

# Seismic observations on the moon: seismic interferometry and moonquakes

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# **Outline**

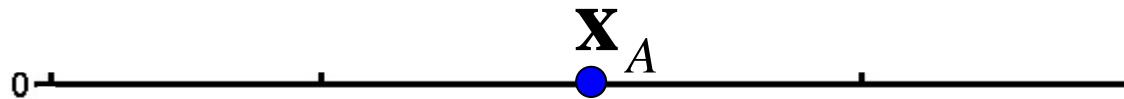
- **Seismic Interferometry**
- **LOFAR**
- **US array**
- **Moonquakes**
- **Seismic observations on the moon**

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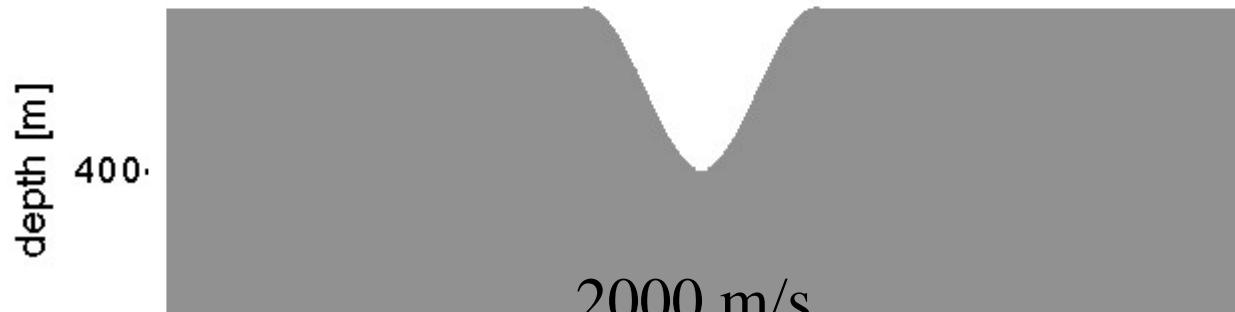
- **Seismic Interferometry**
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# Seismic Interferometry

- Pioneering work by K. Wapenaar
- Currently validation on earth:
  - works for direct surface waves
  - works for active (man-made) sources
  - works for scattered waves ??
  - works for passive sources ??



1500 m/s

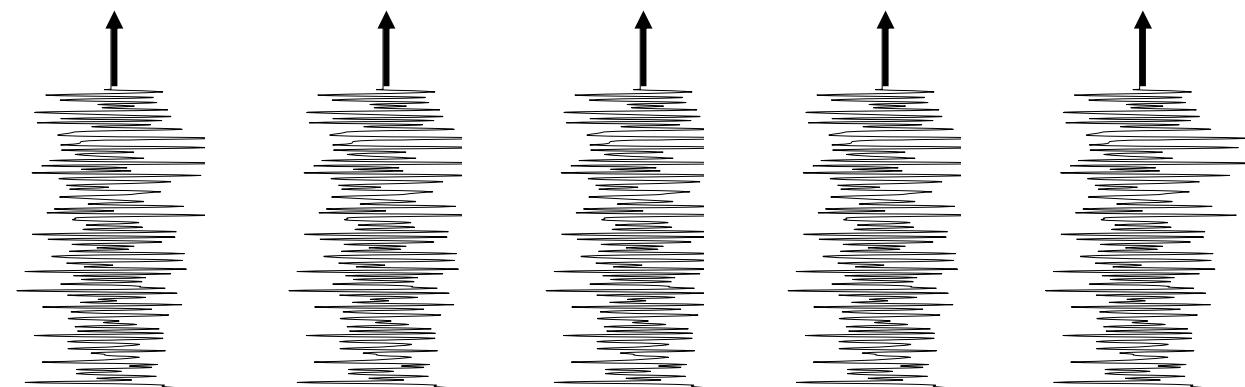


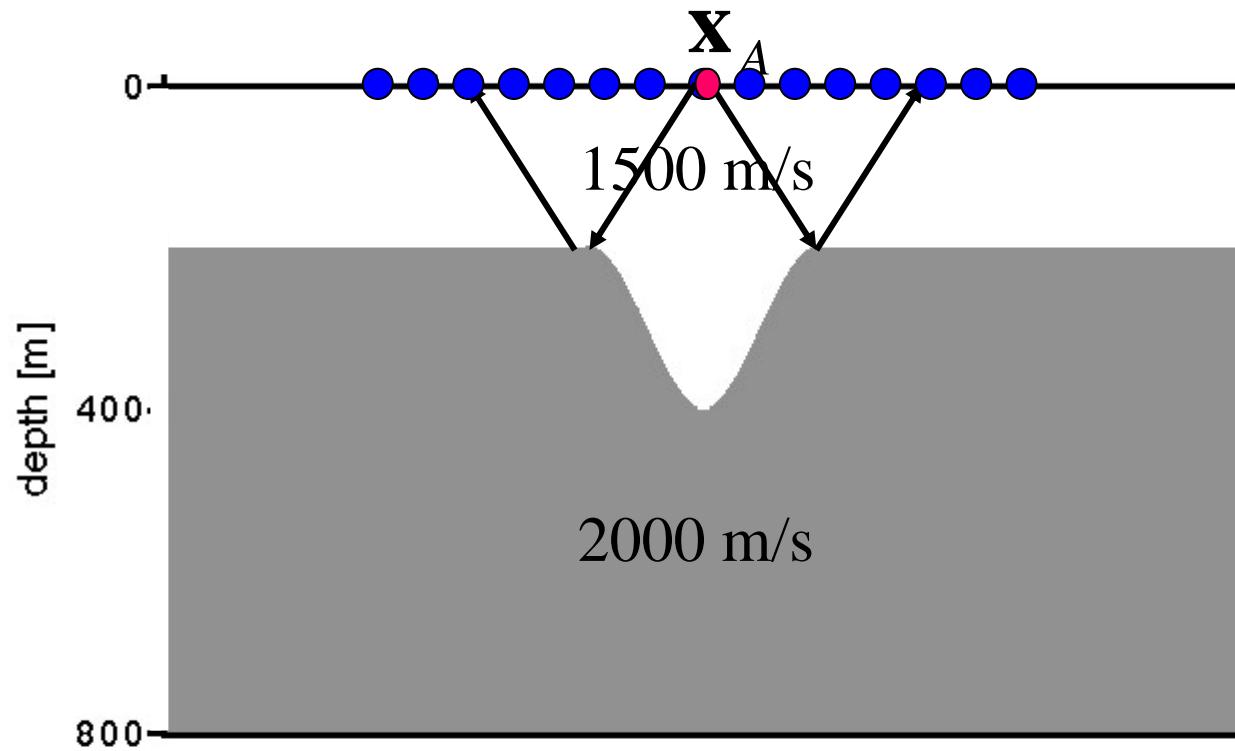
2000 m/s

depth [m]

