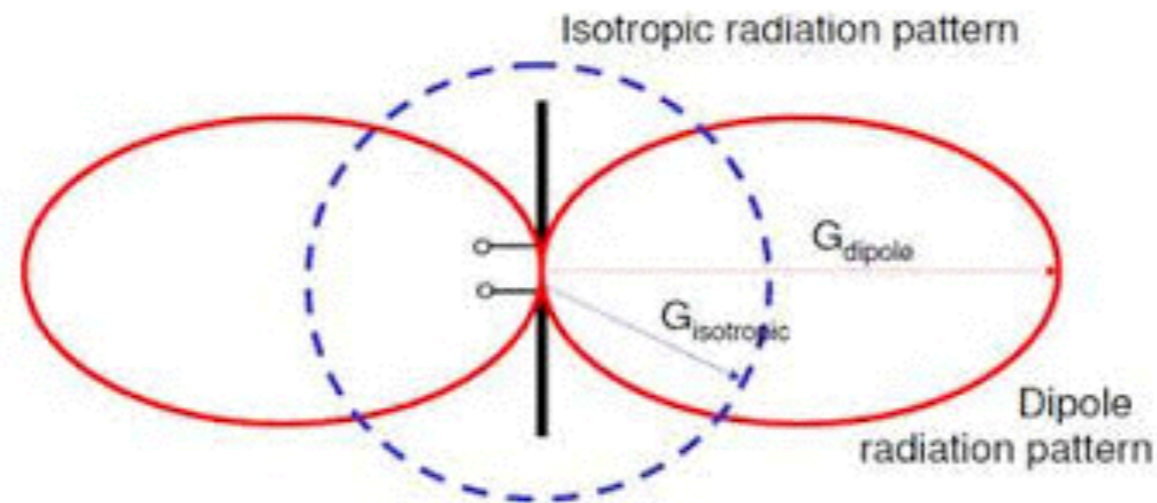


## 2.2 Response of the LOFAR antenna:



## 2.3 Power gain:

$G(\theta, \phi)$  is the power transmitted per unit solid angle in direction  $(\theta, \phi)$  divided by the power transmitted per unit solid angle from an isotropic antenna with the same total power.



- The power or gain are often expressed in logarithmic units of decibels (dB):

$$G(\text{dB}) \equiv 10 \times \log_{10}(G)$$

**Worked example:** What is the maximum and half power of a normalised power pattern in decibels?

Maximum power of a normalised power pattern is  $P_n = 1$

$$P_n(1) = 10 \times \log_{10}(1) = 0 \text{ dB}$$

Half power of a normalised power pattern is  $P_n = 0.5$

$$P_n(0.5) = 10 \times \log_{10}(0.5) = -3 \text{ dB}$$

For a lossless isotropic antenna, conservation of energy requires the directive gain averaged over all directions be,

$$\langle G \rangle \equiv \frac{\int_{\text{sphere}} G d\Omega}{\int_{\text{sphere}} d\Omega} = 1$$

Therefore, for an isotropic lossless antenna,

$$\int_{\text{sphere}} G d\Omega = \int_{\text{sphere}} d\Omega = 4\pi \quad \text{and} \quad G = 1$$

- Lossless antennas may radiate with different directional patterns, but they cannot alter the total amount of power radiated —> the gain of a lossless antenna depends only on the angular distribution of radiation from that antenna.

**Key Concept:** Higher the gain, the narrower the radiation pattern (directivity).

$$\Delta\Omega \approx \frac{4\pi}{G_{\text{max}}}$$



## 2.4 Effective collecting area (what is the collecting area of a dipole?)

- The receiving counterpart of the transmitting gain is the effective collecting area, defined as the product of the geometric area and the incident spectral power per unit area ( $S_\nu$ , the flux-density),

$$A_e \equiv \frac{P_\nu}{S_{(\text{matched})}}$$

Effective area (m<sup>2</sup>)      Spectral power (W Hz<sup>-1</sup>)  
Flux-density (W m<sup>-2</sup> Hz<sup>-1</sup>)

Note: For a dish, we can relate the effective area with the geometric area via the aperture efficiency,

$$A_e = \eta_A A_g$$

Any antenna with a single output measures only one polarisation. Electric fields perpendicular to the antenna wires does not produce currents in the antenna. A pair of crossed dipoles are need to collect the power from both polarisations.

- For an unpolarised source (e.g. like a black body),

$$S_{(\text{matched})} = \frac{S}{2}$$

- The total spectral power from all directions collected by the antenna is,

$$P_\nu = A_e S_{(\text{matched})} = A_e \frac{S}{2} = \int_{4\pi} A_e(\theta, \phi) \frac{B_\nu}{2} d\Omega = kT$$

(must equal the Nyquist spectral power). From the R-J equation,

$$B_\nu = \frac{2kT}{\lambda^2} \quad P_\nu = \frac{2kT}{2\lambda^2} \int_{4\pi} A_e(\theta, \phi) d\Omega = kT$$

$$\int_{4\pi} A_e(\theta, \phi) d\Omega = \lambda^2$$

- The average collecting area is defined as

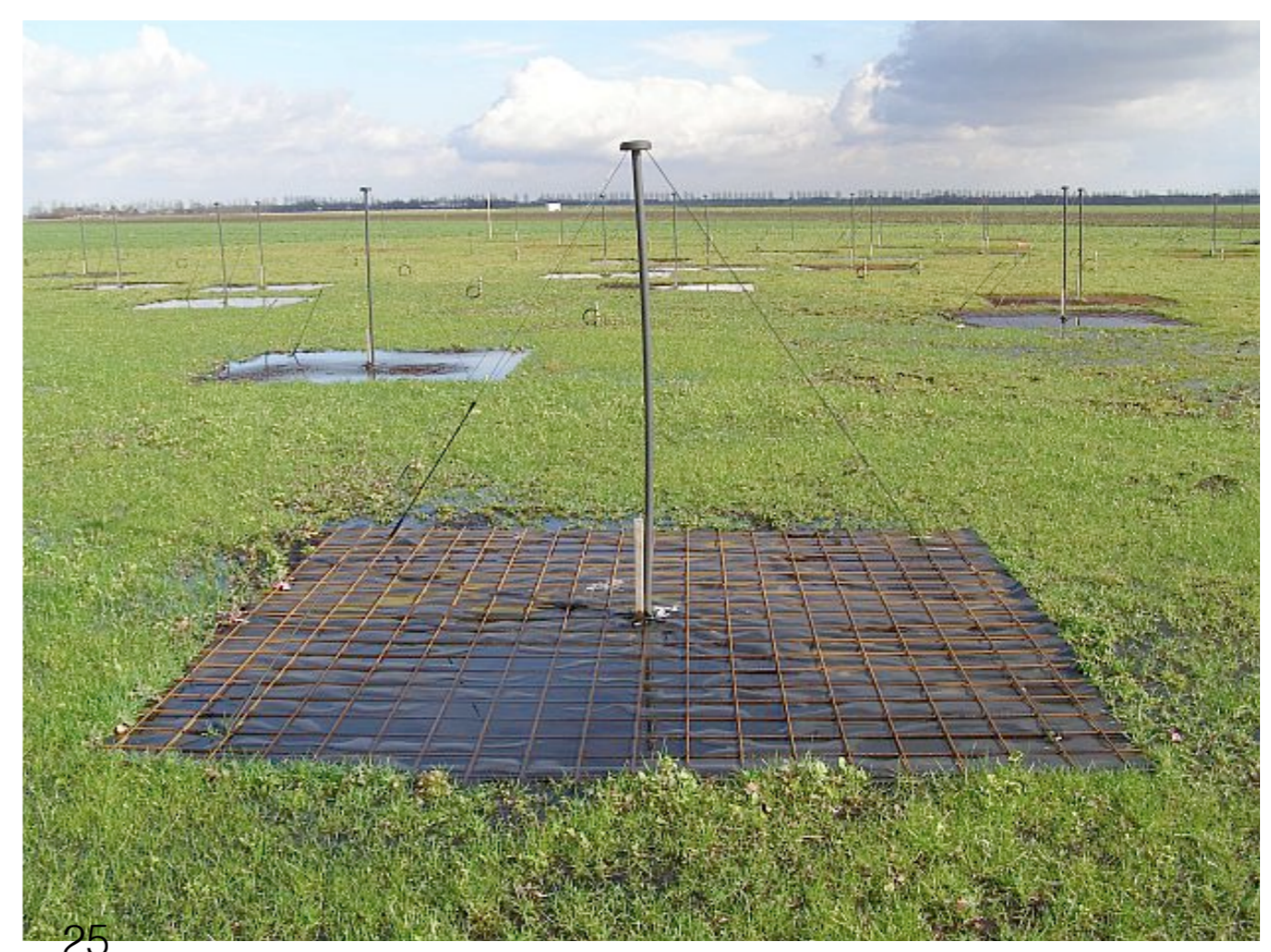
$$\langle A_e \rangle = \frac{\int_{4\pi} A_e(\theta, \phi) d\Omega}{\int_{4\pi} d\Omega}$$

The effective collecting area is independent of the antenna environment, so this relation is valid for any type of radiation (not just black body radiation).

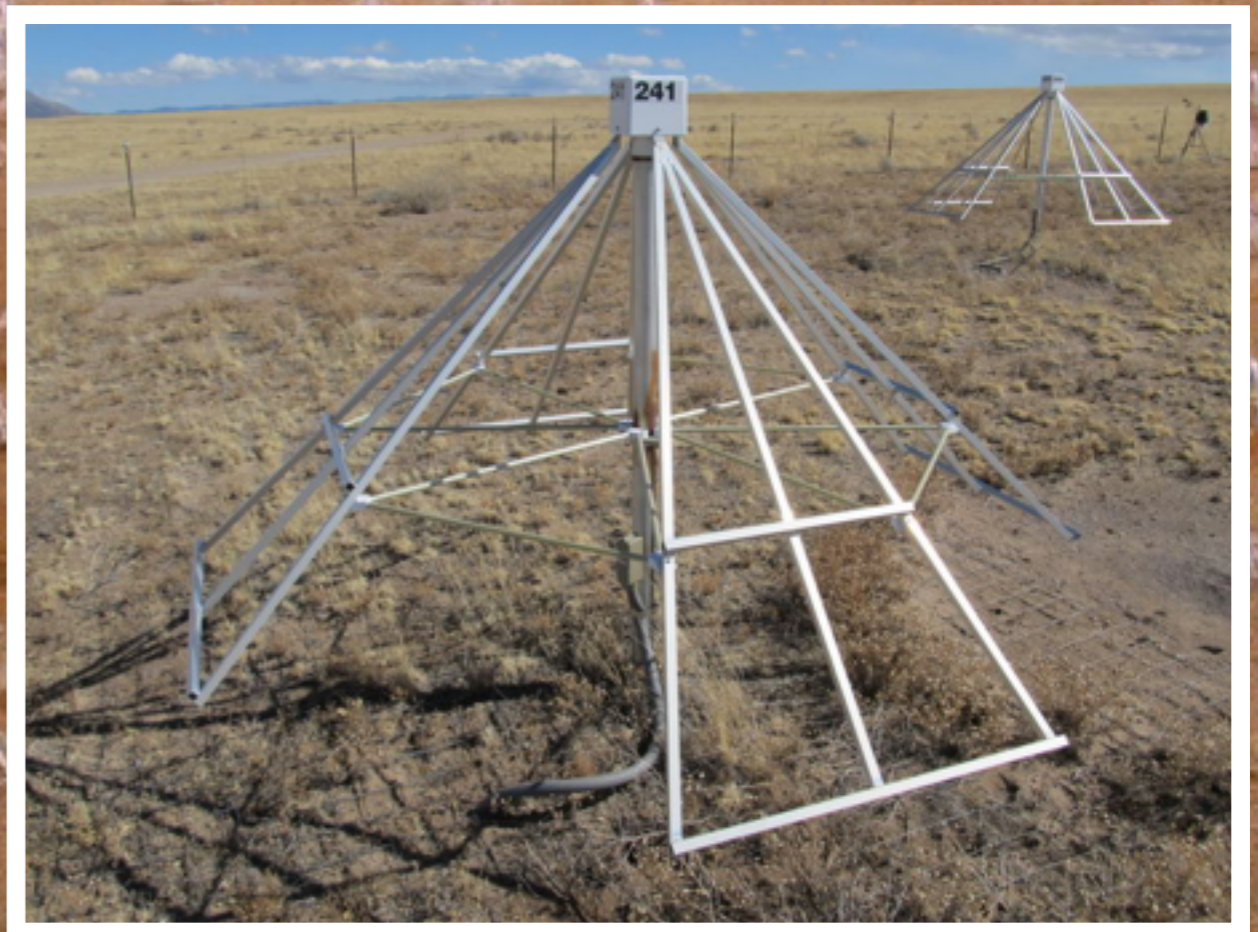
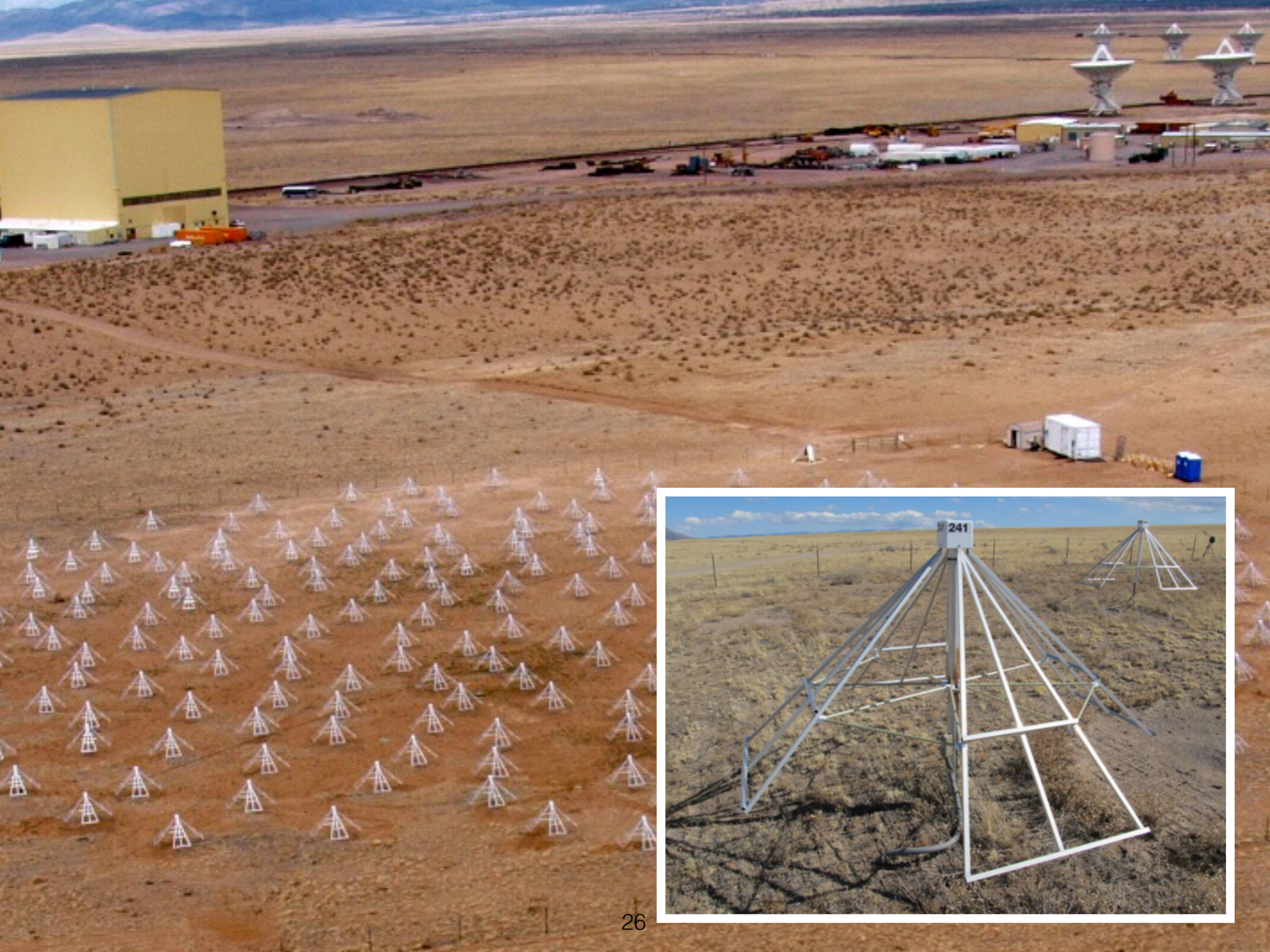
**Key concept:** Any antenna has the same average collecting area  $\langle A_e \rangle$  that depends only on the wavelength of the radiation.

