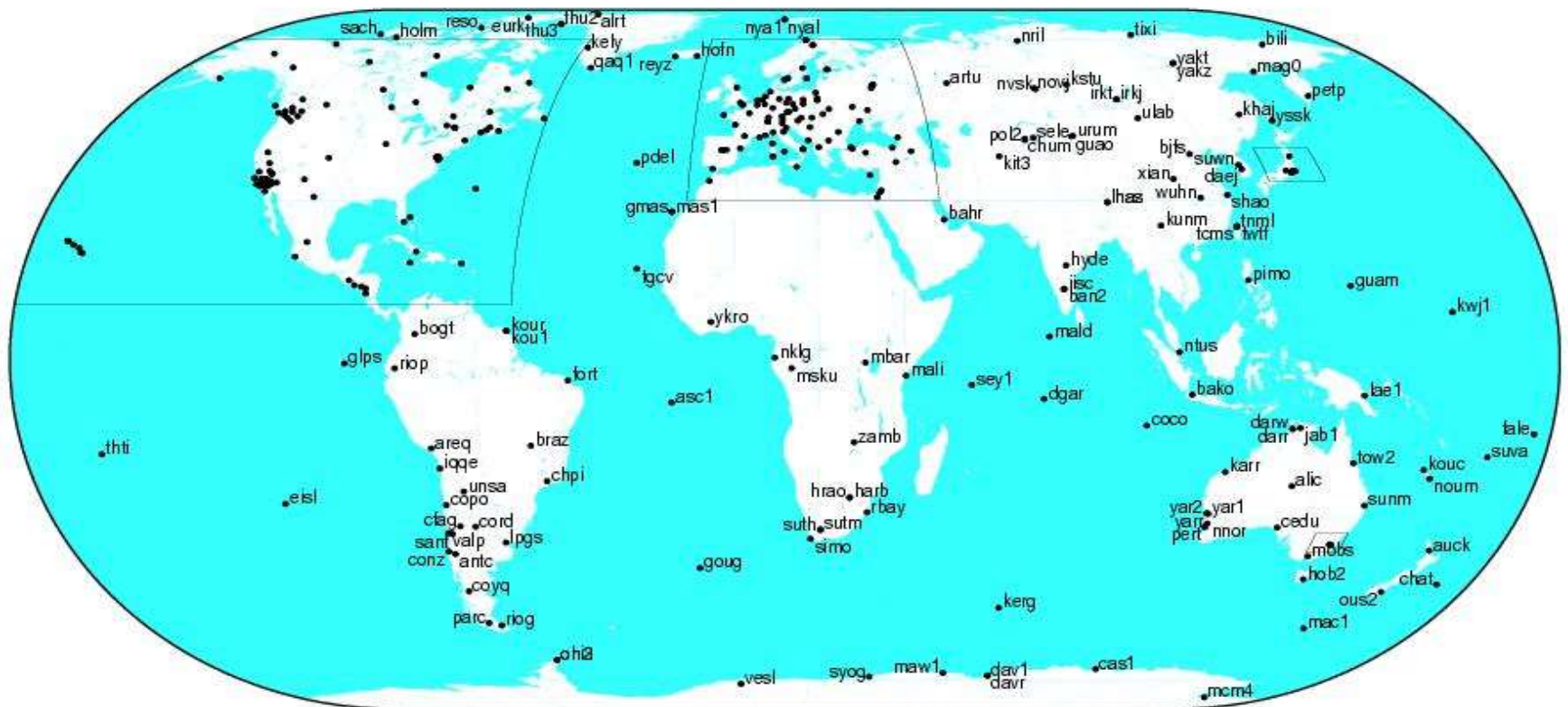


# IGS/UWM Ionosphere Combination and Validation Centre

**Andrzej Krankowski**

# International GNSS Service - IGS



GMT Jun 22 16:10:00 2003

**IGS directly manages ~400 permanent GNSS stations observing 4-12 satellites at 30 s rate: more than 250,000 STEC observations/hour worldwide, but there is lack of stations at some areas (e.g., over the oceans)**

# IGS IONO WG activities

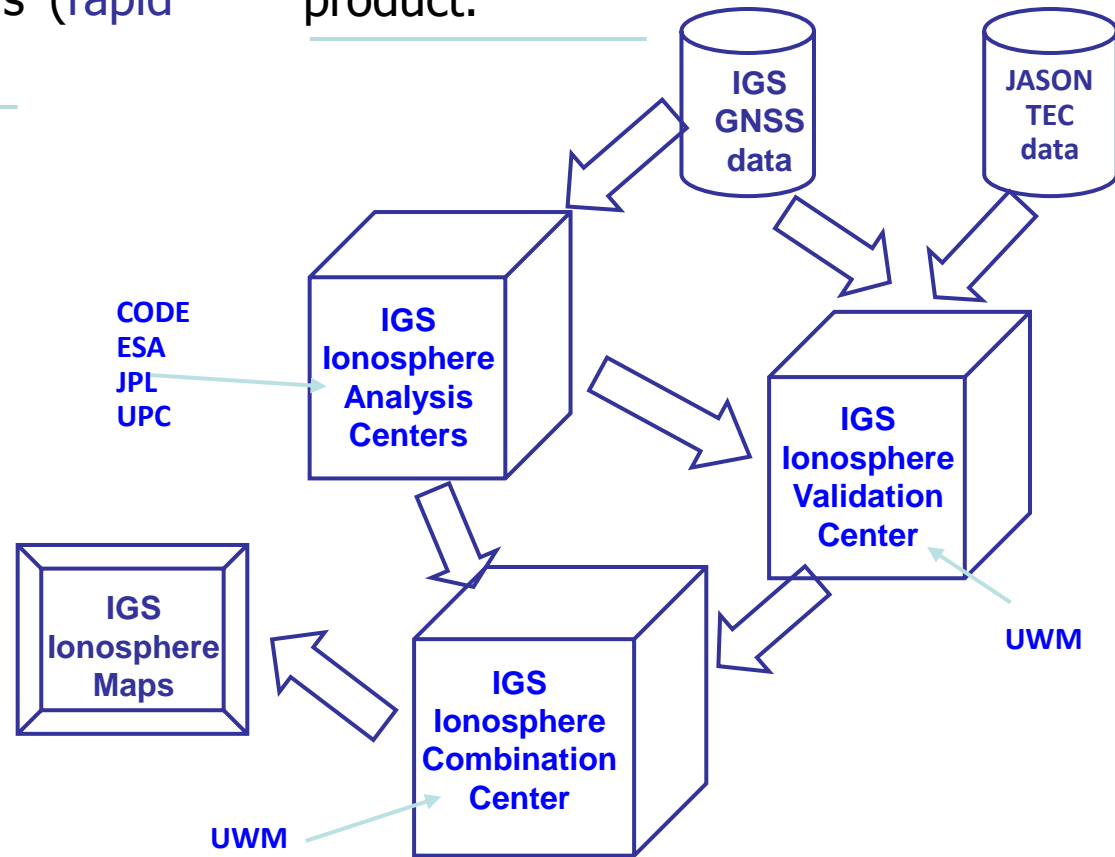
The IGS Ionosphere Working group started its activities in June 1998 with the main goal of a routinely producing IGS Global TEC maps.

This is being done now with a latency of 11 days (final product) and with a latency of less than 24 hours (rapid product).

The IGS ionosphere product is a result of the combination of TEC maps derived by different Analysis Centers by using weights computed by Validation Center, in order to get a more accurate product.

This has been done under the direct responsibility of the Iono-WG chairmans:

1. Dr Joachim Feltens, ESA 1998–2002,
2. Prof. Manuel Hernández-Pajares, UPC, 2002–2007
3. Prof. Andrzej Krankowski, UWM, 2008-





# IGS IONO WG activities

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## Products

- 1. final GIMs** (please note that GIMs also include GPS and GLONASS stations and satellites DCBs)
  - combination of CODE, ESA, JPL and UPC iono products conducted by UWM
  - temporal and spatial resolution - at 2 hours; 1 hour x 5 deg. x 2.5 deg (UTxLon.xLat.),
  - availability with a latency of 11 days

**UPC and ESA conduct test on 15-minute maps, which have been tested successfully in terms of accuracy and reliability.**

### 2. rapid GIMs

- combination of CODE, ESA, JPL and UPC iono products conducted by UWM
- temporal and spatial resolution - at 2 hours; 1 hour x 5 deg. x 2.5 deg (UTxLon.xLat.),
- availability with a latency of less than 12 hours.