400

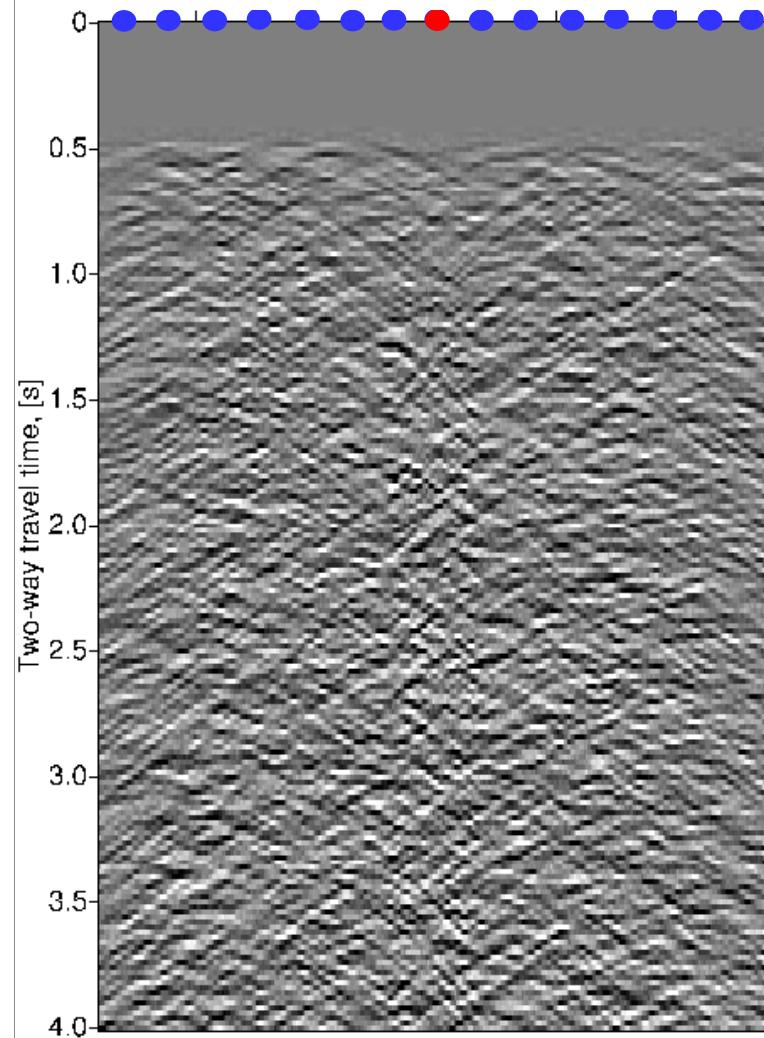
800





# Seismic Interferometry

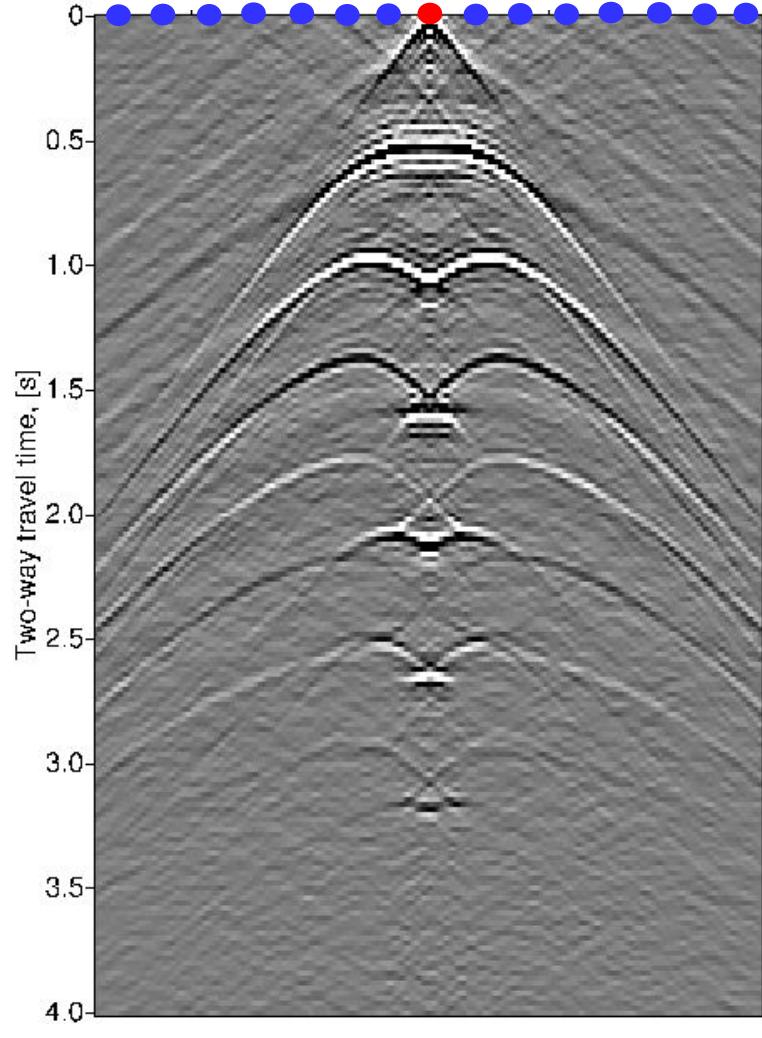
$x_B \dots x_B$     $x_A$     $x_B \dots x_B$



