

Implementation of trigger for Ultra High Energy ($>10^{21}$ eV) Cosmic Rays Detection

LOFAR (DCLA) Meeting

ASTRON, Dwingeloo

26th June 07

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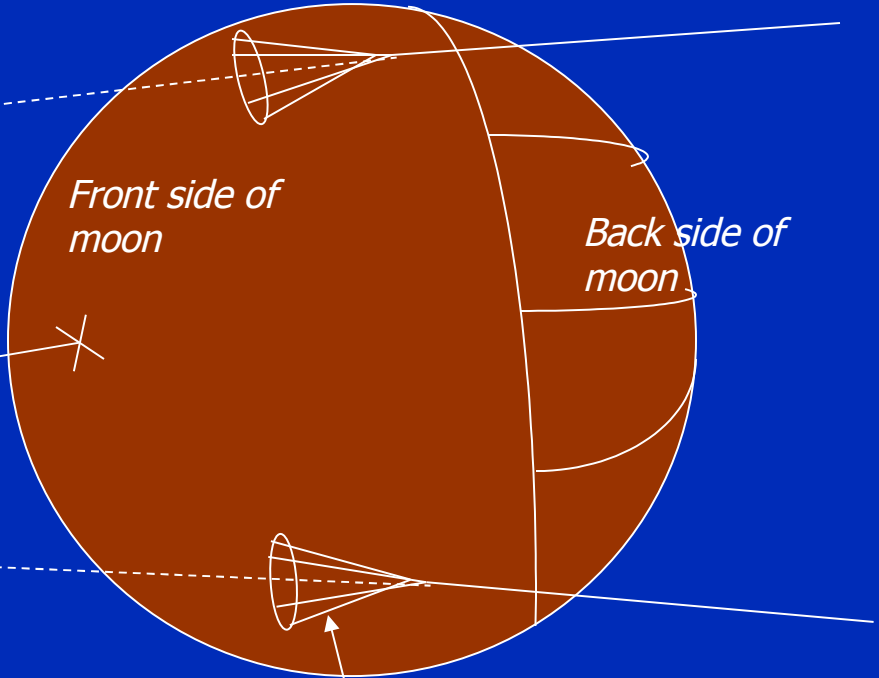
Radboud University

Nijmegen





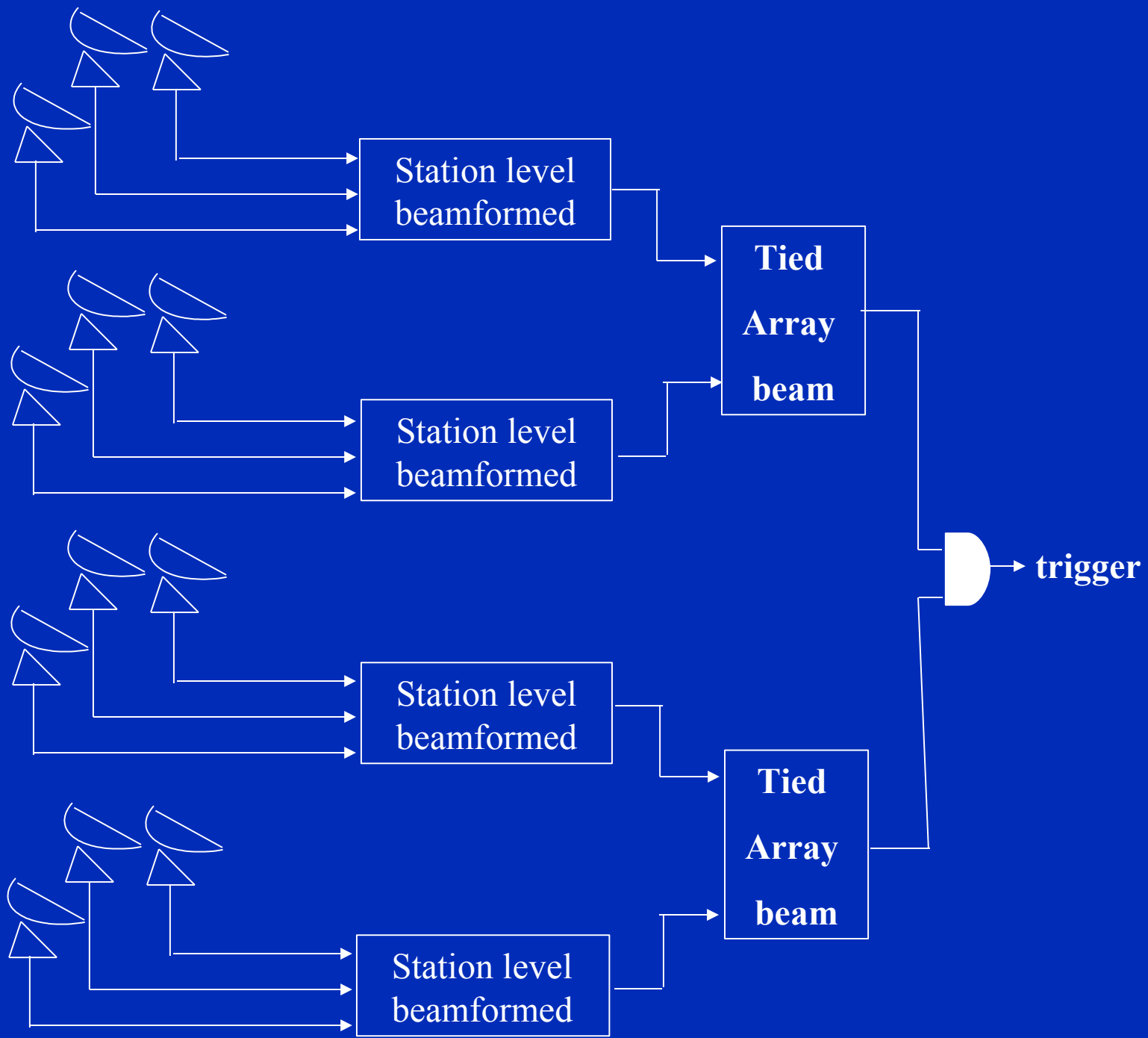
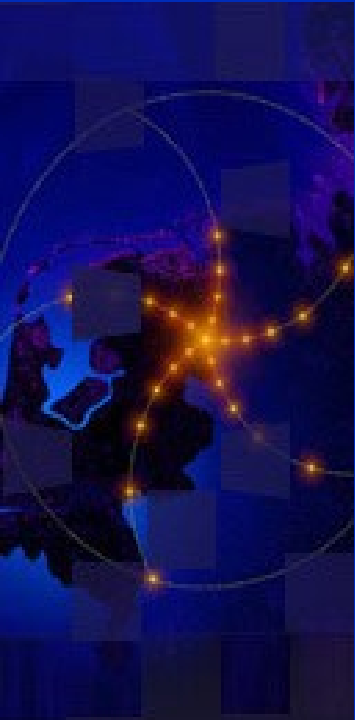
to earth