**UPC and ESA conduct test on 15-minute maps, which have been tested successfully in terms of accuracy and reliability.**

### 3. predicted GIMs for 1 and 2 days ahead (pilot product)

- combination of ESA and UPC iono products conducted by ESA,
- temporal and spatial resolution - at 2 hours; 1 hour x 5 deg. x 2.5 deg (UTxLon.xLat.),

# The IONEX format body

The **IONEX** (IONosphere inter EXchange) format allows to store the VTEC and its error estimates in a grid format.

```

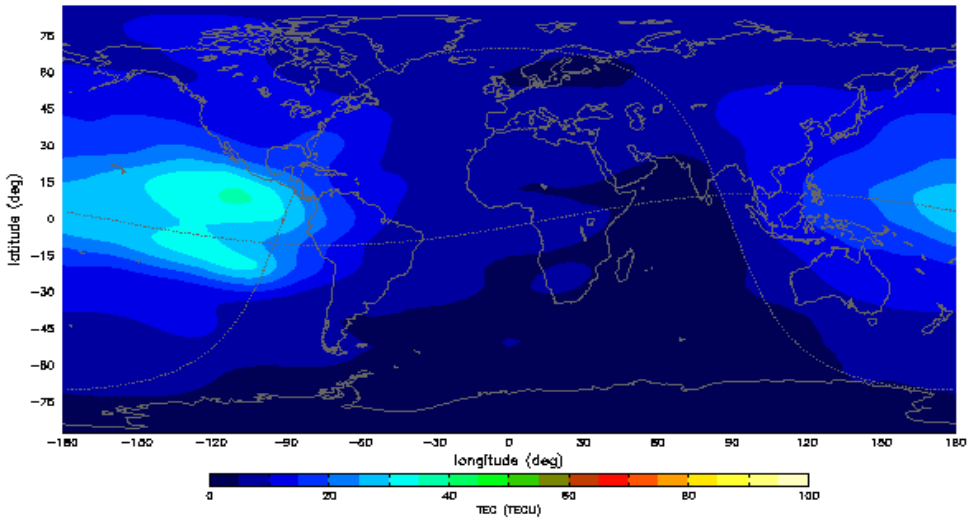
1
2004      4      27      0      0      0
87.5-180.0 180.0      5.0 450.0
123 123 123 124 125 125 126 126 126 126 126 126 125 125 125 128
125 125 125 126 126 125 124 124 124 124 124 124 123 123 122 122 121
120 120 119 118 118 118 118 118 117 117 116 116 115 114 114 113
113 113 114 114 114 114 115 115 115 116 116 116 117 117 118 119 120
120 121 121 122 123 123 123 123 123
85.0-180.0 180.0      5.0 450.0
29 129 130 131 132 132 133 133 134 134 134 134 134 134 134 136
35 136 130 129 129 129 128 128 128 127 126 124 123 122 121 120
19 118 117 117 117 117 116 116 115 115 114 113 112 111 110 109
09 110 109 109 109 110 111 111 112 112 113 113 115 116 117 118
20 122 123 125 126 127 128 129 129
-87.5-180.0 180.0      5.0 450.0
87 88 88 90 90 91 92 93 93 94 94 95 94 93 91 89
87 86 85 84 83 82 81 81 80 80 79 78 78 78 77 77
76 76 76 75 75 76 77 77 76 79 79 79 80 81 82 83
83 84 85 85 85 85 85 85 85 86 87 87 87 88 88 87
87 87 87 88 87 87 87 87 87
1
2
...
...
13
1
2004      4      27      0      0      0
87.5-180.0 180.0      5.0 450.0
7 7 7 7 7 7 7 7 7 7 8 8 9 9 9 6
8 8 8 6 6 7 7 7 7 6 6 6 6 6 6 6
6 6 7 7 7 6 7 6 6 7 7 7 7 8 8 9
10 9 8 8 8 8 7 7 8 8 8 8 7 7 7 7
7 6 6 7 6 7 6 6 7
...
13
END OF TEC MAP
START OF TEC MAP
END OF TEC MAP
START OF RMS MAP
EPOCH OF CURRENT MAP
LAT/LON1/LON2/DLON/H
END OF RMS MAP
END OF FILE

```

# Example of IGS Final GIM: 2010-141 DOY

## TEC map

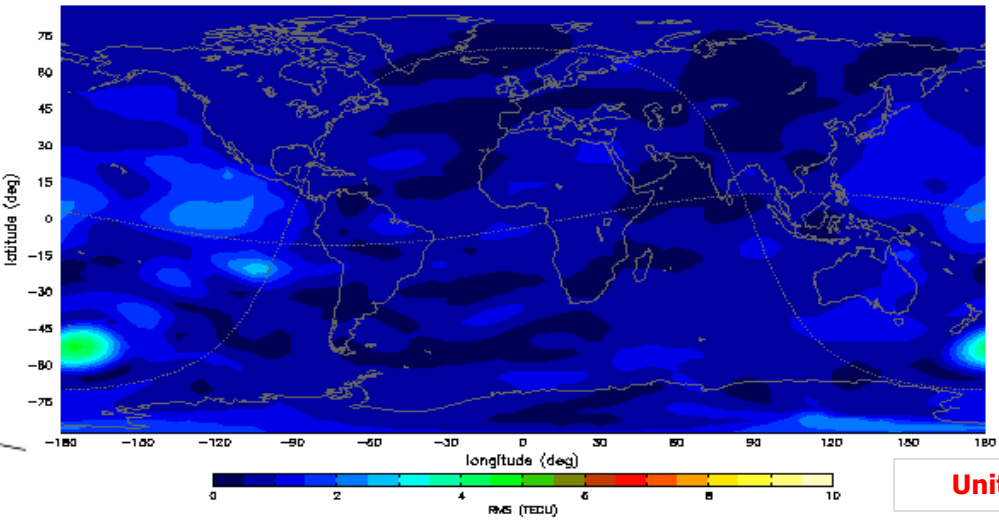
TEC MAP (height= 450.0 km) at 2010/05/21,00:00:00  
IONEX file containing the COMBINED IGS TEC MAPS and DCBs



**4 Analysis Centers (CODE, ESA, JPL, and UPC) and a Validation Center (UPC) have been providing maps (at 1 hours x 5 deg. x 2.5 deg in UT x Lon. x Lat.), weights and external (altimetry-derived) TEC data.**

## RMS map

RMS MAP (height= 450.0 km) at 2010/05/21,00:00:00  
IONEX file containing the COMBINED IGS TEC MAPS and DCBs



**From such maps and weights the Combination Center (at first ESA, then UPC, and since 2008 - UWM) has produced the IGS TEC maps in IONEX format.**

