Minutes of Meeting LOFAR Software

	_
Date:	2010-04-07
Next meeting:	2010-04-14 9:30-10:30
	Multimedia room
Present:	
Andre Gunst	Yes
Ronald Nijboer	Yes
Ruud Overeem	Yes
John Romein	No
Michael Wise	Yes
Harm Munk	No
Hanno Holties	Yes

cc: Arnold Meijster, Rob van Nieuwpoort, Arthur Coolen, Jurjen Sluman, Pieter Donker, Chris Broekema, Joris v. Zwieten, Marcel Loose, Adriaan Renting, Ger van Diepen, Michiel v. Haarlem, Jan Reitsma, Ger de Bruyn, Arno Schoenmaker, Hanno Holties, Corina Vogt, Jan Noordam, Joe Masters, Lars Bähren, Johan Hamaker, Sven Duscha, Jan-David Mol, Teun Grit, Alwin de Jong, Frank Breitling, Anastasia Alexov, Jason Hessels, Joeri van Leeuwen, John McKean, George Heald.

Remarks previous minutes

•

Announcements

- This week there is a transient busy week.
- Stopday is at 12 April 2010.
- In May the software drivers will be upgraded of the BG/P. This takes about 2 days.

Action item overview

ID	Date submitted	Description	Owner	Planned date	Status
104	20100224	Verification test suite should be defined to test the storage manager. Ger and Chris are asked to do this.	Ronald	20100315	Open
105	20100303	Change definition HBA_ONE and HBA_TWO to HBA_ZERO and HBA_ONE. And HBA_BOTH becomes HBA_DUAL. Furthermore a definition HBA_JOINED is added.	Hanno, Ruud, Michael	20100315	Open
107	20100303	Issue tracker decision. Bugzilla (developers), Craft (system and hardware issues), science support wants to make use of the LOFAR observation tracker. For the user software the favor is for Bugzilla as well. Michael will talk to Antonis to see if this is really what we want.	Hanno/Michael	20100315	Open
110	20100317	Currently we have station beams and pencil beams. In the ICDs this will be called primary pointing direction and	All	20100414	Open

		beam. Is this the right naming convention?			
111	20100331	Organize meeting for determining the ratio between storage and processing capacity necessary for the latest CEP procurement.	André	20100405	Closed
112	20100407	Discuss the status and next steps in the pipeline integration with MAC/SAS.	Hanno	20100414	Open

Last: 110

Progress

System Integration

Achieved since last meeting:

- The ITRF beamserver works and is validated. Both for the LBA and HBA.
- The ITRF beamserver needs a 3D vector for the HBA tiles. This used to be 2D. Pieter is changing the coordinate database to support 3D vectors.
- Next step is to include the CalServer.
- In OLAP its now possible to cancel one observation without cancelling the others.
- Chris is checking why the sky is flipped with the new storage data writer together with Joris. Probably this is caused by a wrong sign.
- Hanno sets up a chat with John Swinbank, Ruud Overeem and Chris Broekema about the pipeline integration.

Problems / current activities:

- On several stations the Rubidium is not always in lock. In appears that the number of satellites received at those stations is lower on average than other stations. The exact cause is under investigation.
- Arthur works on a multi user server for the SAS server. During the last week there were some problems with simultaneous queries on the same server. Needs to be tested.

•

Next actions:

- Solutions for the high station temperature in the summer are under investigation.
- A temperature sensor will be installed in the concentrator node as well.

Imaging Pipeline (Ronald):

Achieved since last meeting:

- Ronald is looking into the required processing numbers with a focus towards the imager.
- Analytical beammodel will be implemented in the imager.

- Faraday rotation in BBS was implemented and tested by George. The tests failed and this is now under investigation.
- Joris is looking into the use of shapelets.

Problems / current activities:

- The ionospheric models have been tested on Cygnus and 3C96. Clock correction is also in. Next step doing this on multiple directions.
- Control BBS should be revisited by Marcel. How to deal with failing processing nodes and the use of the global solver.

•

•

Next actions:

• Focus on the minimal required tasks for MSSS.

Pulsar Pipeline (Michael):

Achieved since last meeting:

- All the offline tools are currently integrated and are build.
- Ken has a first version of the pipeline framework working.
- Alwin is working on the datawriter. However the progress is slow now. This has to speed up. The station decoding piece of code we get from Oxford. This costs also another two weeks.

