

# WALLABY/DINGO kinematic pipeline : A new Bayesian MCMC tilted-ring fitter

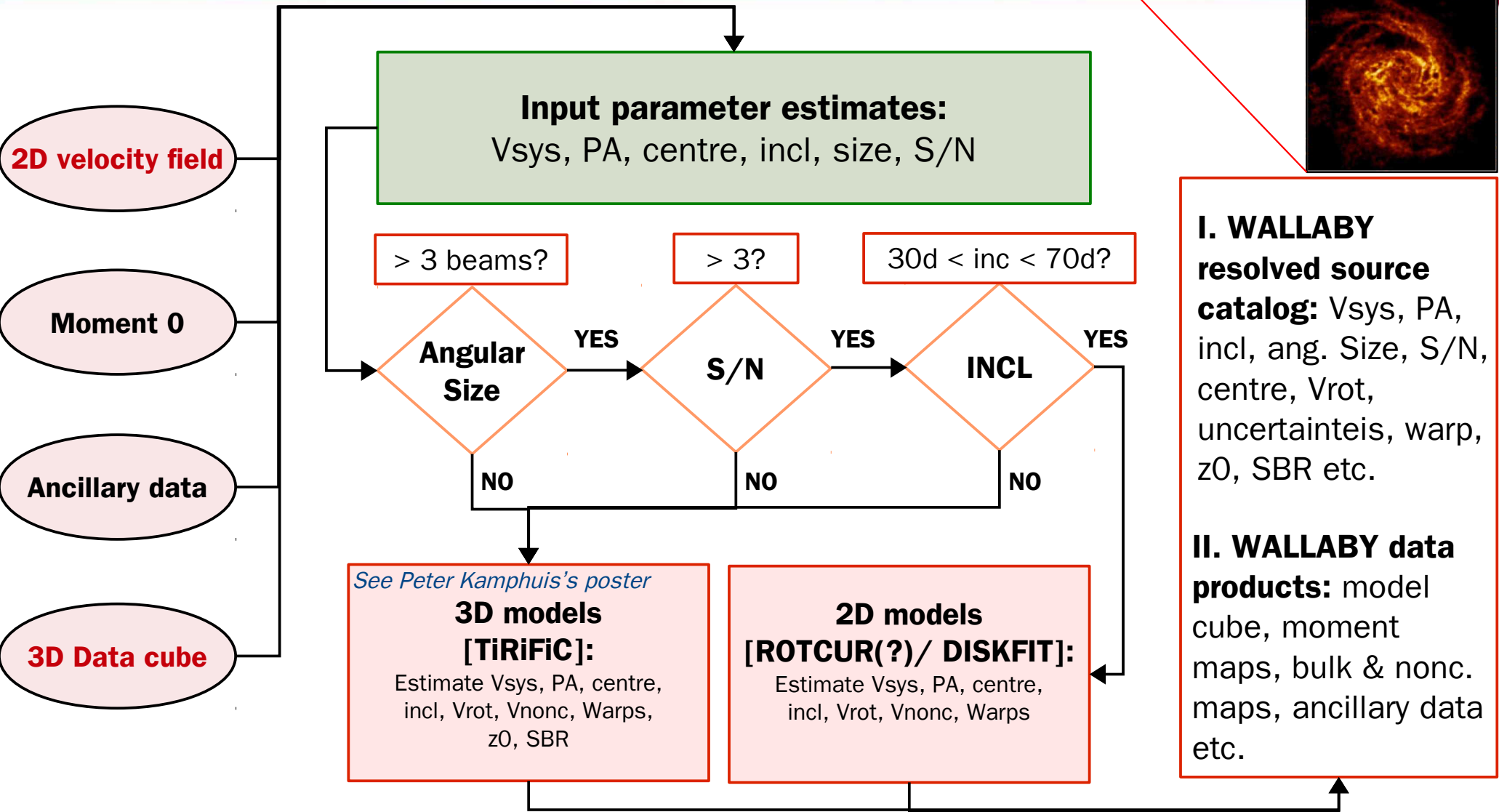
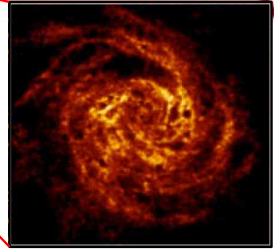
Se-Heon Oh (ICRAR/UWA)

with

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E. Elson (UCT), G. Józsa (ASTRON), **K. Spekkens** (RMC; leader),  
T. Westmeier (ICRAR), P. Serra (CSIRO) + WALLABY kinematics working group

- An overview of WALLABY kinematic pipeline
- A new Bayesian MCMC 2D tilted-ring fitter
- Performance test using sample galaxies from LVHIS
- Summary & future works

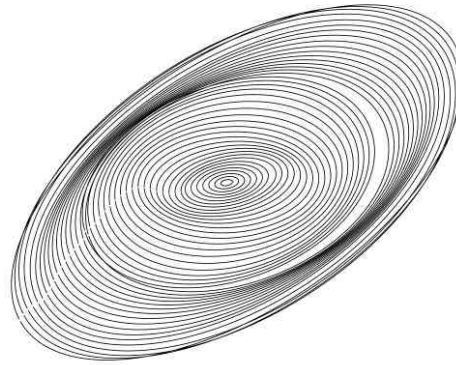
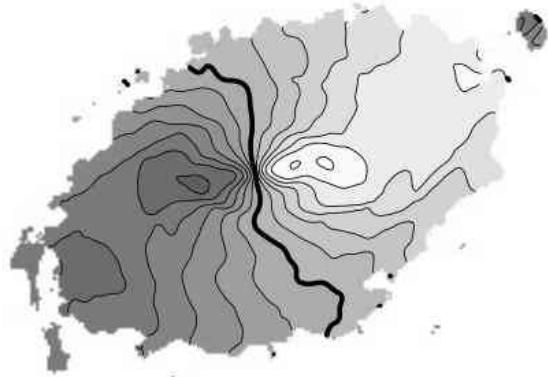
# Kinematic parameter extraction for WALLABY/DINGO: ASKAP WALLABY/DINGO (~5,000) + WSRT WNSHS (~7,000)



See posters + talks (Thursday) by Peter, Ed and Kristine for more details

## 2D tilted-ring model (Rogstad et al. 1974)

NGC 5055 (Battaglia et al. 2005)



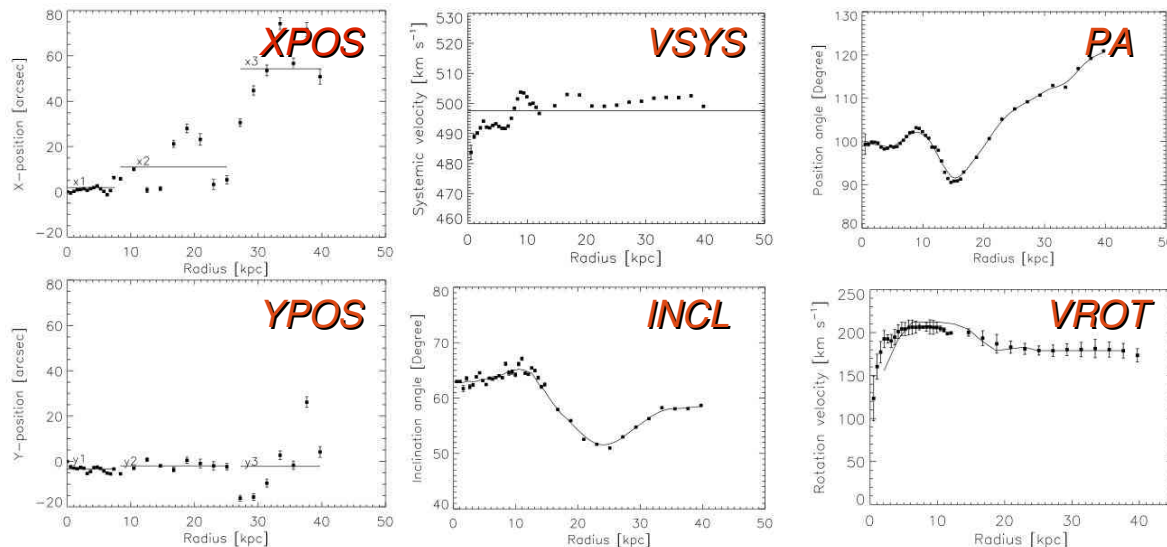
Free: **XPOS**, **YPOS**, **VSYS**, **PA**, **INCL**, **VROT**  
Fixed: **VEXP**