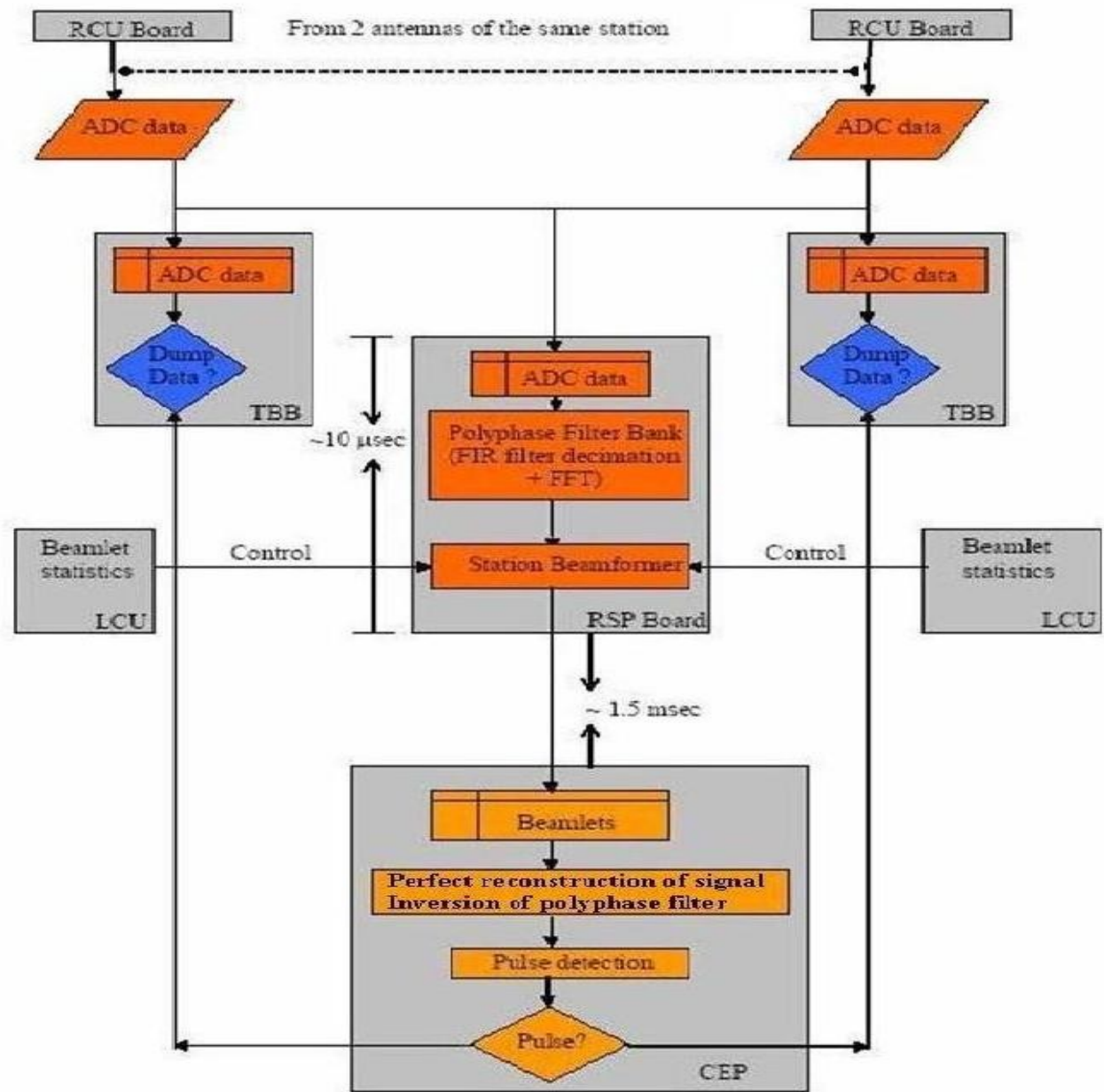


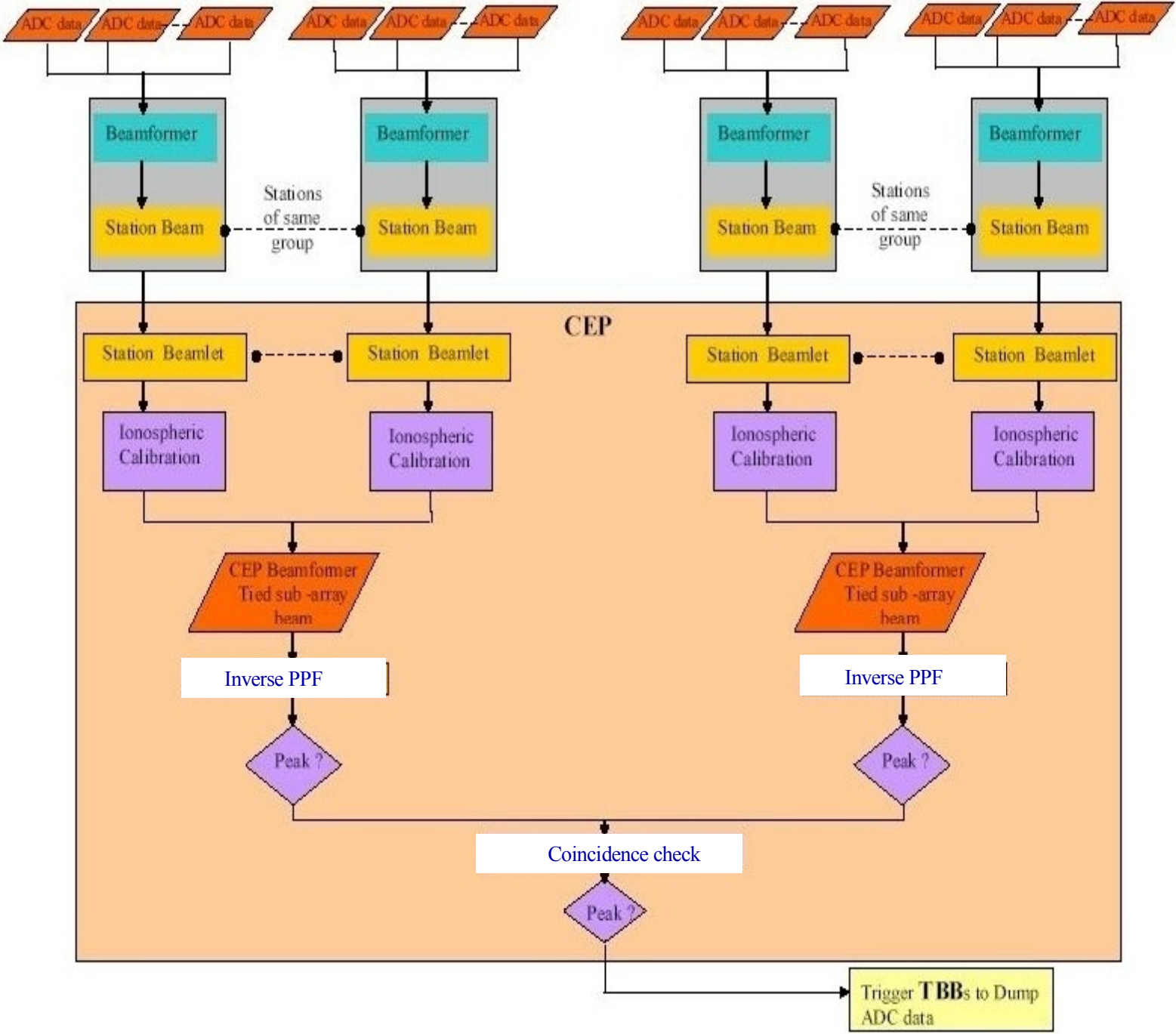
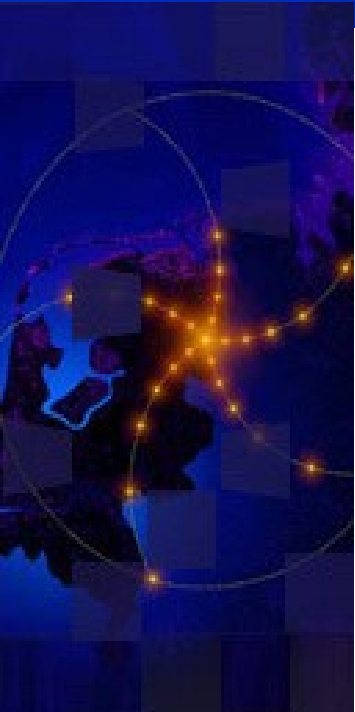
Front side of moon

Back side of moon

Cherenkov cone







DISCRETE FOURIER TRANSFORM

$$X[N] = \begin{bmatrix} 1 & 1 & 1 & \dots & \dots & 1 \\ 1 & W_N^1 & W_N^2 & \dots & \dots & W_N^{N-1} \\ 1 & W_N^2 & W_N^4 & \dots & \dots & W_N^{2(N-1)} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & W_N^{N-1} & W_N^{2(N-1)} & \dots & \dots & W_N^{(N-1) \times (N-1)} \end{bmatrix} x[N]$$

where $W_N = e^{-j2\pi/N}$

for IDFT relations $x[N] = D_N^{-1} X[N]$

where D_N^{-1} is the $N \times N$ matrix given by $D_N^{-1} = \frac{1}{N} D_N^*$
(* denotes complex conjugate).

Basic IIR digital filter structures

$$y[n] = b_0 x[n] + b_1 x[n-1] + \dots + b_p x[n-p] \\ - a_1 y[n-1] - a_2 y[n-2] - \dots - a_q y[n-q]$$

condensed form of the difference equation is ,

$$y[n] = \sum_{i=0}^p b_i x[n-i] - \sum_{j=1}^q a_j y[n-j]$$

which, when rearranged becomes :

$$\sum_{j=1}^q a_j y[n-j] = \sum_{i=0}^p b_i x[n-i] \quad \longrightarrow \quad \sum_{j=1}^q a_j z^{-j} Y(z) = \sum_{i=0}^p b_i z^{-i} X(z)$$

we define the transfer function to be :

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{i=0}^p b_i z^{-i}}{\sum_{j=1}^q a_j z^{-j}}$$

where, z^{-1} is a unit sample delay

Basic FIR digital filter structures

$$H(z) = \sum_{k=0}^{N-1} h[k] z^{-k}$$

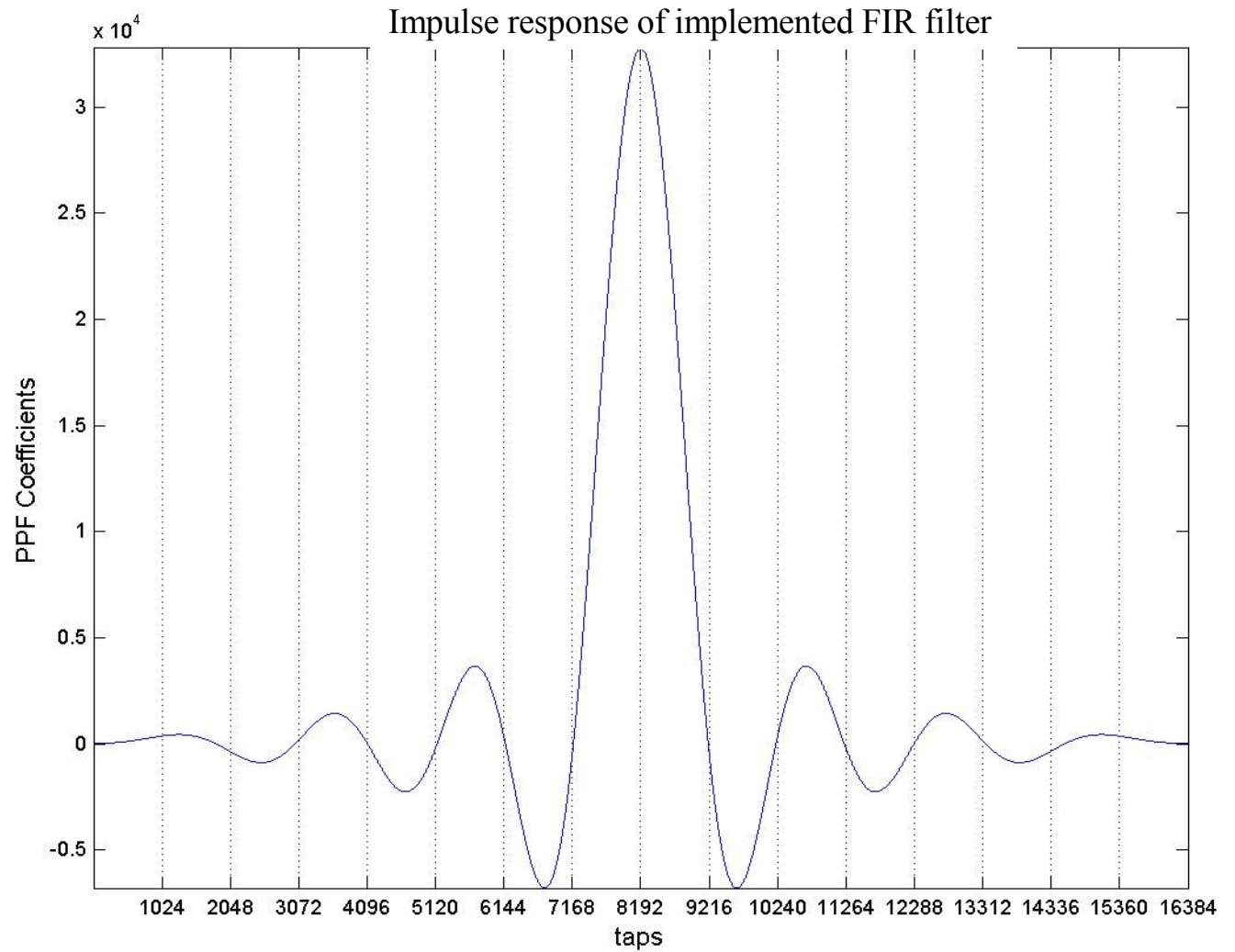
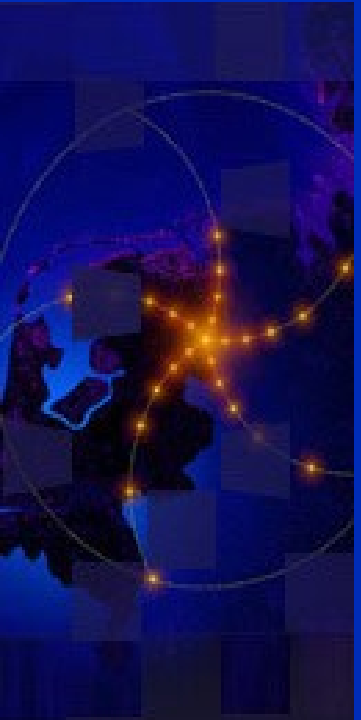
$h[k]$ are b_i 's, however a_i 's are zero, so no feedback effect

which is a polynomial in z^{-1} of degree N .