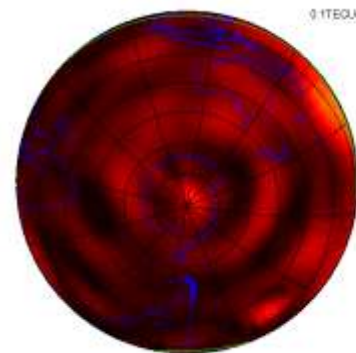
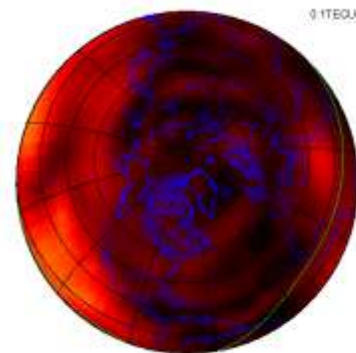
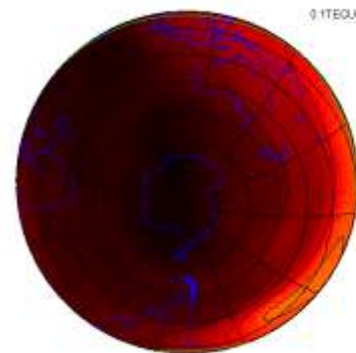
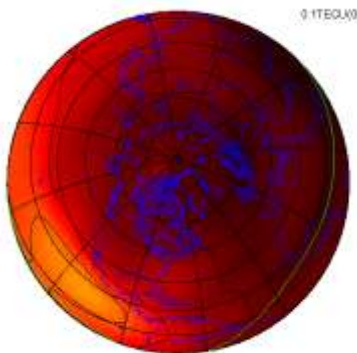
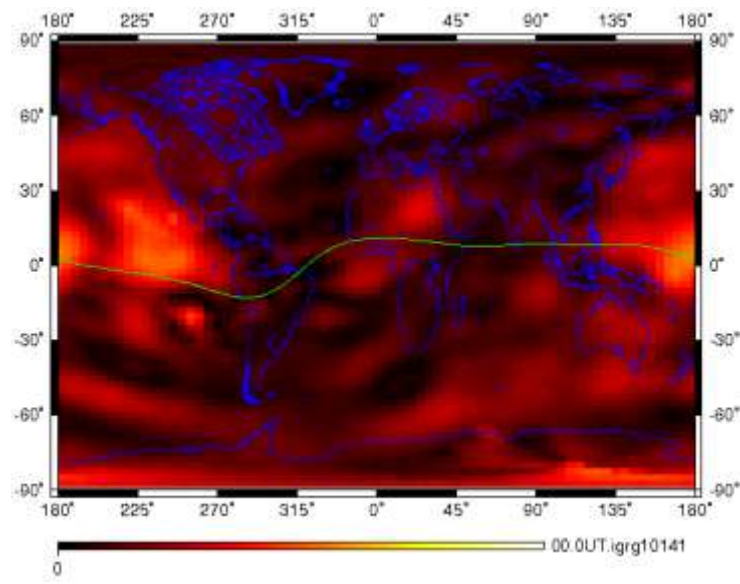
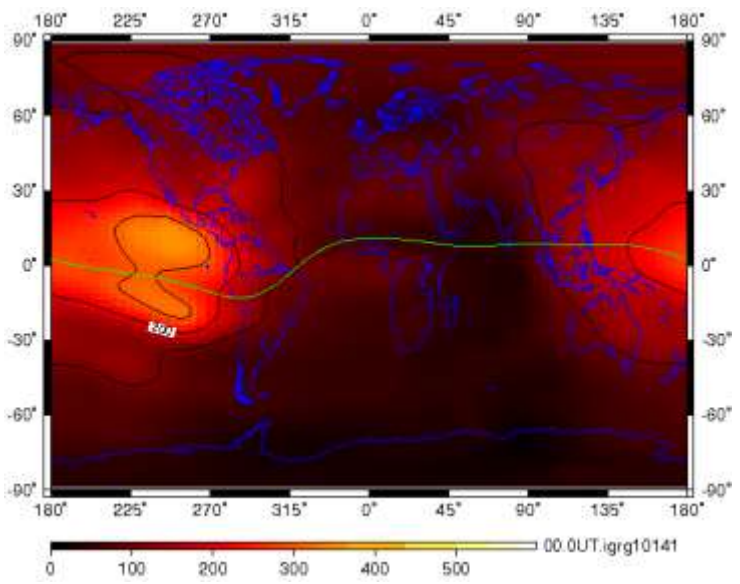
**Units: TECU**

# Example of IGS RAPID GIM: 2010-141 DOY

SPACE RADIO-DIAGNOSTICS RESEARCH CENTRE (SRRC/UWM)  
IGS IONOSPHERE WORKING GROUP

**TEC maps**

**RMS maps**

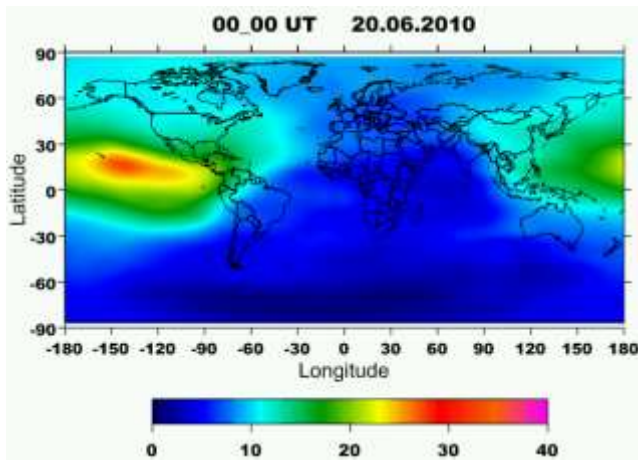


**Units: 0.1 TECUs**

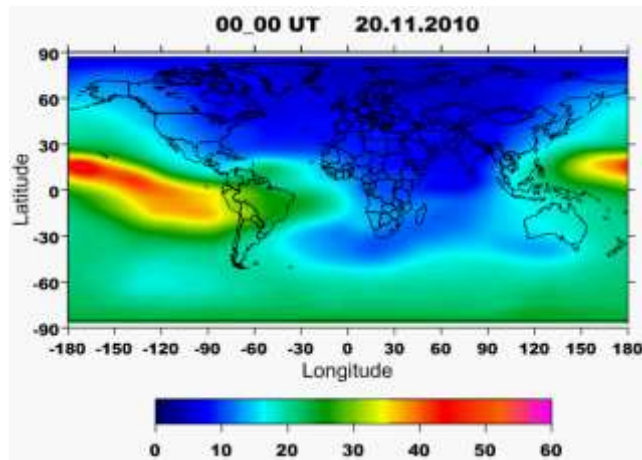
# Example of IGS PREDICTED GIM

## IGS Predicted GIM

June 20, 2010

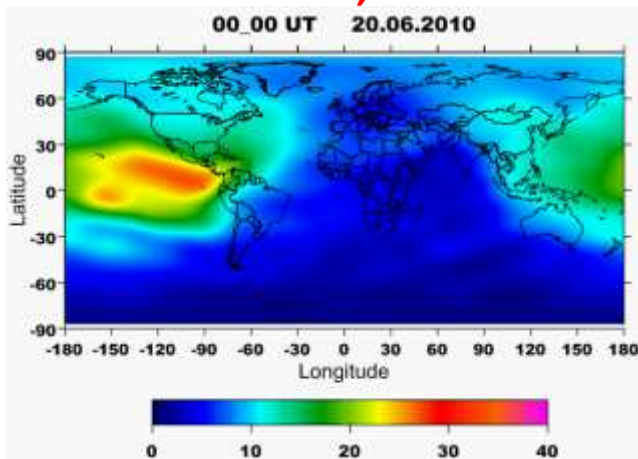


November 20, 2010

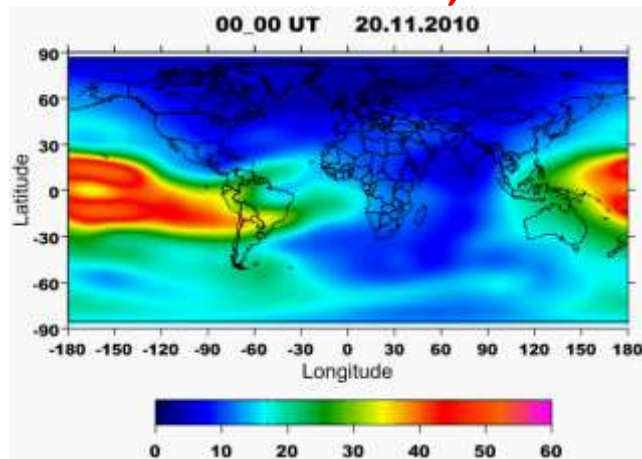


## IGS Final GIM

June 20, 2010



November 20, 2010





# Current updates and future plans of IGS IWG

**The following actions to be considered:**

**- Higher temporal resolution - 15 min**

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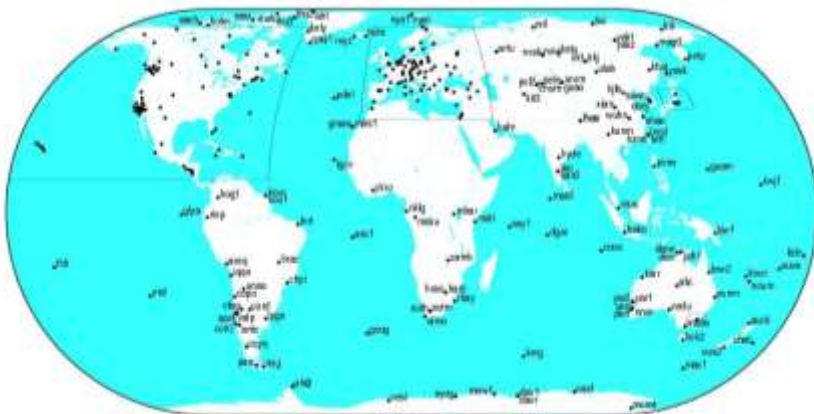
- **New IGS Ionosphere Associate Analysis Centers (IAACs) (from January 2015)**
  - **Natural Resources Canada (NRCan)**
  - **Institute of Geodesy and Geophysics, Chinese Academy of Sciences, Wuhan, China**
  - **Wuhan University, China**

# Recommendations after 2016 IGS Workshop Ionosphere Working Group

**Starting a new official/operational product – TEC fluctuation changes over North Pole to study the dynamic of oval irregularities (carried out by UWM)**