Free: **PA**, **INCL**, **VROT**  
Fixed: **XPOS**, **YPOS**, **VSYS**, **VEXP**

Free: **XPOS**, **YPOS**, **VROT**  
Fixed: **VSYS**, **VEXP**, **PA**, **INCL**

Free: **VROT**  
Fixed: **XPOS**, **YPOS**, **VSYS**, **VEXP**, **PA**, **INCL**

**Derive final rotation curve**



Galaxy Radius

Galaxy Radius

Galaxy Radius

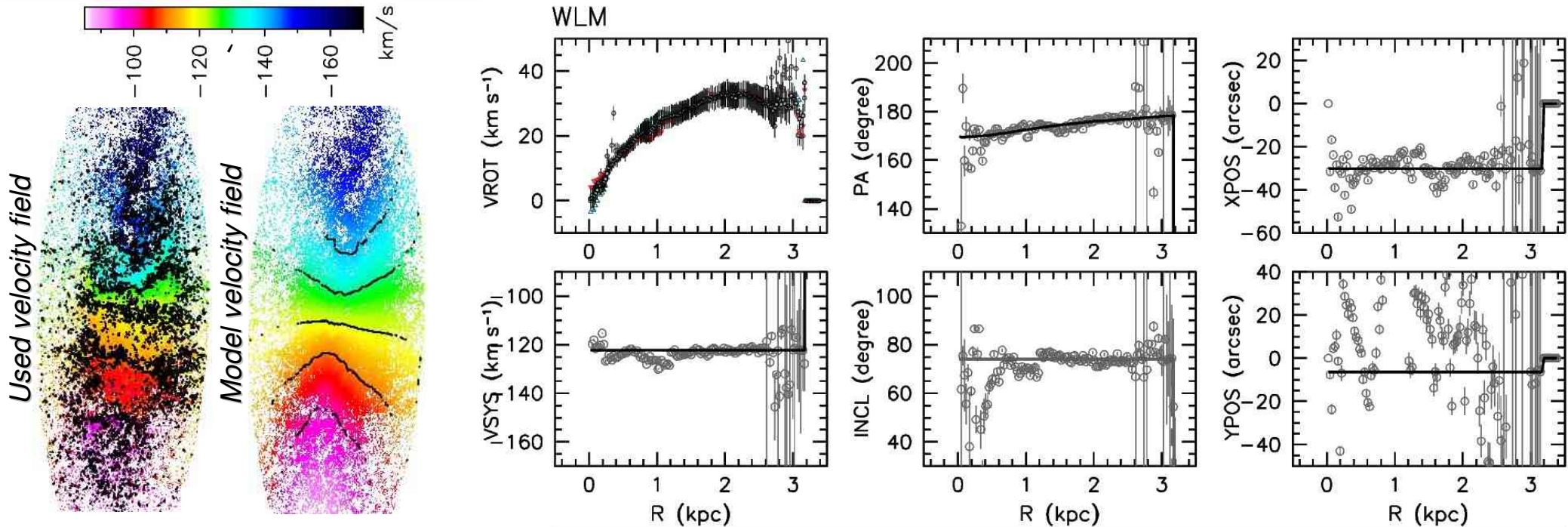
$$V_{\text{obs}}(x, y) = V_{\text{sys}}(x, y) + \sin i \{ V_t(x, y) \cos \theta + V_r(x, y) \sin \theta \}$$

$$\cos \theta = \frac{-(x - \text{XPOS}) \sin(\text{PA}) + (y - \text{YPOS}) \cos(\text{PA})}{r}$$

$$\sin \theta = \frac{-(x - \text{XPOS}) \cos(\text{PA}) - (y - \text{YPOS}) \sin(\text{PA})}{r \cos(\text{INCL})}$$



## Some issues on 2D tilted-ring fits



- 6 free parameters
- VROT/INCL degenerated
- sensitive to initial estimates
- non-parametric models for PA/INCL
- affected by non-circular motions



- **difficult to make the fit automatic**
- Why don't we fitting a tilted-ring model to all pixels at one time rather than dividing them into tilted-rings?

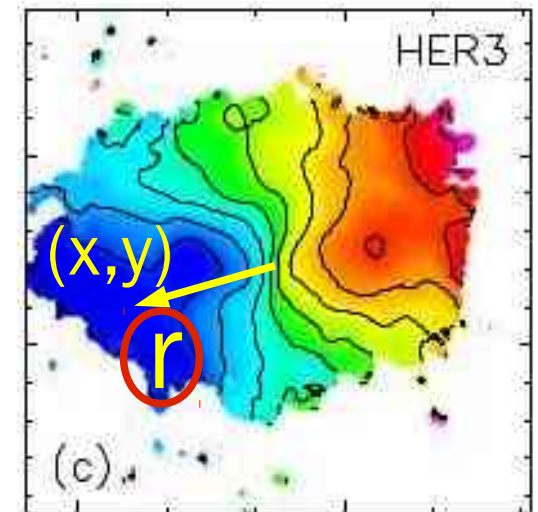
## Fitting a 2D tilted-ring model to the velocity field

$$V_{MODEL}(x, y) = V_{SYS}(x, y) + \underline{V_{ROT}(r)} \times \cos \theta \sin I + V_{exp}(r) \times \sin \theta \sin I$$

$$\cos \theta = \frac{-(x - XPOS) \times \sin PA + (y - YPOS) \times \cos PA}{r}$$

$$\sin \theta = \frac{-(x - XPOS) \times \cos PA - (y - YPOS) \times \sin PA}{r \cos I}$$

$$\underline{r} = \sqrt{[-(x - XPOS) \times \sin \theta + (y - YPOS) \times \cos PA]^2 + \left[ \frac{(x - XPOS) \times \cos PA + (y - YPOS) \times \sin PA}{\cos I} \right]^2}$$

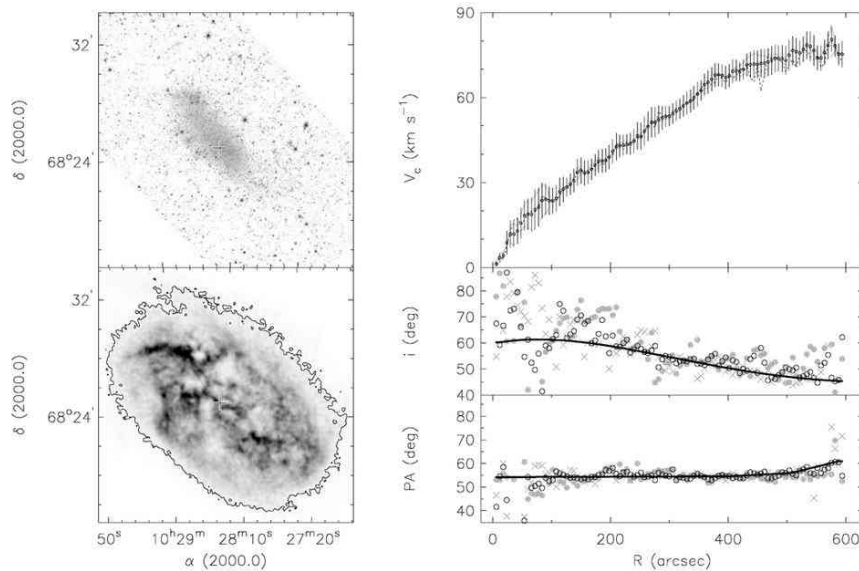




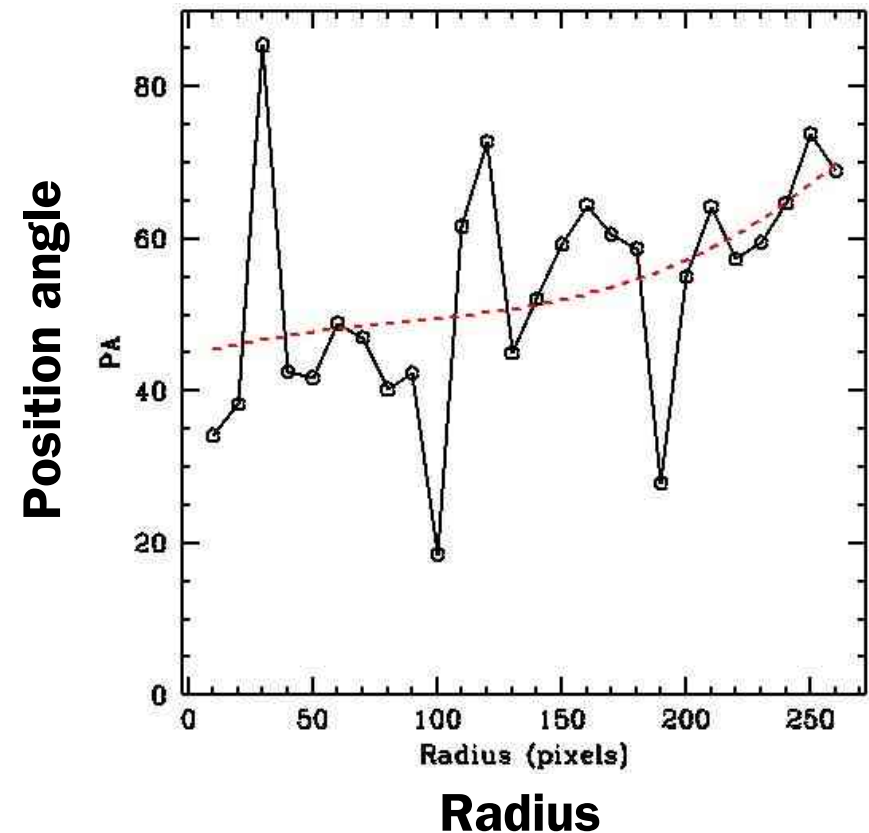
## Kinematic position angle

- Several dynamical structures in galaxies (e.g., lopsideness, bar-like potential, spiral arms, non-circular motions etc.) change kinematic PA in radial.
- Usually, well modeled by a polynomial function with a moderate order (e.g.,  $m=5$ )