In the time domain, the input output relationship can be written as,

$$y[n] = \sum_{k=0}^{N-1} h[k] x[n-k]$$

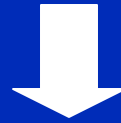
where $y[n]$ and $x[n]$ are input and output sequences respectively.



Symmetric Impulse response inherits the linear phase property

Polyphase realization of FIR filters

$$H(z) = h[\cdot] + h[\cdot]z^{-1} + h[\cdot]z^{-2} + h[\cdot]z^{-3} + h[\cdot]z^{-4} + h[\cdot]z^{-5} + h[\cdot]z^{-6} + h[\cdot]z^{-7} + h[\cdot]z^{-8} + h[\cdot]z^{-9}$$



$$H(z) = \{h[\cdot]z^0 + h[\cdot]z^{-2} + h[\cdot]z^{-4} + h[\cdot]z^{-6} + h[\cdot]z^{-8}\} \\ + \{h[\cdot]z^{-1} + h[\cdot]z^{-3} + h[\cdot]z^{-5} + h[\cdot]z^{-7} + h[\cdot]z^{-9}\}$$



$$H(z) = \{h[\cdot] + h[\cdot]z^{-2} + h[\cdot]z^{-4} + h[\cdot]z^{-6} + h[\cdot]z^{-8}\} \\ + z^{-1} \{h[\cdot] + h[\cdot]z^{-2} + h[\cdot]z^{-4} + h[\cdot]z^{-6} + h[\cdot]z^{-8}\}$$



$$H(z) = E_0(z^2) + z^{-1}E_1(z^2)$$

where,

$$E_0(z^2) = h[\cdot] + h[\cdot]z^{-2} + h[\cdot]z^{-4} + h[\cdot]z^{-6} + h[\cdot]z^{-8}$$

$$E_1(z^2) = h[\cdot] + h[\cdot]z^{-2} + h[\cdot]z^{-4} + h[\cdot]z^{-6} + h[\cdot]z^{-8}$$

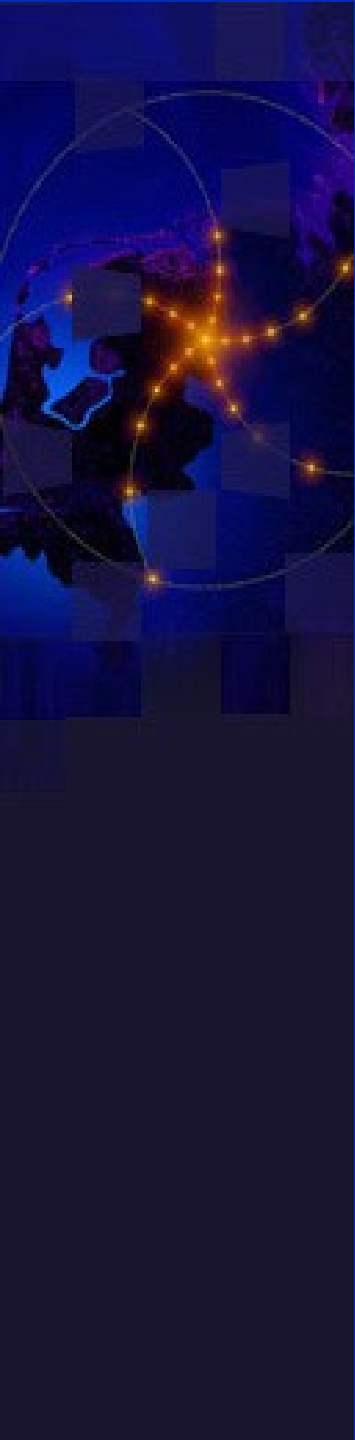
$$H(z) = E_0(z^L) + z^{-1} E_1(z^L) + z^{-2} E_2(z^L)$$

L-branch polyphase decomposition of transfer function of order N can be written as

$$H(z) = \sum_{m=0}^{L-1} z^{-m} E_m(z^L)$$

where $E_m(z) = \sum_{n=0}^{\lfloor \frac{N+m}{L} \rfloor} h[Ln + m] z^{-n}, \quad 0 \leq m \leq L-1$

with $h[n] = 0$ for $n > N$



A linear phase FIR filters of order N is either characterized by a symmetric impulse response, i.e., $h[n] = h[N-n]$ or by an antisymmetric impulse response.

$$H(z) = h[0](1 + z^{-8}) + h[1](z^{-1} + z^{-7}) + h[2](z^{-2} + z^{-6}) + h[3](z^{-3} + z^{-5})$$

it requires 4 multipliers, compared to 8 multipliers in the direct form realization of the original length-8 FIR filter.

Uniform Filter Bank

$H_0(z)$ represent a lowpass digital (FIR) filter with an impulse response $h_0[n]$:

$$H_0(z) = \sum_{n=0}^{\infty} h_0[n]z^{-n}$$

The transfer function of k^{th} subfilter $H_k(z)$ whose impulse response $h_k[n]$ is defined to be

$$h_k[n] = h_0[n]W_M^{-kn}, \quad 0 \leq k \leq M-1$$

where $W_M = e^{-j\pi/M}$

In general,

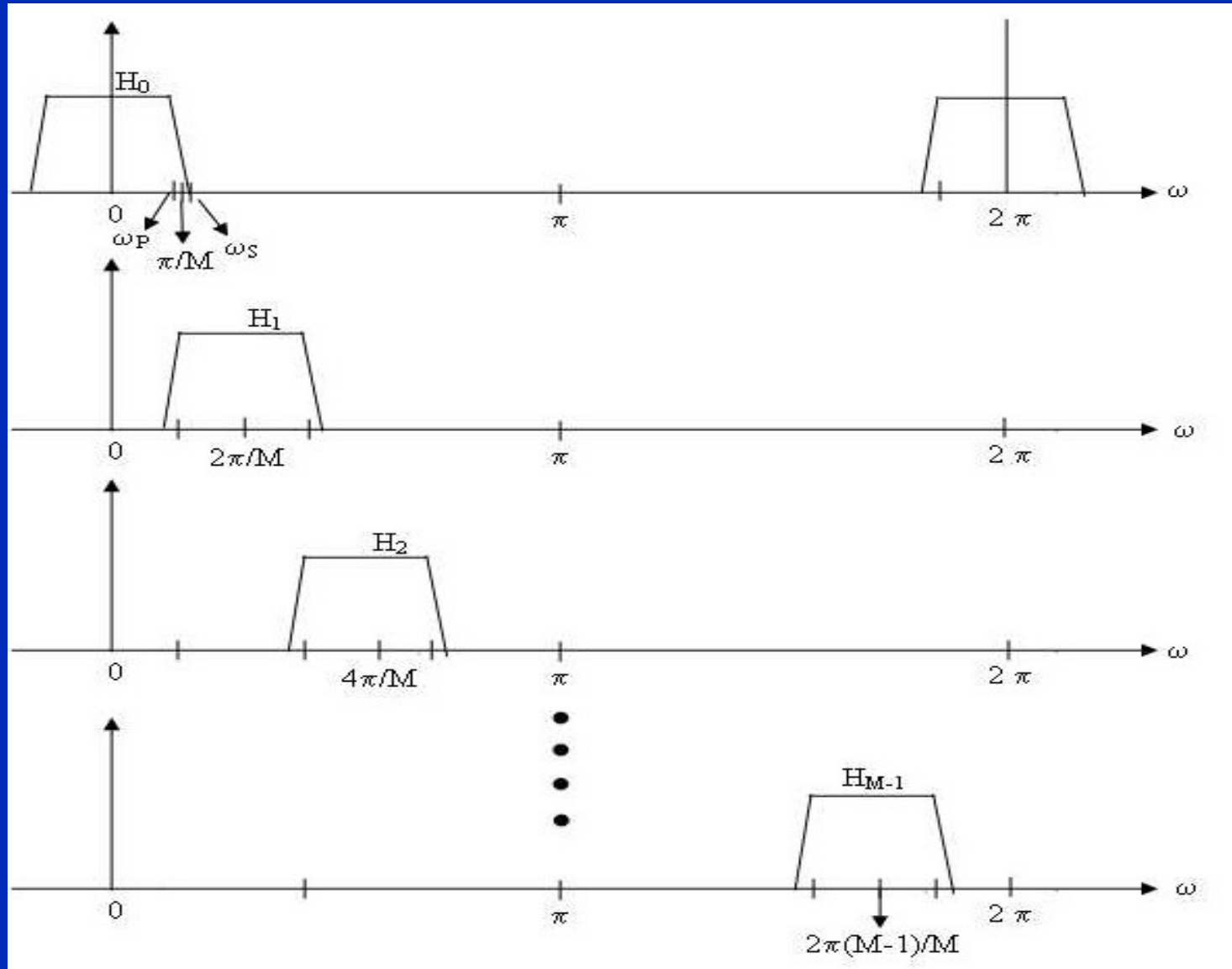
$$H_k(z) = \sum_{n=0}^{\infty} h_k[n]z^{-n} = \sum_{n=0}^{\infty} h_0[n](zW_M^k)^{-n}, \quad 0 \leq k \leq M-1$$