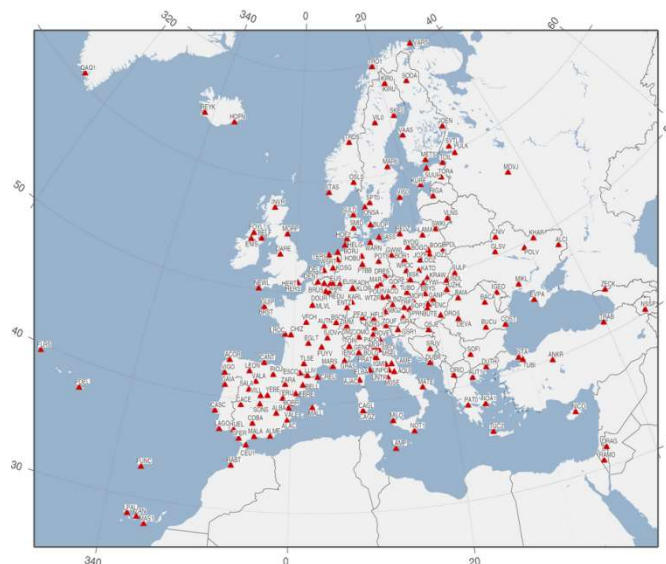
# GNSS networks

SPACE RADIO-DIAGNOSTICS RESEARCH CENTRE (SRRC/UWM)  
IGS IONOSPHERE WORKING GROUP

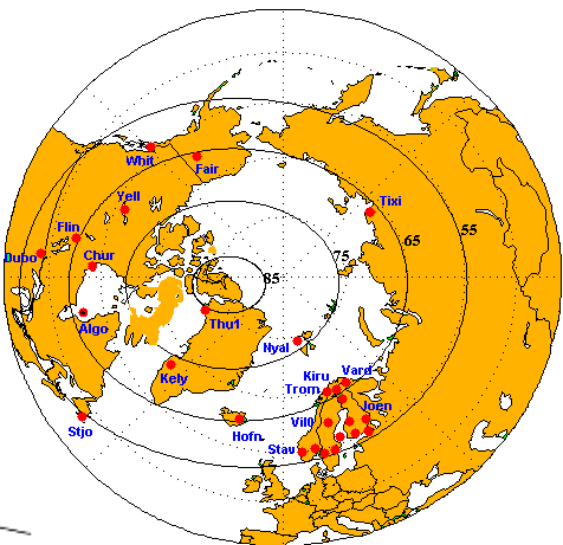


International GNSS Service - IGS

EUREF Permanent Tracking Network



IGS/EPN (EUREF Permanent Tracking Network)



IGS polar stations



IGS Antarctic stations



PBO Network – Plate Boundary Observatory  
POLENET - The Polar Earth Observing Network

# Monitoring of the TEC fluctuations using GNSS data

## High latitude TEC fluctuations

For detecting of the phase fluctuation occurrence the Rate of TEC (dTEC/dt) is more preferred (Wanninger, 1993):

$$ROT = 9.52 \cdot 10^{16} \text{ el/m} \cdot (\Delta\Phi_i - \Delta\Phi_k)$$

$\Delta\Phi_{ki}$  - differential carrier phase sample with 30 sec interval

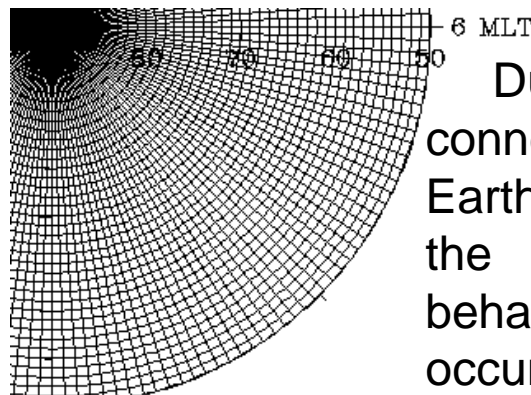
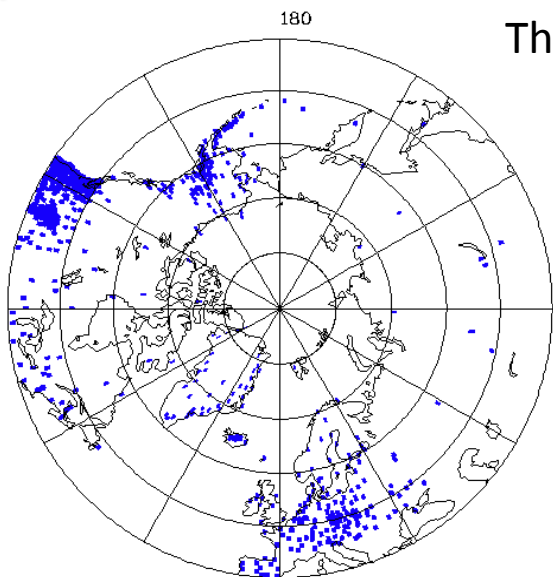
$$\Delta t = t_k - t_i = 1 \text{ min.}$$

As a measure of ionospheric activity we used also the Rate of TEC Index (ROTI) based on standard deviation of ROT (for 5 minut intervals), proposed by Pi et al, 1997:

$$ROTI = \sqrt{\langle ROT^2 \rangle - \langle ROT \rangle^2}$$

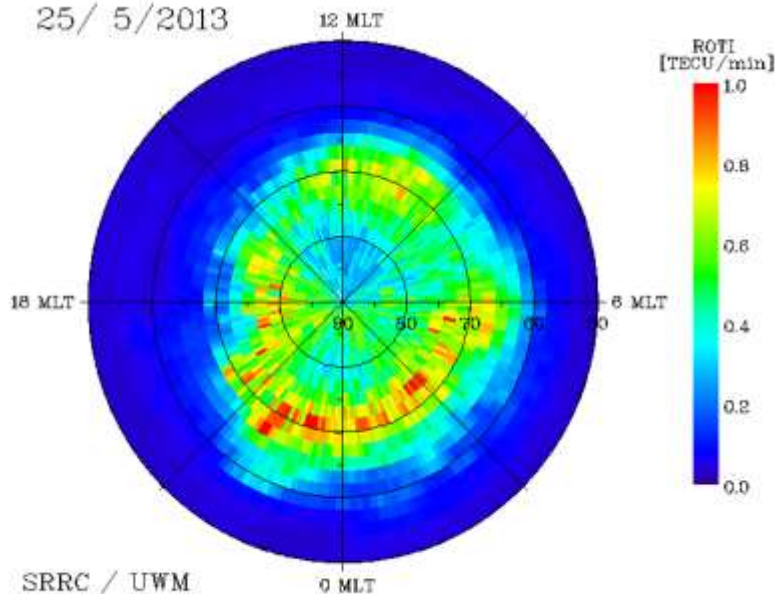
# TEC fluctuation service for creating ROTI maps

The locations of the stations in the North Hemisphere used for ROTI map construction



Due to strong connections between the Earth's magnetic field and the ionosphere, the behavior of the fluctuation occurrence is represented as a function of the magnetic local time (MLT) and of the corrected magnetic latitude. The grid of ROTI maps in polar coordinates with cell size 2 degree (magnetic local time) and 2 degree (geomagnetic latitude).

25 / 5 / 2013



SRRC / UWM

0 MLT

Each map, as a daily map, demonstrates ROTI variation with geomagnetic local time (00-24 MLT).

In the updated version more than 700 permanent stations (from IGS, UNAVCO and EUREF databases) have been involved into processing for the ionosphere fluctuation service. Such number of stations provides enough data for representation a detailed structure of the ionospheric irregularities pattern.