•

•

Problems / current activities:

•

Next actions:

- Implement second transpose operation.
- Update BF datawriter.

•

VHECR Pipeline (Michael):

Achieved since last meeting:

• TBB metadata can not be included now because of other priorities (imaging pipeline) of Pieter, Ruud. As soon as the ITRF beamserver, calserver and central coordinate database is in place this will get attention.

- The triggers at the horizon found by Arthur in RS205 are probably caused by an electric fence.
- Currently the offline cosmic ray code is one big pile of software. This does not work from a maintainability point of view. Furthermore working on the same code with multiple people at the same time is very hard. Martin is busy to regroup the software and break it into multiple sources.

Problems / current activities:

•

Next actions:

•

Infrastructure (Harm)

Achieved since last meeting:

•

•

Problems / current activities:

•

Next actions:

•

•

User Data and Archive (Hanno)

Achieved since last meeting:

- Yesterday a steering group meeting was held. Progress was presented and a planning was made.
- Requested from Big Grid 0.5 FTE to support us getting the imaging pipeline software to work on Grid computing platforms. Furthermore the pipelines needs to run as well from Astrowise.
- There is already a Target cluster (3000 cores) which can be used. This can be claimed by LOFAR.
- Grid cluster of 2000 cores can be used as well.
- Test platform of 600 TByte disks, 900 TByte on tape is available in Groningen which can be partly used by LOFAR.
- Juelich will be included in the working group.
- This afternoon there is a meeting with IBM. One of the discussion items is how to use the test platform of Target for LOFAR.

• For the CEP hardware procurement archive staging machines needs to be procured as well. They should be able to achieve an overall average bandwidth of 2 Gbps. The designed peak performance should be 10-20 Gbps.

Problems / current activities:

- A quick look at Juelich: data transport protocol is now working yet. Although there are still some communication problems.
- The speed at the Lexars is still an issue.
- Identity management: half April we are able to transfer user accounts and project information through the archive.
- 21 April an archive meeting will be held with our international partners.

•

Next actions:

•

Decisions

ID	Date submitted	Decision	
02	20061220	Every Step will start with a Kick-off meeting, in which the complete software team participates.	
03	20061220	The project team starts immediately with the preparations of the next CDR in order to	
		preserve progress of the CS1 realization	
04	20070116	This meeting will take place every week on Tuesday 11:00. The existing software team meeting with all developers will stop to exist.	
05	20070130	Step 1 will be changed to 16 subbands instead of 32 subbands.	
06	20070130	Step 2 will contain a multiple node BBS. 6 µStations/Station will be postponed. Instead of this, 32 subbands measurements will be realized.	
07	20070206	Step 1 will support 160 MHz observations. The other steps will support 200 MHz as well.	
08	20070424	Step 2 will support 16 subbands @ 200MHz and 24 MHz at 160 MHz	
09	20070424	During the rest of step two, OLAP will only support observations during the weekend.	
10	20070522	The number of subbands per Measurement Set is set to 6 or 8 default.	
11	20070522	Scheduler activities will be preferably activated in Q4 2007.	
12	20070522	Procure, three Local Control Units to accommodate 12 microstations in CS010 in a quick way.	
13	20070529	Integrate version numbers in all software.	
14	20070529	Distinguish the software between a production version and an engineering version (partly now already the case).	
15	20070605	All developed software under CVS will be transferred to Subversion. The main reason for this is that Subversion supports the integration of version numbers in the executables. In this way you can always retrieve which software is used for a certain build. First the impact of the transfer will be investigated by Marcel.	
16	20070619	Marcel Loose will be the librarian of the LOFAR software. The available time for this will be shared with his BBS work.	
17	20070710	The known pulsar survey mode will be the next mode to support (not in its full extent but partly on-line and off-line).	
18	20070710	The temporarily off-line part of the known pulsar mode pipeline will not be under control of SAS/MAC. This will be put under control of SAS/MAC as soon as that	