$$\langle A_e \rangle = \frac{\lambda^2}{4\pi}$$

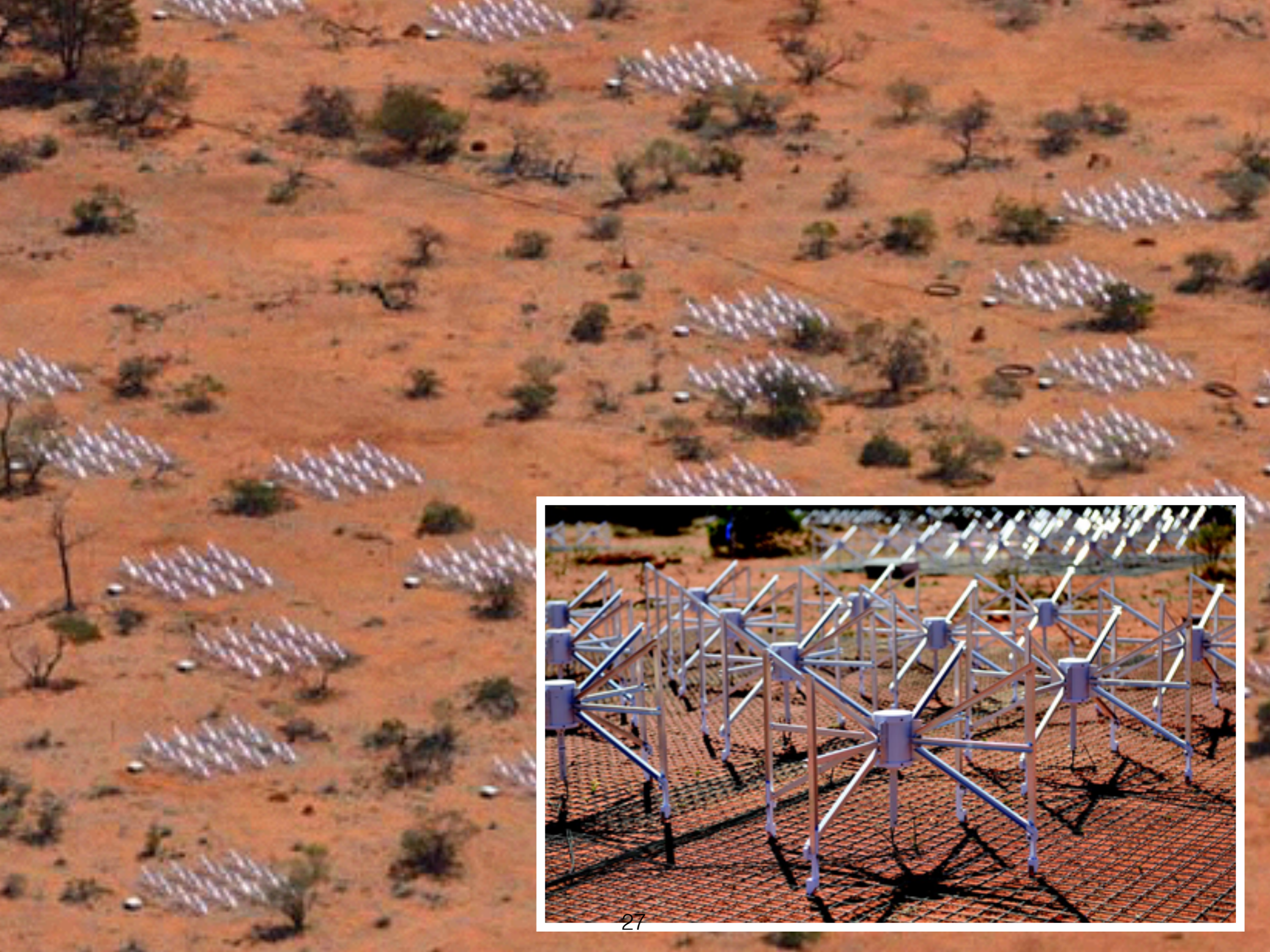




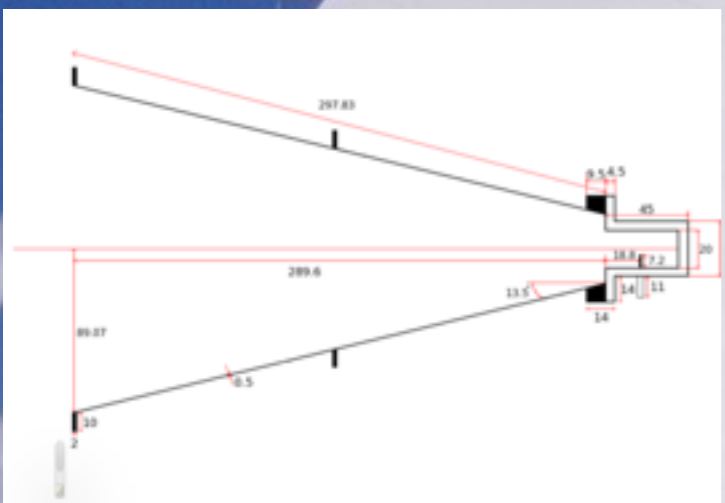
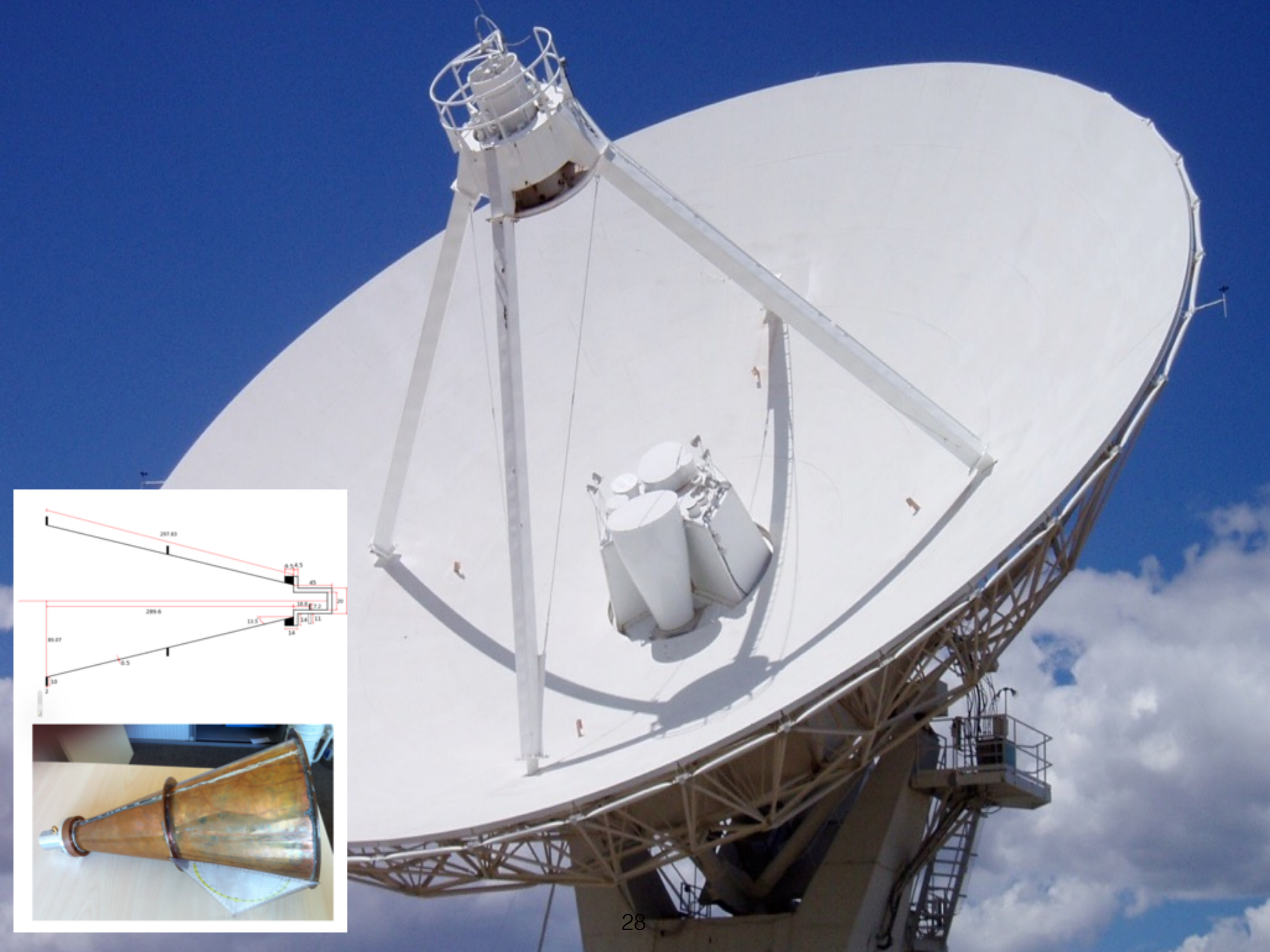