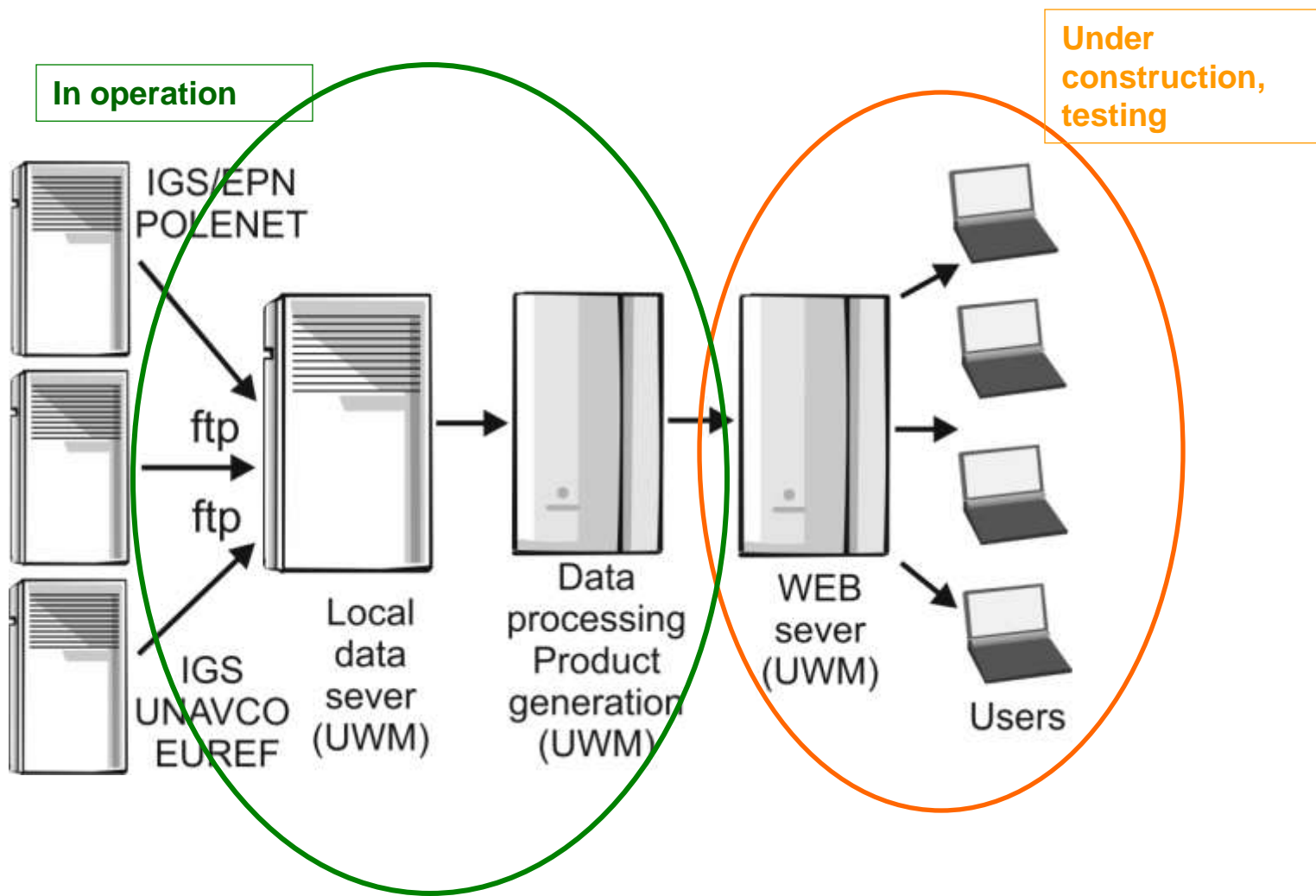
## The proposed format to store the ROTI values

For ROTI data storing it is proposed simple ASCII format based on grid 2 x 2 degree - geomagnetic latitude from 89o to 51o with step 2 and corresponded to magnetic local time (00-24 MLT) polar coordinates from 0 to 360.

	89	87	85	83	81	79	77	75	73	71	69	67	65	63	61	59	57	55	53	51
1	0.2959	0.4422	0.465	0.311	0.3678	0.4486	0.3578	0.3835	0.4148	0.3314	0.3425	0.126	0.0913	0.032	0.0351	0.0331	0.036	0.0372	0.0382	0.0336
3	0.2927	0.4224	0.3924	0.3731	0.4034	0.4608	0.3389	0.4352	0.4048	0.2986	0.248	0.1268	0.1171	0.0378	0.0352	0.0335	0.0346	0.0343	0.0396	0.0335
5	0.2792	0.394	0.3942	0.4697	0.3284	0.4379	0.3944	0.465	0.3843	0.2807	0.2481	0.1496	0.1099	0.0438	0.0323	0.0327	0.0355	0.0367	0.0374	0.0336
7	0.2609	0.4365	0.3266	0.3829	0.4267	0.5317	0.4661	0.4689	0.3635	0.3103	0.2117	0.1402	0.0725	0.0444	0.0335	0.0344	0.0363	0.0382	0.0357	0.034
9	0.4455	0.4226	0.3477	0.4237	0.4313	0.5694	0.5135	0.3641	0.4155	0.2923	0.2217	0.1319	0.0794	0.0449	0.0369	0.0335	0.0385	0.0396	0.0383	0.0358
11	0.5008	0.4245	0.4262	0.3578	0.3814	0.5214	0.5073	0.3896	0.3925	0.3136	0.2374	0.1492	0.08	0.0393	0.0322	0.033	0.0367	0.0411	0.0384	0.0389
13	0.3294	0.3593	0.4965	0.3778	0.4072	0.7487	0.5215	0.3219	0.3607	0.3442	0.2959	0.1609	0.0808	0.0463	0.0344	0.0292	0.0343	0.0422	0.0377	0.038
15	0.3004	0.3847	0.4443	0.3325	0.3606	0.6081	0.3513	0.3715	0.368	0.307	0.2705	0.1739	0.068	0.0364	0.0365	0.0293	0.0342	0.0416	0.0397	0.0401
.....																				
.....																				
345	0.3648	0.6725	0.3646	0.4227	0.4633	0.4701	0.568	0.433	0.3694	0.3681	0.2091	0.1214	0.0726	0.0373	0.0385	0.0391	0.0347	0.0342	0.0352	0.0336
347	0.3667	0.4735	0.3784	0.3845	0.5204	0.5891	0.5423	0.434	0.4858	0.3508	0.2132	0.1101	0.0882	0.0437	0.0373	0.0412	0.0361	0.0345	0.0343	0.0345
349	0.3688	0.5449	0.4021	0.3499	0.5294	0.6081	0.578	0.4124	0.4193	0.3378	0.2235	0.1295	0.0939	0.0418	0.0367	0.0369	0.0379	0.0346	0.0334	0.036
351	0.4049	0.5729	0.4159	0.3901	0.4119	0.5135	0.4602	0.4285	0.4767	0.3112	0.2217	0.1312	0.0837	0.0399	0.0355	0.034	0.0536	0.035	0.0328	0.0325
353	0.3524	0.389	0.4495	0.3115	0.5101	0.5135	0.4072	0.4766	0.5348	0.282	0.2186	0.1162	0.0782	0.0412	0.0342	0.0314	0.0545	0.0372	0.0326	0.0339
355	0.297	0.3992	0.3368	0.3606	0.5323	0.4776	0.367	0.4452	0.5001	0.336	0.282	0.1088	0.0834	0.0404	0.0327	0.0321	0.0391	0.0441	0.0323	0.0352
357	0.2614	0.4348	0.31	0.4465	0.3972	0.4235	0.3796	0.3958	0.44	0.3829	0.3155	0.1115	0.0709	0.0361	0.033	0.0318	0.0408	0.0397	0.0382	0.0367
359	0.2838	0.3851	0.3392	0.4338	0.4432	0.3893	0.323	0.3949	0.4581	0.3688	0.3274	0.147	0.0744	0.0332	0.0331	0.0338	0.0365	0.0378	0.0377	0.0364

The sample of ROTI-ex format body

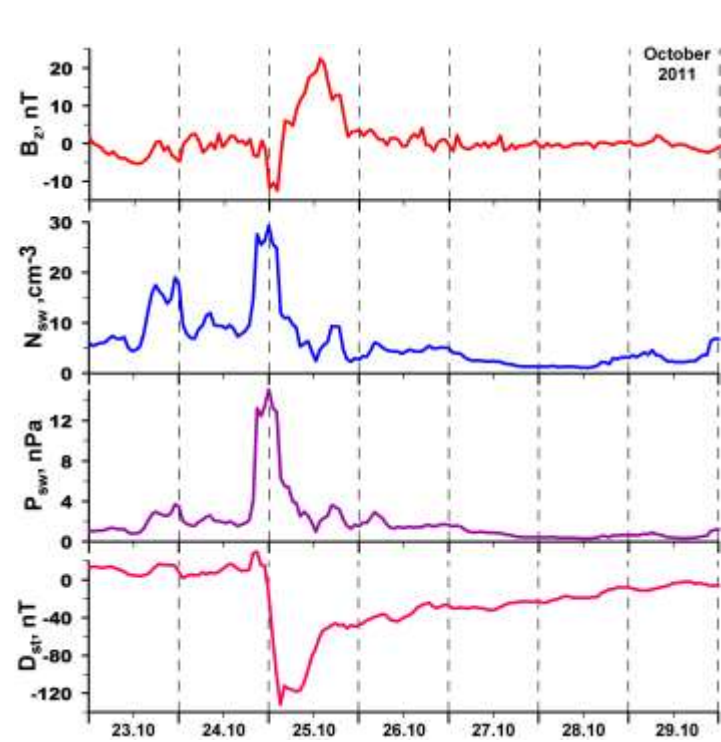
# TEC fluctuation service for creating ROTI maps



