A new analytic function for describing ne HI double-horn spectrum of galaxies

Tobias Westmeier (ICRAR/UWA)



International Centre for Radio Astronomy Research









Dwingeloo, 18 March 2014

The Busy Function

2



- ★ Future HI surveys:
 - ► WALLABY, DINGO, WNSHS, etc.
 - ► Large number of galaxies.
- ★ Parametrisation of galaxies:
 - ► Accurate.
 - ► Automated.



Runva[®] HWE15000 industrial winch



Dingo (*Canis lupus*). (Credit: Sam Fraser-Smith)

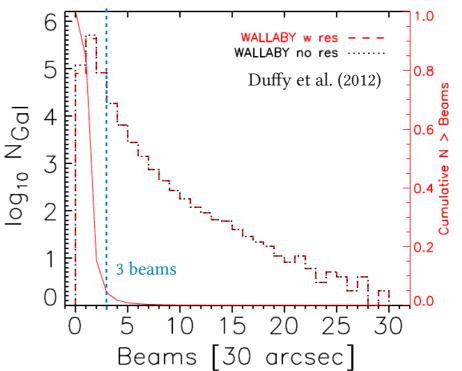


Bennett's Wallaby (*Macropus rufogriseus*). (Credit: J. J. Harrison)





- ★ Future HI surveys:
 - ► WALLABY, DINGO, WNSHS, etc.
 - ► Large number of galaxies.
- ★ Parametrisation of galaxies:
 - ► Accurate.
 - ► Automated.
- ★ Most galaxies barely resolved:
 - ▶ 95% less than 3 beams across. (Duffy et al. 2012)
 - ► Parametrisation of integrated HI spectrum sufficient.

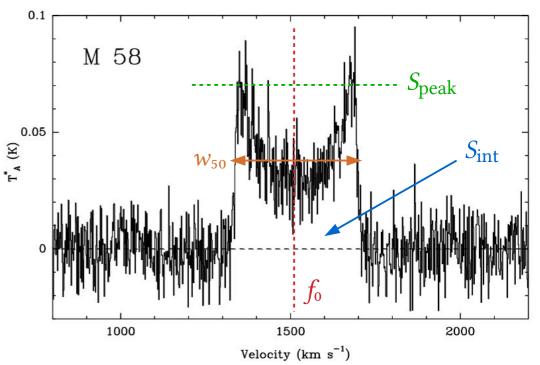




- ★ Integrated HI spectra:
 - ► Characteristic double-horn profile.

 f_0

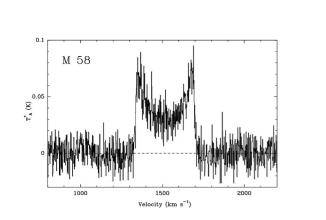
- ▶ Line centroid:
- Line width: w_{50}, w_{20}, \dots
- Peak flux density: S_{peak}
- Integrated flux: S_{int}
- ★ Direct parametrisation suffers from large statistical and systematic errors.
- ★ Better: fitting of analytic model to spectrum.
 - ► Less sensitive to individual noise peaks.
 - ► Covariance matrix of fit to derive uncertainties of parameters.