$$PA = \sum_{i=0}^m p_i r^i$$

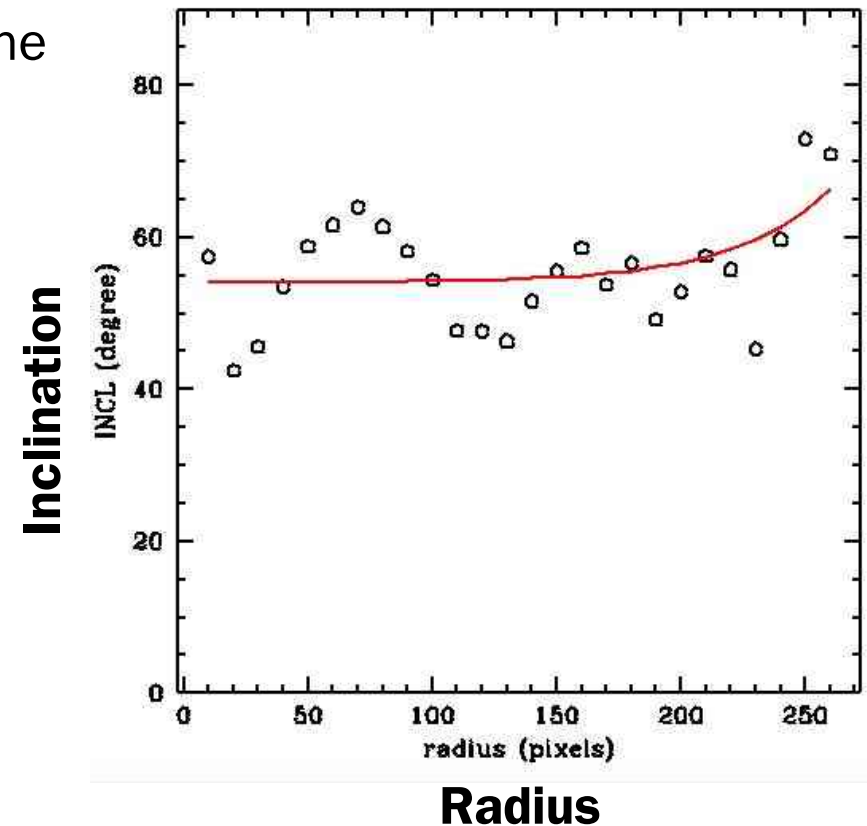


*de Blok et al. (2008)*



- Kinematic INCL change is often seen in galaxies but its sudden change in the inner region (probably due to non-circular motions or low filling factor) is unphysical except for outer regions where warps may exist.
- A modified Sersic profile is used for INCL
- Constant or linear variation of INCL in the inner region (e.g.,  $n=0$  or  $1$ )

$$I = \sum_{i=0}^n i_i r^i + \kappa \exp\left(\left[\frac{r}{\alpha}\right]^\beta\right)$$





## Fitting a 2D tilted-ring model to the velocity field

$$V_{MODEL}(x, y) = V_{SYS}(x, y) + \underline{V_{ROT}(r)} \times \cos \theta \sin I + V_{exp}(r) \times \sin \theta \sin I$$

$$\cos \theta = \frac{-(x - XPOS) \times \sin PA + (y - YPOS) \times \cos PA}{r}$$

$$PA = \sum_{i=0}^m p_i r^i$$

$$\sin \theta = \frac{-(x - XPOS) \times \cos PA - (y - YPOS) \times \sin PA}{r \cos I}$$

$$I = \sum_{i=0}^n i_i r^i + \kappa \exp\left(\left[\frac{r}{\alpha}\right]^\beta\right)$$

$$r = \sqrt{\left[-(x - XPOS) \times \sin \underline{PA} + (y - YPOS) \times \cos \underline{PA}\right]^2 + \left[\frac{(x - XPOS) \times \cos \underline{PA} + (y - YPOS) \times \sin \underline{PA}}{\cos \underline{I}}\right]^2}$$

→  $r = f(x, y, XPOS, YPOS, p_0, p_1, \dots, i_0, i_1, \dots, \kappa, \alpha, \beta)$

→ Solve this non-linear equation and derive the radius,  $r$  in the galaxy plane for given  $(x, y)$ ,  $XPOS$ ,  $YPOS$ ,  $p_0$ ,  $p_1$ ,  $\dots$ ,  $i_0$ ,  $i_1, \dots$ ,  $\kappa$ ,  $\alpha$ ,  $\beta$  (e.g., Newton-Rapson method etc.)

## Fitting a 2D tilted-ring model to the velocity field

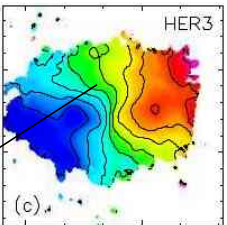
$$V_{MODEL}(x, y) = V_{SYS}(x, y) + V_{ROT}(r) \times \cos \theta \sin I + V_{exp}(r) \times \sin \theta \sin I$$

$$r = f(x, y, XPOS, YPOS, p_0, p_1, \dots, i_0, i_1, \dots, \kappa, \alpha, \beta)$$

$$V_{ISO}(r) = \sqrt{4\pi G \rho_0 r_c^2 \left[1 - \frac{r_c}{r} \arctan\left(\frac{r}{r_c}\right)\right]}$$



$$\rightarrow V_{MODEL} = F(XPOS, YPOS, V_{SYS}, V_{EXP}, \underbrace{r_c}_{VROT}, \underbrace{\rho_0}_{PA}, \underbrace{p_0, p_1, \dots, i_0, i_1, \dots, \kappa, \alpha, \beta}_{INCL})$$



$$\log \mathcal{L} = -\frac{N}{2} \log 2\pi - \sum_{i=0}^{NAX1} \sum_j^{NAX2} \log \sigma_{ij} - \frac{1}{2} \sum_{i=0}^{NAX1} \sum_{j=0}^{NAX2} \left[ \frac{V_{OBS}(i, j) - V_{MODEL}(i, j)}{\sigma_{ij}} \right]^2$$

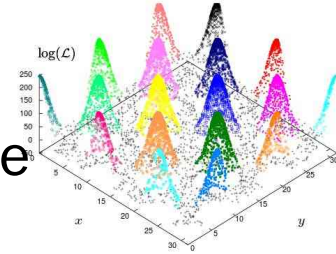
↑  
Log likelihood

- **Bayesian parameter estimation**
  - Markov Chain Monte Carlo (MCMC) sampling (see Mackay 2003 and refs therein)
  - less sensitive to initial values and gives good error estimation
  - MCMC sampling (e.g., Metropolis-Hastings algorithm and its variants, Gibbs or Hamiltonian samplings)
  - **CPU intensive and sampling problems in multimodal posteriors**
- **Bayesian model selection**
  - CPU expensive for the calculation of the Bayesian evidence which is used to assign relative probabilities to different models
  - thermodynamic integration method (e.g., O Ruanaidh & Fitzgerald 1996)
  - inefficient sampling in multimodal posteriors



## MultiNest (Feroz & Bridges 2007, 2008) : a Bayesian inference tool

- Improves the sampling efficiency and robustness based on the clustered nested sampling in Shaw et al. (2007)
- Calculates the evidence and explores parameter space even with multimodals and curving degeneracies in high dimensions
- Refer to Feroz & Bridges (2008) for a complete discussion on the new sampling scheme, “the improved simultaneous ellipsoidal nested sampling method”
  - a fully parallelized algorithm using MPI
- Successfully implemented in astrophysics and cosmology (e.g., CosmoMC, SuperBayeS, SUSY, gravitational lensing, exo-planet detection, **ASKAP FLASH absorption line finder** (Allison et al. 2012))



- Standalone C program for 2D tilted-ring fits based on Bayesian MCMC
  - MultiNest v2.18, CFITSIO, standard ANSI C libraries
  - **fully automatic**: estimation for initial values, convergence check and derivation of the final rotation curve for a given 2D velocity field
  - **several builtin rotation curve shape functions** are provided (e.g., pseudo-isothermal, Burkert, polynomial rotation curves etc.)
  - the larger number of sampling, the higher quality of fits but the more cpu time
  - supports MPI which enables us to do **parallel computing**

## Program run

```
seheon@darkmatter rotcur.develop.mpi]$
seheon@darkmatter rotcur.develop.mpi]$ mpirun -np 1 --bysocket -loadbalance ./wallaby_2D_TRfitter

+ -----+
+ WALLABY 2D TILTED-RING FITTER+
+ by SE-HEON OH (ICRAR/UWA) + WALLABY KINEMATICS WORKING GROUP+
+ -----+
+
+ Development history+
+ : V.1.0 14/Sept/2013+
+
+ Usage+
+ : mpirun -loadbalance -np [0. N-cpus= 8] ./wallaby_2D_TRfitter+
+
+ A. Input 2D velocity field to fit -----+
+ [1. 2D VELOCITY FIELD= vf.fits)+
+ [2. NAX1= 1024] [3. NAX2= 1024]+
+ [4. XLOWER= 200] [5. YLOWER= 200] [6. XUPPER= 800] [7. YUPPER= 800]+
+
+ B. Binning option -----+
+ [8. grid_X_ISOFIT= 5] [9. grid_Y_ISOFIT= 5] [10. BIN_X_TRFIT= 1] [11. BIN_X_TRFIT= 1]+
+
+ C. Uniform priors of ring parametres -----+
+ [12. XPOS= 512] [13. xpos0= 500] [14. xpos1= 520]+
+ [15. YPOS= 512] [16. ypos0= 500] [17. ypos1= 520]+
+ [18. VSYS= 0] [19. vsys0= -10] [20. vsys1= 10]+
+ [21. PA= 45] [22. pa0= 0.1] [23. pa1= 0.9]+
+ [24. INCL= 45] [25. incl0= 0.1] [26. incl1= 0.9]+
+ [27. VROT= 10] [28. vrot0= 0.0] [29. vrot1= 200]+
+
+ D. Tilted rings -----+
+ [30. RING_start= 4] [31. RING_end= 100] [32. RING_width= 4]+
+ [33. RING_inner_regrad= 20] [34. PIXEL_scale= 5]+
+ [35. PA_Poly-Order= 5] [36. INCL_Poly-Order= 1]+
+
+ E. MULTINEST parameters -----+
+ [37. nlive= 100] [38. efr= 0.8] [39. tol= 0.1] [40. fb= 0] [41. outfile= 0] [42. maxiter= 0]+
+
+
+ ! EXAMPLE -----+
+ mpirun -loadbalance -np 8 ./wallaby_2D_TRfitter \+
+ test.VF1024.fits \+
+ 1024 1024 \+
+ 200 200 800 800 \+
+ 5 5 1 1 \+
+ 512 490 530 \+
+ 512 490 530 \+
+ 0 -20 20 \+
+ 45 0.1 0.9 \+
+ 60 0.1 0.9 \+
+ 10 0.0 120 \+
+ 3 100 3 \+
+ 20 5 \+
+ 5 1 \+
+ 100 0.8 0.1 0 0 0+
+ -----+
+
seheon@darkmatter rotcur.develop.mpi]$
seheon@darkmatter rotcur.develop.mpi]$
seheon@darkmatter rotcur.develop.mpi]$
```