200701814 Joe Masters makes the routine to read in the TBB data.			coftware is available in the on line part of the system	
20 20071002 Fault tolerance of the system (mainly OLAP) is put at the top of the priority list after closing the SAS-MAC and CEP integration. 21 20071123 Kubuntu 7.10 desktop 64 bit OS is chosen for all machines except the BG/L and MAC/SAS machines 22 20071121 Station calibration work is smeared out over Step 4 and Step 5. 23 20071211 Station calibration work is smeared out over Step 4 and Step 5. 24 20071211 Multiple beams per observation will be implemented instead of multiple observations (this is consistent with the plan). 25 20071211 Step 3 will be closed next Thursday. Any open items will be finished in Step 4. 26 20080130 Multiple beams are defined as multiple directions with the same set of antennas. 27 20080206 Step 4 and Step 5 for MAC/SAS will be changed. The control of the offline pipeline will be postponed because the offline subsystems are not fixed yet. Currently the definition and design of the metadata flows will be set as goal for Step 4 and the implementation of the metadata is included in the Measurement Set. 28 20080213 Currently a single subband and single beam is stored in a Measurement Set. As soon as we are ready for mosaicing this probably should be changed in the future. 29 20080227 For storing the raw station beams the samitizing operations like input buffer will be included in the online part. For this OLAP h	10	20070014	software is available in the on-line part of the system.	
closing the SAS-MAC and CEP integration.				
20071123 Kubuntu 7.10 desktop 64 bit OS is chosen for all machines except the BG/L and MAC/SAS machines	20	200/1002		
MAC/SAS machines	21	20071123	Kubuntu 7 10 deskton 64 bit OS is chosen for all machines except the BG/L and	
20071123 Gilobal bandpass shape is moved to Step 5 because of its low priority.	21	20071123	1	
23 20071123 Global bandpass shape is moved to Step 5 because of its low priority. 24 20071211 Multiple beams per observation will be implemented instead of multiple observations (this is consistent with the plan). 25 20071211 Step 3 will be closed next Thursday. Any open items will be finished in Step 4. 26 20080130 Multiple beams are defined as multiple directions with the same set of antennas. Hence, only the angle, subbands and beamlets can be modified per beam. 27 20080206 Step 4 and Step 5 for MAC/SAS will be changed. The control of the offline pipeline will be postponed because the offline subsystems are not fixed yet. Currently the definition and design of the metadata flow will be the end goal of Step 5. Hence, after Step 5 (part of) the metadata is included in the Measurement Set. 28 20080213 Currently a single subband and single beam is stored in a Measurement Set. As soon as we are ready for mosaicing this probably should be changed in the future. 29 20080220 For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. 30 20080227 Weekly build environment will be updated and automated. 31 2008023 Weekly build environment will be updated and obsolet	22	20071123	Station calibration work is smeared out over Step 4 and Step 5.	
20071211 Multiple beams per observation will be implemented instead of multiple observations (this is consistent with the plan).	23			
(this is consistent with the plan). 25 20071211 Step 3 will be closed next Thursday. Any open items will be finished in Step 4. 26 20080130 Multiple beams are defined as multiple directions with the same set of antennas. Hence, only the angle, subbands and beamlets can be modified per beam. 27 20080206 Step 4 and Step 5 for MAC/SAS will be changed. The control of the offline pipeline will be postponed because the offline subsystems are not fixed yet. Currently the definition and design of the metadata flow will be the end goal of Step 4 and the implementation of the metadata flow will be the end goal of Step 4 and the implementation of the metadata flow will be the end goal of Step 5. Hence, after Step 5 (part of) the metadata is included in the Measurement Set. 28 20080213 Currently a single subband and single beam is stored in a Measurement Set. As soon as we are ready for mosacing this probably should be changed in the future. 29 20080220 For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. 30 20080227 Weekly build environment will be updated and automated. 31 20080423 Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. <	24			
25 20071211 Step 3 will be closed next Thursday. Any open items will be finished in Step 4. 26 20080130 Multiple beams are defined as multiple directions with the same set of antennas. Hence, only the angle, subbands and beamlets can be modified per beam. 27 20080206 Step 4 and Step 5 for MAC/SAS will be changed. The control of the offline pipeline will be postponed because the offline subsystems are not fixed yet. Currently the definition and design of the metadata flow will be set as goal for Step 4 and the implementation of the metadata flow will be the end goal of Step 5. Hence, after Step 5 (part of) the metadata is included in the Measurement Set. As soon as we are ready for mosaicing this probably should be changed in the future. 29 20080220 For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. 30 20080227 Weekly build environment will be updated and automated. 31 20080227 Weekly build environment will be updated and automated. 32 20080423 Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. 33 20080528 The position of all individual dipoles will be made available centrally in the database.				
20080206	25	20071211	Step 3 will be closed next Thursday. Any open items will be finished in Step 4.	
Step 4 and Step 5 for MAC/SAS will be changed. The control of the offline pipeline will be postponed because the offline subsystems are not fixed yet. Currently the definition and design of the metadata flow will be set as goal for Step 4 and the implementation of the metadata flow will be the end goal of Step 5. Hence, after Step 5 (part of) the metadata is included in the Measurement Set. As soon as we are ready for mosaicing this probably should be changed in the future. 20080220	26	20080130	Multiple beams are defined as multiple directions with the same set of antennas.	
will be postponed because the offline subsystems are not fixed yet. Currently the definition and design of the metadata flows will be set as goal for Step 4 and the implementation of the metadata flow will be the end goal of Step 5. Hence, after Step 5 (part of) the metadata is included in the Measurement Set. 28 20080213 Currently a single subband and single beam is stored in a Measurement Set. As soon as we are ready for mosaicing this probably should be changed in the future. 29 20080220 For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. 30 20080227 Weekly build environment will be updated and automated. 31 20080227 After Step 5 the software documentation will be updated and obsolete packages will be removed. 32 20080423 Baically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. 33 20080528 The position of all individual dipoles will be made available centrally in the database. 34 20080603 The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in TIRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. 35 20080903 Kubuntu will be installed on LOFAR18, which will serve as a software development machine. 36 20081029 Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). 37 20081029 We will transfer the build environment to cmake. 38 20081029 Step 1 will be closed at 11 November. 39 20081126 The 4 bit mode wi		20000206		