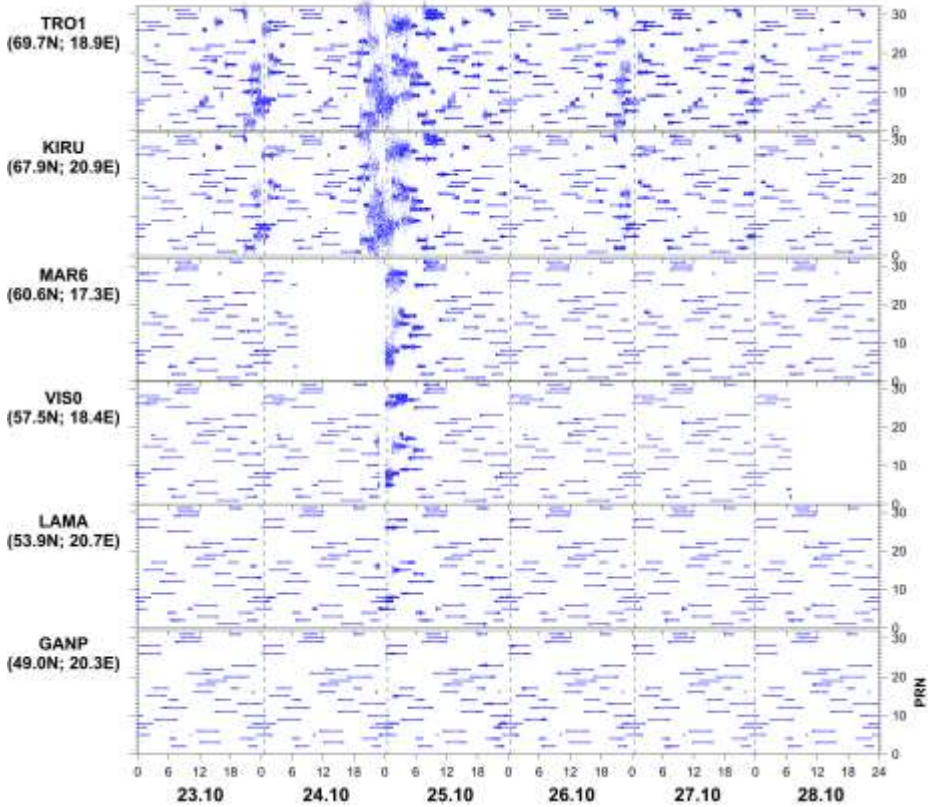
The TEC fluctuation service operation diagram and status

# Ionospheric irregularities observed using GNSS networks: case study

Variability of ROT values over chain of selected European GNSS stations  
Geomagnetic storm 23 -29 October 2011.



The interplanetary geomagnetic field  $B_z$  component, density and pressure of solar wind and Dst index variations for 23 -29 October 2011.



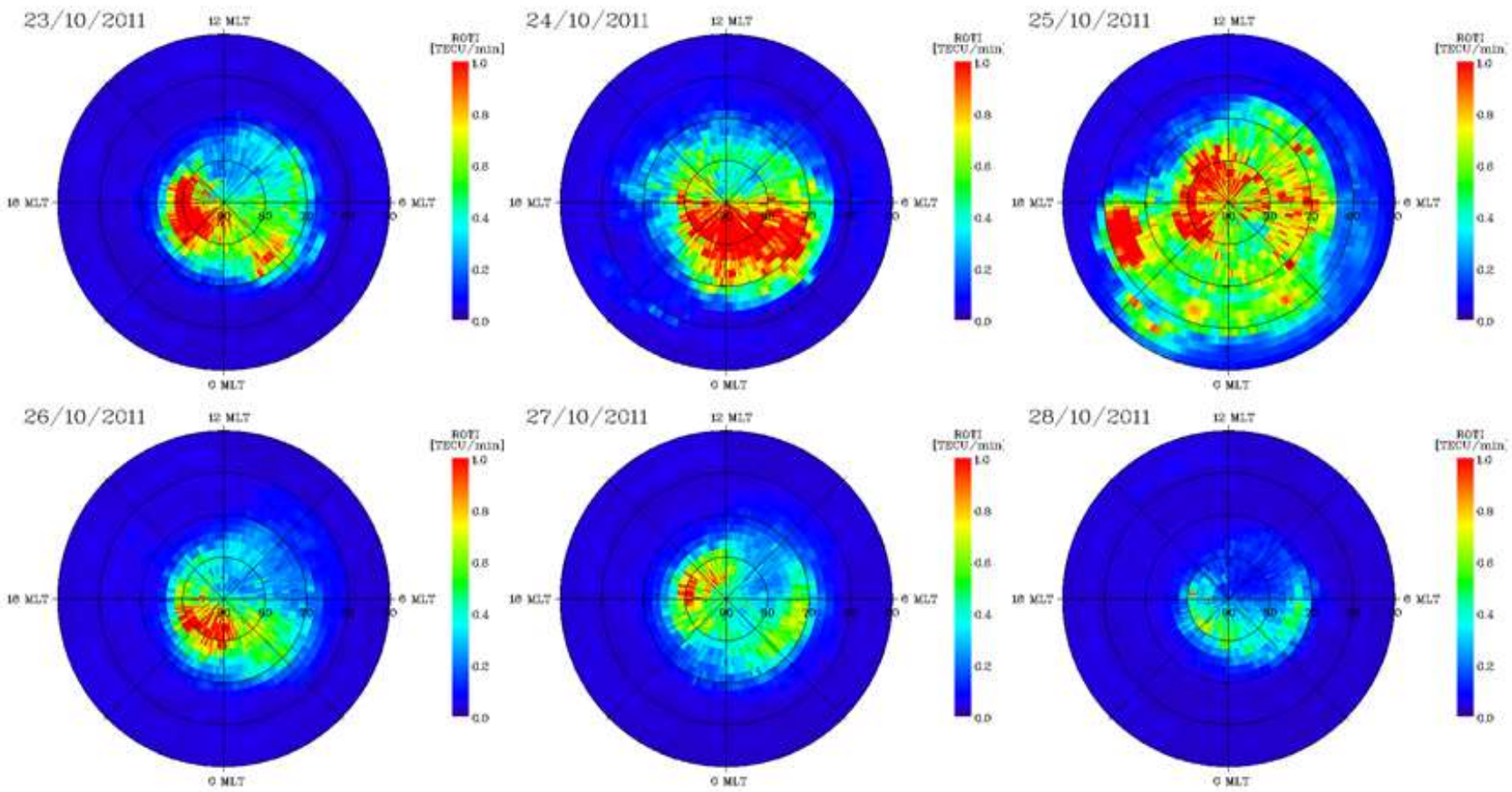
Variability of ROT values over chain of selected European GNSS stations (23-28 October 2011). Right vertical axis shows the number of satellite (PRN).



# ROTI maps

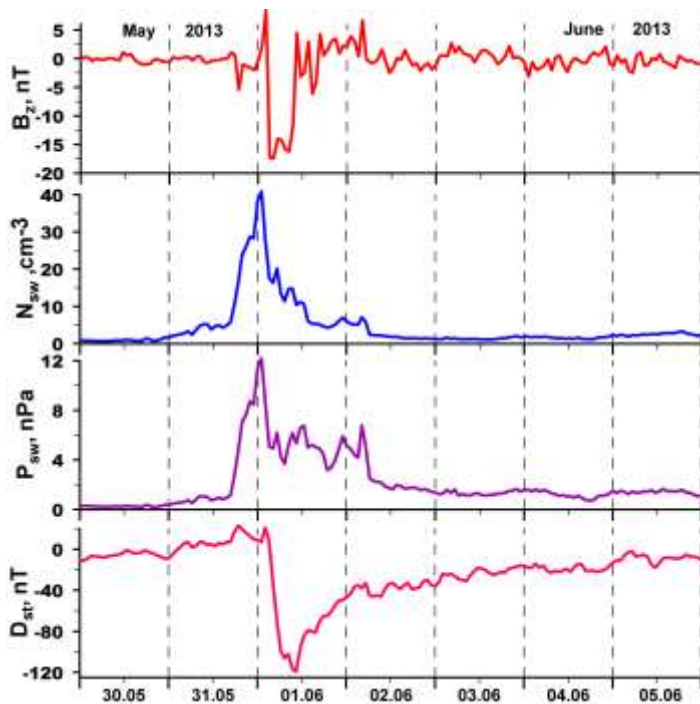
Geomagnetic storm 23 -29 October 2011.