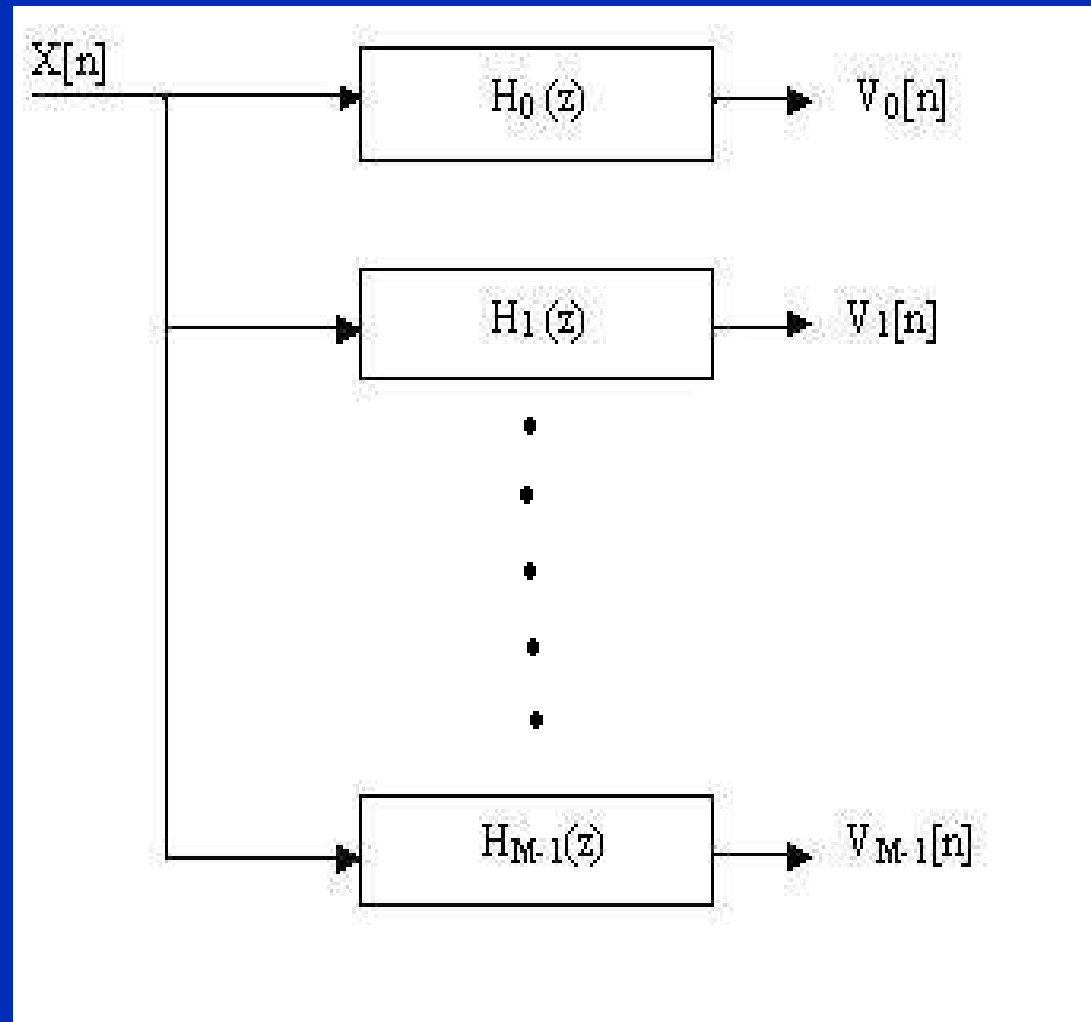
i.e.,

$$H_k(z) = H_0(zW_M^k), \quad 0 \leq k \leq M-1$$

With corresponding frequency response, shifts by an amount $2\pi k / M$

$$H_k(e^{i\omega}) = H_k(z) = H_0(zW_M^k), \quad 0 \leq k \leq M-1$$





Polyphase implementation of Uniform Filter Bank

M branch polyphase decomposition

$$H_0(z) = \sum_{l=0}^{M-1} z^{-l} E_l(z^M)$$

where $E_l(z)$ is the l^{th} polyphase component of $H_0(z)$:

$$E_l(z) = \sum_{n=0}^{\infty} h_l[n] z^{-n}, \quad 0 \leq l \leq M-1$$

Substituting z with $z W_M^k$, we arrive at the M-band polyphase decomposition of $H_k(z)$:

$$H_k(z) = \sum_{l=0}^{M-1} z^{-l} W_M^{-kl} E_l(z^M W_M^{kM}) = \sum_{l=0}^{M-1} W_M^{-kl} z^{-l} E_l(z^M), \quad k = 0, 1, \dots, M-1$$

In matrix form k^{th} subfilter,

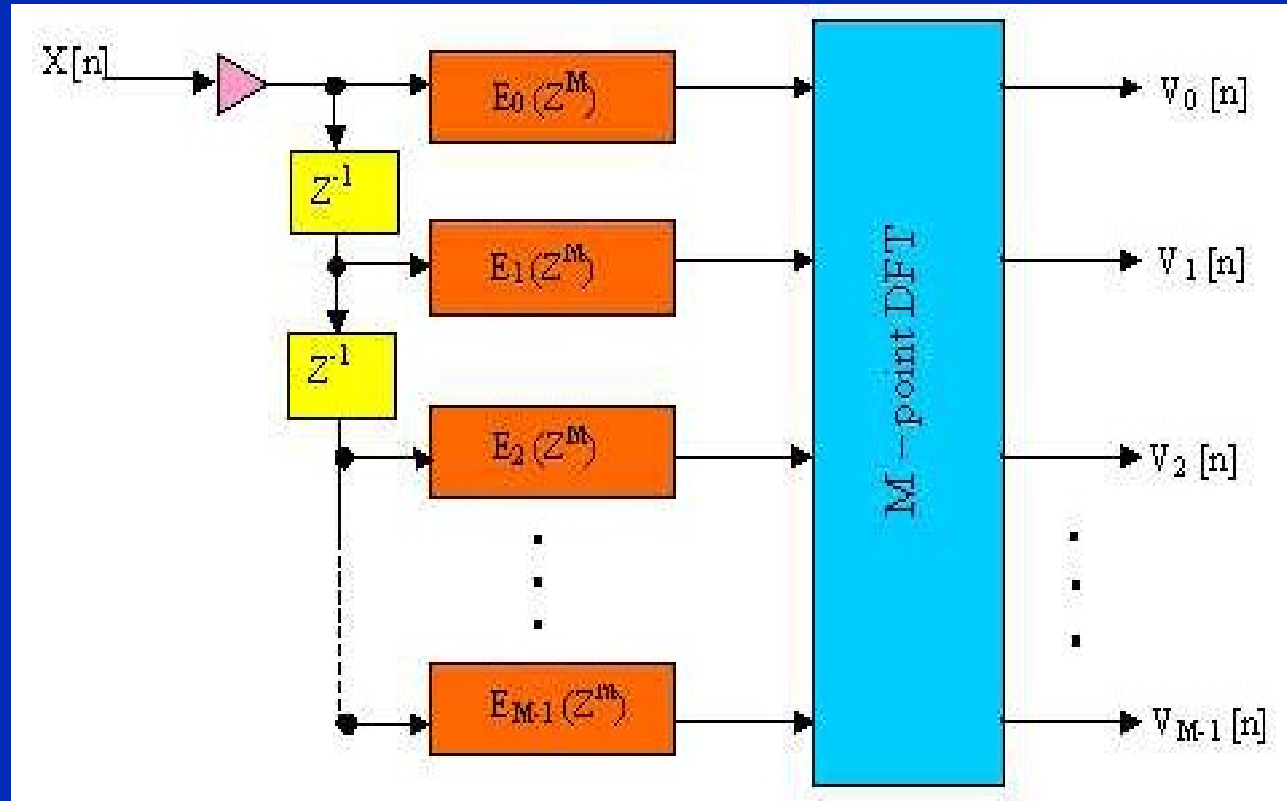
$$H_k(z) = \begin{bmatrix} 1 & W_M^{-k} & W_M^{-\gamma k} & \dots & W_M^{-(M-1)k} \end{bmatrix} \begin{bmatrix} E_0(z^M) \\ z^{-1} E_1(z^M) \\ z^{-\gamma} E_\gamma(z^M) \\ \vdots \\ z^{-(M-1)} E_{M-1}(z^M) \end{bmatrix}$$

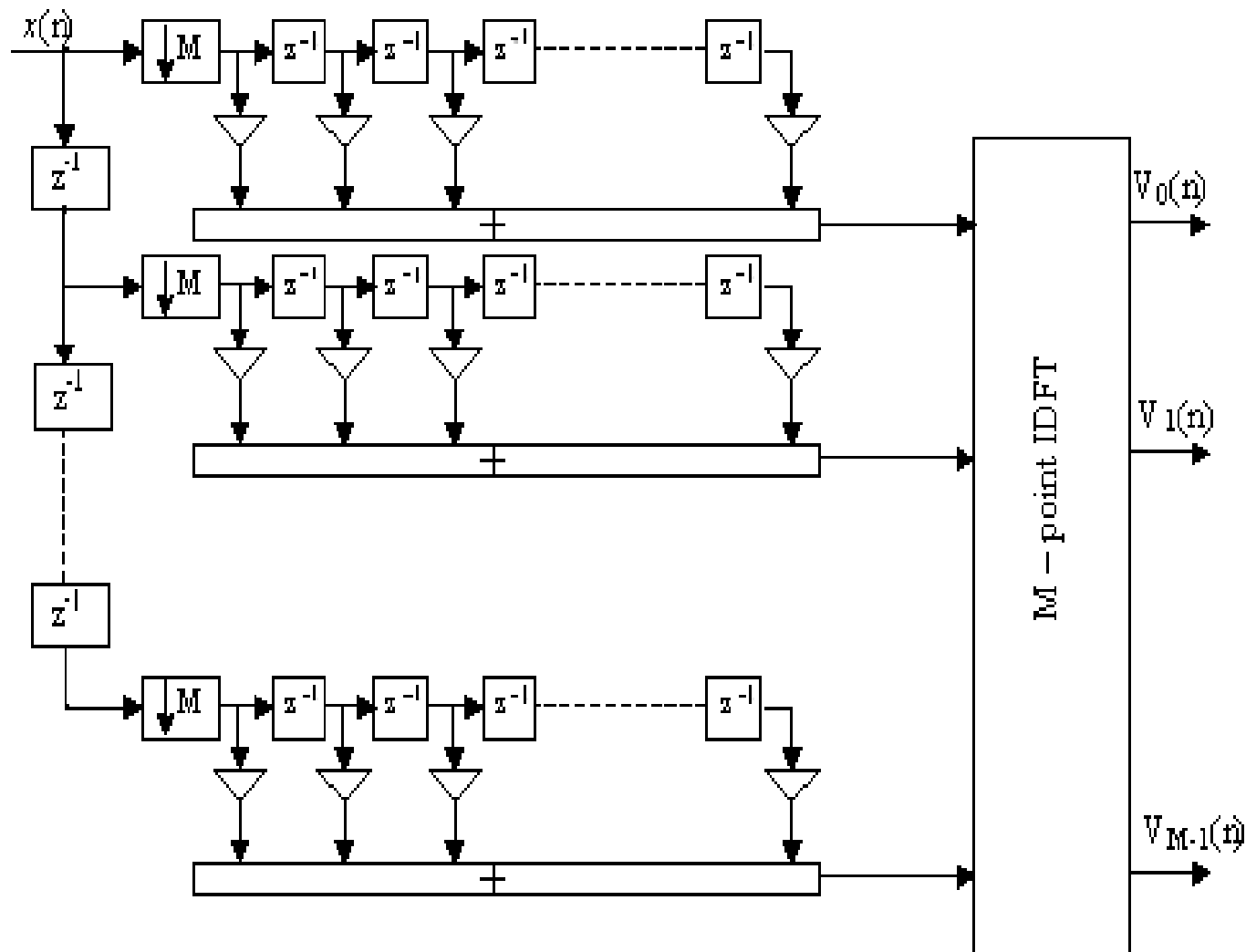
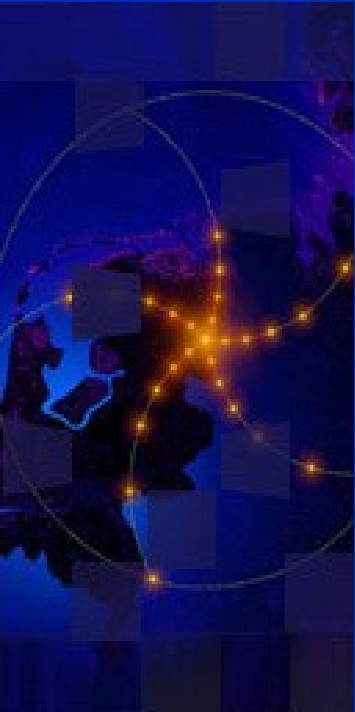
For $k=0,1,\dots, M-1$. All these M equations can be combined into a matrix equation as

$$\begin{bmatrix} H_0(z) \\ H_1(z) \\ H_\gamma(z) \\ \vdots \\ H_{M-1}(z) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & W_M^{-1} & W_M^{-\gamma} & \dots & W_M^{-(M-1)} \\ 1 & W_M^{-\gamma} & W_M^{-\xi} & \dots & W_M^{-\gamma(M-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & W_M^{-(M-1)} & W_M^{-\gamma(M-1)} & W_M^{-\gamma(M-1)} & W_M^{-(M-1)\gamma} \end{bmatrix} \begin{bmatrix} E_0(z^M) \\ z^{-1} E_1(z^M) \\ z^{-\gamma} E_\gamma(z^M) \\ \vdots \\ z^{-(M-1)} E_{M-1}(z^M) \end{bmatrix}$$