definition and design of the metadata flows will be set as goal for Step 4 and the implementation of the metadata is included in the Measurement Set. 28 20080213	27	20080206		
implementation of the metadata flow will be the end goal of Step 5. Hence, after Step 5 (part of) the metadata is included in the Measurement Set. 2080213 Currently a single subband and single beam is stored in a Measurement Set. As soon as we are ready for mosaicing this probably should be changed in the future. 29 20080220 For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. 30 20080227 Weekly build environment will be updated and automated. 31 20080227 After Step 5 the software documentation will be updated and obsolete packages will be removed. 32 20080423 Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. 33 20080528 The position of all individual dipoles will be made available centrally in the database. The data format of the positions will be elivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. 35 20080903 Kubuntu will be installed on LOFAR18, which will serve as a software development machine. 36 20081029 Step 1 will be closed at 11 November. 37 20081029 We will transfer the build environment to emake. 38 20081029 Step 1 will be closed at 11 November. 39 20081029 The data format will be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 W				
Social part of) the metadata is included in the Measurement Set.				
20080221 Currently a single subband and single beam is stored in a Measurement Set. As soon as we are ready for mosaicing this probably should be changed in the future. For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC.				
as we are ready for mosaicing this probably should be changed in the future. For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. Weekly build environment will be updated and automated. After Step 5 the software documentation will be updated and obsolete packages will be removed. Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. The position of all individual dipoles will be made available centrally in the database. The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Sou80903 Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. We will modify the build environment to cmake from now on. Z0081126 The 4 bit mode will be supported after MS on the formation of the positions. Since, this is an order to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS on	20	20000212		
For storing the raw station beams the sanitizing operations like input buffer will be included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. 30 20080227 Weekly build environment will be updated and automated. 31 20080227 After Step 5 the software documentation will be updated and obsolete packages will be removed. 32 20080423 Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. 33 20080528 The position of all individual dipoles will be made available centrally in the database. The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. 35 20080903 Kubuntu will be installed on LOFAR18, which will serve as a software development machine. 36 20081029 Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). 37 20081029 We will transfer the build environment to cmake. 38 20081029 Step 1 will be closed at 11 November. 39 20081112 Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 2008126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Pelay deadline of Step 2 to	28	20080213		
included in the online part. For this OLAP has to give operational support or instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. Weekly build environment will be updated and automated. After Step 5 the software documentation will be updated and obsolete packages will be removed. Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. The position of all individual dipoles will be made available centrally in the database. The position of all individual dipoles will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Stap 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. The 4 bit mode will be supported after MS to succeed the succeeding. Poly 1 were as a software meeting. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3.	20	20000020		
instructions to the observers how to start up manually such observations. Since, this is an between solution this will not be automated via SAS/MAC. Weekly build environment will be updated and automated. After Step 5 the software documentation will be updated and obsolete packages will be removed. Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. The position of all individual dipoles will be made available centrally in the database. The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. We will modify the build environment to cmake from now on. Transient source modeling tool under Python will be used for source modeling. The stations including the ring splitter near the core will be renamed to CS stations.	29	20080220		
an between solution this will not be automated via SAS/MAC. 30 20080227 Weekly build environment will be updated and automated. 31 20080227 After Step 5 the software documentation will be updated and obsolete packages will be removed. 32 20080423 Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. 33 20080528 The position of all individual dipoles will be made available centrally in the database. 34 20080603 The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. 35 20080903 Kubuntu will be installed on LOFAR18, which will serve as a software development machine. 36 20081022 Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). 37 20081029 We will transfer the build environment to cmake. 38 20081029 Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
20080227 Weekly build environment will be updated and automated.				
After Step 5 the software documentation will be updated and obsolete packages will be removed.			an between solution this will not be automated via SAS/MAC.	
be removed. Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense. The position of all individual dipoles will be made available centrally in the database. The position of all individual dipoles will be made available centrally in the database. The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. We will modify the build environment to cmake from now on. Transient source modeling tool under Python will be used for source modeling. Poleay deadline of Step 2 to 26 February 2009. Remote Stations including the ring splitter near the core will be renamed to CS stations.	30	20080227	Weekly build environment will be updated and automated.	
Basically two Low Band modes will be supported initially: a LBL and LBH mode. The connection between antennas and RCUs have to be chosen such that those to modes make sense.	31	20080227	After Step 5 the software documentation will be updated and obsolete packages will	
The connection between antennas and RCUs have to be chosen such that those to modes make sense. The position of all individual dipoles will be made available centrally in the database. The position of all individual dipoles will be made available centrally in the database. The data format of the positions will be stored in ITRF coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. We will modify the build environment to cmake from now on. Transient source modeling tool under Python will be used for source modeling. Delay deadline of Step 2 to 26 February 2009. Remote Stations including the ring splitter near the core will be renamed to CS stations.			be removed.	