### 3.1 Interferometers

Combined telescopes

$$\theta_{\text{res}} \sim \frac{\lambda}{B}$$

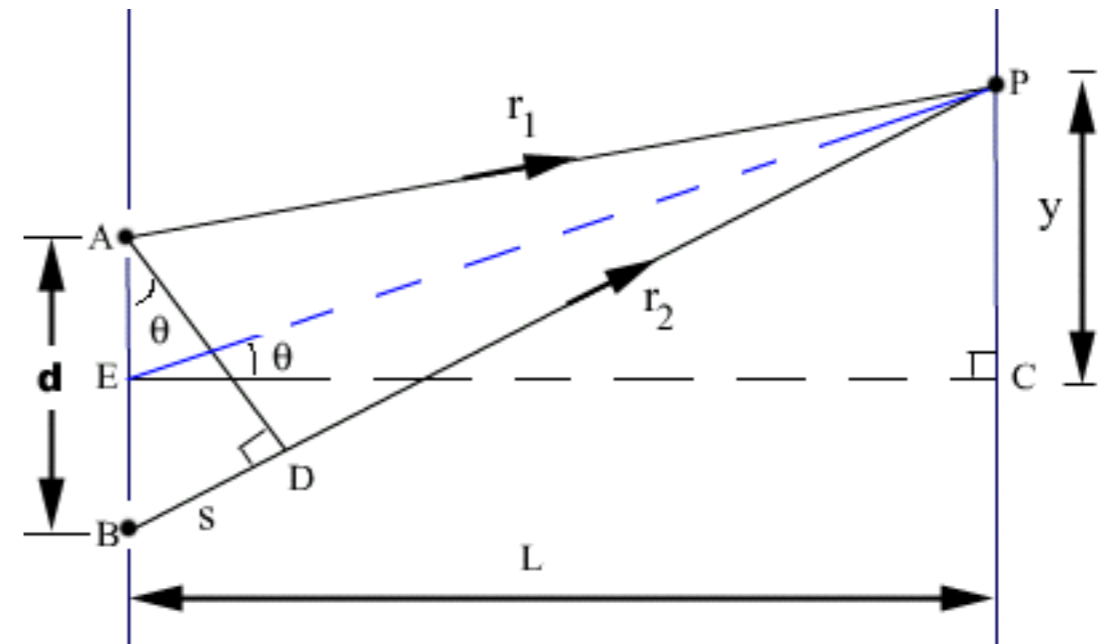
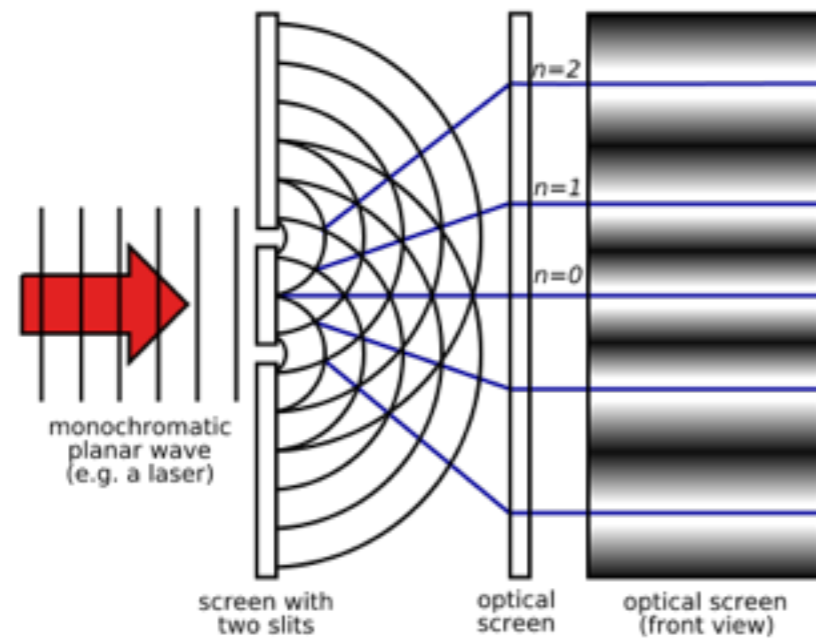
Individual telescope

$$\theta_{\text{res}} \sim \frac{\lambda}{D}$$

- We can overcome this problem by correlating the signals from different telescopes to effectively increase  $D$  to an arbitrarily large value by increasing the distance between the telescopes, called the baseline length  $B$ . Now,  $\theta \sim \lambda / B$ .
  1. High angular resolution (down to  $< 1$  mas; best in astronomy), e.g. VLBI.
  2. Better sensitivity (Area =  $N\pi D^2 / 4$ ,  $N$  is number of telescopes), e.g. LOFAR, JVLA, ALMA.
  3. Large field-of-view (10s deg<sup>2</sup>) in the case of phased array feeds, e.g. WSRT-Aperitif.



## 3.2 Young's double slit experiment



Constructive interference **fringes** occur when the path difference is an integer number wavelengths, i.e.

$$d \sin \theta = n\lambda \quad \text{and for destructive interference,} \quad d \sin \theta = (n + 1/2)\lambda$$

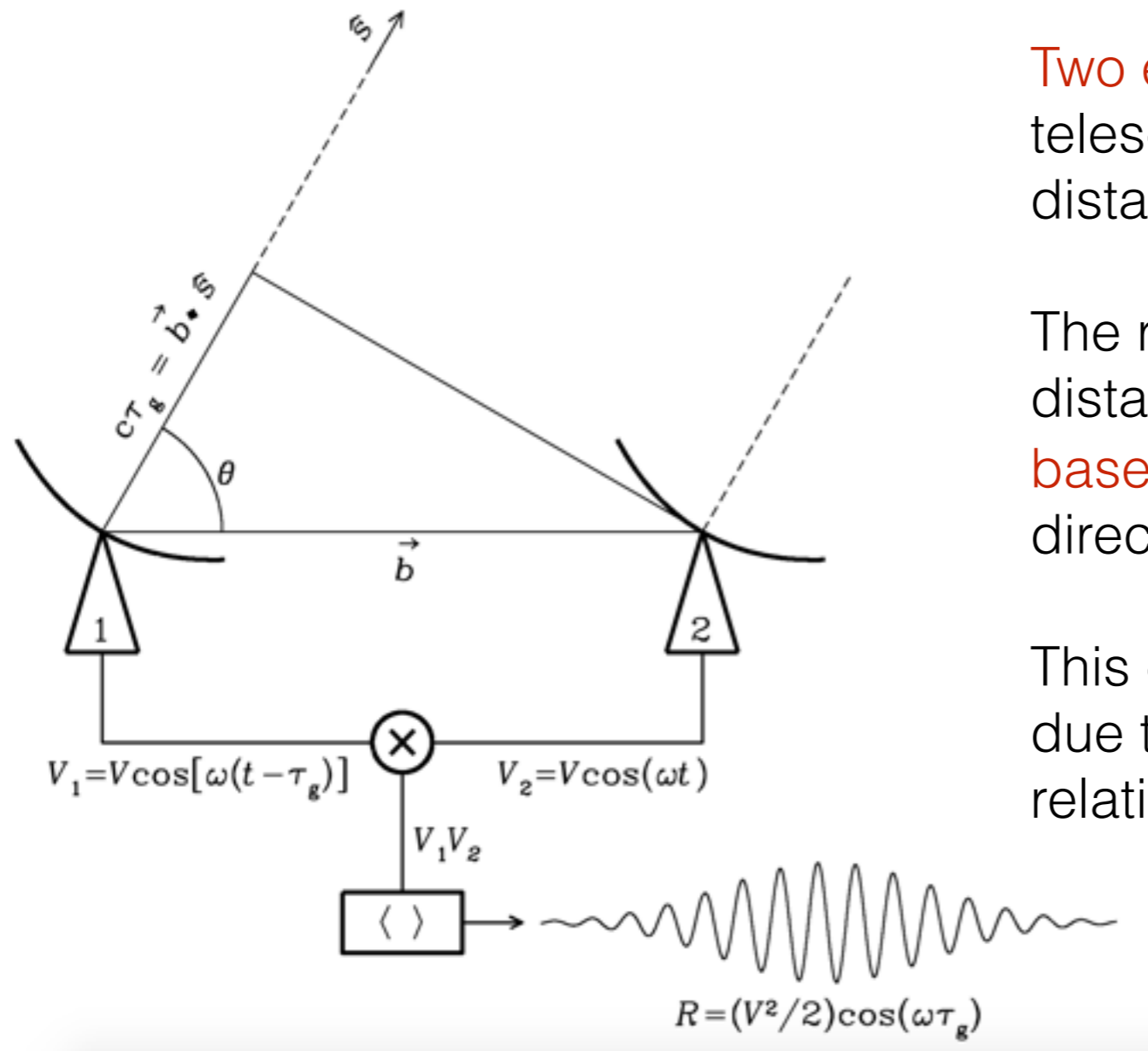
when  $y \ll L$ , we can approximate  $\sin \theta = y / L$  and the positions of the maxima and minima are,

$$y_c = \frac{n\lambda L}{d} \quad \text{and} \quad y_d = \frac{(n + 1/2)\lambda L}{d}$$

and the spacing between successive fringes is,

$$\Delta y = \frac{\lambda L}{d} \quad \text{or, expressed as an angular size,} \quad \theta \sim \frac{\lambda}{d}$$

### 3.3 A simple two-element interferometer



**Two element interferometer:** Two identical telescopes observe the electric field of some distant source (c.f. Young's double slit).

The radiation to antenna 1 travels an extra distance  $\vec{b} \cdot \hat{s} = b \cos \theta$ , where  $\vec{b}$  is the vector **baseline** length and  $\hat{s}$  a unit vector in the direction of the source.

This can be expressed as a **geometric delay** due to the projected position of the source, relative to the baseline of the antennas.

$$\tau_g = \vec{b} \cdot \hat{s} / c$$

For a **quasi-monochromatic** interferometer (responds to a narrow frequency range  $\nu = 2\pi / \lambda$ ), the output voltages over time  $t$  from the two antennas are,

$$V_1 = V \cos[\omega(t - \tau_g)] \quad \text{and} \quad V_2 = V \cos(\omega t)$$

The **correlator** multiplies the voltages from the two antennas together to give,

$$V_1 V_2 = V^2 \cos[\omega(t - \tau_g)] \cos(\omega t) = \left(\frac{V^2}{2}\right) [\cos[2\omega t - \omega\tau_g] + \cos(\omega\tau_g)]$$

and then a time average  $[\Delta t \gg (2\omega)^{-1}]$  to remove the high frequency component to give,

$$R = \langle V_1 V_2 \rangle = \left(\frac{V^2}{2}\right) \cos(\omega\tau_g)$$

Uncorrelated noise from gain variations within the receivers, the atmosphere and radio frequency interference does not correlate (advantage over single dish measurements).

The output voltage  $R$  varies sinusoidally with the change of the source direction in the interferometer frame, i.e. the delay changes. These sinusoids are called **fringes**, and we can define the **fringe phase** as,

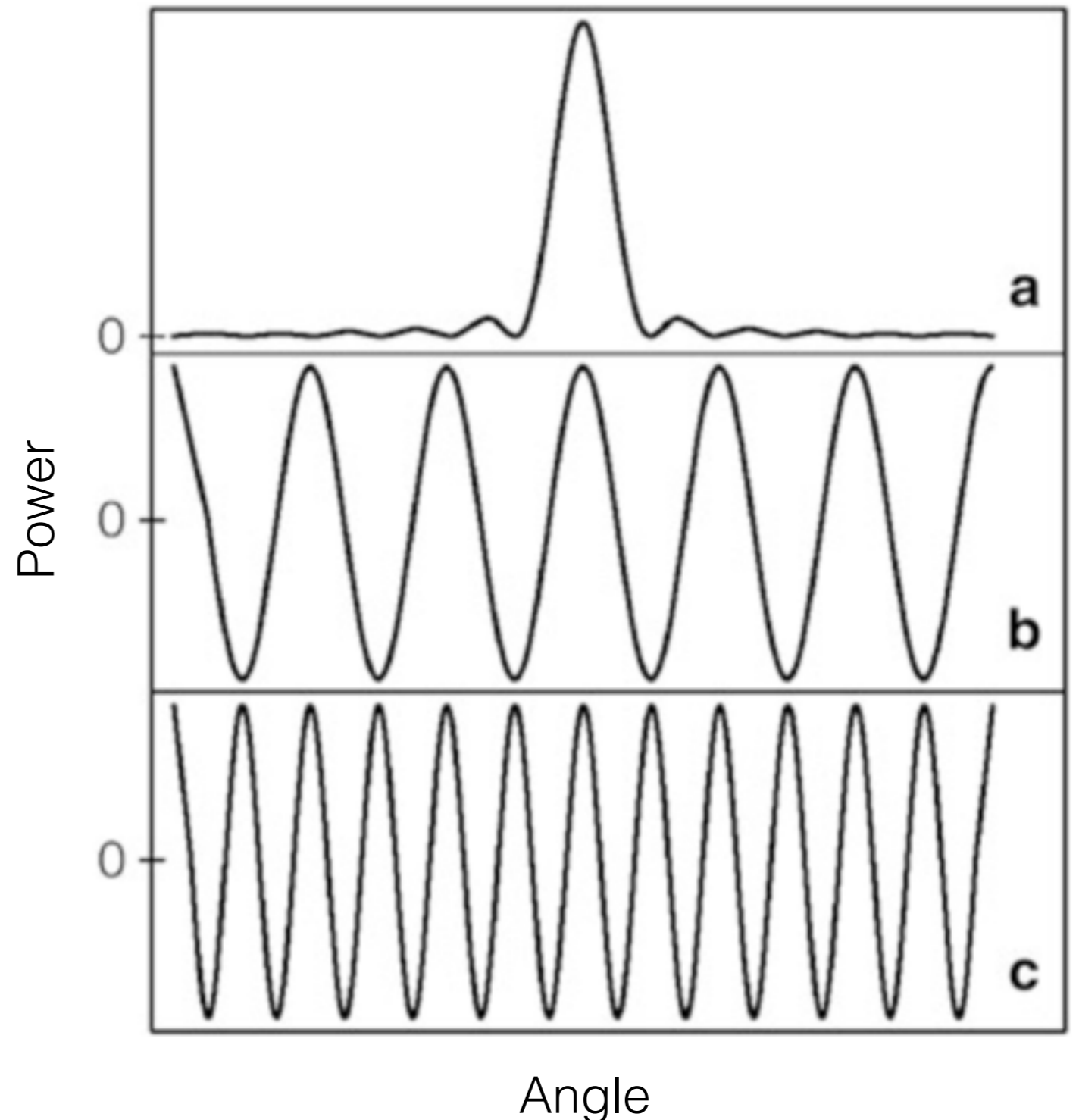
$$\phi = \omega\tau_g = \frac{\omega}{c} b \cos \theta \quad \text{and} \quad \frac{d\phi}{d\theta} = \frac{\omega}{c} b \sin \theta = 2\pi \left(\frac{b \sin \theta}{\lambda}\right)$$

The fringe period ( $\Delta\phi = 2\pi$ ) corresponds to an angular change of  $\Delta\theta = \lambda / (b \sin \theta)$ , and so, for large  $b$ , interferometers can measure very accurate positions of sources (typically  $\sigma_\theta \sim 10^{-3}$  arcsec).