SPACE RADIO-DIAGNOSTICS RESEARCH CENTRE (SRRC/UWM)  
IGS IONOSPHERE WORKING GROUP

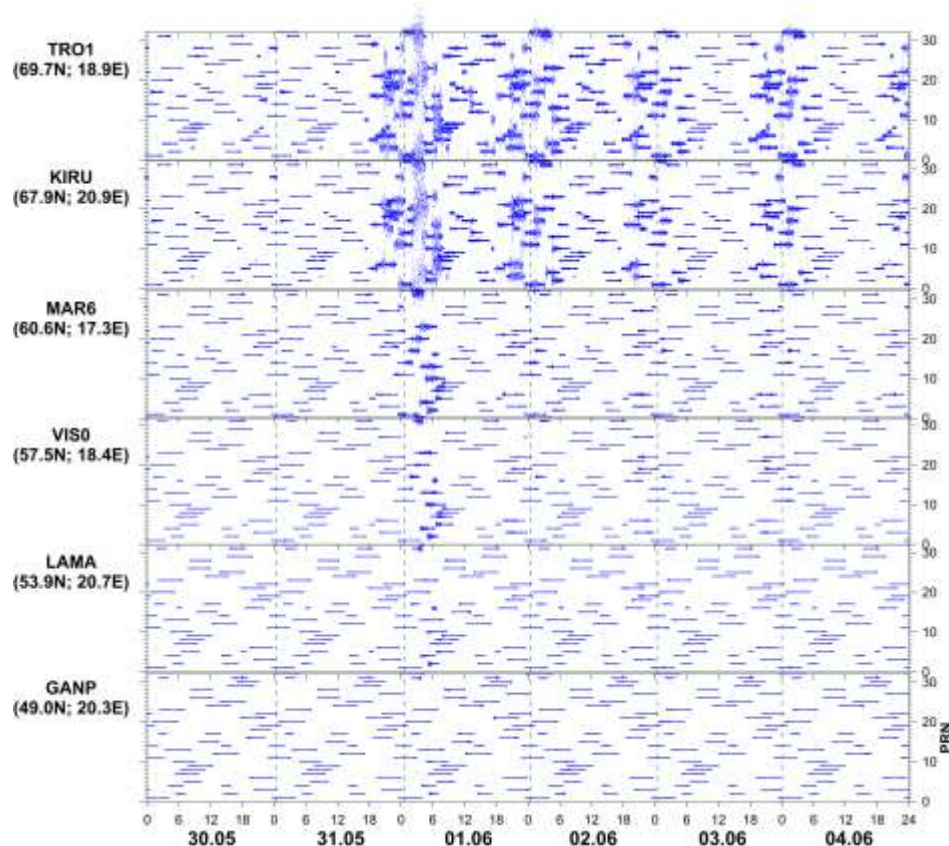


Evolutions of the daily ROTI for 23 – 28 October 2011

# Variability of ROT values over chain of selected European GNSS stations Geomagnetic storm 30 May – 5 June 2013.



The interplanetary geomagnetic field  $B_z$  component, density and pressure of solar wind and Dst index variations for 30 May – 5 June 2013.

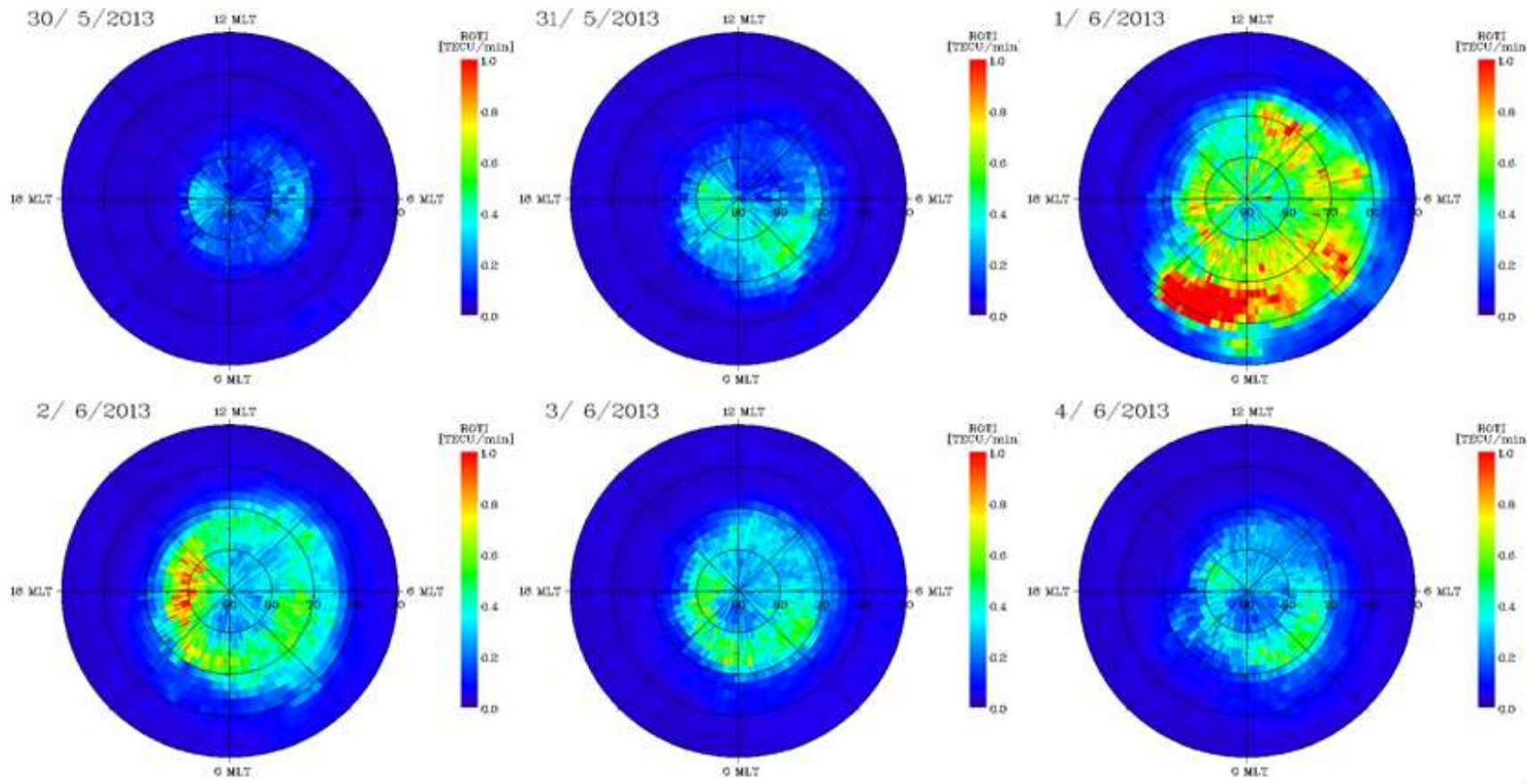


Variability of ROT values over chain of selected European GNSS stations (30 May – 4 June 2013). Right vertical axis shows the number of satellite (PRN).