modes make sense. The position of all individual dipoles will be made available centrally in the database. The position of all individual dipoles will be made available centrally in the database. The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Substance of the LOFAR system. Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. We will modify the build environment to cmake from now on. Transient source modeling tool under Python will be used for source modeling. 20090129 Transient source modeling tool under Python will be renamed to CS stations.	32	20080423		
3320080528The position of all individual dipoles will be made available centrally in the database.3420080603The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system.3520080903Kubuntu will be installed on LOFAR18, which will serve as a software development machine.3620081022Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU).3720081029We will transfer the build environment to cmake.3820081029Step 1 will be closed at 11 November.3920081112Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded.4020081126The 4 bit mode will be supported after MS^3.4120081203We will modify the build environment to cmake from now on.4220090129Transient source modeling tool under Python will be used for source modeling.4320090129Delay deadline of Step 2 to 26 February 2009.4420090209Remote Stations including the ring splitter near the core will be renamed to CS stations.			The connection between antennas and RCUs have to be chosen such that those to	
The data format of the positions will be delivered in ETRS coordinates by the roll out team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. The 4 bit mode will be supported after MS on the formation of the source modeling. Transient source modeling tool under Python will be used for source modeling. Delay deadline of Step 2 to 26 February 2009. Remote Stations including the ring splitter near the core will be renamed to CS stations.				
team. However, the data format of the positions will be stored in ITRF format in the LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Stubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. The 4 bit mode will be supported after MS^3. Transient source modeling tool under Python will be used for source modeling. Transient source modeling tool under Python will be renamed to CS stations.				
LOFAR databases. Hence, all software and configuration files dealing with coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. 35 20080903 Kubuntu will be installed on LOFAR18, which will serve as a software development machine. 36 20081022 Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). 37 20081029 We will transfer the build environment to cmake. 38 20081029 Step 1 will be closed at 11 November. 39 20081112 Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.	34	20080603		
coordinates must be made compatible with the ITRF dataformat. Hans van de Marel is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Substitution (1988) Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. We will modify the build environment to cmake from now on. Transient source modeling tool under Python will be used for source modeling. Delay deadline of Step 2 to 26 February 2009. Remote Stations including the ring splitter near the core will be renamed to CS stations.				
is responsible to convert the ETRS coordinates to ITRF coordinates for the LOFAR system. Kubuntu will be installed on LOFAR18, which will serve as a software development machine. Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). We will transfer the build environment to cmake. Step 1 will be closed at 11 November. Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. The 4 bit mode will be supported after MS^3. We will modify the build environment to cmake from now on. Transient source modeling tool under Python will be used for source modeling. Delay deadline of Step 2 to 26 February 2009. Remote Stations including the ring splitter near the core will be renamed to CS stations.				
System. Substitute Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU).				
Kubuntu will be installed on LOFAR18, which will serve as a software development machine.			-	
machine. 36 20081022 Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU). 37 20081029 We will transfer the build environment to cmake. 38 20081029 Step 1 will be closed at 11 November. 39 20081112 Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.	2.5	2000000		
3620081022Station cabinet will be heated (if necessary) to 10 degrees Celsius (for the LCU).3720081029We will transfer the build environment to cmake.3820081029Step 1 will be closed at 11 November.3920081112Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded.4020081126The 4 bit mode will be supported after MS^3.4120081203We will modify the build environment to cmake from now on.4220090129Transient source modeling tool under Python will be used for source modeling.4320090129Delay deadline of Step 2 to 26 February 2009.4420090209Remote Stations including the ring splitter near the core will be renamed to CS stations.	35	20080903	=	
3720081029We will transfer the build environment to cmake.3820081029Step 1 will be closed at 11 November.3920081112Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded.4020081126The 4 bit mode will be supported after MS^3.4120081203We will modify the build environment to cmake from now on.4220090129Transient source modeling tool under Python will be used for source modeling.4320090129Delay deadline of Step 2 to 26 February 2009.4420090209Remote Stations including the ring splitter near the core will be renamed to CS stations.	36	20081022		
Step 1 will be closed at 11 November.				
Bugs found in the field have the highest priority to solve. Bugs which take more than a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
a week to solve will be added to the task list and prioritized in the software meeting. During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
During bug solving tests should be written up, which proves the correct behavior. These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
These tests will result in a procedure to check the functionality when new soft/firm ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
ware is loaded. 40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
40 20081126 The 4 bit mode will be supported after MS^3. 41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
41 20081203 We will modify the build environment to cmake from now on. 42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.	40	20081126		
42 20090129 Transient source modeling tool under Python will be used for source modeling. 43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
43 20090129 Delay deadline of Step 2 to 26 February 2009. 44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
44 20090209 Remote Stations including the ring splitter near the core will be renamed to CS stations.				
45 20090813 No connection from the Dwingeloo test environment to Groningen is necessary			stations.	
	45	20090813	No connection from the Dwingeloo test environment to Groningen is necessary	