Input velocity field

Binning factors

Uniform priors of tilted-ring parametres

radii, width, pixel-scale, PA/INCL p-orders

Multinest parametres

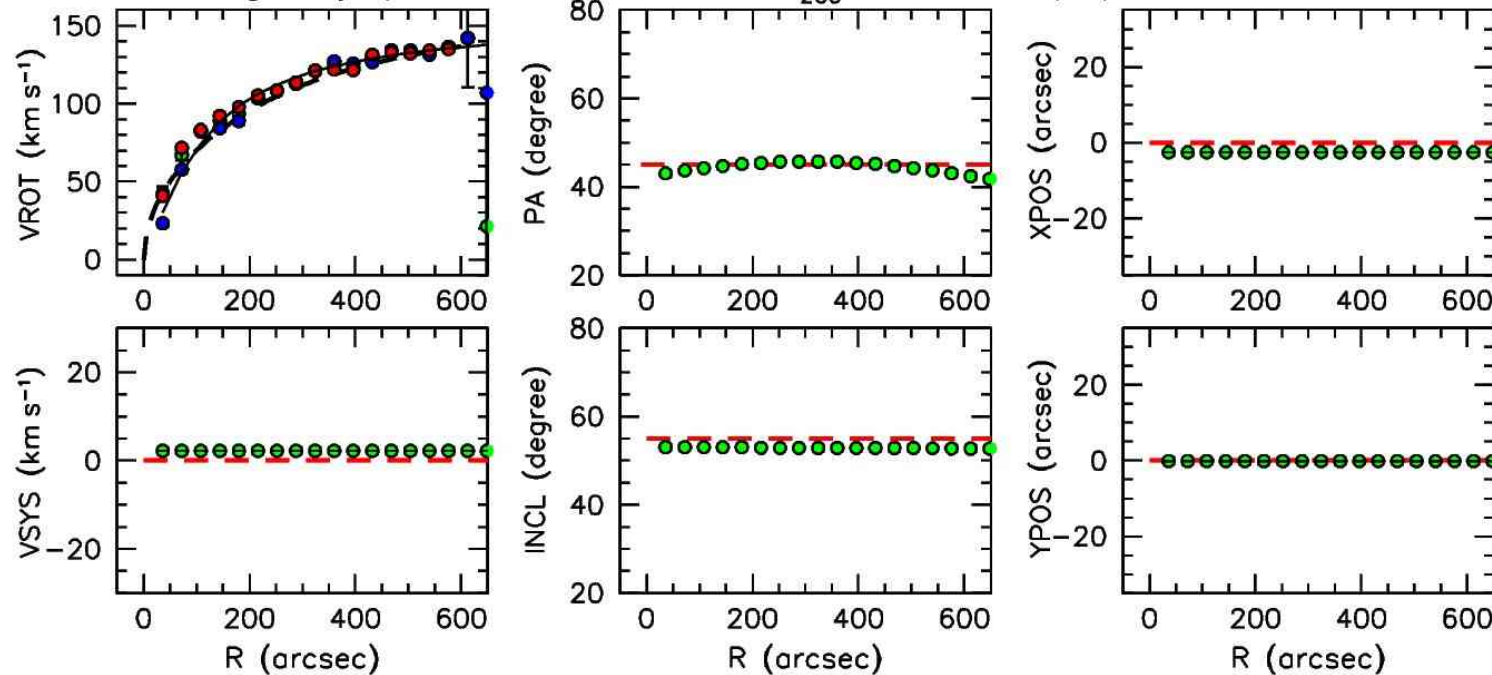




## Performance test

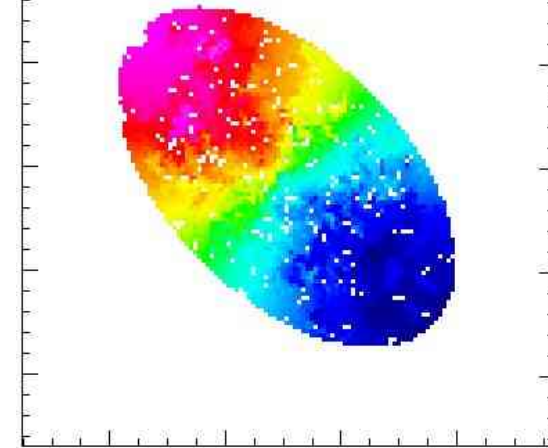
: a model galaxy (NFW halo:  $c=8.1$   $V_{200}=140$  km/s + non-circular motions

model galaxy (NFW halo:  $c = 8.1$   $V_{200} = 140$  km/s)