As the source(s) moves across the sky, the response of the interferometer changes because the geometric delay changes. The maximum in the fringe pattern occurs when  $\tau_g c$  is an integral number of wavelengths (similar to the Young's double slit).

This effect of combining antennas changes the response of our instrument to the sky.

- a. The power pattern of a filled aperture of diameter  $D$  with a constant illumination pattern. The FWHM of the main beam is  $\sim \lambda / D$ .
- b. The power pattern of a two-element interferometer with 2 antennas of diameter  $d$  and separation  $D$ . The side-lobe level is constant and the power is centred on 0. The FWHM of the fringes is  $\sim \lambda / D$ .
- c. The power pattern of a two-element interferometer with 2 antennas of diameter  $d$  and separation  $2D$ . The FWHM of the fringes is now  $\sim \lambda / 2D$ .





### 3.4 Extended sources

A spatially incoherent extended source with sky brightness  $I_\nu(\hat{s})$  near frequency  $\nu = \omega / 2\pi$  can be considered as the sum of independent point sources. The response of an interferometer is then,

$$R_c = \int I_\nu(\hat{s}) \cos(2\pi\nu\vec{b} \cdot \hat{s}/c) d\Omega = \int I_\nu(\hat{s}) \cos(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

Note that, the output from the correlator is a complex quantity and so far we have only considered the (real) cosine part of the signal. The (imaginary) sine component is found by inserting a  $90^\circ$  phase delay ( $t - \tau_g - \pi/2$ ).

$$R_s = \int I_\nu(\hat{s}) \sin(2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

It is convenient to express this in terms of complex exponentials,

$$e^{i\phi} = \cos \phi + i \sin \phi$$

Allowing us to define the **complex visibility**  $V = R_c - iR_s$  as,

$$V = Ae^{-i\phi}$$

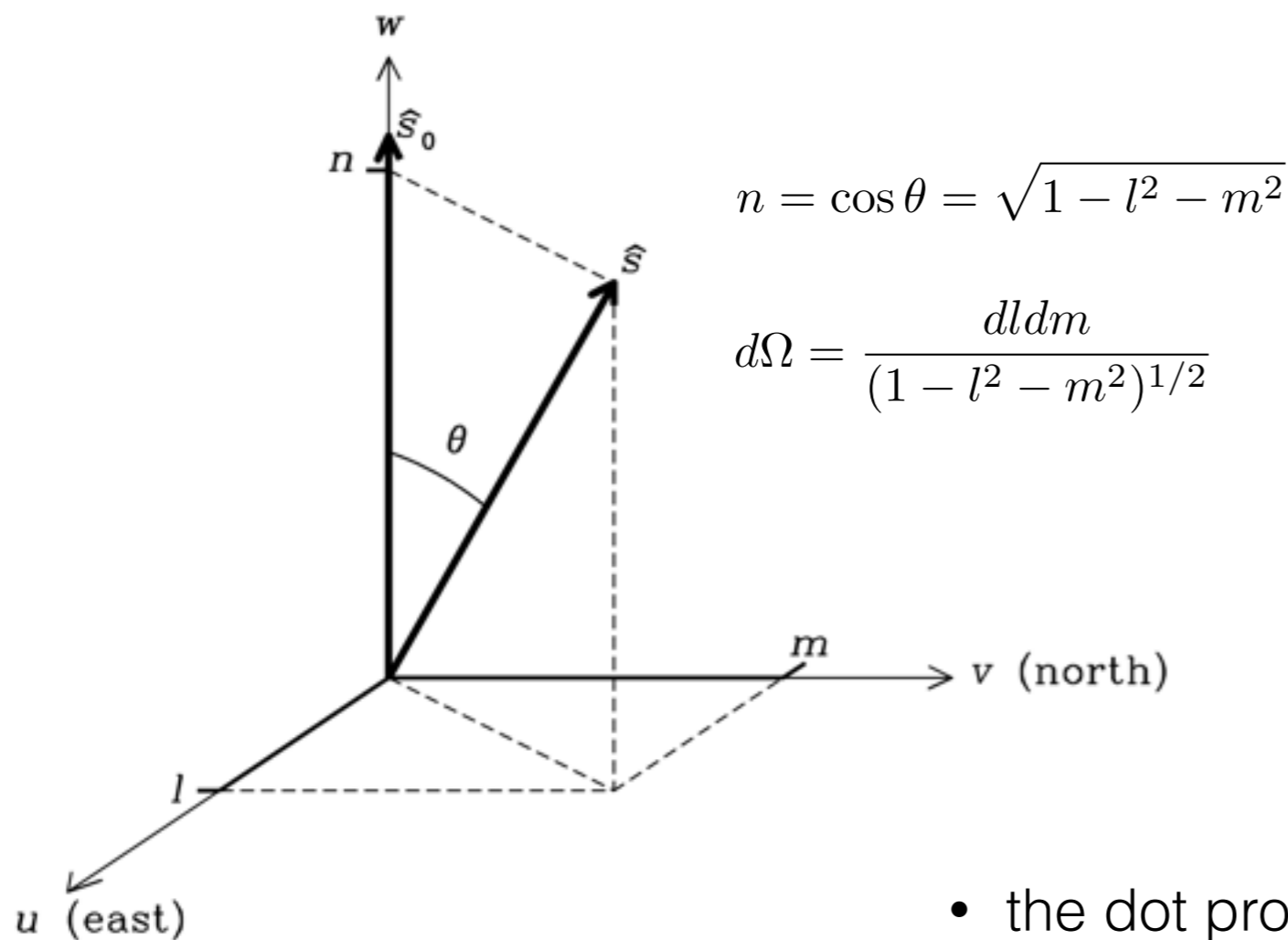
where the amplitude is,  $A = (R_c^2 + R_s^2)^{1/2}$  and the phase is,  $\phi = \tan^{-1}(R_s/R_c)$

So, we can write the response of a two element interferometer to an extended source with brightness distribution  $I_\nu(\hat{s})$  as,

$$V_\nu = \int I_\nu(\hat{s}) \exp(-i2\pi\vec{b} \cdot \hat{s}/\lambda) d\Omega$$

### 3.5 General response of an interferometer

First, we define our co-ordinate systems.



- baseline

$$\frac{\vec{b}}{\lambda} = (u, v, w)$$

North-South  
 /  
 East-West      Up-Down

- source

$$\hat{s} = (l, m, \sqrt{1 - l^2 - m^2})$$

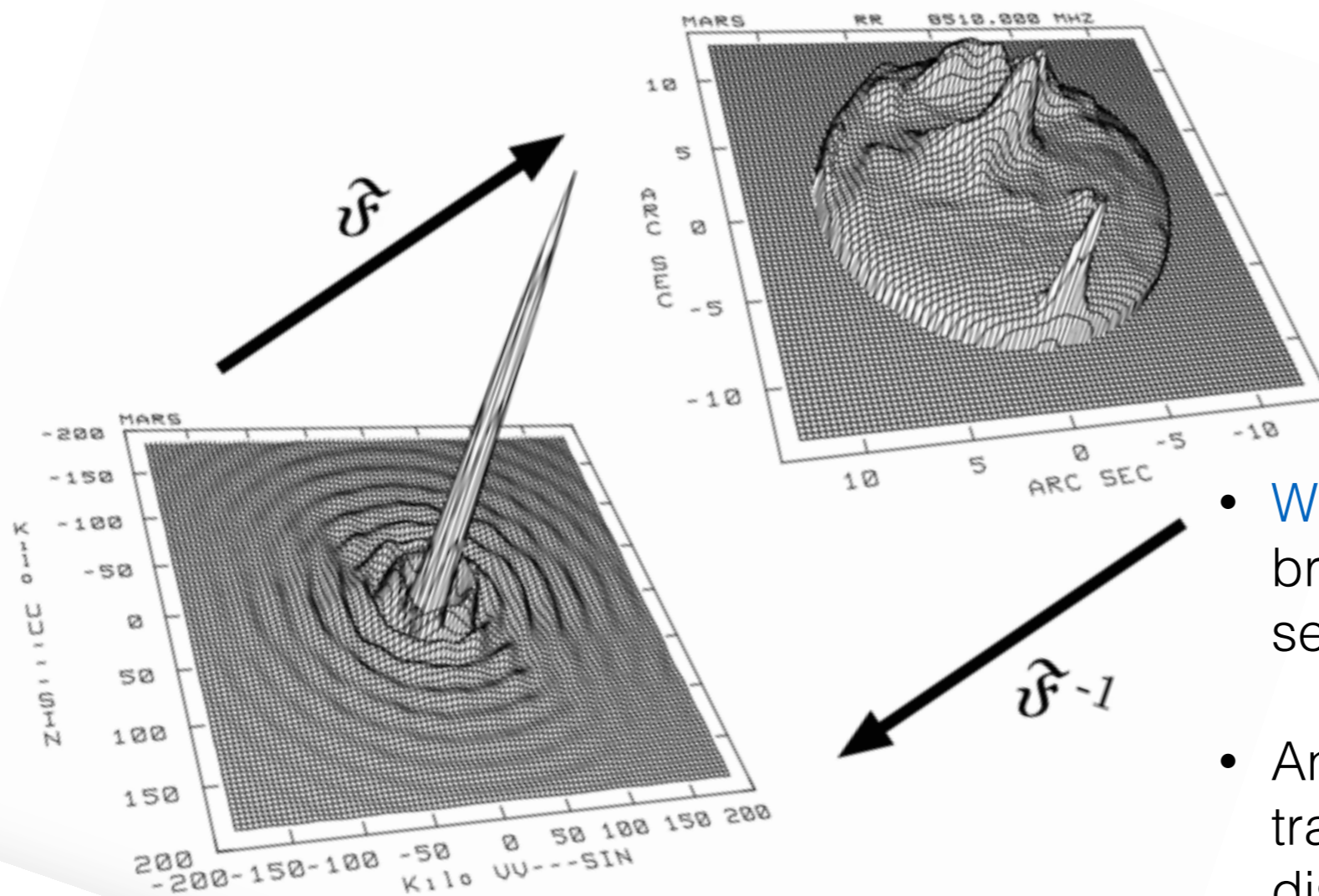
North-South  
 /  
 East-West      Up-Down

- the dot product  $\frac{\vec{b}}{\lambda} \cdot \hat{s} = ul + vm + w\sqrt{1 - l^2 - m^2}$

We can then describe the response of an interferometer to any position in the sky as,

$$V_\nu(u, v, w) = \iint \frac{I_\nu(l, m)}{(1 - l^2 - m^2)^{1/2}} \exp[-i2\pi(ul + vm + wn)] dl dm$$