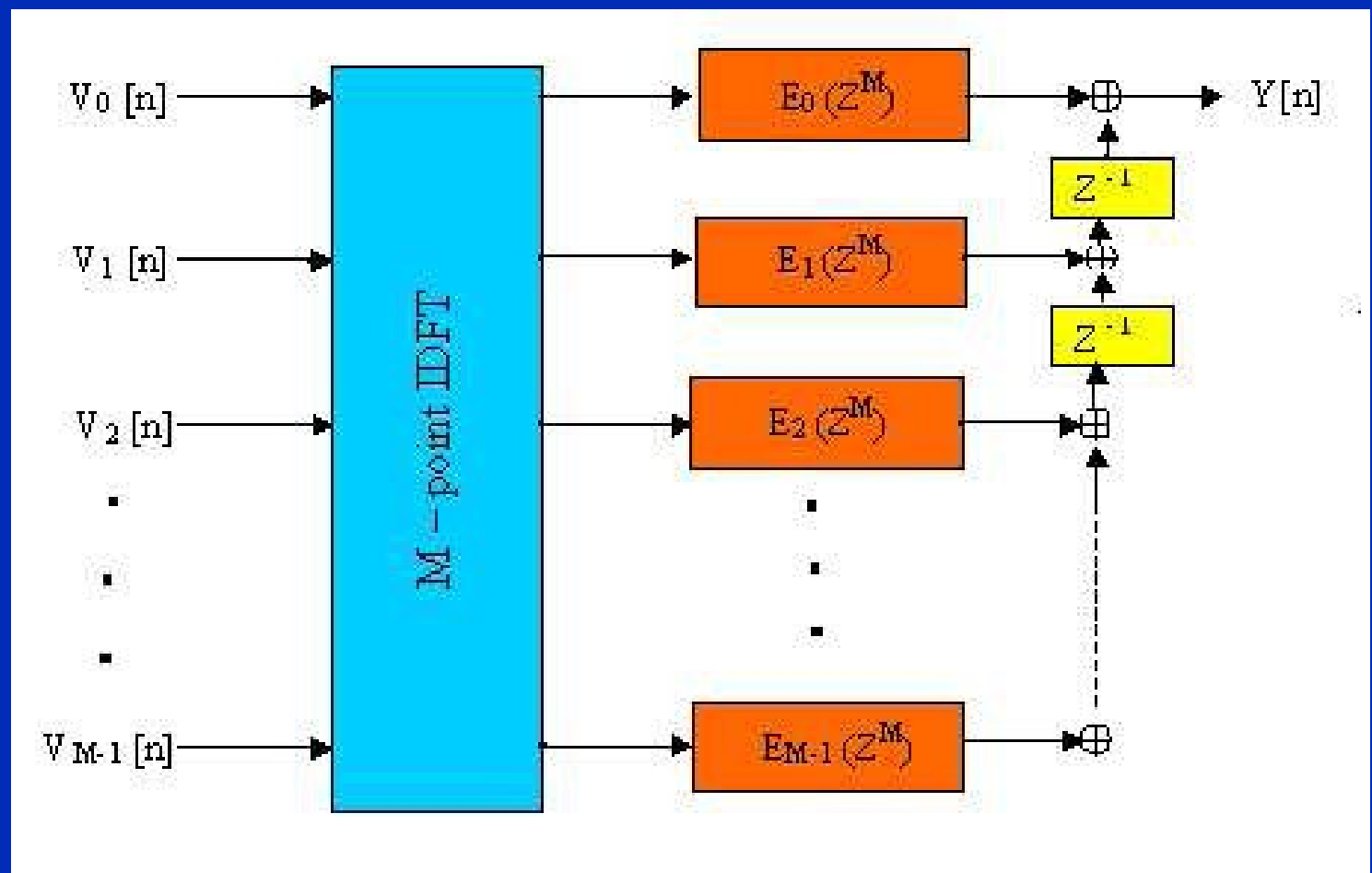
Which is equivalent to

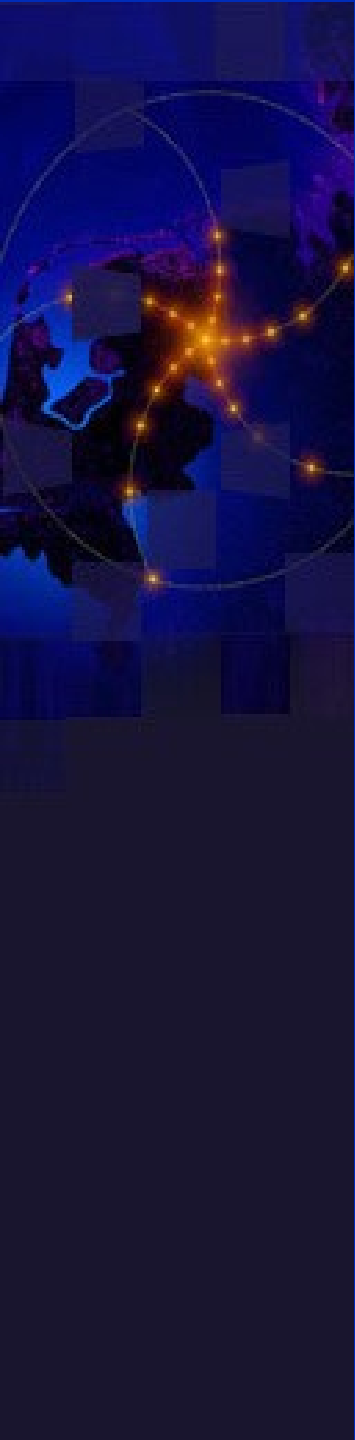
$$\begin{bmatrix} H_0(z) \\ H_1(z) \\ H_2(z) \\ \vdots \\ H_{M-1}(z) \end{bmatrix} = M \cdot D^{-1} \begin{bmatrix} E_0(z) & \cdot & \cdot & \cdot & \cdot \\ \cdot & E_1(z) & \cdot & \cdot & \cdot \\ \cdot & \cdot & E_2(z) & \cdot & \cdot \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ \cdot & \cdot & \cdot & \cdot & E_{M-1}(z) \end{bmatrix}$$





Perfect Reconstruction of Signal (Inversion of Polyphase Filter Bank)





$$\tilde{E} = \begin{bmatrix} E_0(z) & 0 & 0 & 0 & 0 \\ 0 & E_1(z) & 0 & 0 & 0 \\ 0 & 0 & E_2(z) & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & E_{M-1}(z) \end{bmatrix}$$

To invert the effect of FIR filters, we need to invert this diagonal matrix

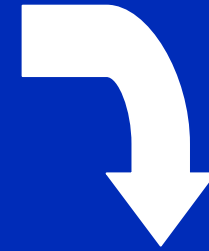
$$\tilde{E}^{-1} = \begin{bmatrix} E_0^{-1}(z) & 0 & 0 & 0 & 0 \\ 0 & E_1^{-1}(z) & 0 & 0 & 0 \\ 0 & 0 & E_2^{-1}(z) & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & E_{M-1}^{-1}(z) \end{bmatrix}$$

where $E_N^{-1}(z) = \frac{1}{E_N(z)}$

$$\hat{X}(n) = \tilde{E}^{-1} D D^{-1} \tilde{E} \propto x(n)$$

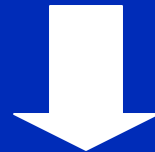
In general,

$$H(z) = \frac{Y(z)}{X(z)} = \frac{\sum_{i=0}^p b_i z^{-i}}{\sum_{j=0}^q a_j z^{-j}}$$



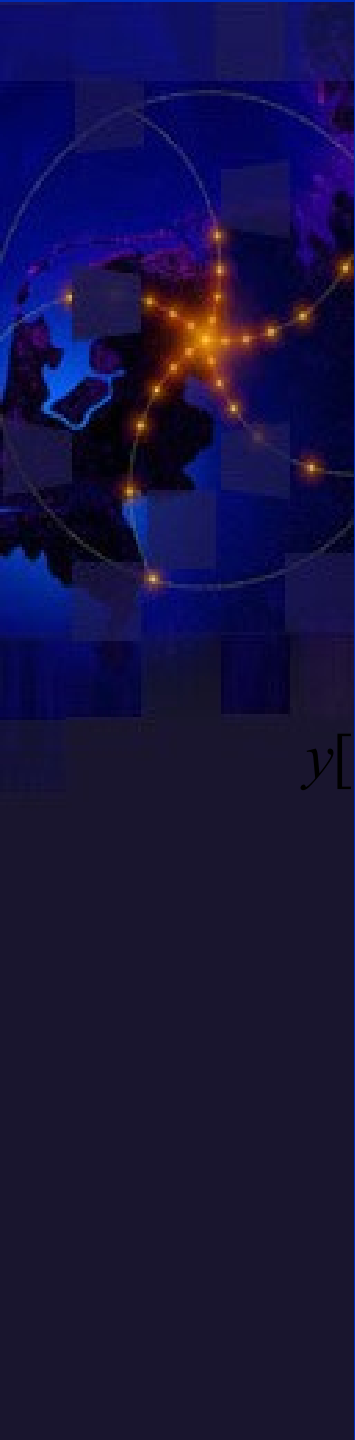
$$a_0 y[n] = b_0 x[n] + b_1 x[n-1] + \dots + b_p x[n-p] \\ - a_1 y[n-1] - a_2 y[n-2] - \dots - a_q x[n-q]$$