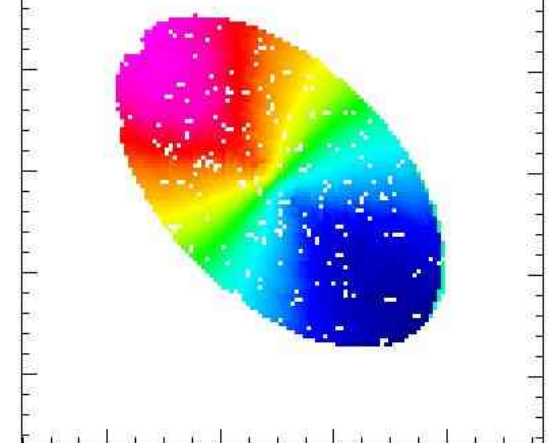


- Input rotation curves
- Derived using the new program

Input velocity field



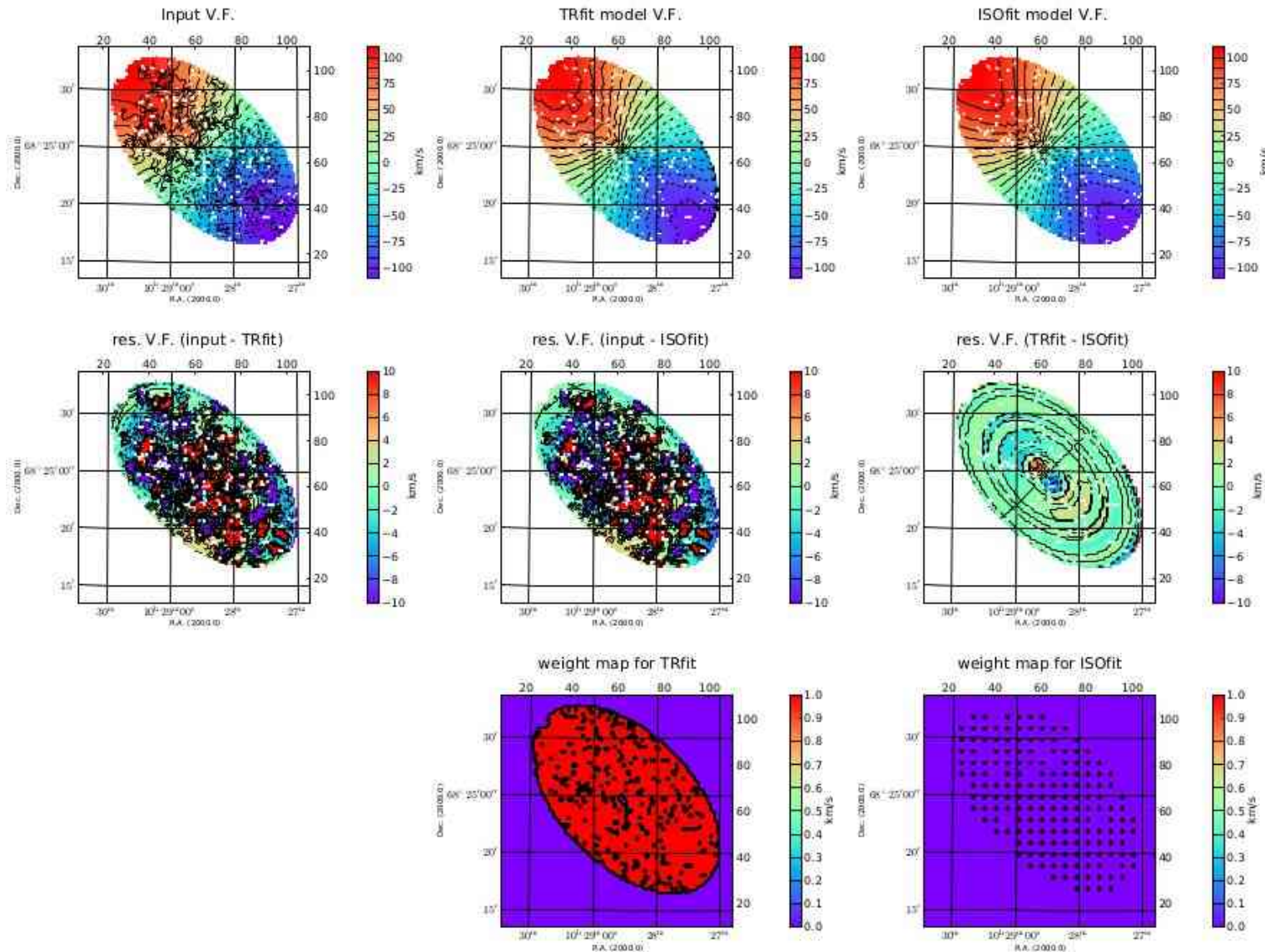
model velocity field



## Performance test

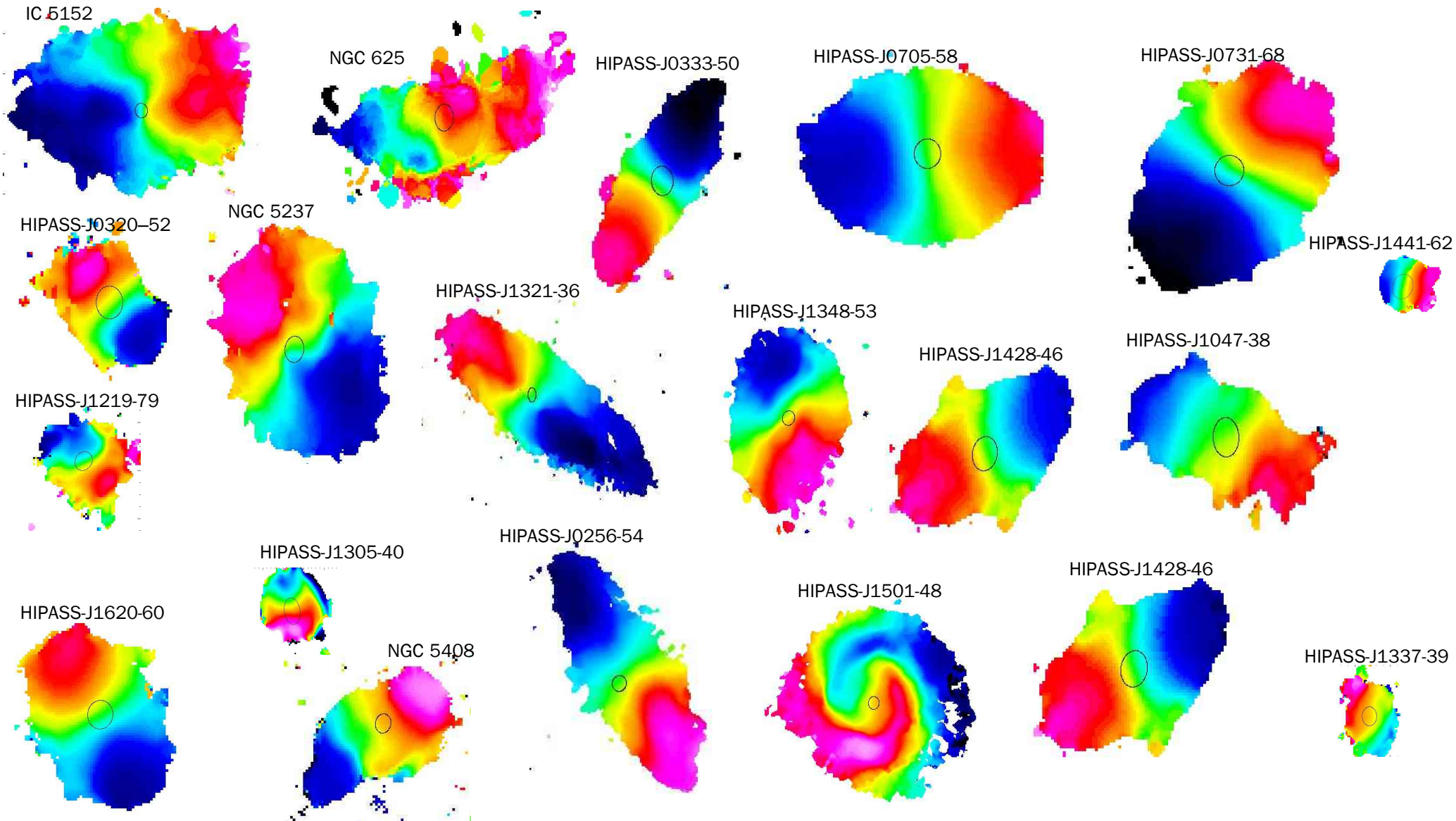
: model galaxy (NFW halo:  $c=8.1$   $V_{200}=140$  km/s + non-circular motions

model galaxy (NFW halo:  $c = 8.1$   $V_{200} = 140$  km/s)



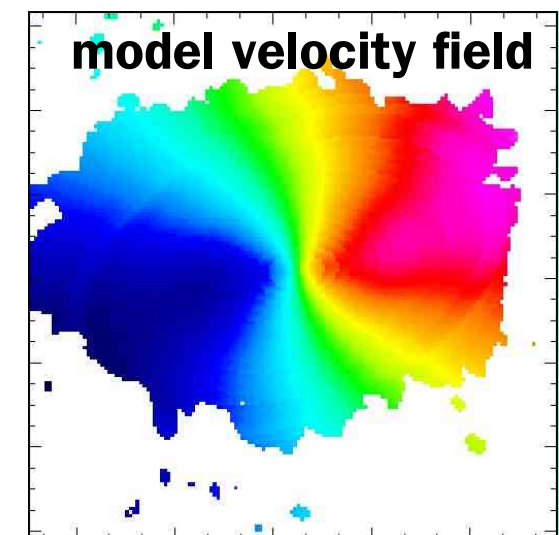
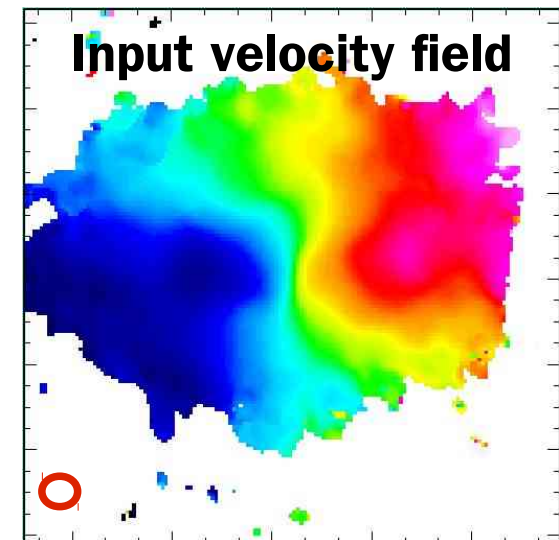
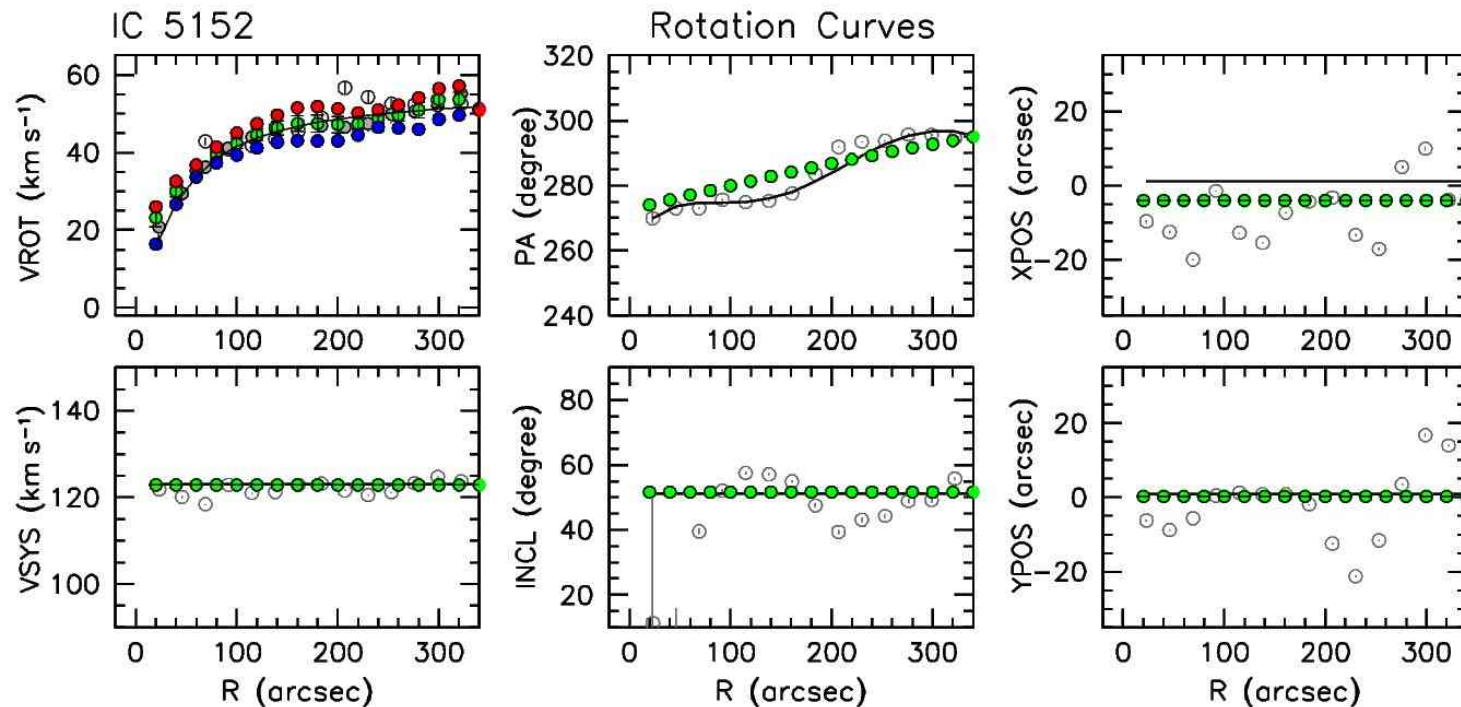