# ROTI maps

## Geomagnetic storm 30 May – 5 June 2013.

SPACE RADIO-DIAGNOSTICS RESEARCH CENTRE (SRRC/UWM)  
IGS IONOSPHERE WORKING GROUP

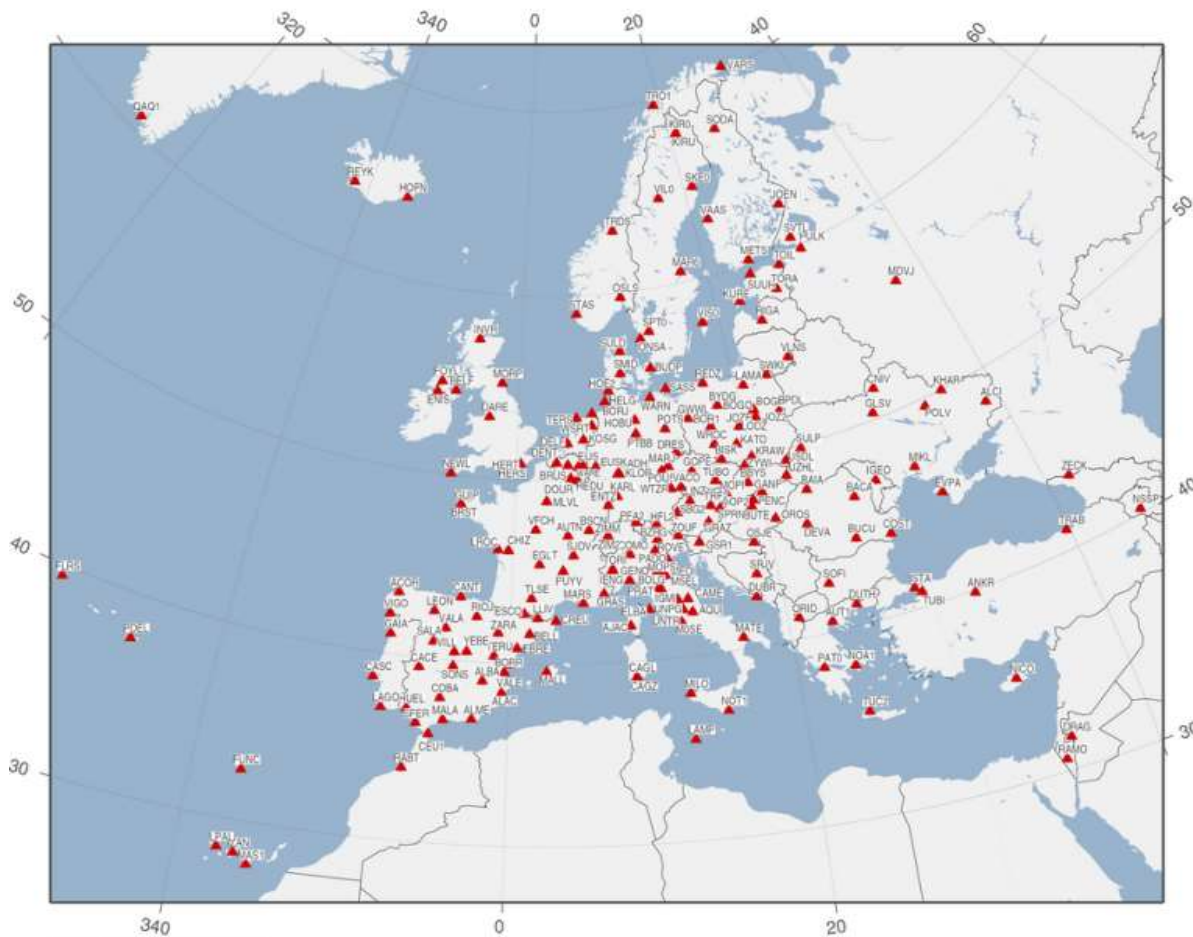


Evolutions of the daily ROTI maps for 30 May – 4 June 2013

# Regional TEC maps for ILT

- temporal and spatial resolution - at 15 min x 0.5 deg. X 0.5 deg (UTxLon.xLat.),
- availability with a latency of 3-5 min.

*EUREF Permanent Tracking Network*



# ASG-EUPOS system



Presently this segment is composed of the following set of reference stations:

- 81 stations with the GPS module,

- 18 stations with the GPS/GLONASS

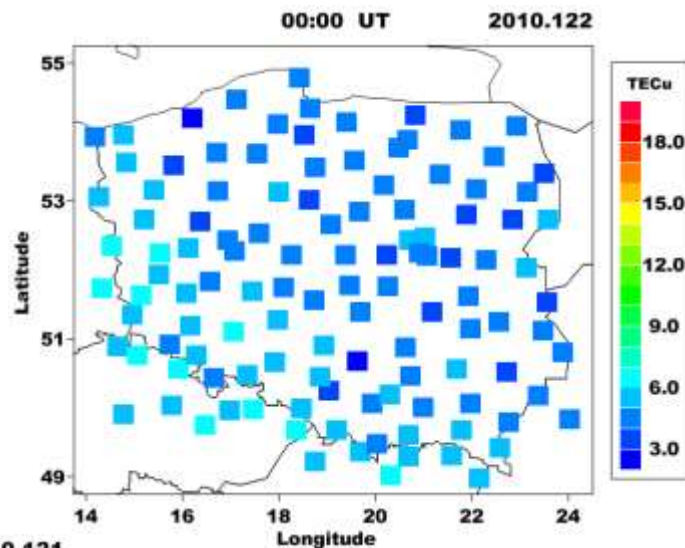
module,

Products (services)

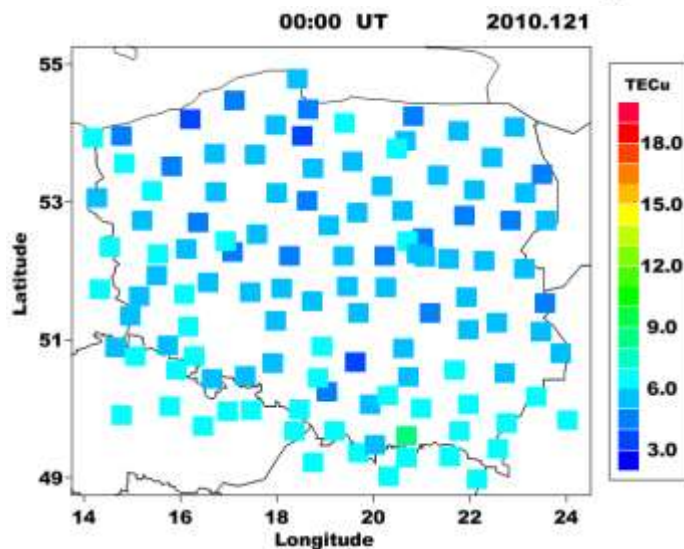
Type	Name	Survey method	Data transmission	Estimated precision
Real-time services	NAWGEO	kinematic (RTK)	Internet, GSM (GPRS)	do 0,03 m (hor.) do 0,05 m (vert.)
	KODGIS	kinematic (DGPS)		up to 0,25 m
	NAWGIS			up to 3 m
Post-processing services	POZGEO	static, rapid static	Internet	Depends on survey conditions (0,01 - 0,10 m)
	POZGEO D	static, kinematic		

# TEC changes over Poland

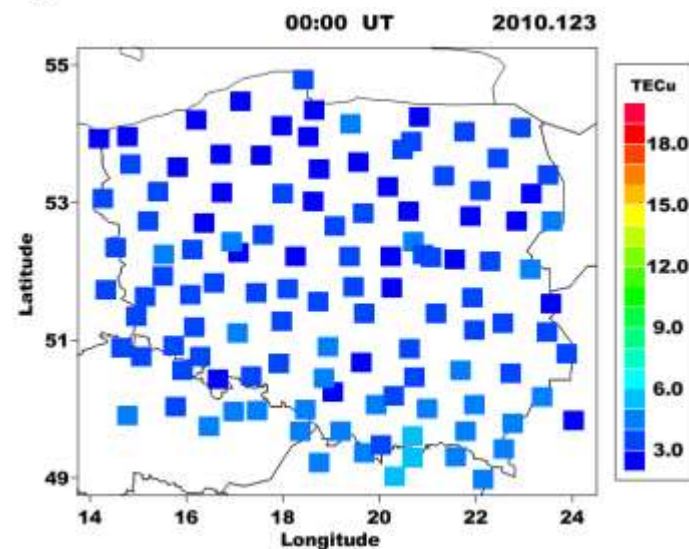
May 2, 2010



May 1, 2010

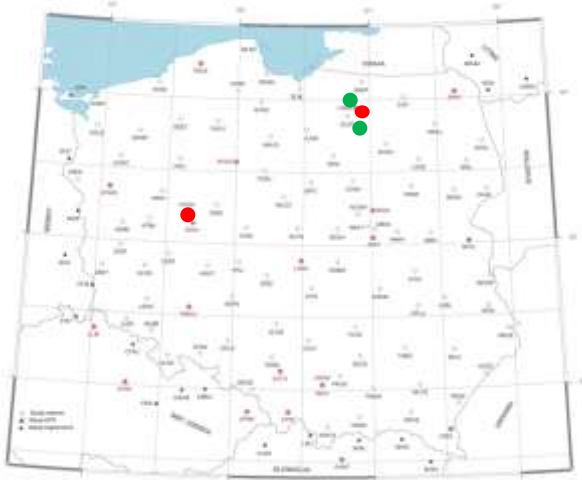


May 3, 2010



# Scintillation measurements

July 28, 2011



## Scintillation receivers

- Javad Sigma G3T
- Septentrio PolaRx3 and Leica G25

$$S_4 = \sqrt{\frac{\langle I^2 \rangle - \langle I \rangle^2}{\langle I \rangle^2}}$$

$$\sigma_\phi = \sqrt{\langle \phi^2 \rangle - \langle \phi \rangle^2}$$