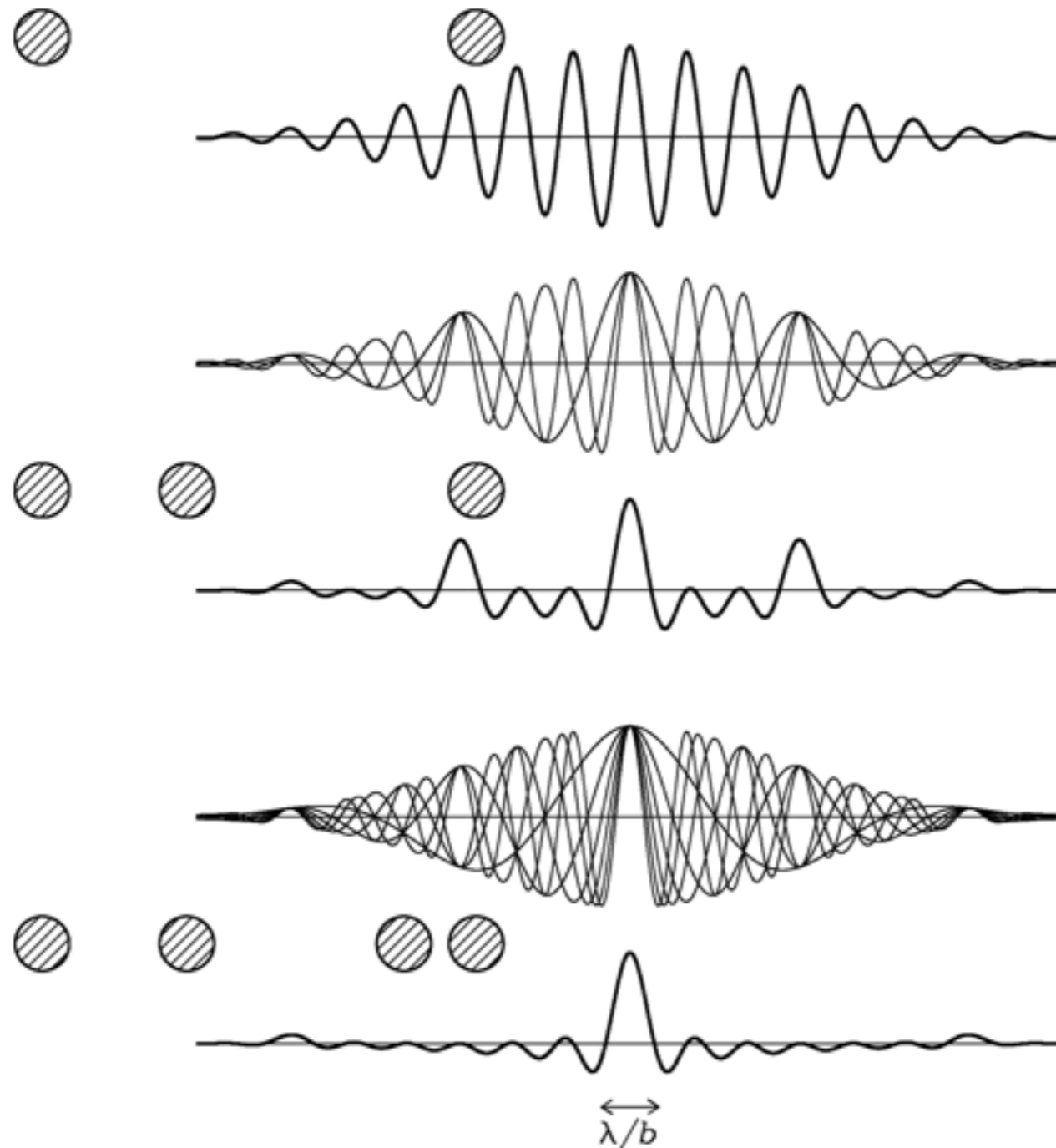
**Key Concept:** The response of an interferometer is the (inverse) Fourier transform of the (apparent) sky brightness distribution.



- **Worked example:** Here is the surface brightness distribution of Mars, as seen at 3.6 cm.
- An interferometer will see the Fourier transform of this surface brightness distribution.



- Incomplete measurement of the Fourier plane results in significant structure in the point spread function response of the interferometer.



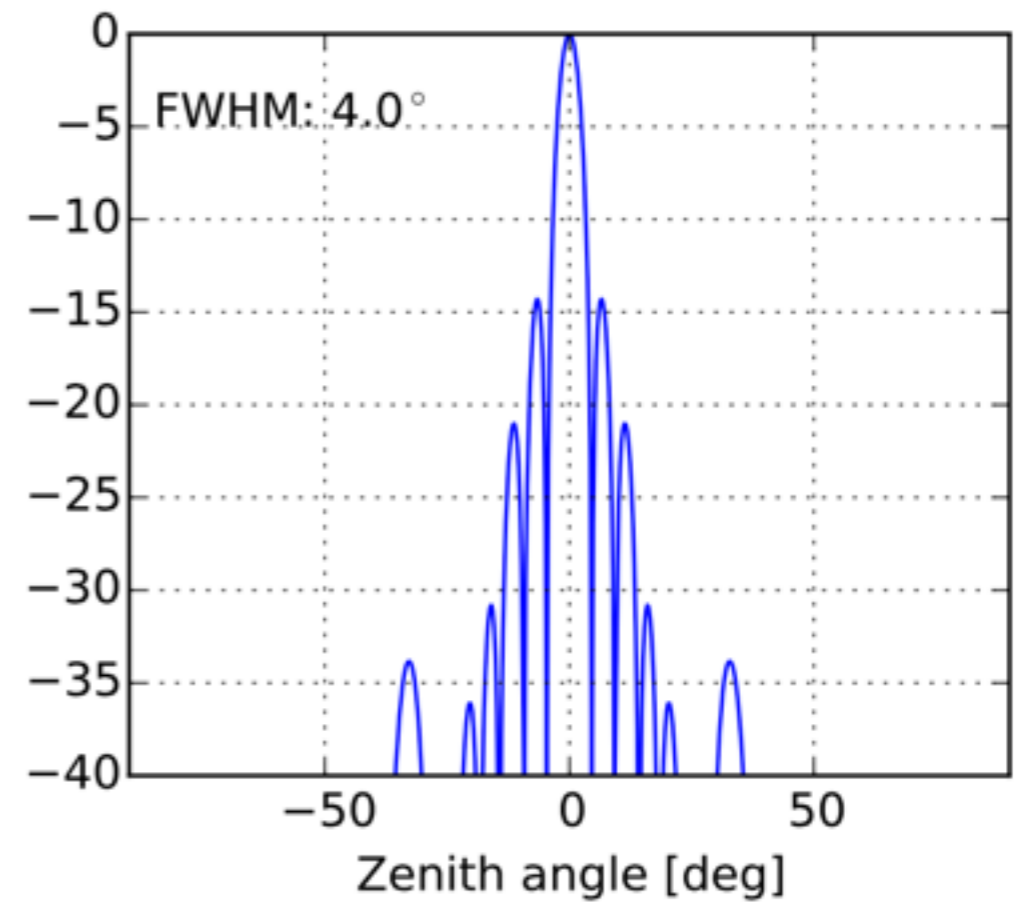
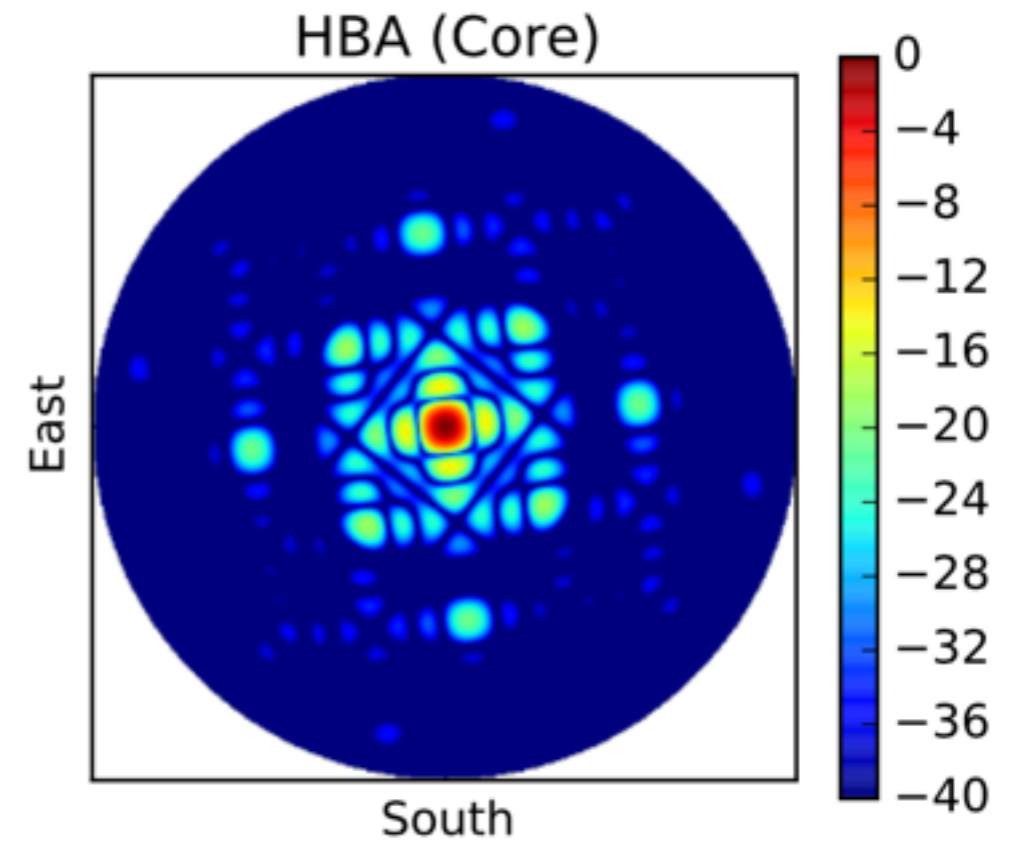
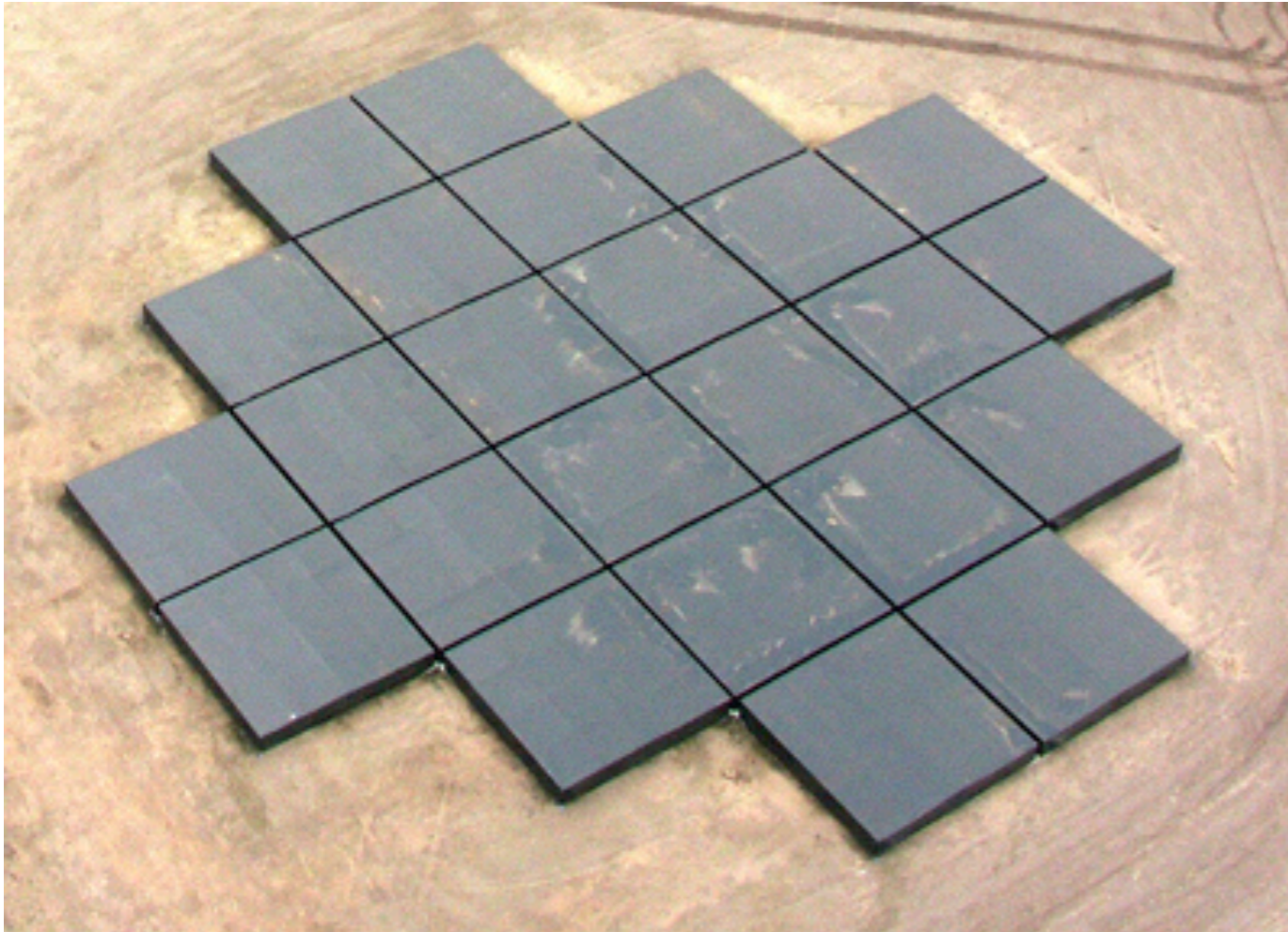
- Two antennas