Transmission measurements

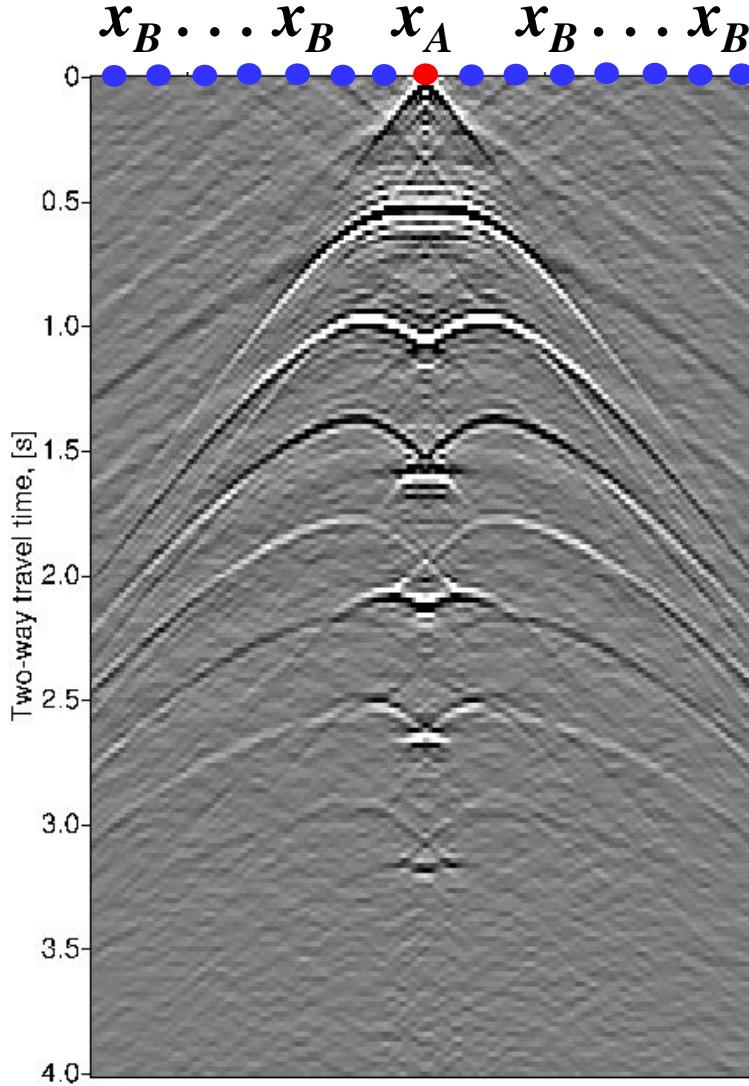
correlation

$x_B \dots x_B$     $x_A$     $x_B \dots x_B$



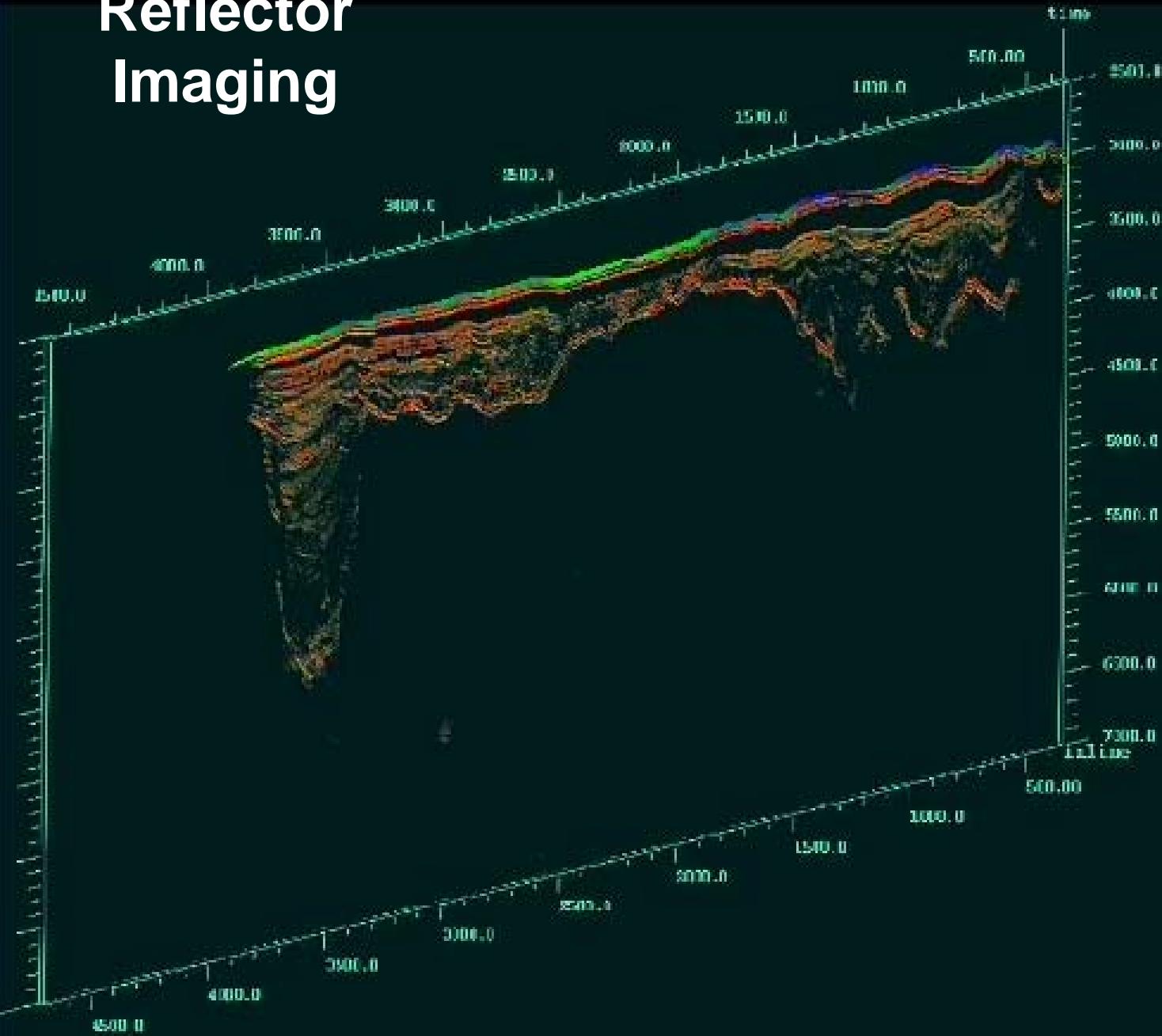
Reflection measurements

# Reflector Imaging



Reflection measurements

# Reflector Imaging



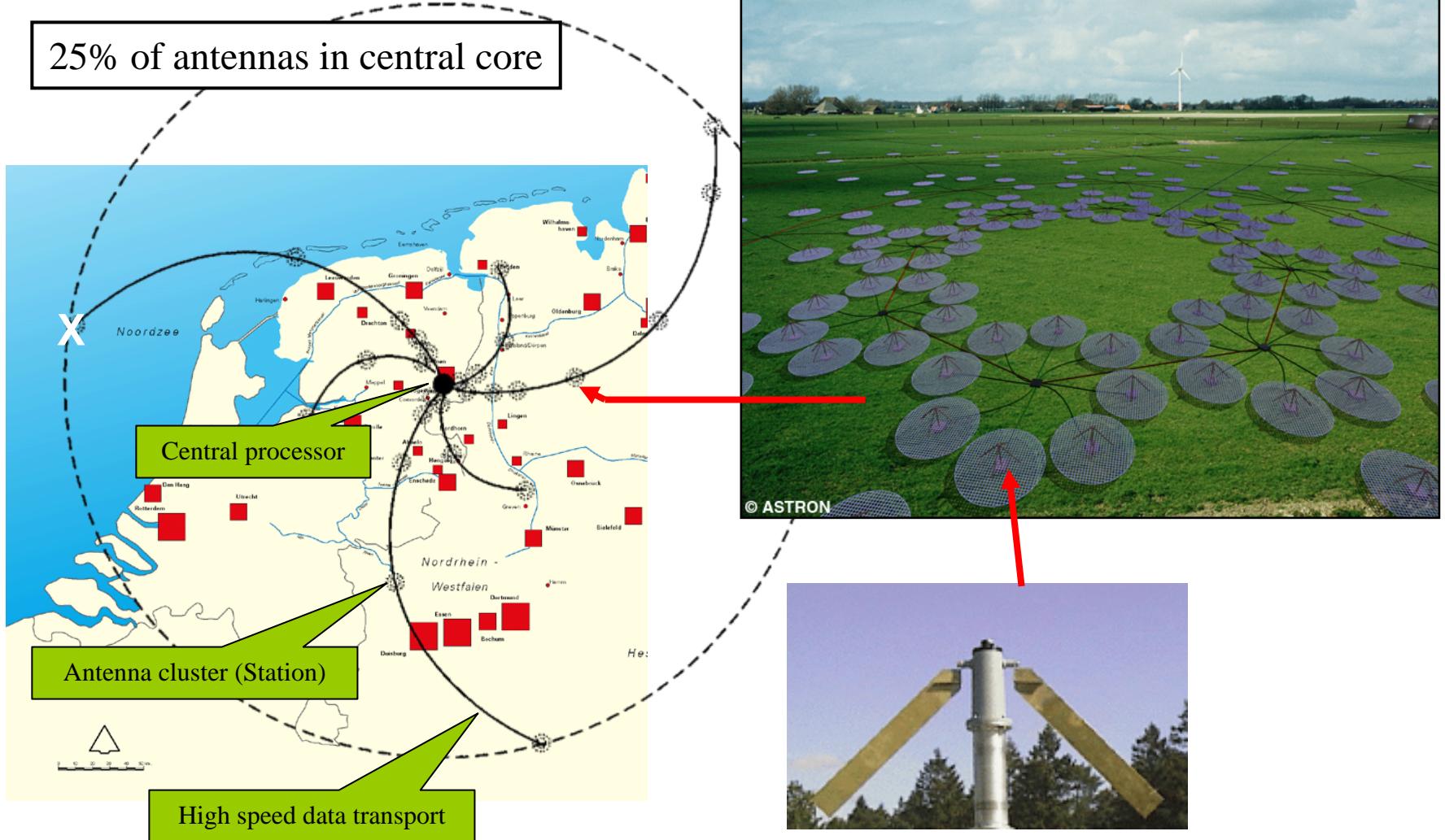
# **Interferometry: Differences with astronomy:**