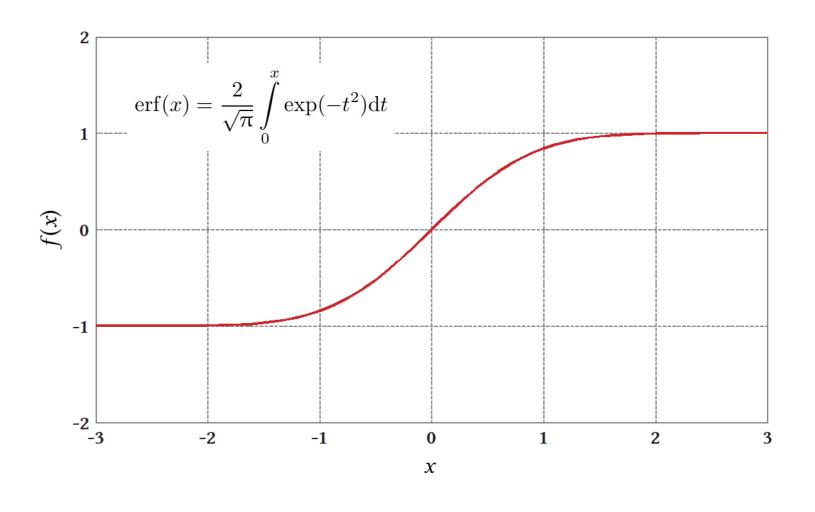






- ★ Error function:
 - $f(x) = \operatorname{erf}(x)$



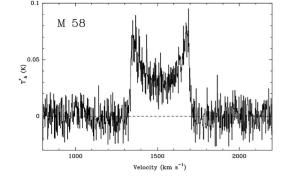


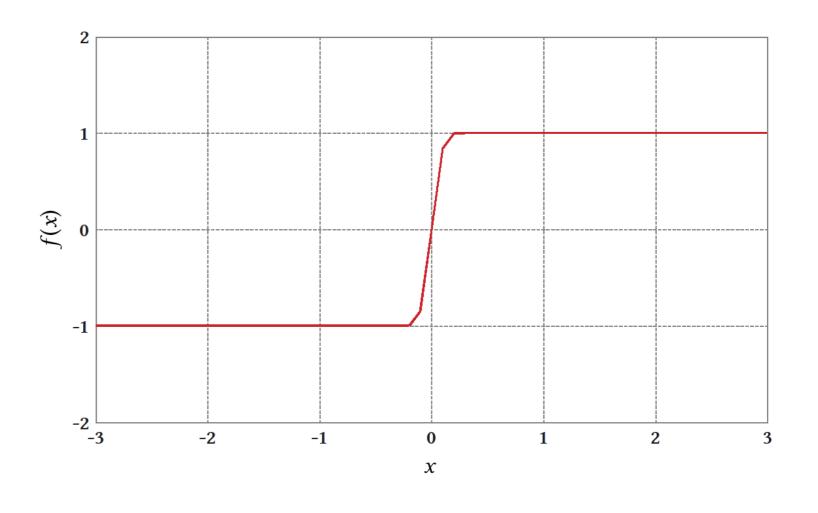
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- ★ Error function:
 - $f(x) = \operatorname{erf}(x)$
- ★ Modifications:
 - $f(x) = \operatorname{erf}(bx)$

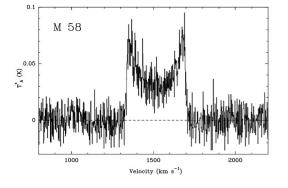


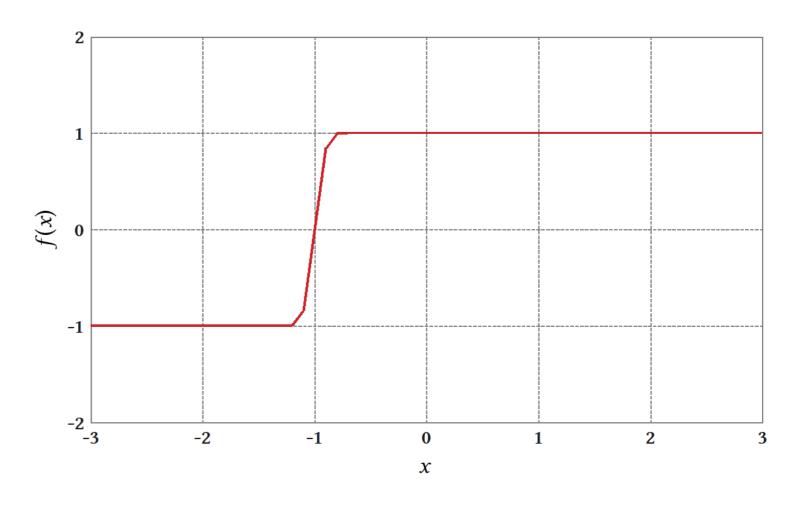






- ★ Error function:
 - $f(x) = \operatorname{erf}(x)$
- ★ Modifications:
 - $f(x) = \operatorname{erf}(bx)$
 - ► $f(x) = \operatorname{erf}(b[w+x])$

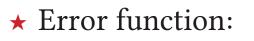




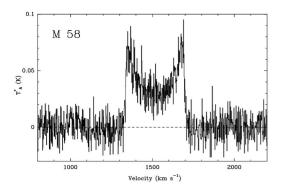
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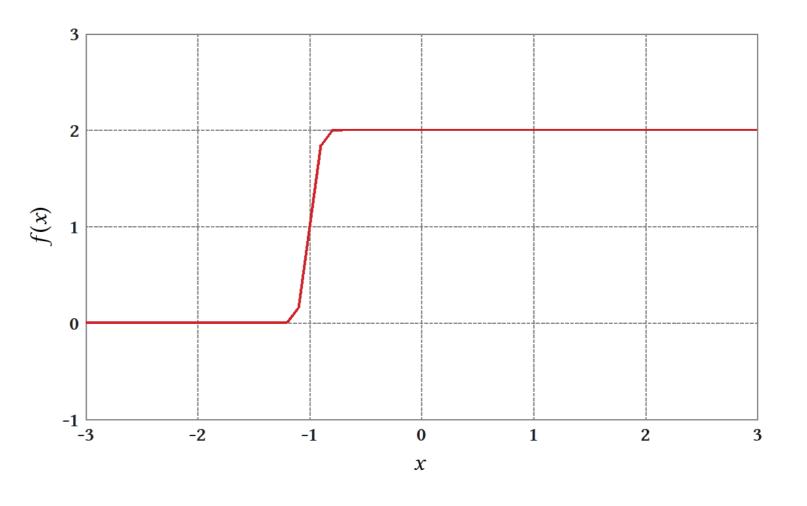