# Local Volume HI Survey (LVHIS) : *Koribalski et al.* : HI velocity field

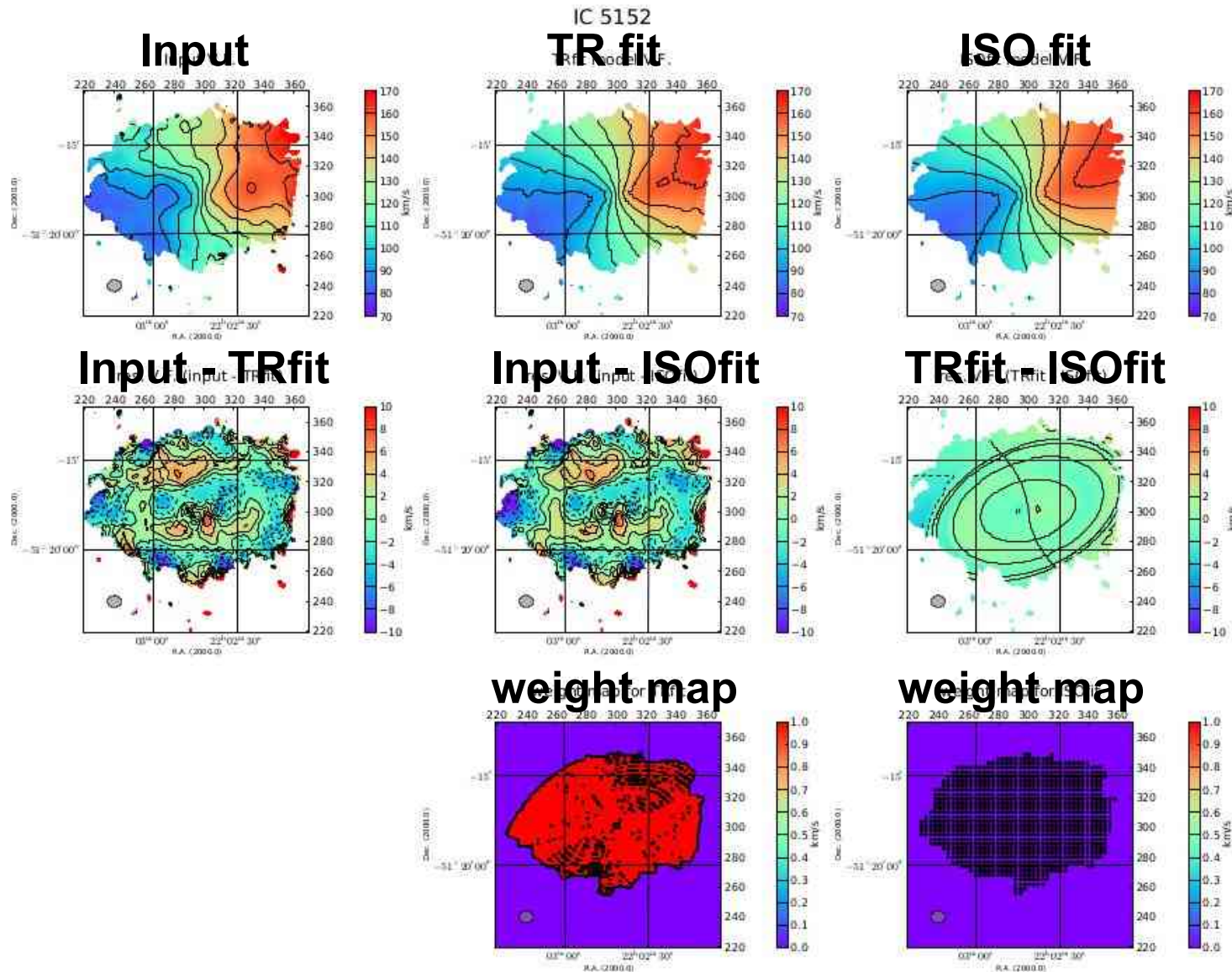




# Performance test : IC 5152 (> 5 beams )



# Performance test : IC 5152 (model velocity fields)

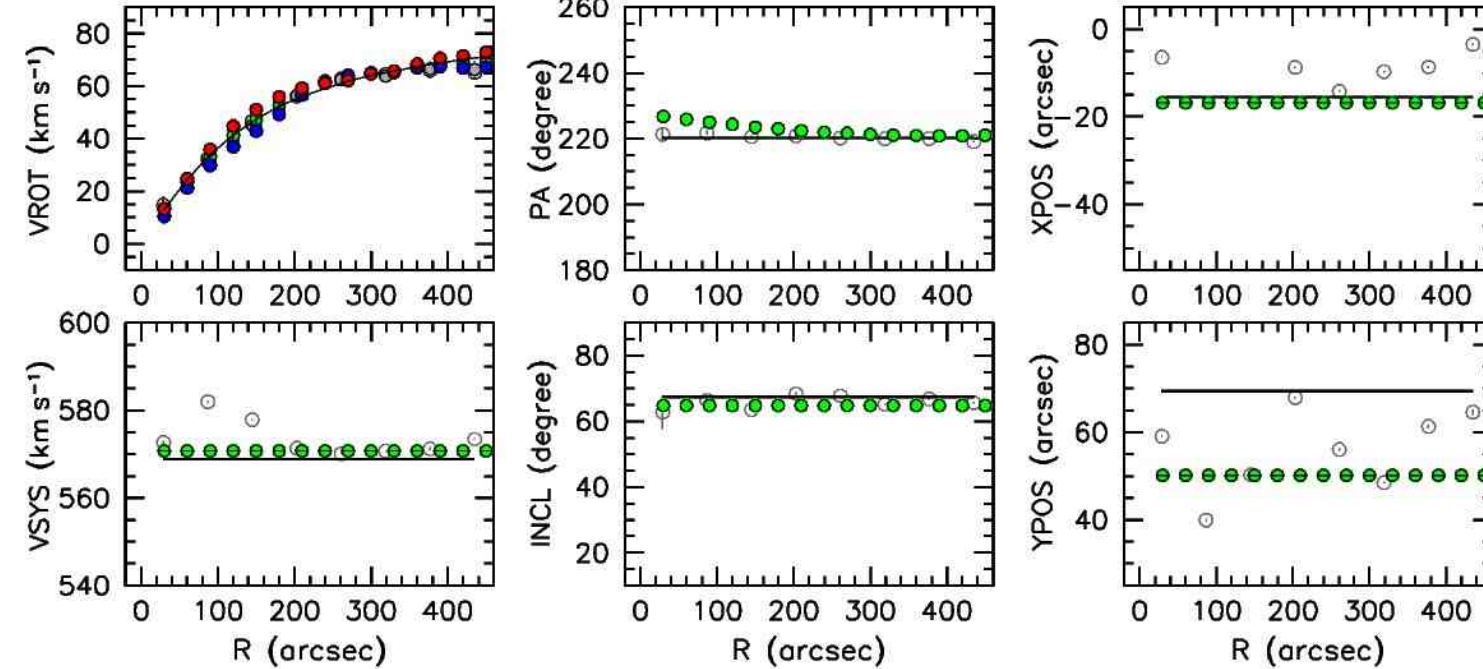




# Performance test : ESO 154 g23 (~5 beams)

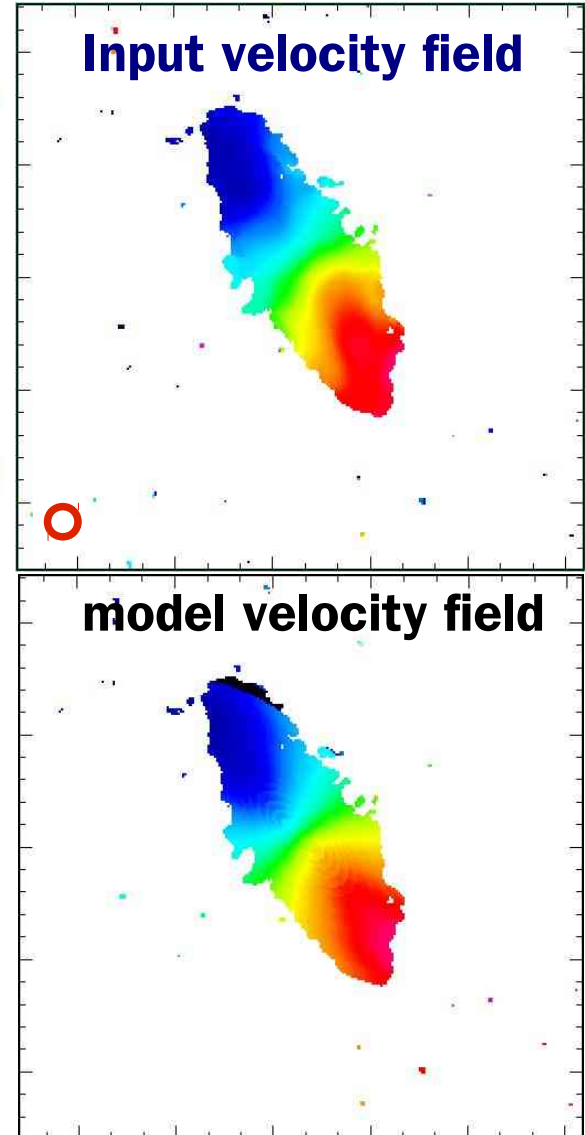
ESO 154 g23

Rotation Curves



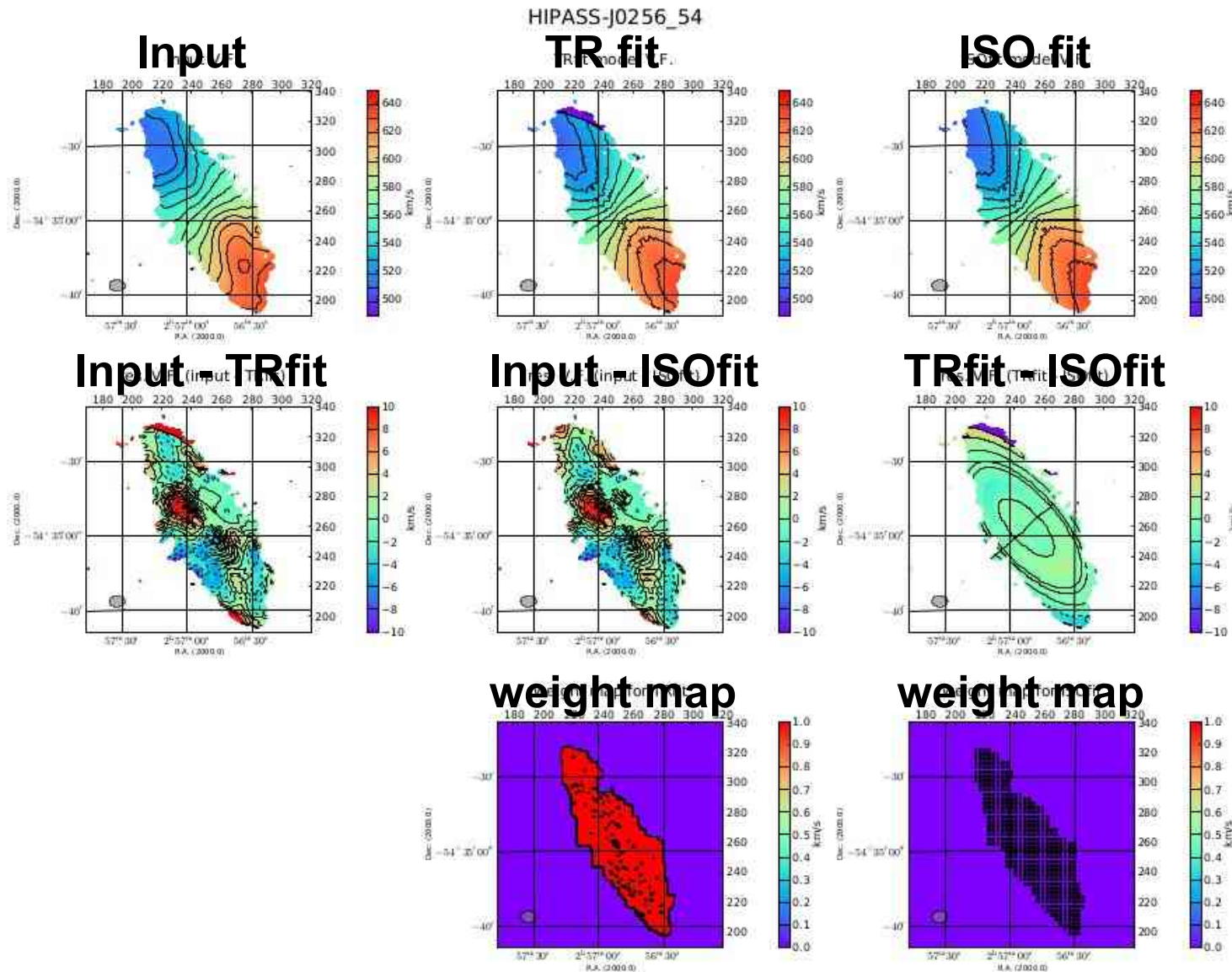
Input velocity field

model velocity field

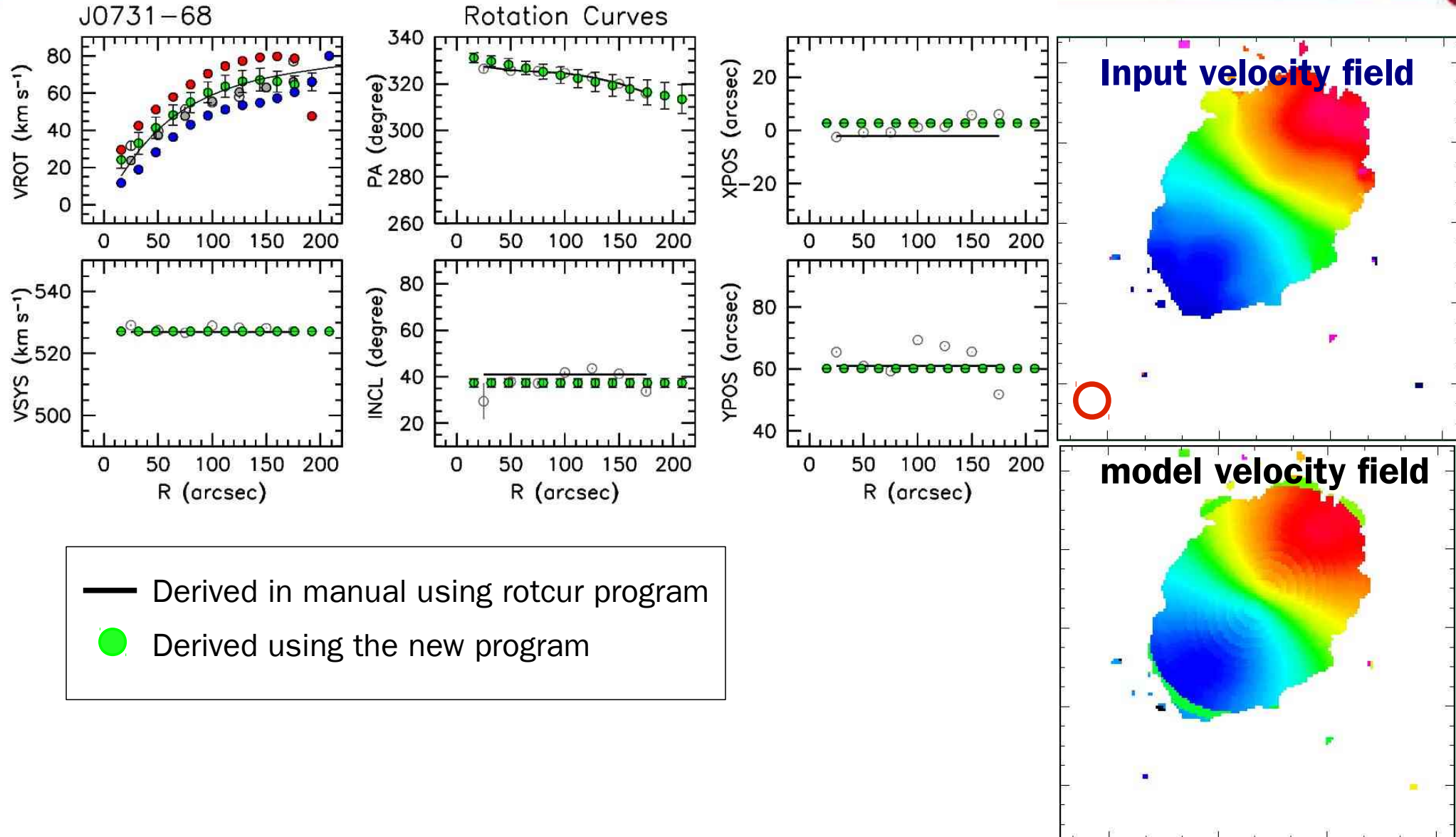




# Performance test : ESO 154 g23 (model velocity fields)

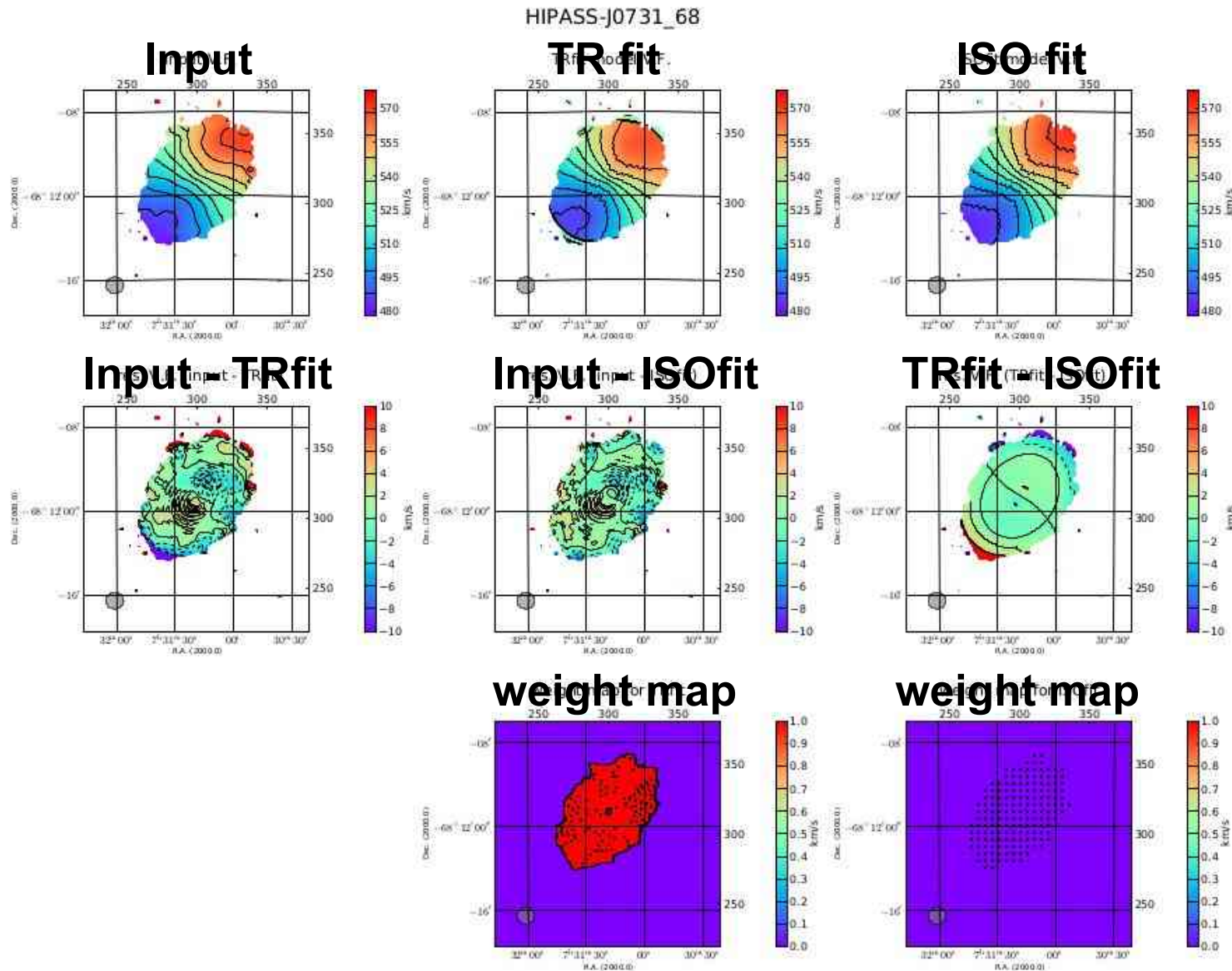


# Performance test : HIPASS-J0731-68 (~ 4 beams)





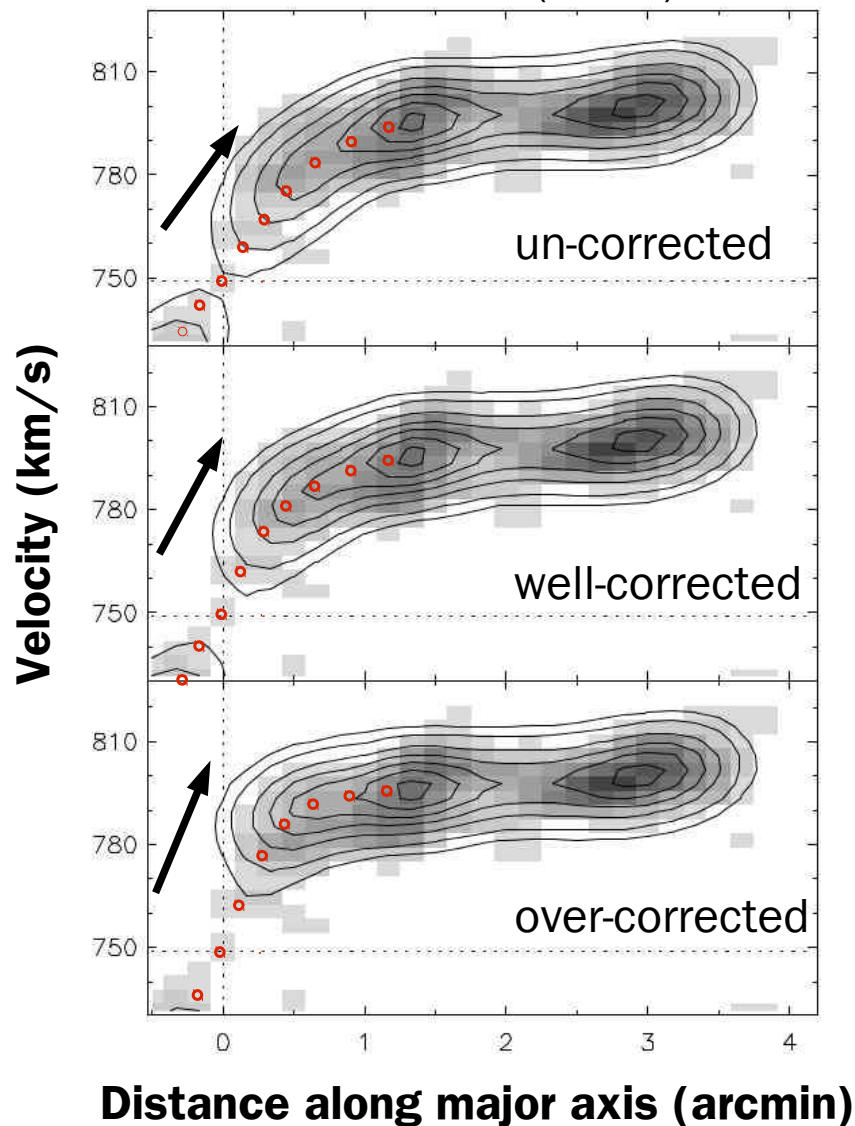