- Three antennas

- Four antennas

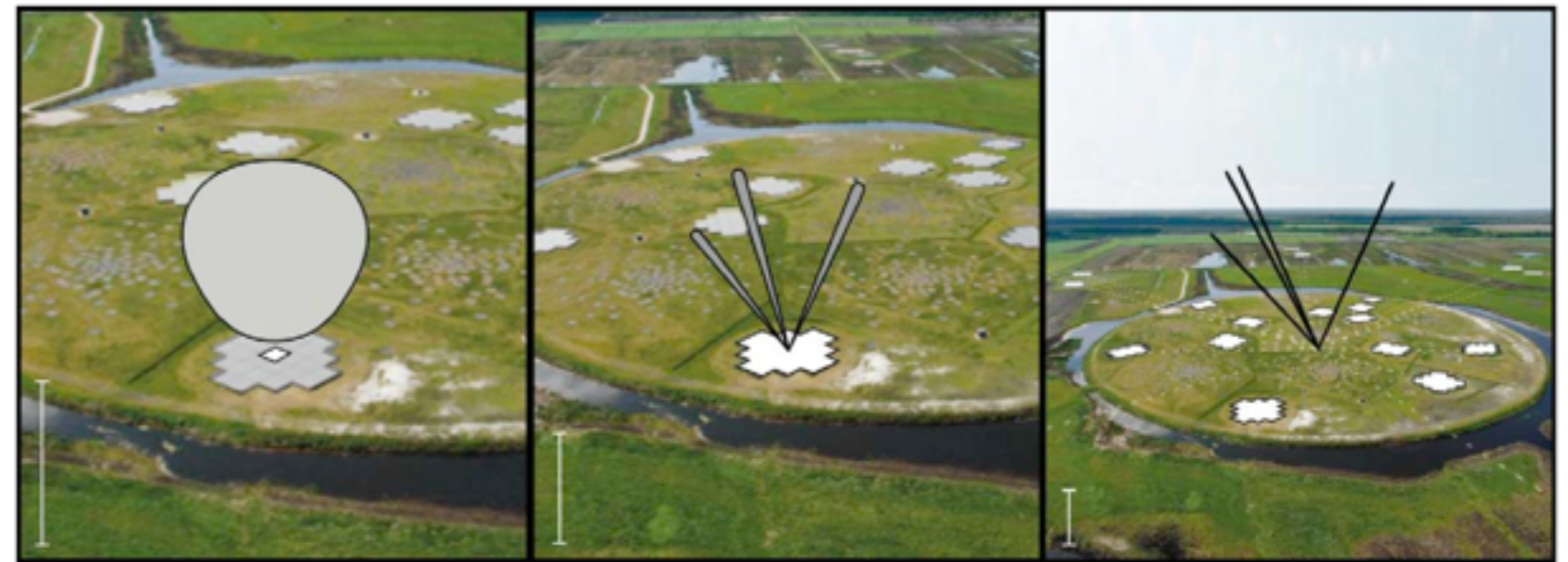
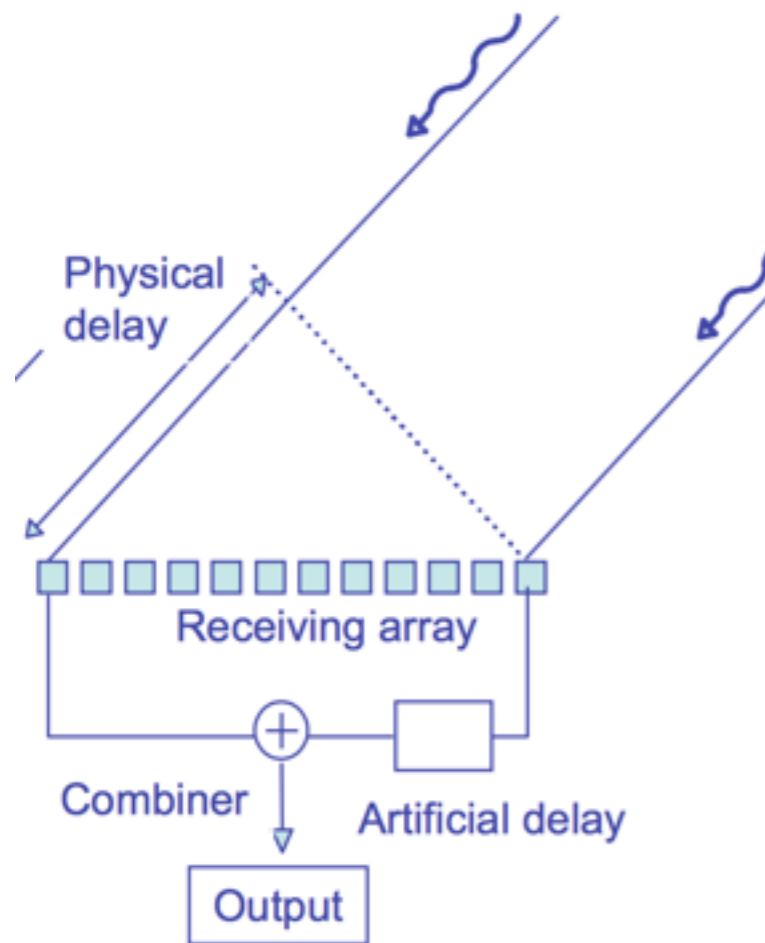
- Negative bowl around the centre is due to the lack of information at short spacings ( $b$  cannot be  $< D$ , the antenna diameter).

**Worked example:** The combined 24 tiles of a LOFAR High Band Antenna station (120-250 MHz) arranged in a regular grid.



## 3.6 Next generation interferometers

- We can also combine different antenna receiver elements together coherently to form an **aperture array** (e.g. LOFAR; MWA; LWA).



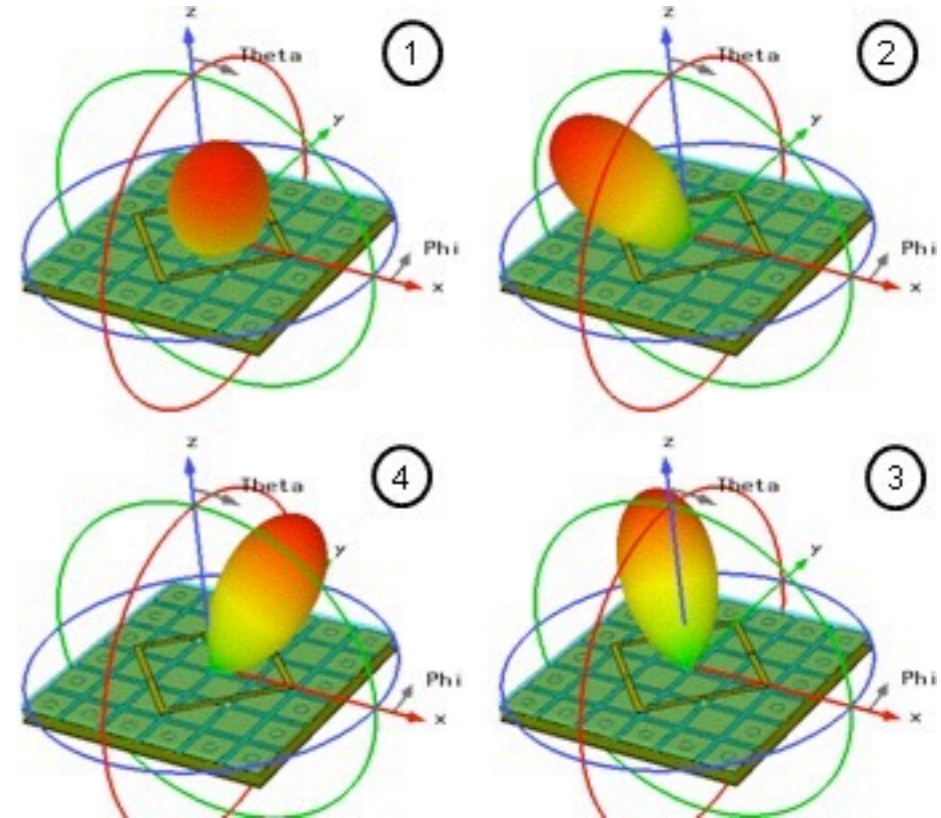
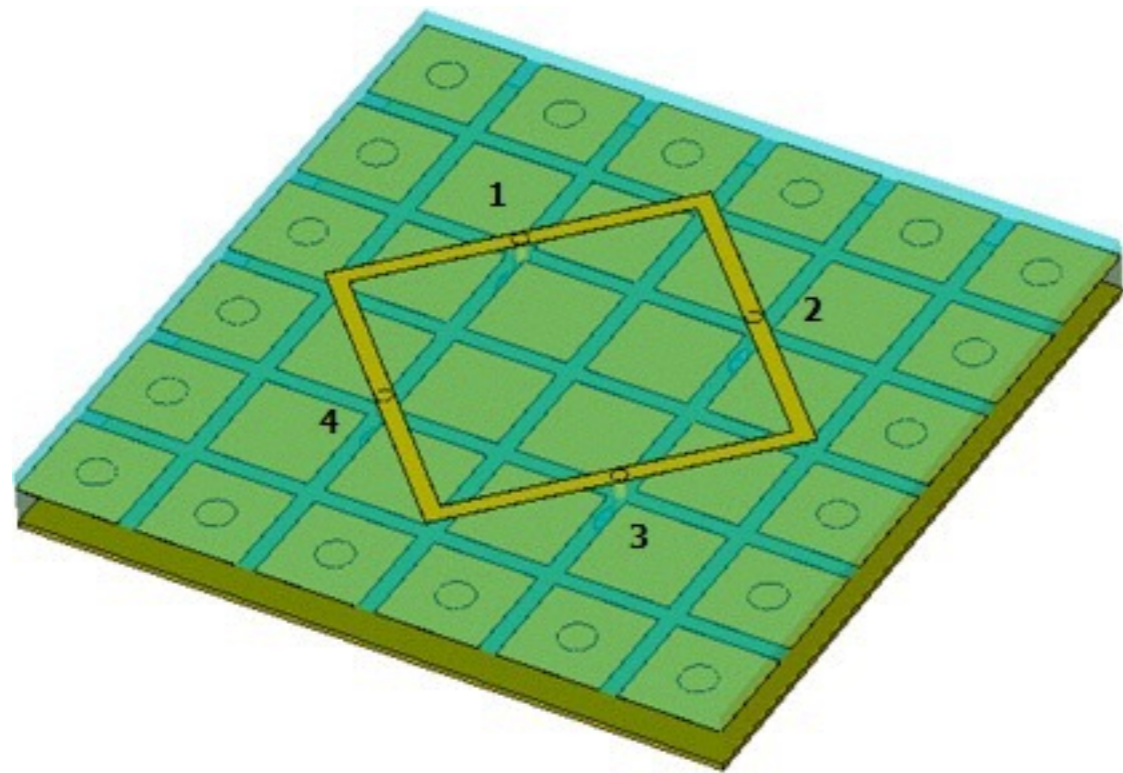
**Tile**

**Station**

**Core**

- Aperture array**: In the same way that an interferometer works, the receiving elements are added together by taking into account the **delay** due to the waves arriving at different times, from **different directions**.
  - Low cost (no moving parts, dipole elements).
  - Better effective area at low radio frequencies.
  - Large fields-of-view and flexible electronic beam forming.

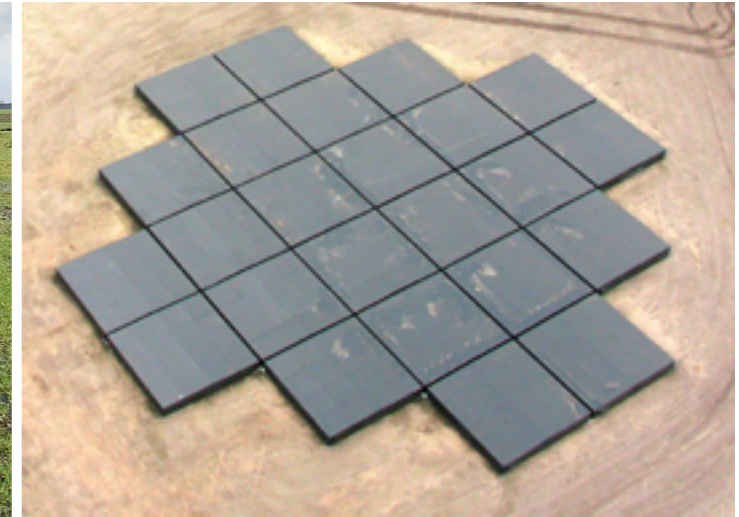
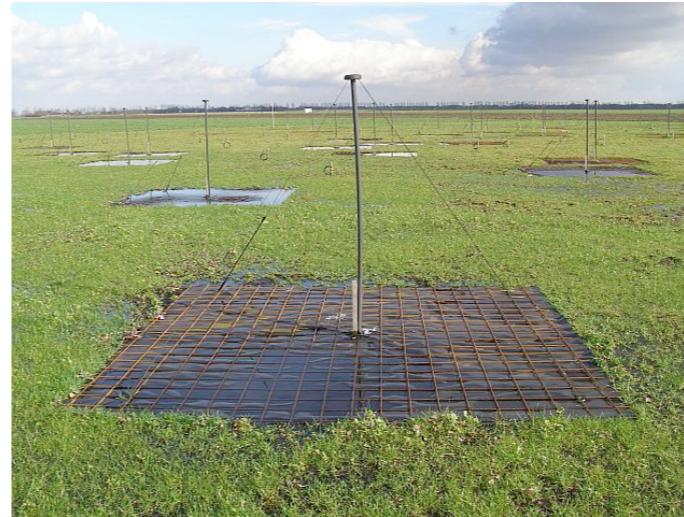