- $f(x) = \operatorname{erf}(x)$
- ★ Modifications:
 - $f(x) = \operatorname{erf}(bx)$
 - ► $f(x) = \operatorname{erf}(b[w+x])$
 - $\blacktriangleright f(x) = \operatorname{erf}(b[w+x]) + 1$



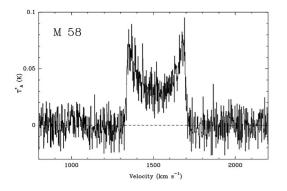


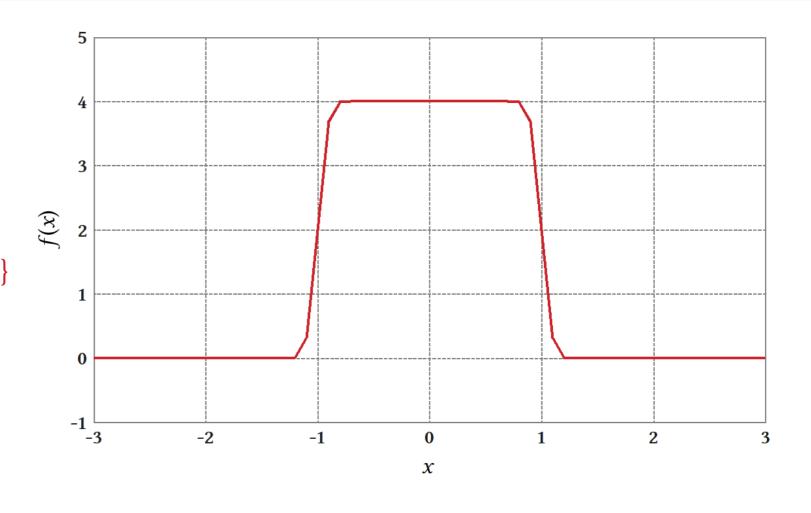






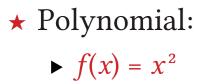
- ★ Error function: ► f(x) = erf(x)
- ★ Modifications:
 - $f(x) = \operatorname{erf}(bx)$
 - ► $f(x) = \operatorname{erf}(b[w+x])$
 - ► $f(x) = \{ erf(b[w+x]) + 1 \}$ × $\{ erf(b[w-x]) + 1 \}$

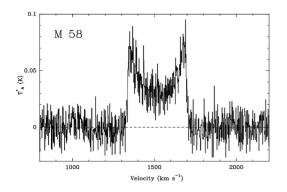


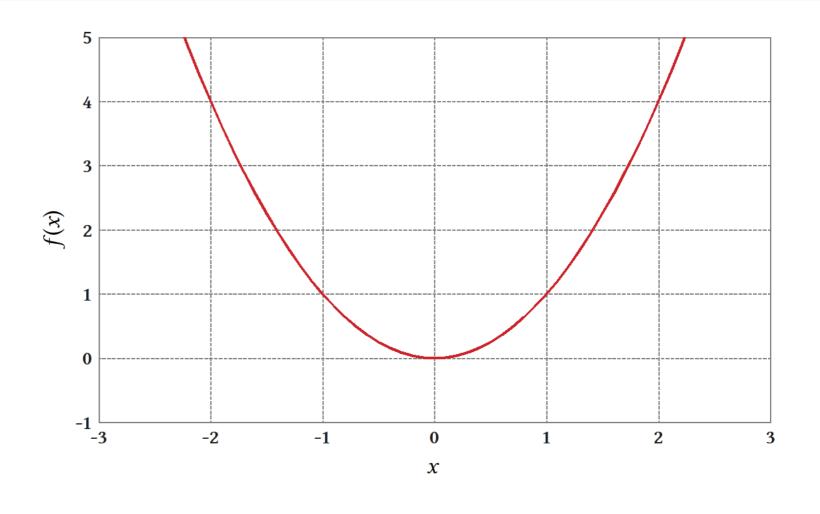


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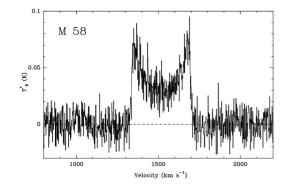