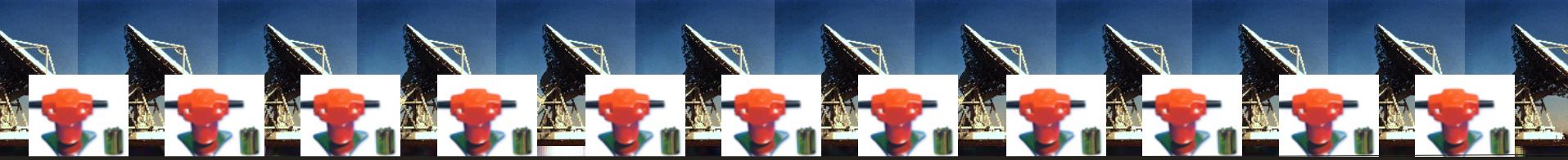
- Strongly inhomogeneous propagation model
- Reflection instead of source imaging
- Sky moving while earth static (losing 1 dimension)

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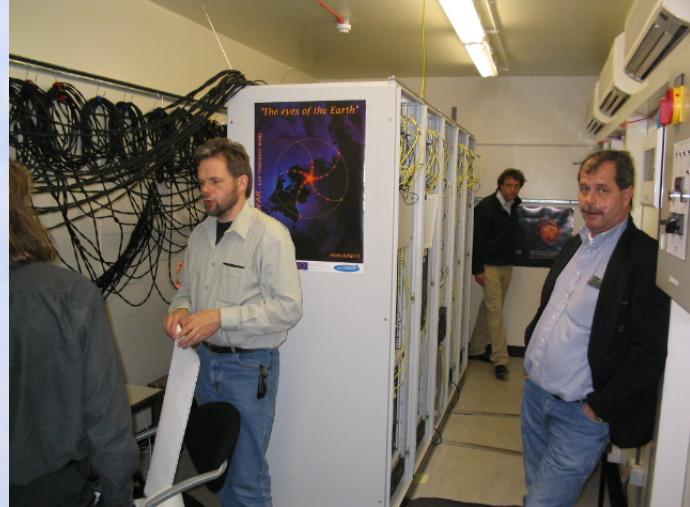
- Seismic Interferometry
- **LOFAR: crust scale**
- US array: earth scale
- Moonquakes
- Seismic observations on the moon