## 4.1 The Low Frequency Array

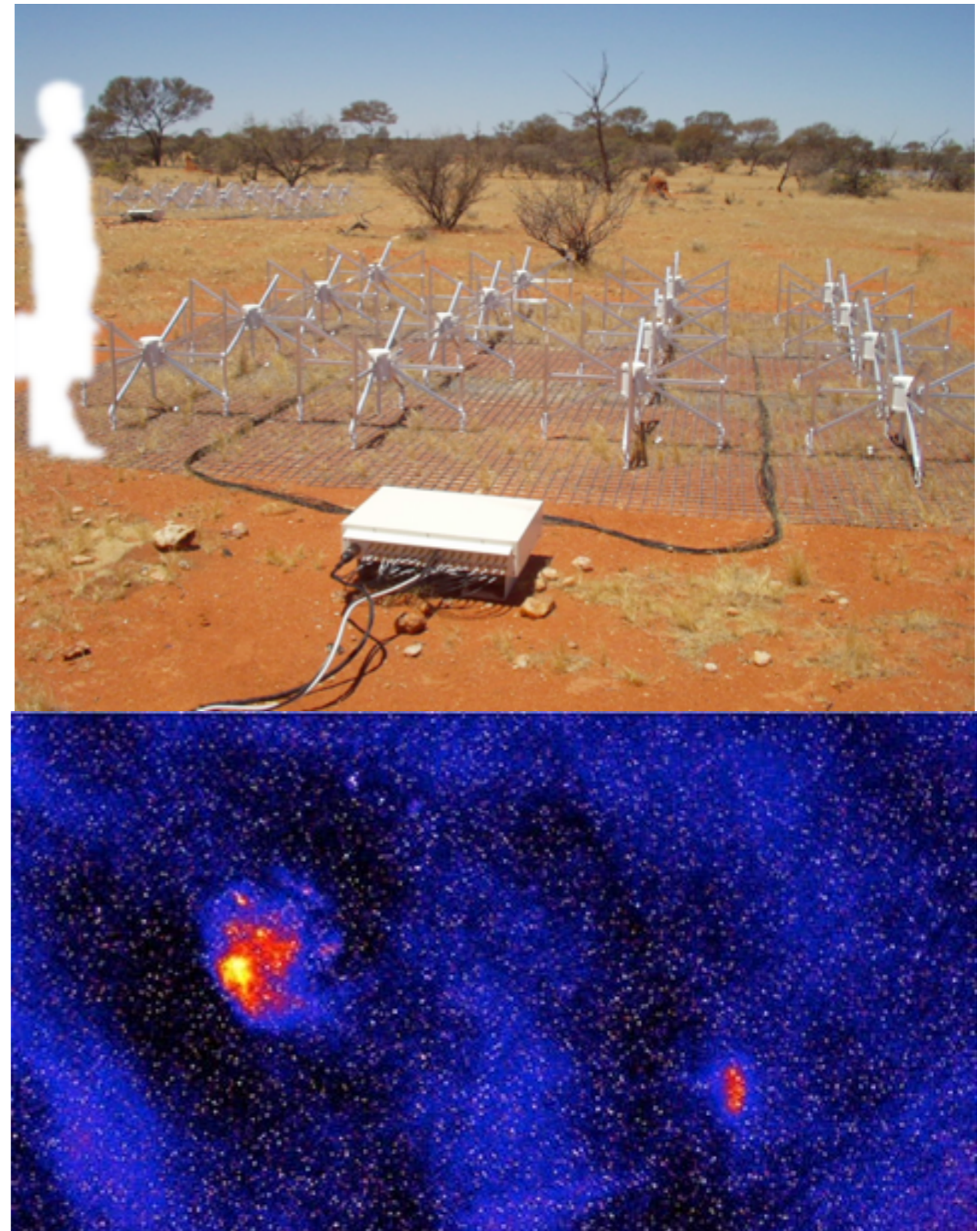
- International LOFAR Telescope being built by a consortium of institutes in the Netherlands, Germany, UK, France, Sweden, Poland and Ireland.
- Low Band Antenna (LBA; 10--90 MHz) - simple dipoles.
- High Band Antenna (110-180 MHz, 210-240 MHz) - tiled array.
- 96 MHz bandwidth.
- 50 Stations throughout Europe (~50 m to 1500 km baselines), resolution ~few degrees to sub-arcsec.





## 4.2 The Murchison Wide-Field Array

- Low frequency pathfinder based in Australia (quiet-site).
- 80--300 MHz frequency coverage, with 32 MHz instantaneous bandwidth.
- 128 tiles, with 4 x 4 dipoles (very like LOFAR).
- Max baseline to 3 km outriggers; most tiles (112) within 1.5 km.
- Wide field-of-view (15-45 degrees)
- Resolution of 2.5 to 8.5 arcmin





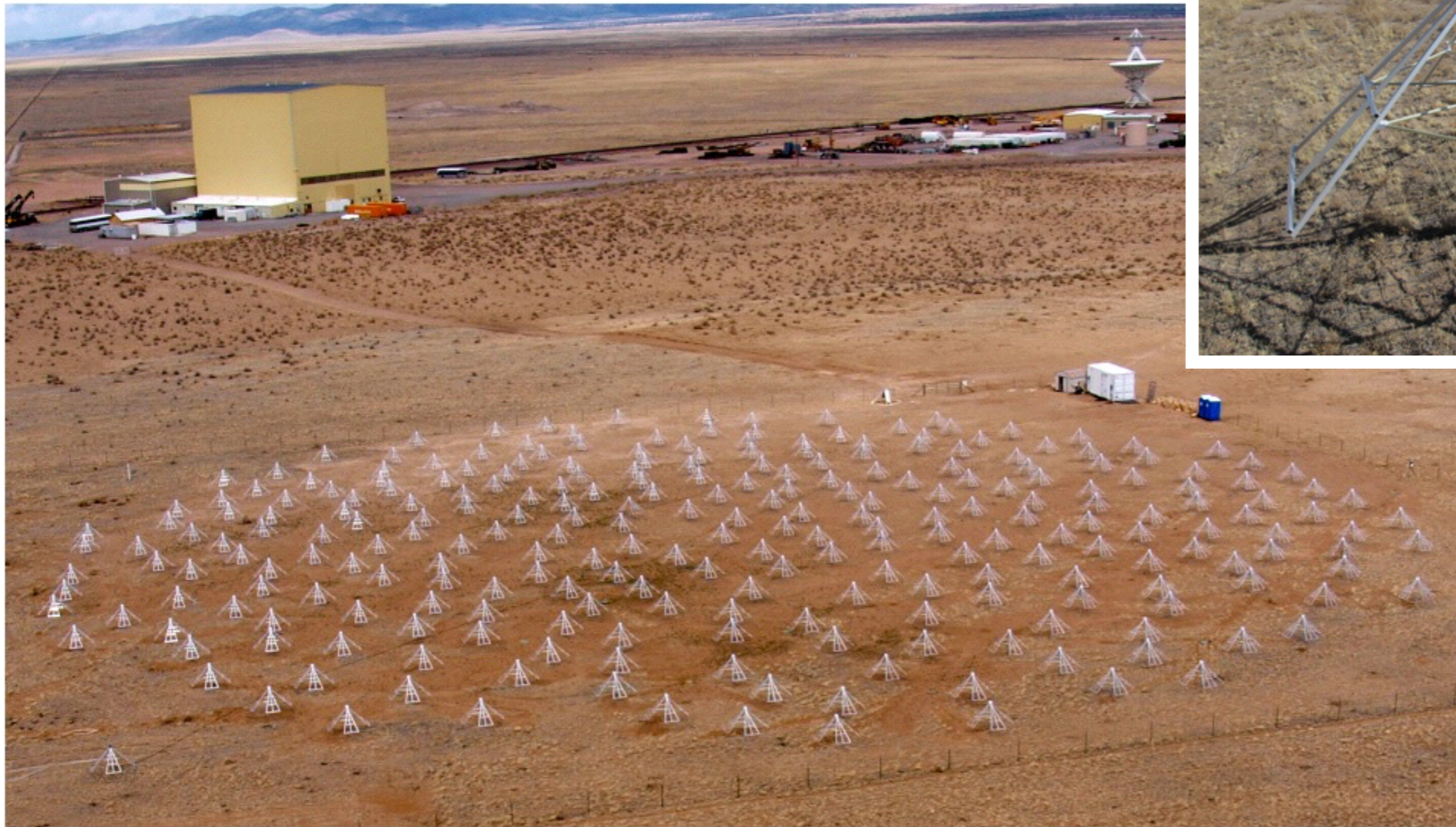
## 4.3 The Very Large Array

- Upgraded VLA, P-band (230-470 MHz).
- Receivers in place to sample down to 50 MHz.
- 27 x 25 m dish antennas with baselines up to 36 km in 4 configurations (A-D)





## 4.4 Long Wavelength Array



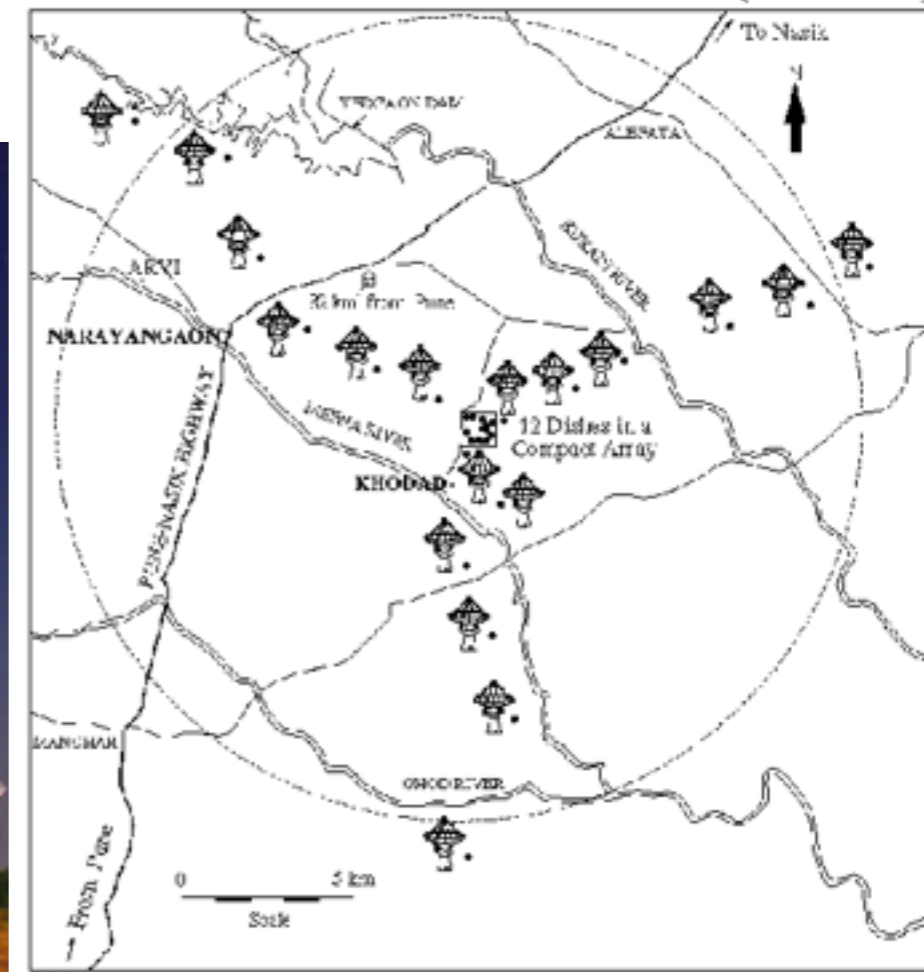
- 10-88 MHz; 4 simultaneous beam.
- LWA1 = 256 (+1) dual polarisation dipoles (100 x 110 m station)
- Full array; Ambitions to have baselines up to 400 km (~50 stations in NM; USA)
- LWA2 currently under construction (19 km baseline to LWA1)



## 4.5 Giant Metrewave Radio Telescope



LOCATIONS OF GMRT ANTENNAS ( 30 dishes )