		anymore.	
46	20090825	Create a Bugzilla environment for the USG software.	
47	20090825	Use one subcluster per group, contactpersons and guidelines defined (see section	
		Software integration).	
48	20090909	Use the filter range names of MAC/SAS for the ICDs and the archive model.	
49	20100116	HBA beam pointing: we decided that one observation is prime and determines the	
		HBA beam. The other observations will be ranked. An additional field for the HBA	
		beam pointing can be set. If this field is not set, then an average of all digital beams	
		will be made within the prime observation.	
50	20100303	Changes in definitions which are used in various places in the system will be decided	
		in this meeting.	
51	20100303	HBA_ONE and HBA_TWO will be renamed to HBA_ZERO and HBA_ONE for	
		consistency reasons.	
52	20100317	Change HBA_BOTH into HBA_DUAL (using two HBA ears independently) and add	
		HBA_ALL to indicate both HBA fields will be added at station level (so treated as	
		one field).	
53	20100317	The software should be documented more. However we decide not to set this as	
		priority now and accept this as a risk we take.	
54	20100317	The CImager will be the imager used in LOFAR. This is the only one which scales	
		up.	
55	20100331	The name HBA_ALL will be replaced by HBA_JOINED.	
56	20100407	It was decided earlier to have only one beam per observation.	

Last: 56

Table round

- Ruud: After installing a new development server (rs005) also a new test environment was installed. This works and we will switch to the new machines. Now we can test on the same software as in the field.
- Michael: James was asking for the Rubidium information of the Effelsberg station. At the end the Rubidium information logs can be made available centrally. But for the time being we could give the NTP log files manually to James.