# LOFAR: LOw Frequency ARray





# Test-site Exloo

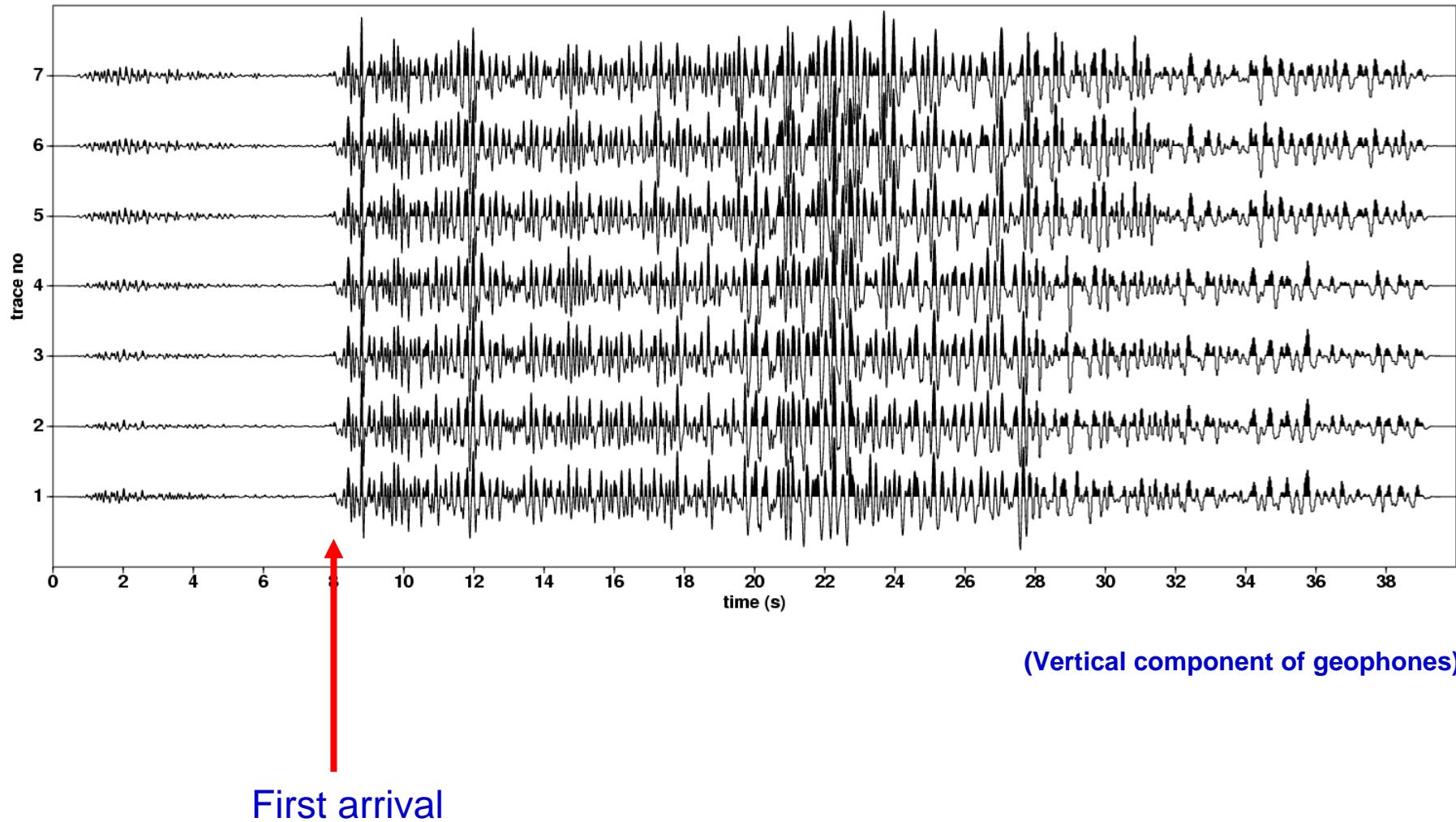


# Test-site Exloo



ISES

Quake 08 August 2006: tapered filtered(0-2-35-45) GEOPHONES



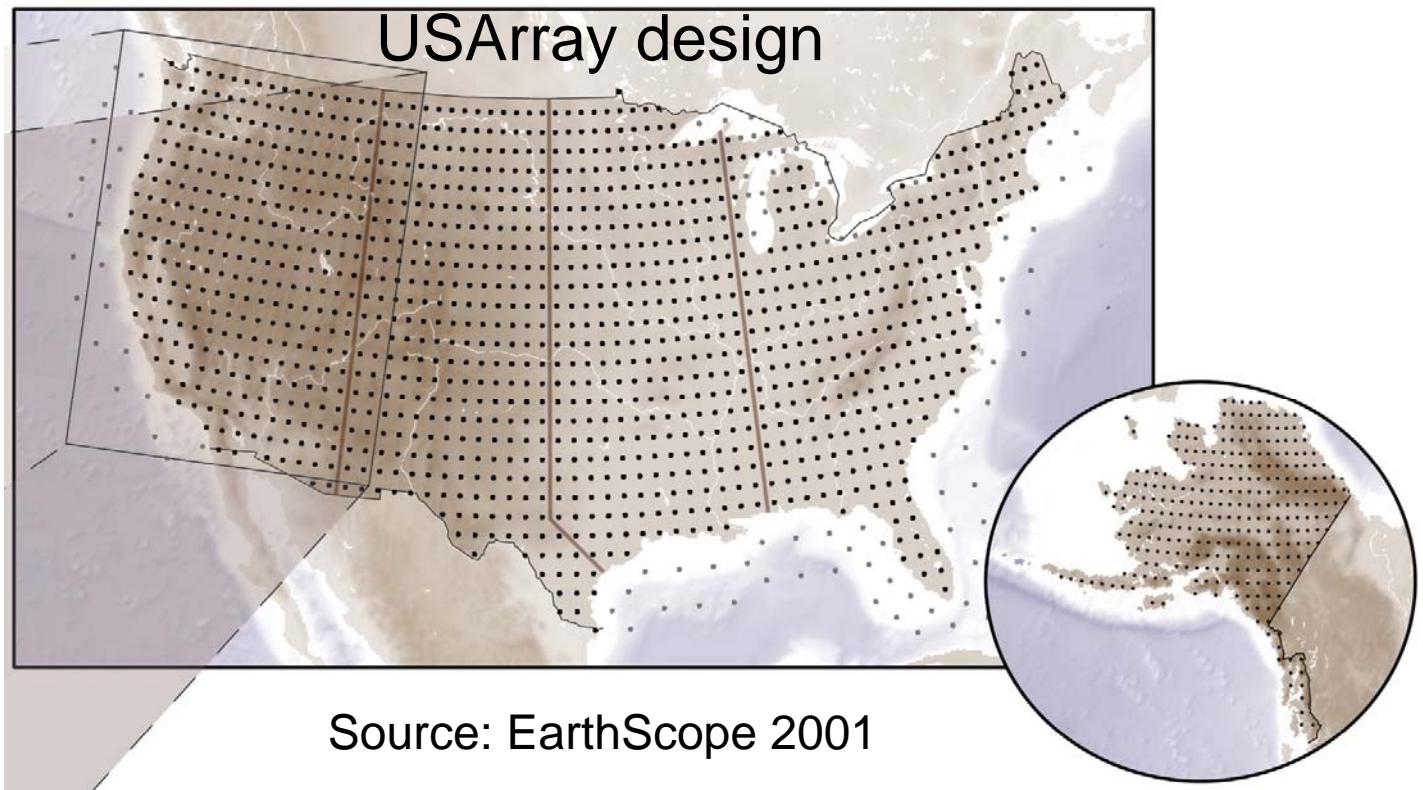
**Earthquake 08 August 2006,  
Recording at LOFAR test-site**

# Outline

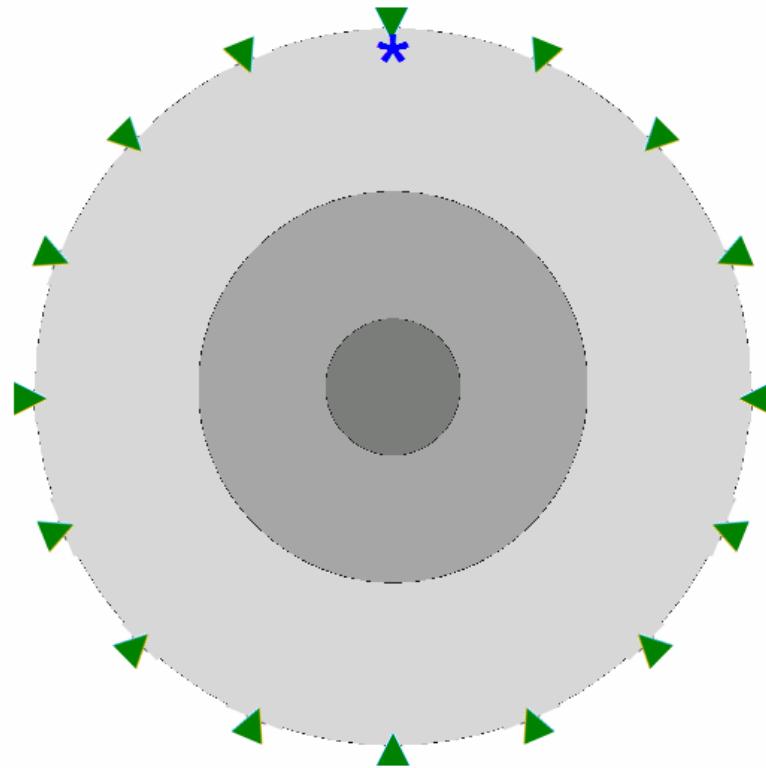
- Seismic Interferometry
- LOFAR: crust scale
- US array: earth-scale**
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# US array