# Performance test : HIPASS-J0731-68 (model velocity fields)





## Correcting for beam smearing effect

Swaters et al. (2009)



Construct a model cube using the derived ring params ( $V_{ROT} + \Delta V$ )

Calculate  $\chi^2$  values of residual cubes between models and the observation

Find the optimal  $\Delta V(R)$  minimising the  $\chi^2$  value

- **Time consuming work**

- manual adjustment of  $\Delta V$  (e.g., galmod)
- regularised  $\chi^2$  minimisation (e.g., TiRiFiC)
- Bayesian search for  $\Delta V$ ?

# Bayesian search for beam smearing correction (work in progress...)

Log likelihood

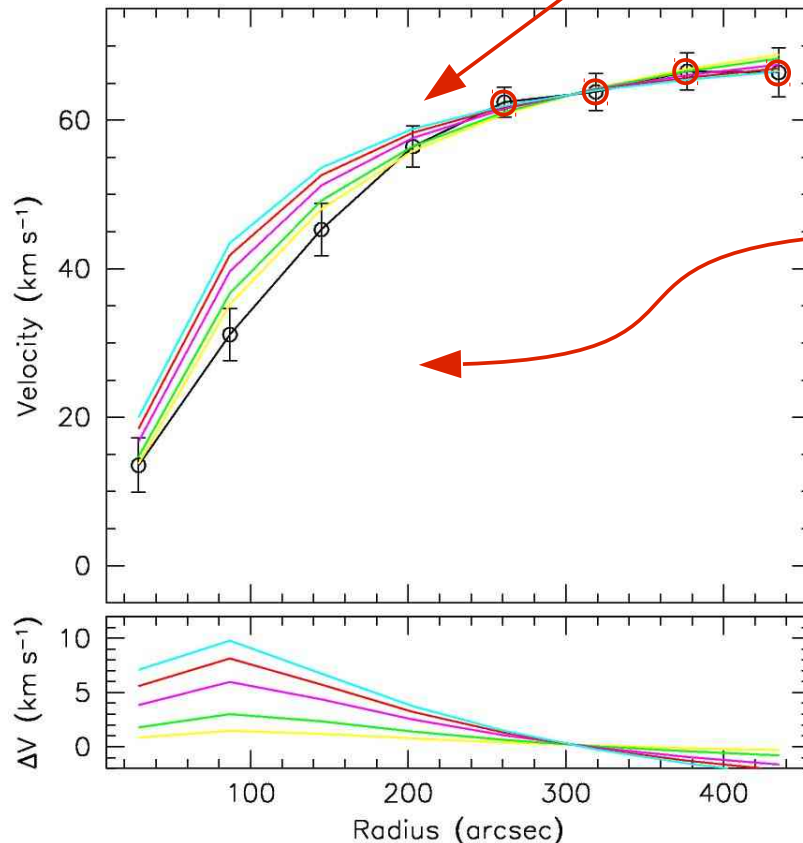