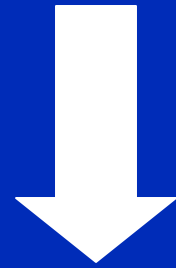
$$H(z) = \frac{Y(z)}{X(z)} = \sum_{i=0}^p b_i z^{-i}$$



Inversion of PPF

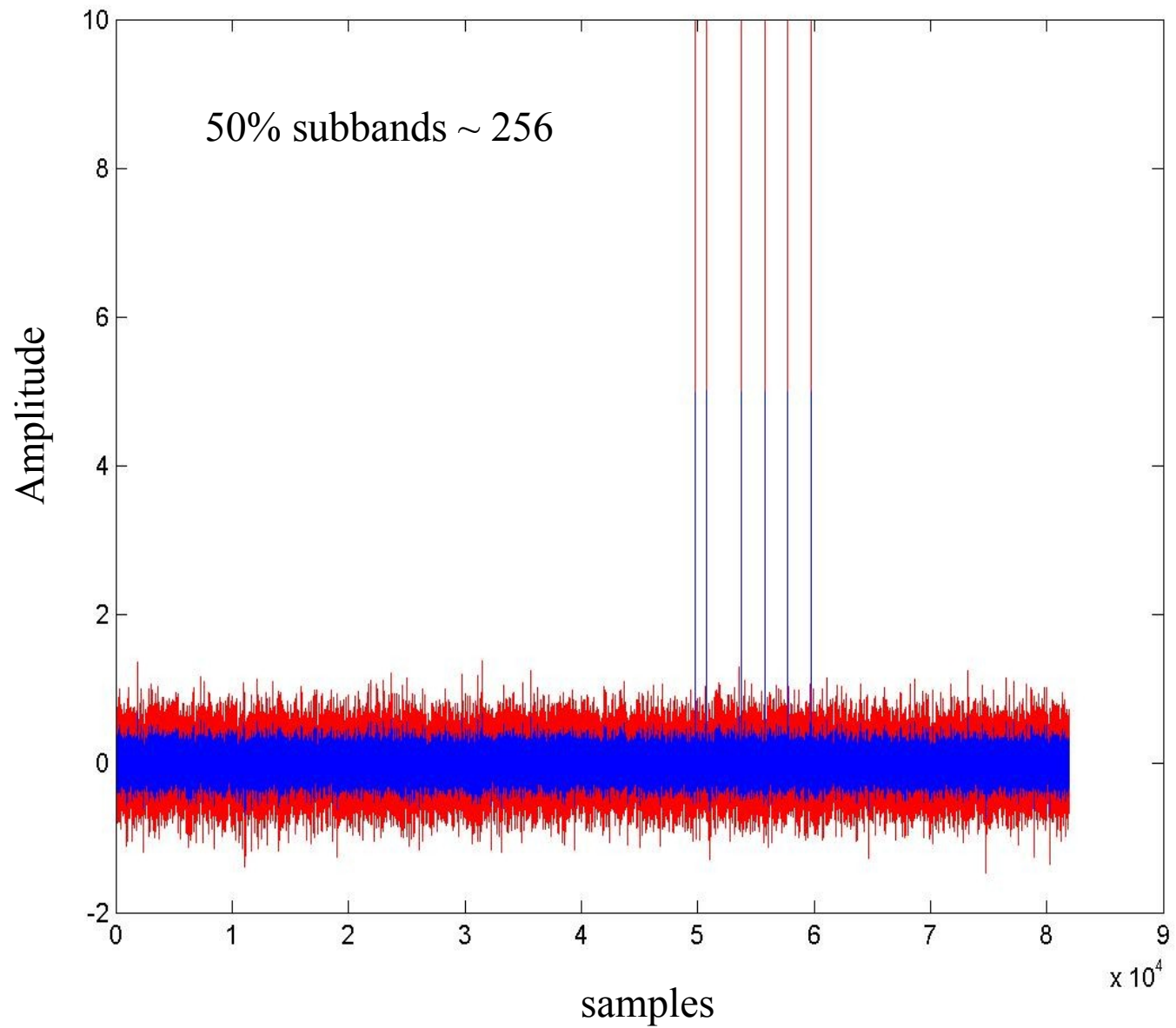
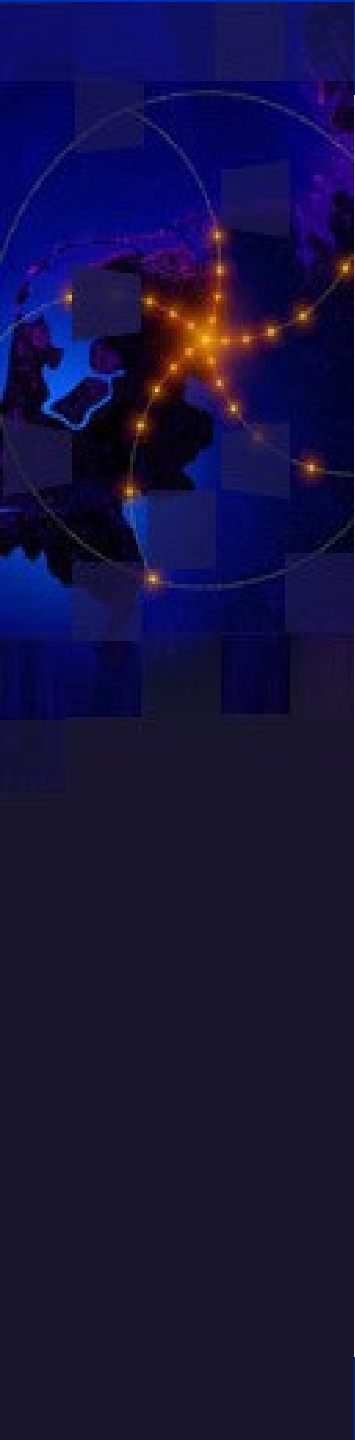
$$H(z) = \frac{Y(z)}{X(z)} = \frac{1}{\sum_{i=0}^p b_i z^{-i}}$$