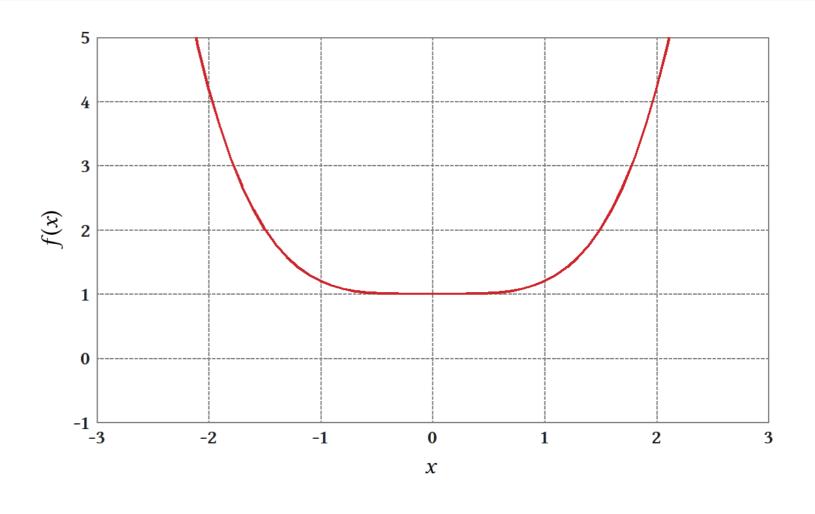


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- ★ Polynomial:
 - $f(x) = x^2$
- ★ Modifications:
 - $f(x) = cx^n + d$



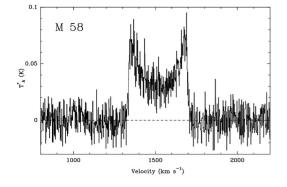


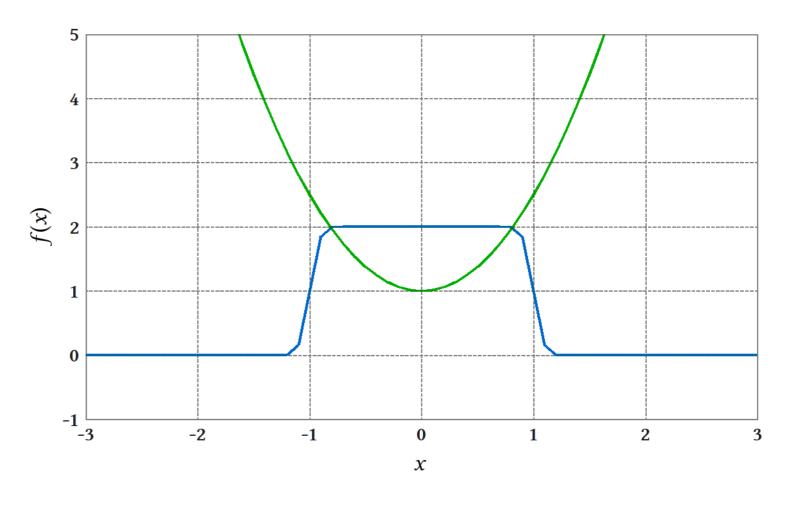






- ★ Error functions:
 - ► $f(x) = \{ erf(b[w+x]) + 1 \}$ × $\{ erf(b[w-x]) + 1 \} \times a$
- ★ Polynomial:
 - $g(x) = cx^n + d$