$$\log \mathcal{L} = -\frac{M}{2} \log 2\pi - \sum_{i=0}^{NAX1} \sum_{j=0}^{NAX2} \sum_{k=0}^{NAX3} \log \sigma_{i,j,k} - \frac{1}{2} \sum_{i=0}^{NAX1} \sum_{j=0}^{NAX2} \sum_{k=0}^{NAX3} \left[ \frac{F_{OBS}(i,j,k) - F_{MODEL}(i,j,k)}{\sigma_{i,j,k}} \right]^2$$

Observed cube

Model cube

$$F_{MODEL} = F(VROT, XPOS, YPOS, VSYS, VEXP, PA, INCL, VDISP, DENS, z0)$$

ESO 154-G23



(from 2D tilted-ring model)

(from mom0 & mom2)

$$V_{ISO}(r) = \sqrt{4\pi G \rho_0 r_c^2 \left[ 1 - \frac{r_c}{r} \arctan\left(\frac{r}{r_c}\right) \right]}$$

$$F_{MODEL}(r_c, \rho_0) \longleftrightarrow F_{OBS}$$

→ Find the optimal  $\Delta V [r_c, \rho_0]$  to provide the best matching model cube

• Work in progress: standalone galmod made; will be linked into the Bayesian platform of the main body

## Summary & future direction