**Seismic Interferometry on global-scale seismology**

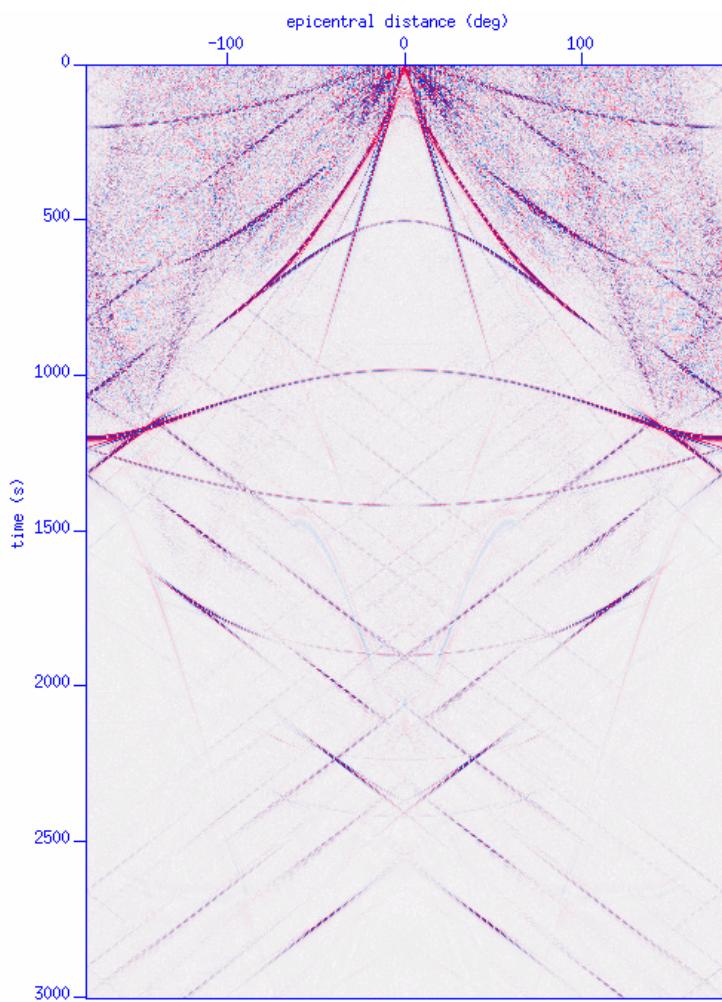


# All epicentral distances

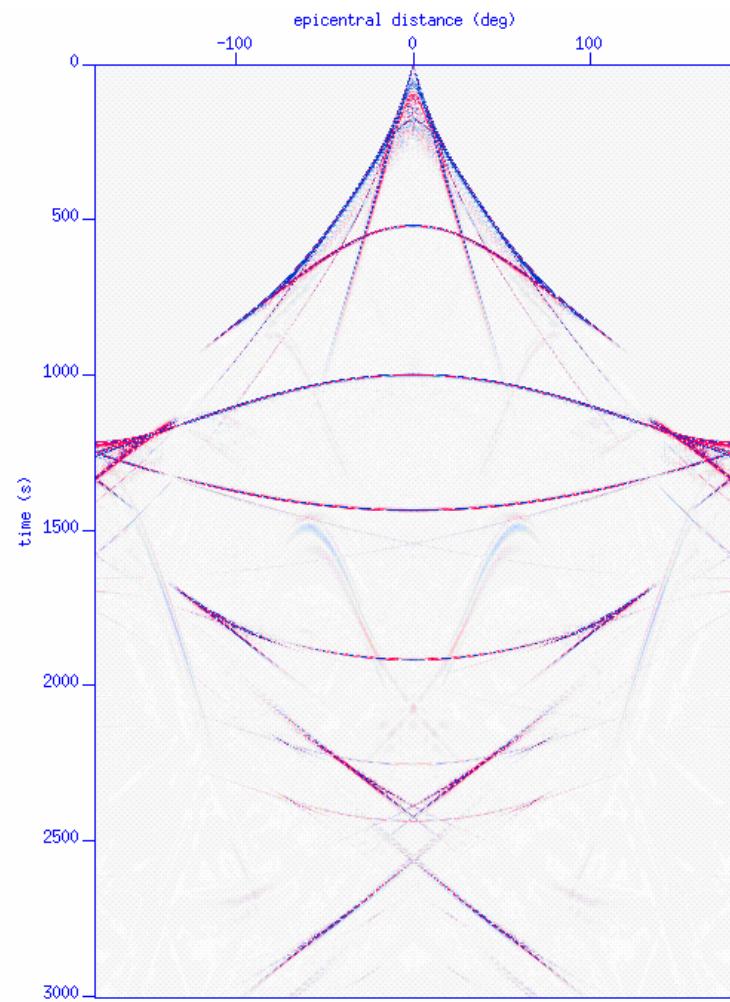


# Causal result

Reconstructed

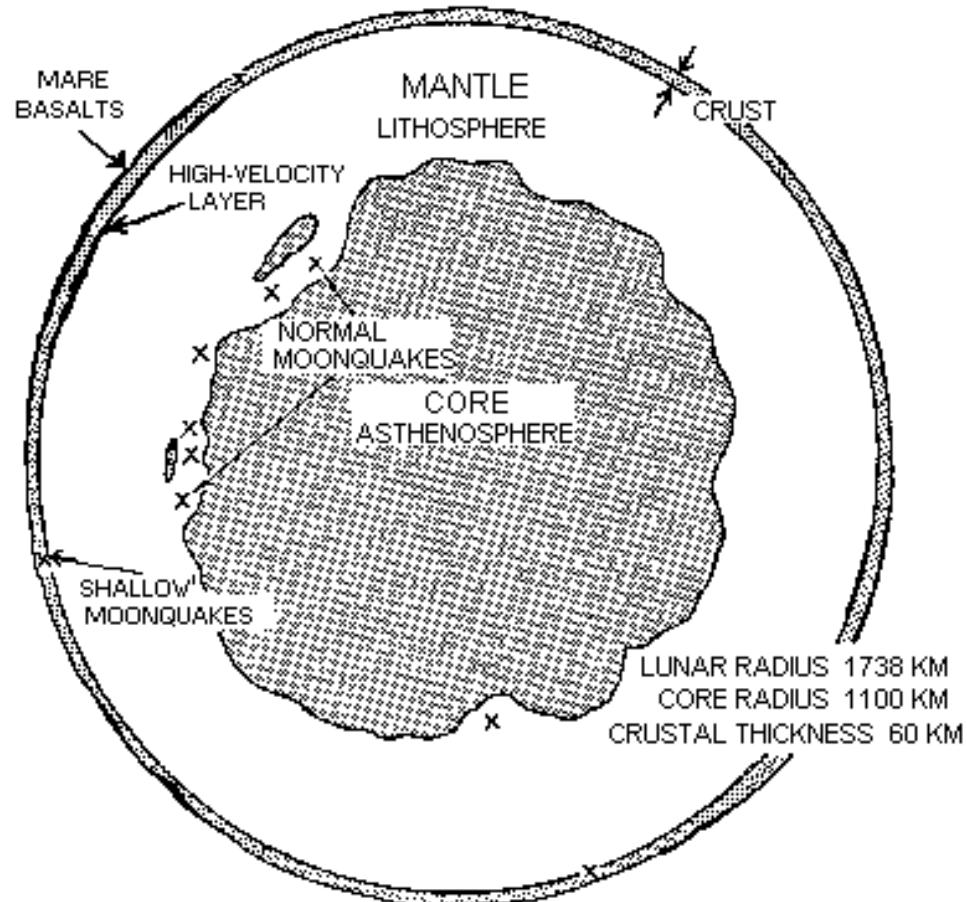


Directly modeled  $G_0^{p,f}(\mathbf{x}, \mathbf{x}_B, t)$



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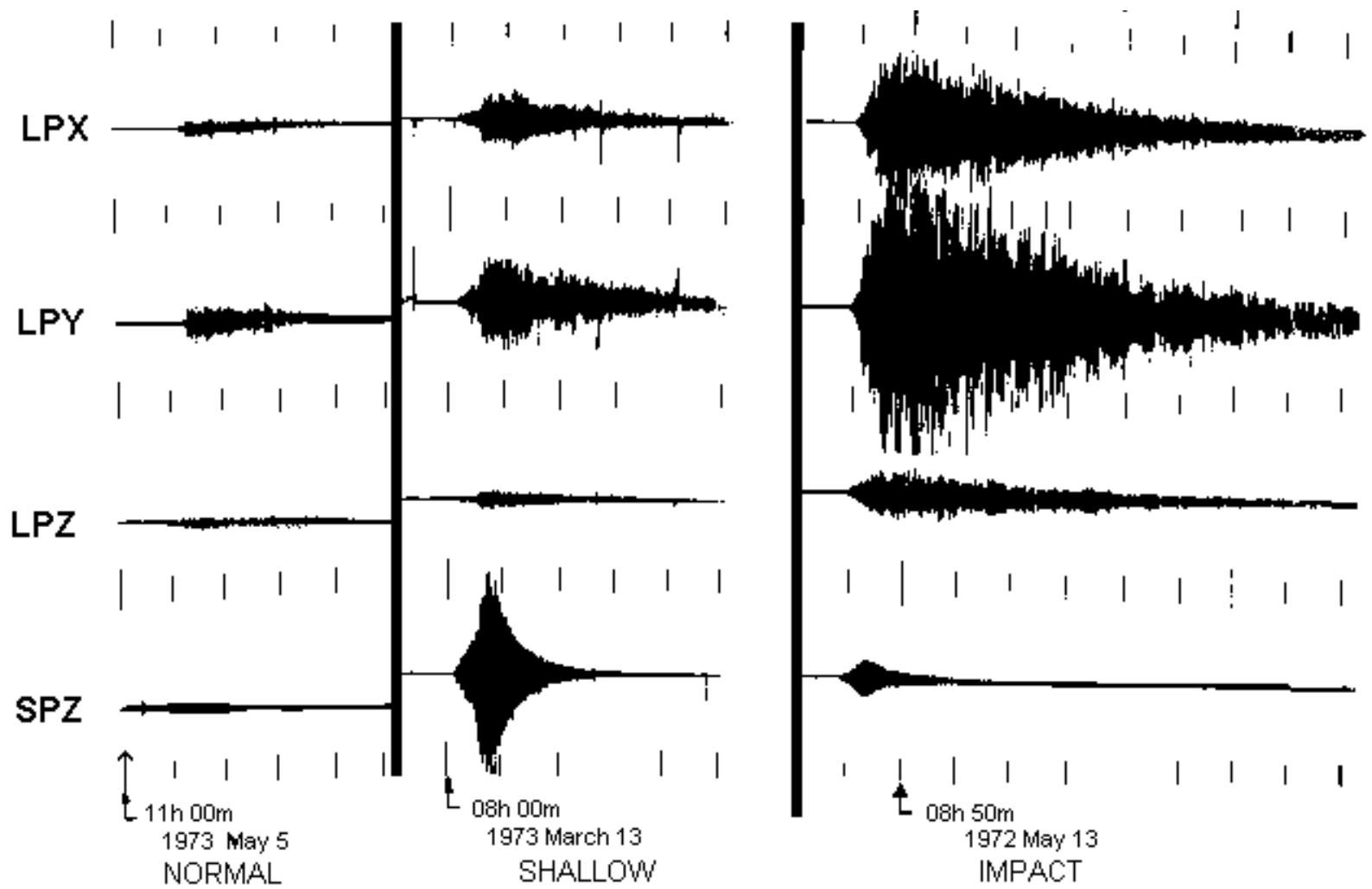
**Some background on the seismology of Moonquakes.  
G.A. EIBY: "EARTHQUAKES"**