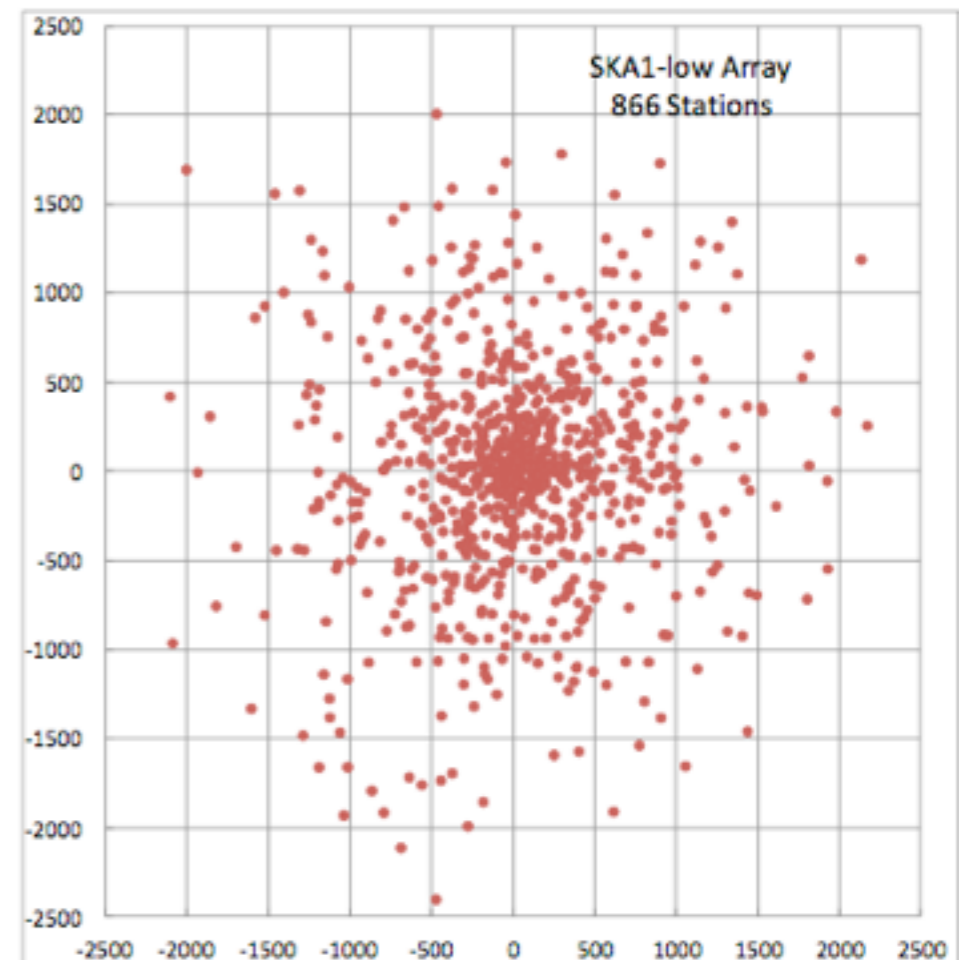
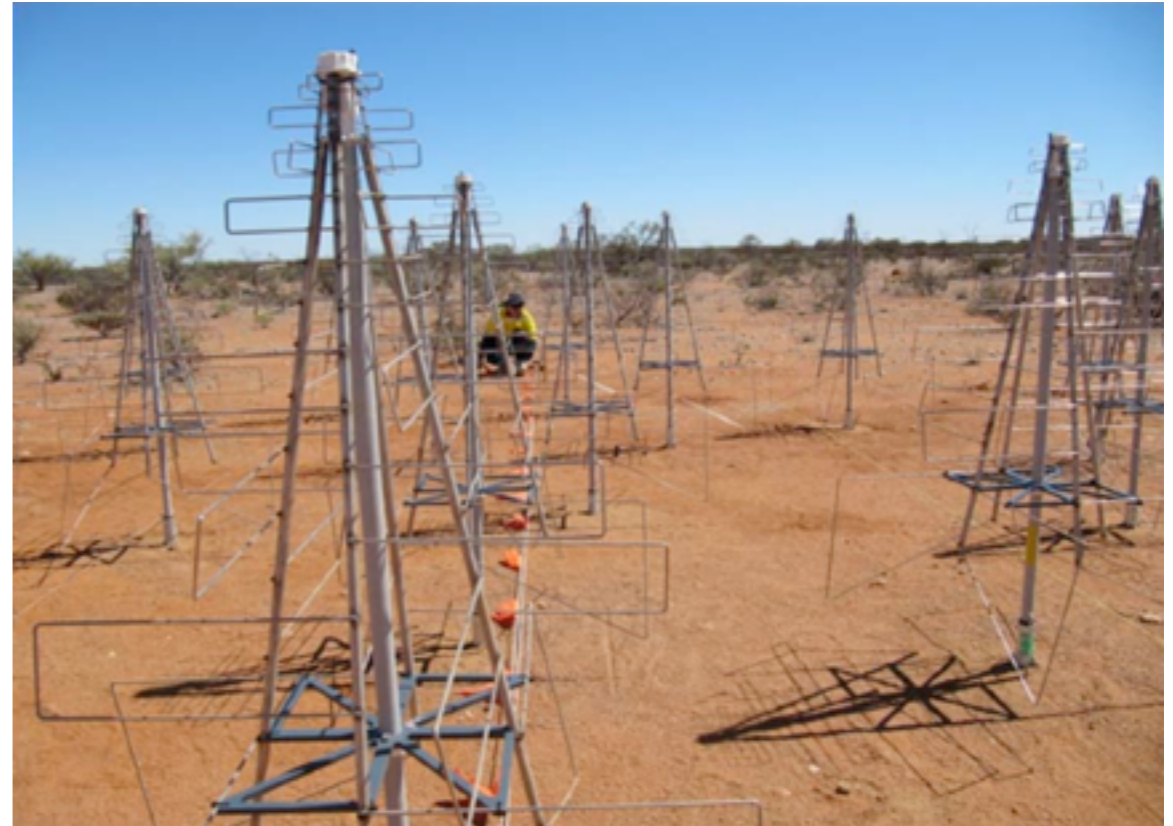


- Low frequency bands at 150, 235, 327 MHz (32 MHz bandwidth).
- 30 x 45 m antennas.
- Baselines up to 25 km
- Upgrade underway, providing contiguous 120–1500 MHz (400 MHz bandwidth).

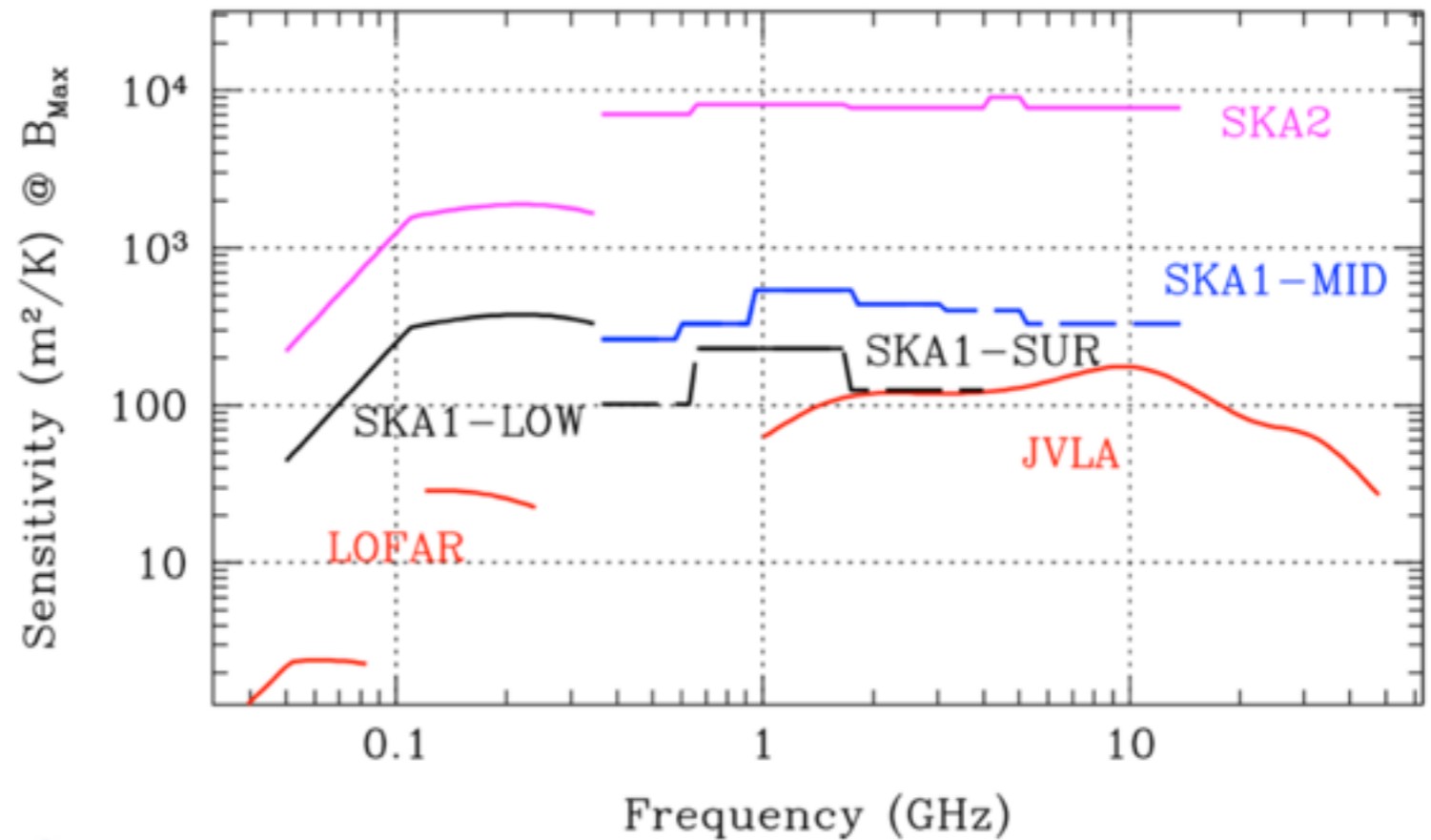
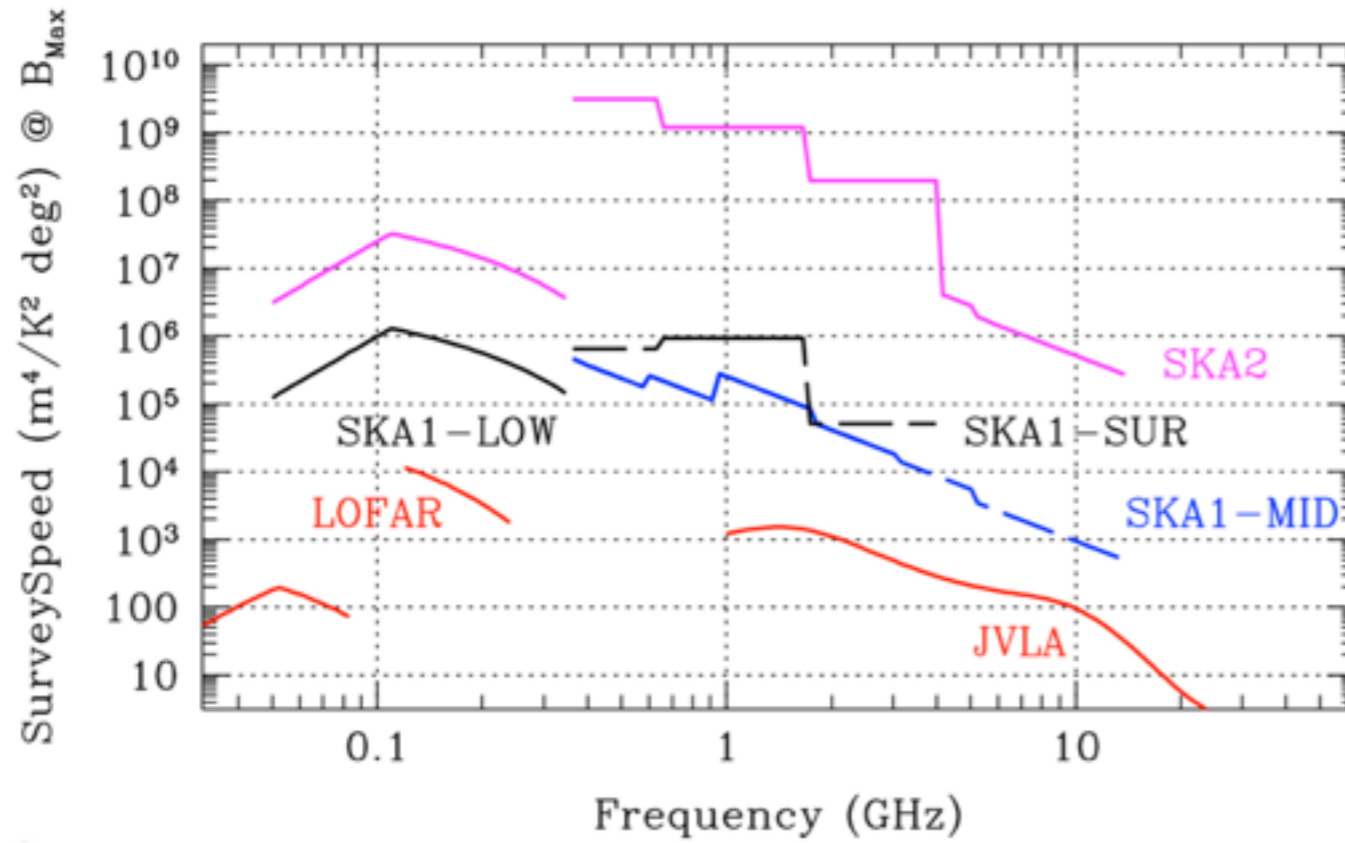


## 4.6 Square Kilometre Array (SKA)

- Sparse dipoles (dual pol; similar to LOFAR).
- Freq: 50 to 350 MHz (300 MHz bandwidth).
- 130000 dipole antennas.
- 8 x more sensitive than LOFAR
- 50% collecting area at  $< 600$  m, 75% at  $< 1$  km.
- Spiral arms out to 50 km (100 km baselines), containing only  $\sim 4\%$  of the collecting area.
- Dense core for EoR and Pulsar timing experiments (1 mK brightness temperature for 5 arcmin structures).
- $A_{\text{eff}} / T_{\text{sys}} \sim 1000 \text{ m}^2 / \text{K}$  ( $> 100$  MHz).



## 4.6 Square Kilometre Array (SKA)





# Summary

1. Radio astronomy had its origins at low frequencies, and after a successful diversion to higher frequencies, attention is returning to  $< 350$  MHz.
  - Modern dipoles still quite simple (cheap, easily replaced, large fields-of-view, large effective collecting area).
  - Need large computing power for correlation and data processing (see lecture on LOFAR Overview).
2. Interferometry is essential for competitive low frequency science.
  - Increases angular resolution and sensitivity at cost to filtering structure on large angular-scales and complicating the point-spread function.
  - Requires detailed calibration (see lectures on Calibration, Error Analysis and Ionosphere) and special wide-field, wide-bandwidth imaging techniques (see lectures on Imaging).
3. Several important low frequency radio telescopes available (LOFAR, LWA, GMRT, VLA, MWA) and upcoming (SKA).