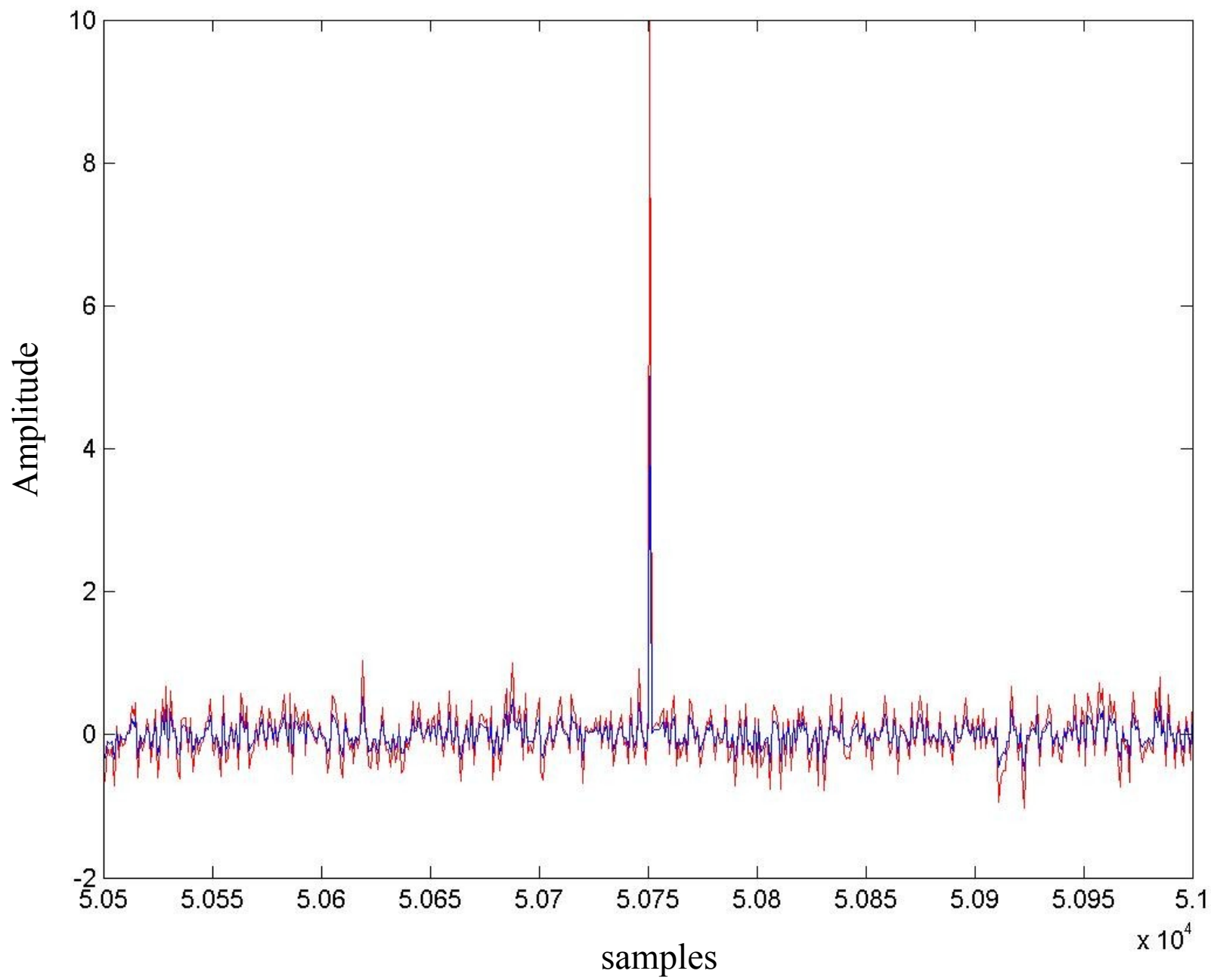

$$\sum_{j=0}^q b_j y[n-j] = \sum_{i=0}^p a_i x[n-i] = a_0 x[n]; \quad a_0 = 1$$

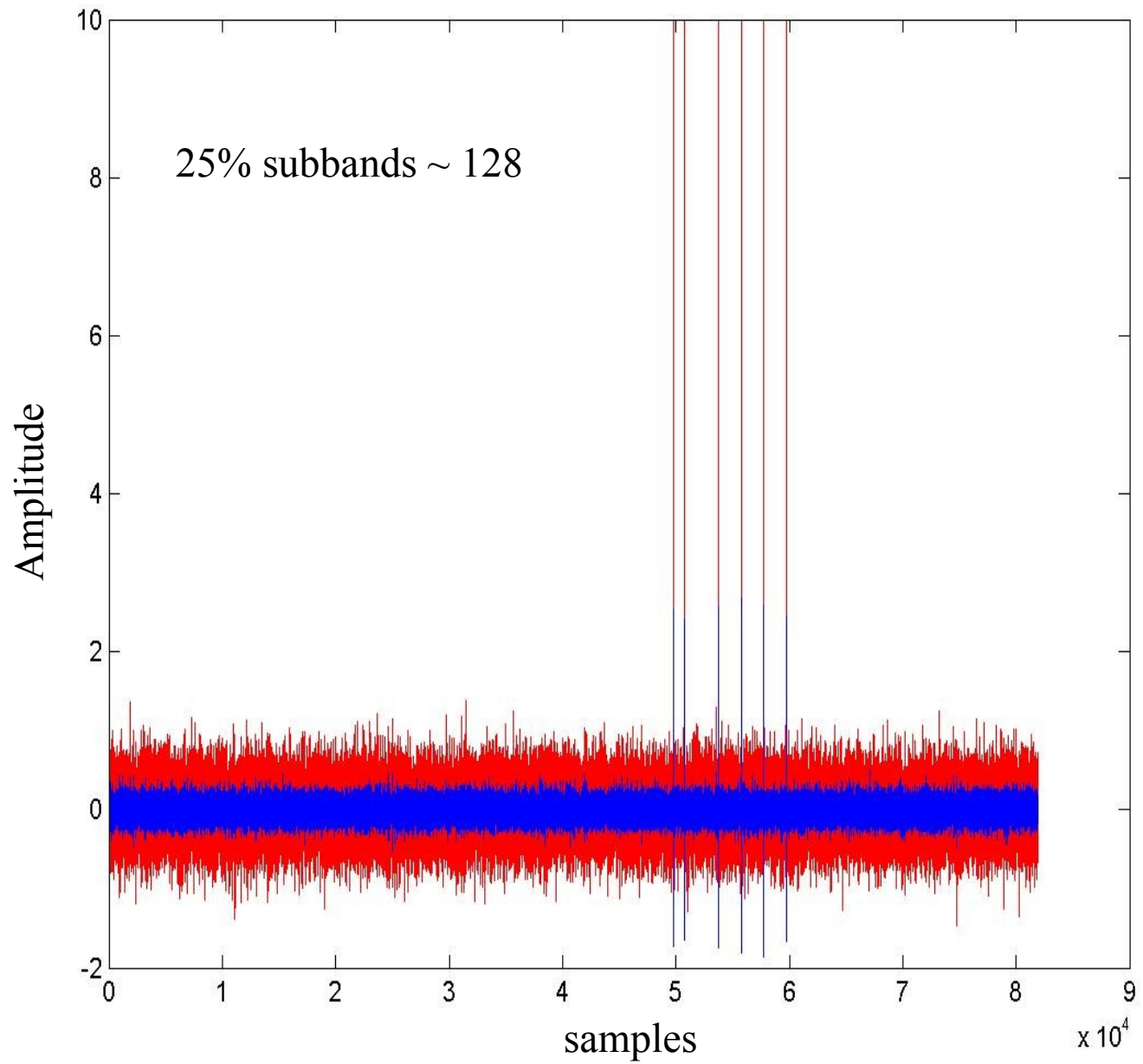
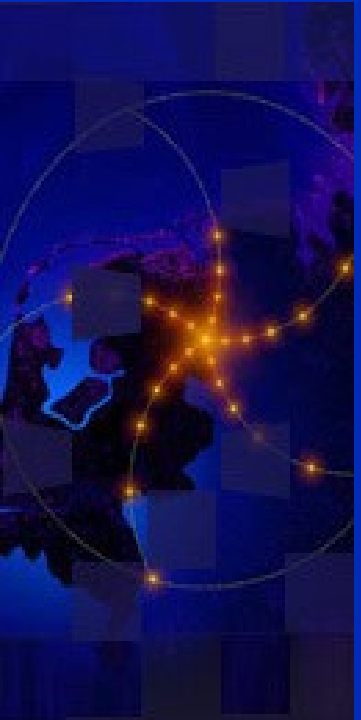


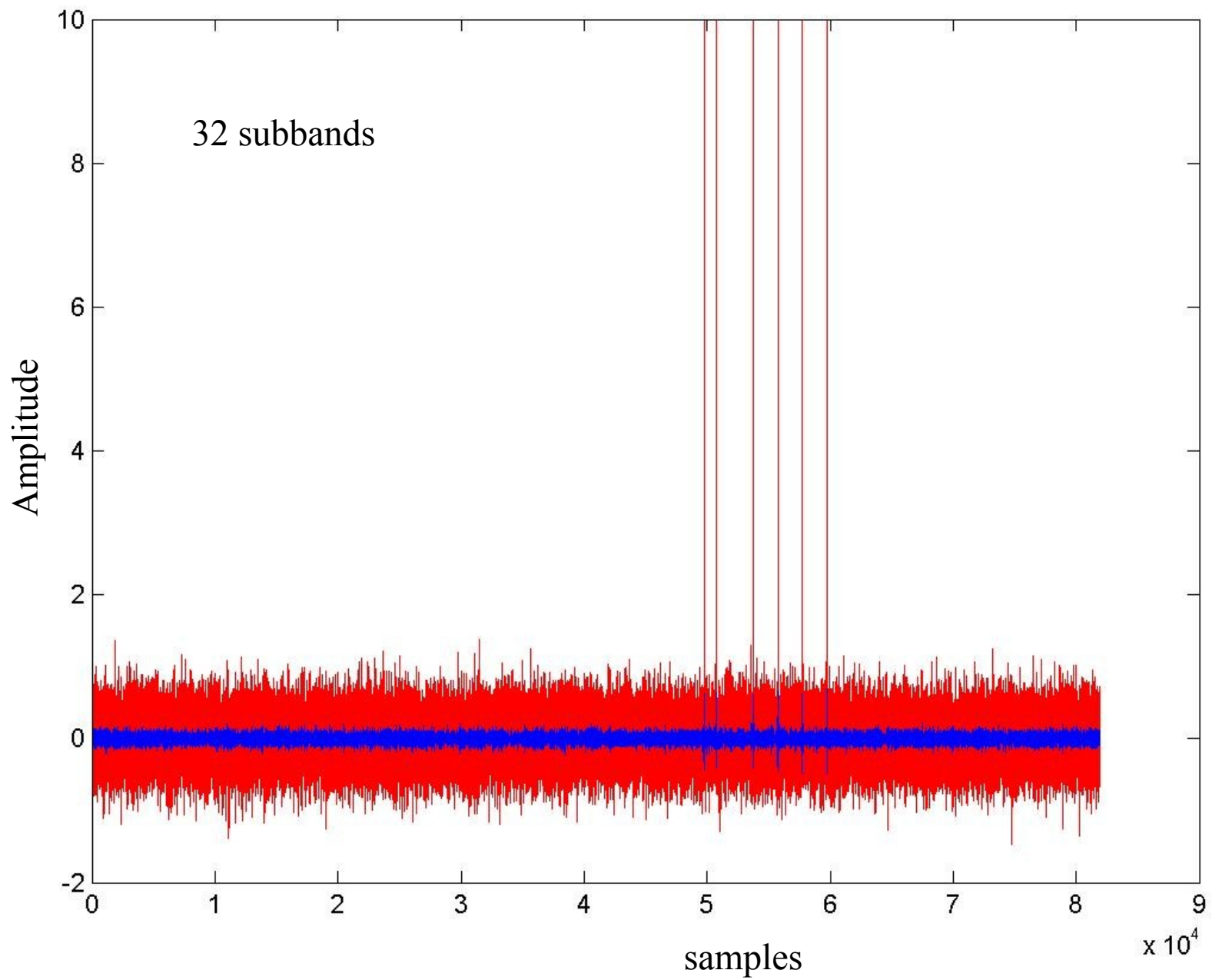
Impulse response

$$y[n] = \frac{1}{b_0} \{a_0 x[n] - b_1 y[n-1] - b_2 y[n-2] - \dots - b_q x[n-q]\}$$









Ionospheric Calibration

$$n(f) = \sqrt{1 - \frac{f_p^2}{f^2}}$$

$n(f)$ Refractive index

f_p plasma frequency

$$k(f) = \frac{2\pi f \sqrt{1 - \frac{f_p^2}{f^2}}}{c}$$

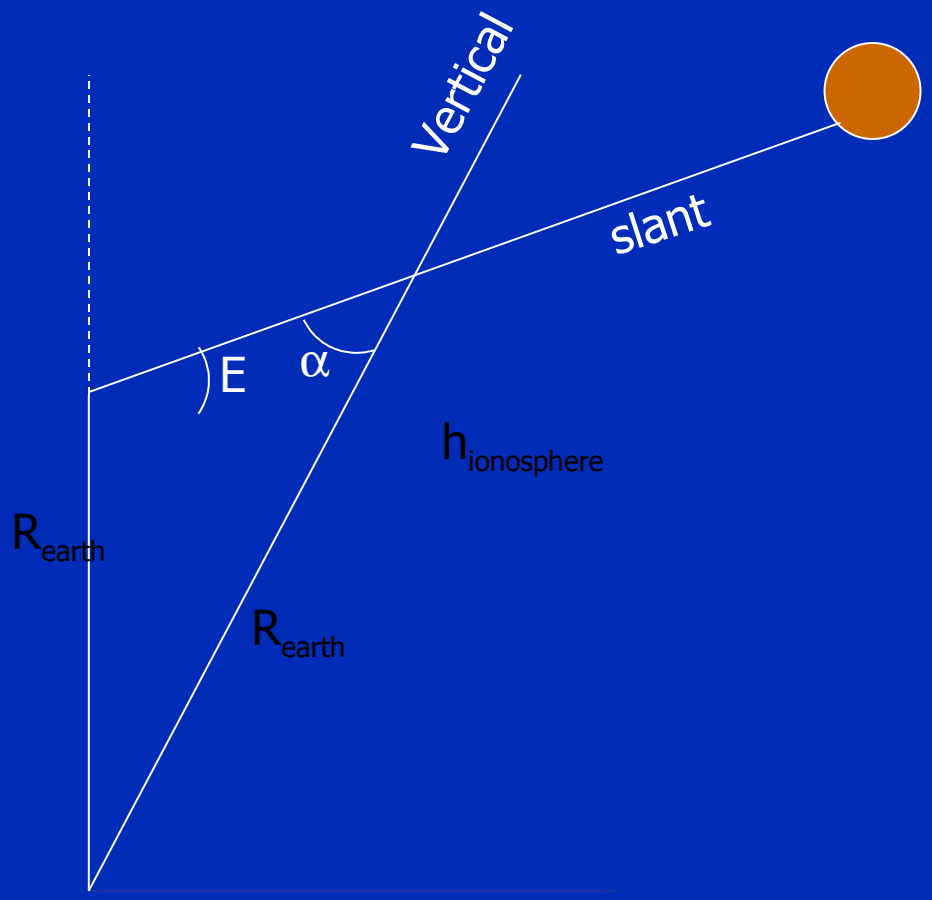
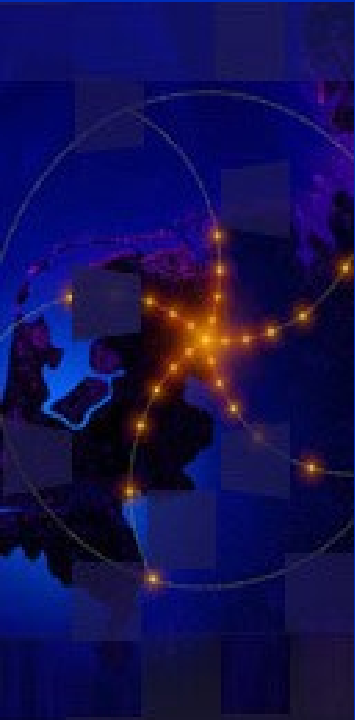
$$f_p = \sqrt{\frac{n_e e^2}{\pi m_e}} \cong 9 \sqrt{n_e} \text{ kHz} \quad n_e \text{ plasma density}$$