# **Three causes of lunar seismicity:**

- Impacts
- Shallow: 0-60 km (crustal stresses)
- Deep : 600 – 900 km (tidal forces)

## **Features:**

- ‘High’ frequency (0.1 – 1.0 Hz)
- Small amplitudes (0.5 – 1.3 Richter)
- Low damping
- Long reverberations (~ 60 minutes)



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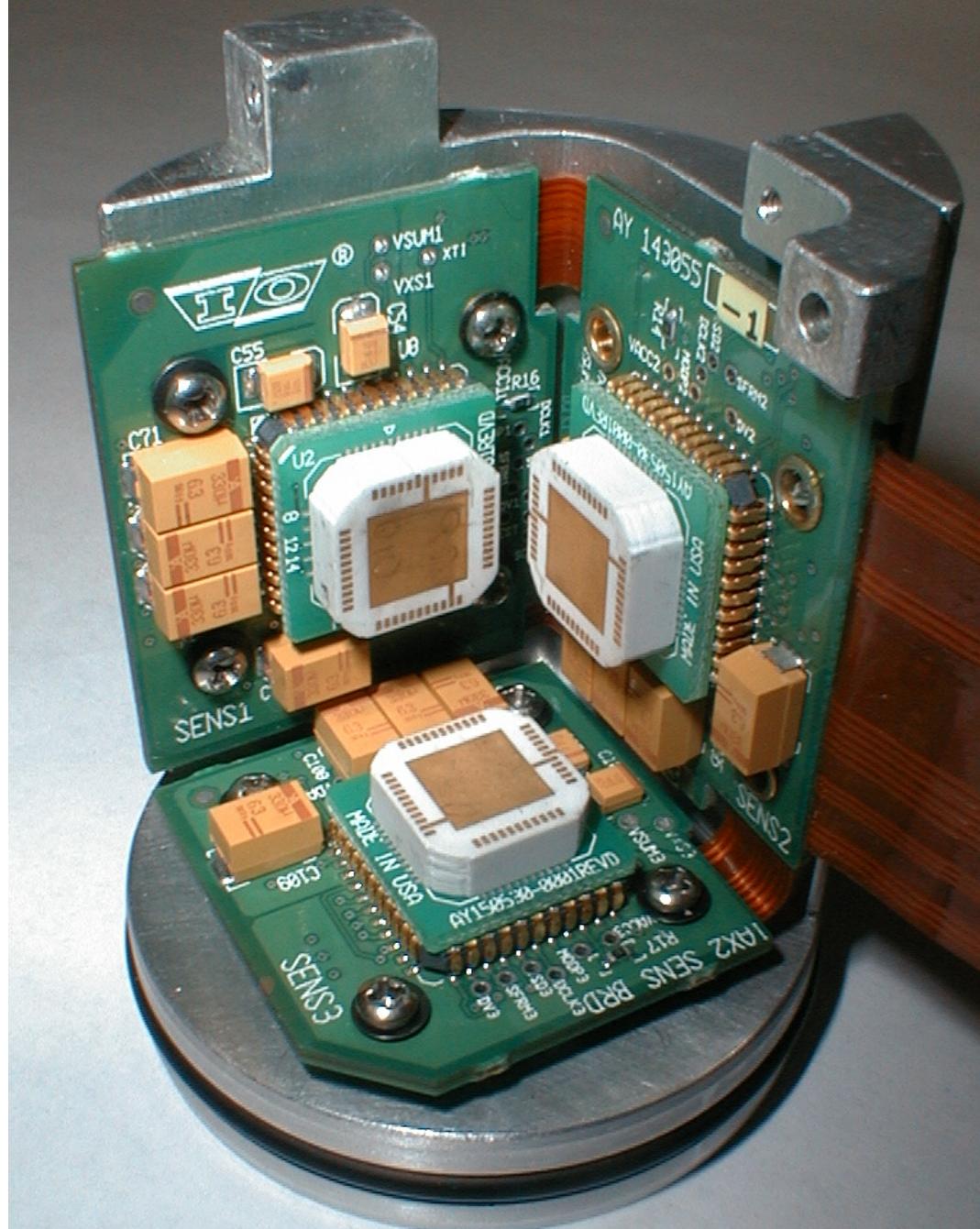
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# Idea:

- Not a few but *many* stations: only then structure can be imaged
- Light-weight low-power sensors:
  - Micro-machined sensors

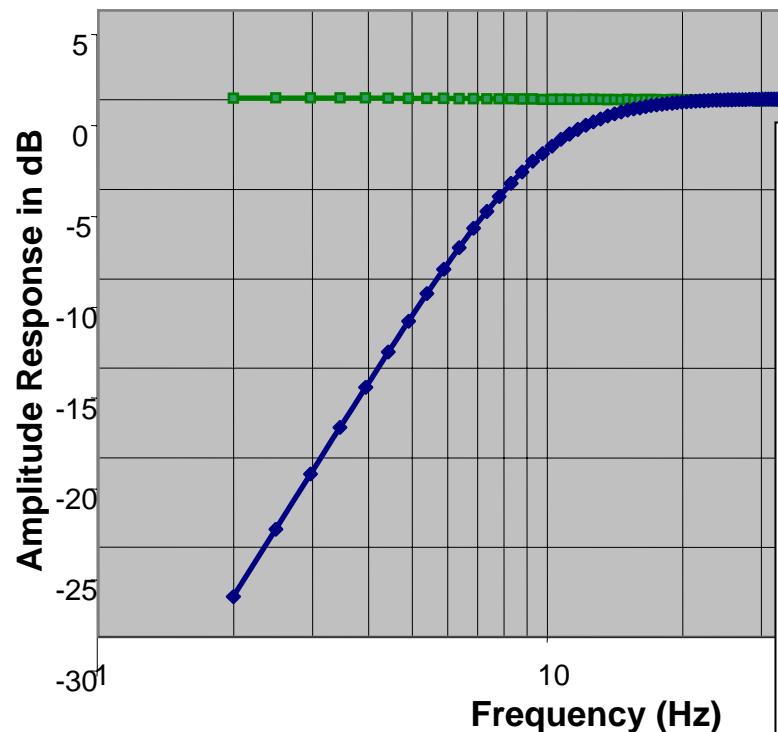
# VectorSeis® Digital Sensor

- No tilt limitations

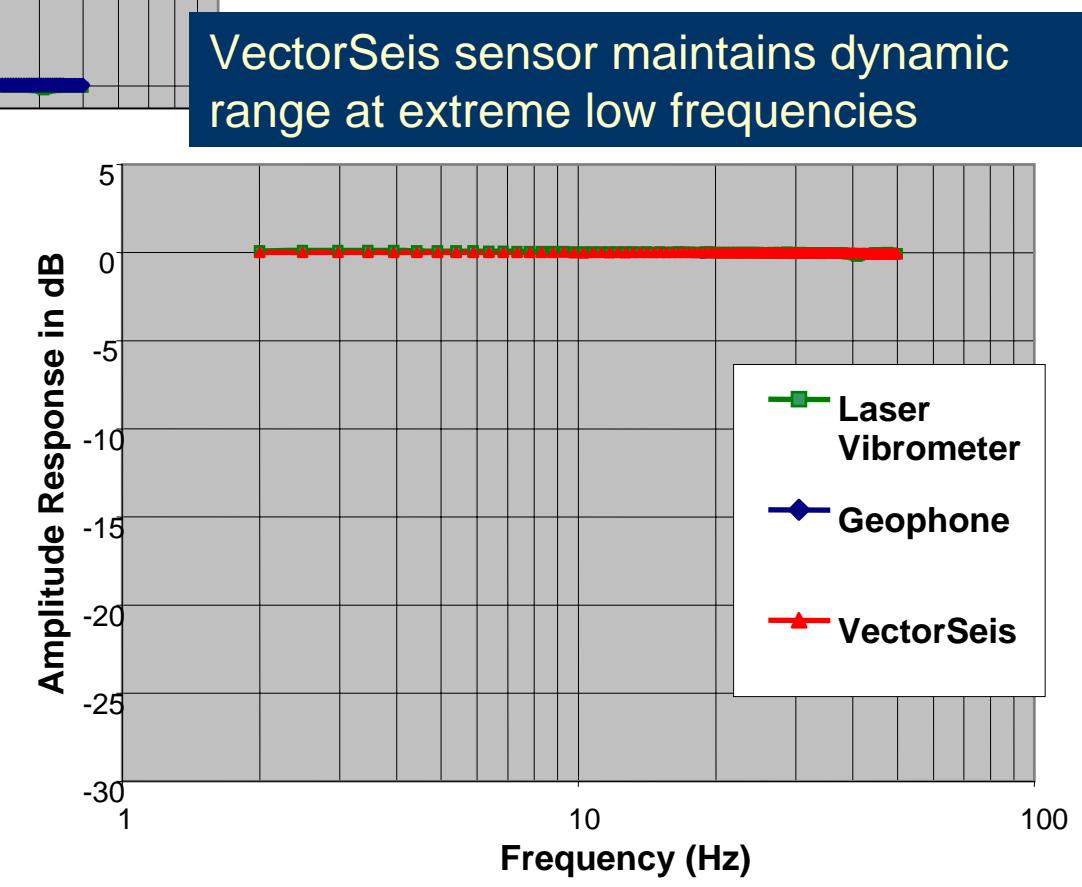


# Frequency Response

Geophone & VectorSeis<sup>®</sup> simultaneously shaken, table motion measured by Laser Vibrometer, Geophone and VectorSeis outputs normalized to Vibrometer



VectorSeis sensor maintains dynamic range at extreme low frequencies



**Thank you for your attention**