Corresponding phase delay,

$$\Delta \phi (f) = \frac{2\pi}{f} \left\{ \frac{e^2}{8\pi^2 m_e \epsilon_0 c} \right\} STEC$$

time delay between adjacent subbands,

$$\Delta T = \frac{\Delta \phi}{2\pi f}$$



$$m = \frac{STEC}{VTEC} = \frac{1}{\cos \alpha};$$

$$m = \frac{1}{\sqrt{1 - \left(\frac{R_{earth}}{R_{earth} + h_{ionosphere}} \right)^2 \cos^2 E}}$$

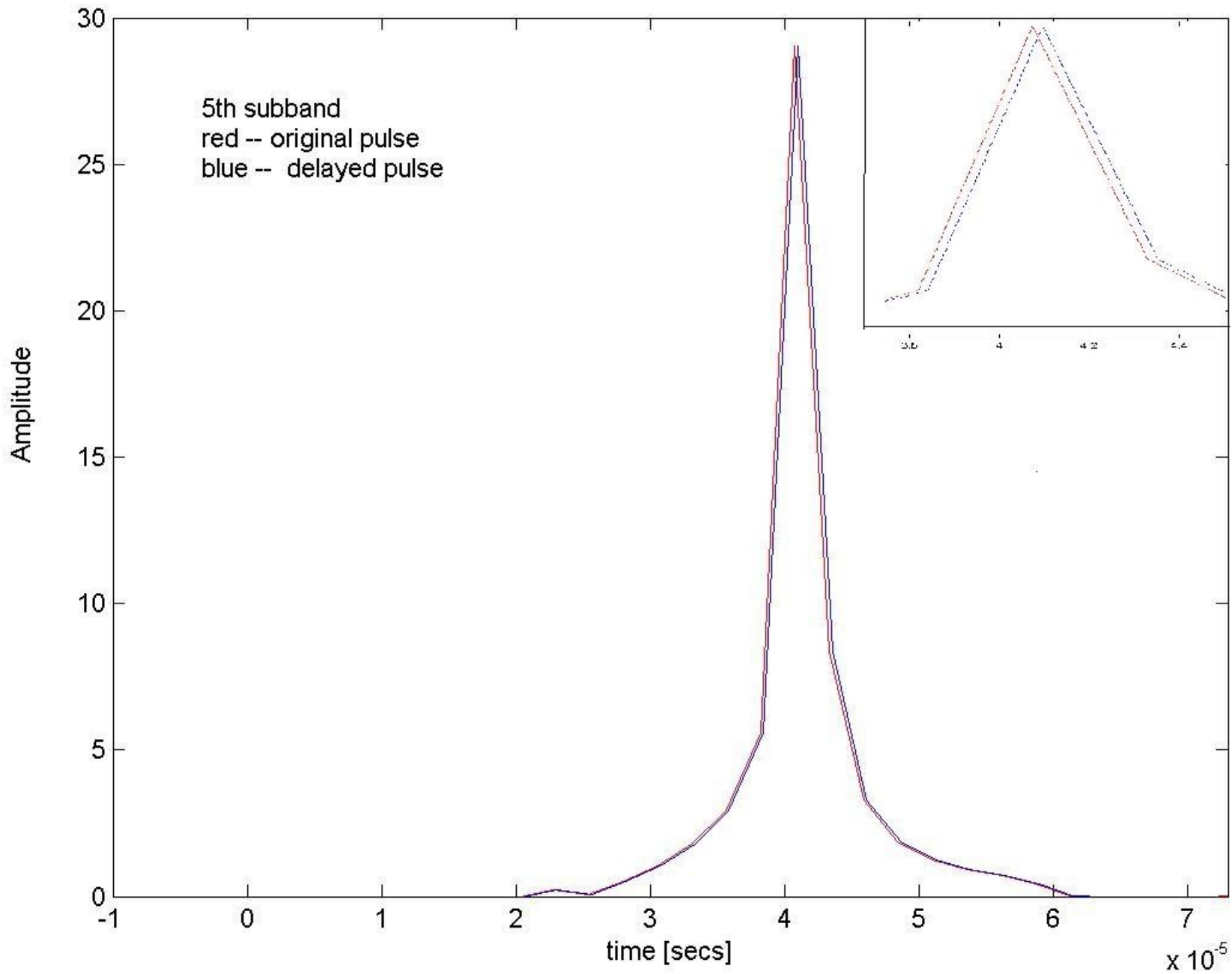
$$\sin E = \sin \phi \cdot \sin \delta + \cos \phi \cdot \cos \delta \cdot \cos H$$

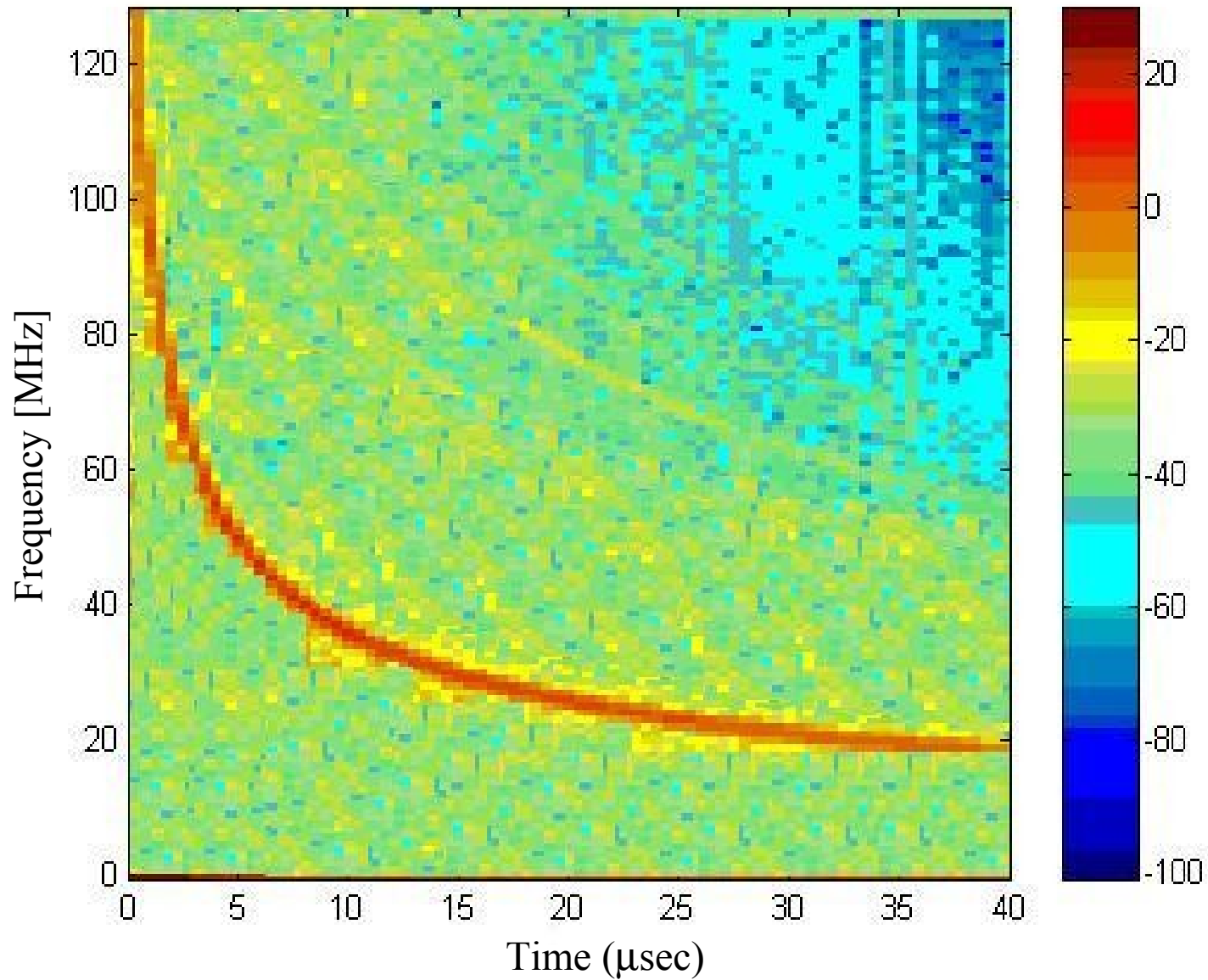
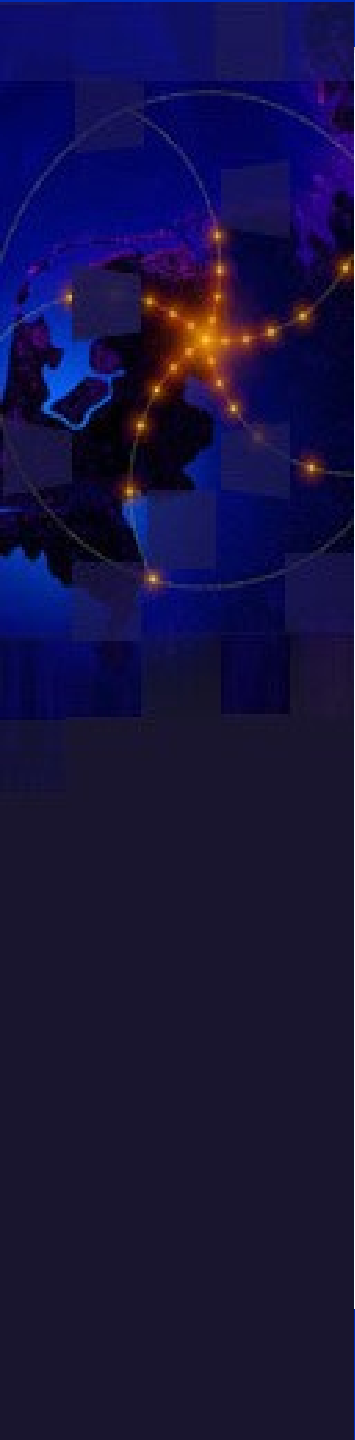
where,

ϕ = geomagnetic latitude of observer

δ = equatorial coordinate declination

H = hour angle





Thank you !!