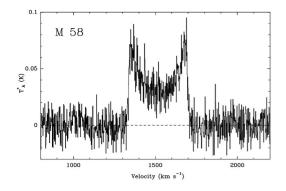


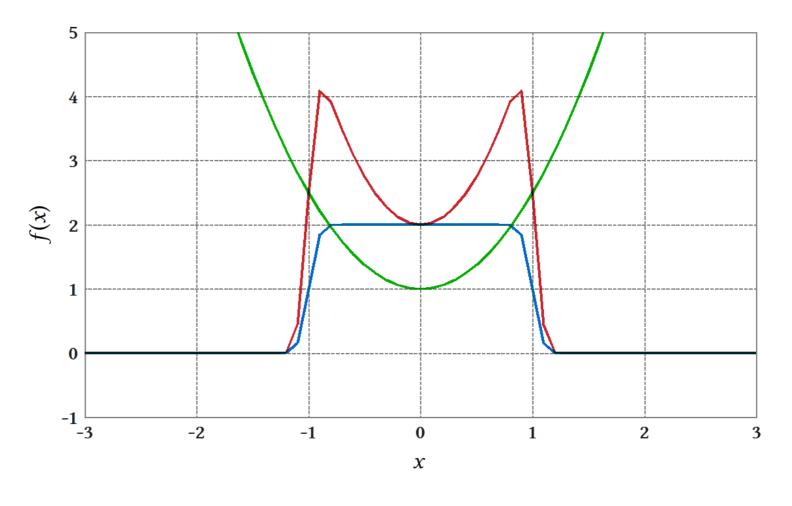






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- ★ Polynomial:
 - $g(x) = cx^n + d$
- ★ Combination:
 - $\blacktriangleright B(x) = f(x) \times g(x)$





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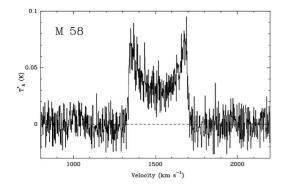
The Busy Function

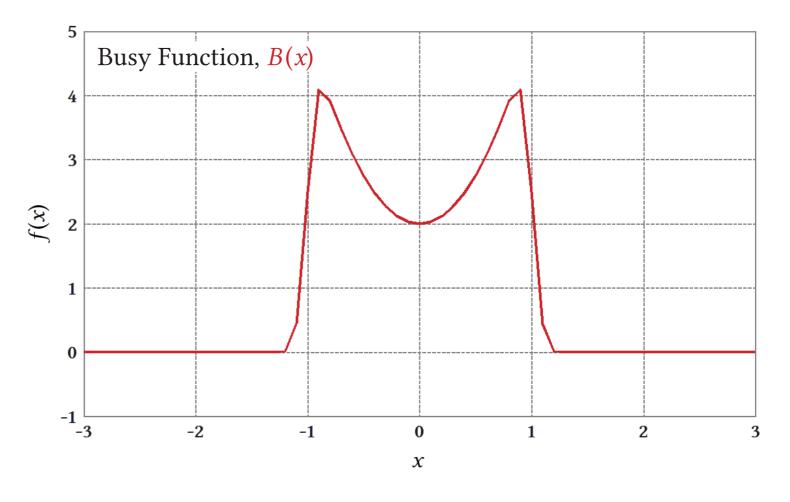
15





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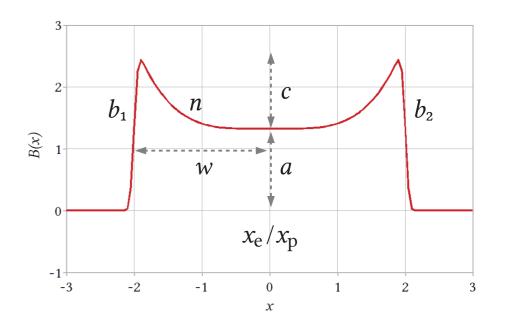






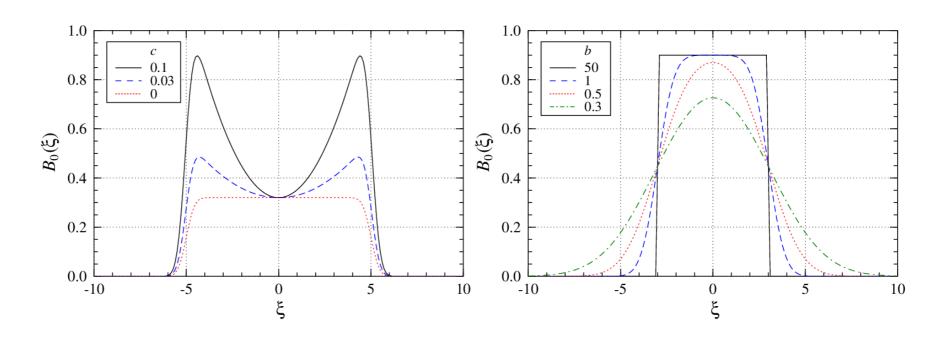


- ★ General form of the Busy Function:
 - $\blacktriangleright B(x) = [a/4] \times [erf(b_1\{w + x x_e\}) + 1] \times [erf(b_2\{w x + x_e\}) + 1] \times [c|x x_p|^n + 1]$
- ★ Maximum of 8 free parameters:
 - ► *a* scaling factor
 - $\blacktriangleright b_1, b_2$ steepness of line flanks
 - w half-width of profile
 - x_e, x_p centroid of error functions / polynomial
 - **c** scaling factor of polynomial trough
 - ▶ n order of polynomial



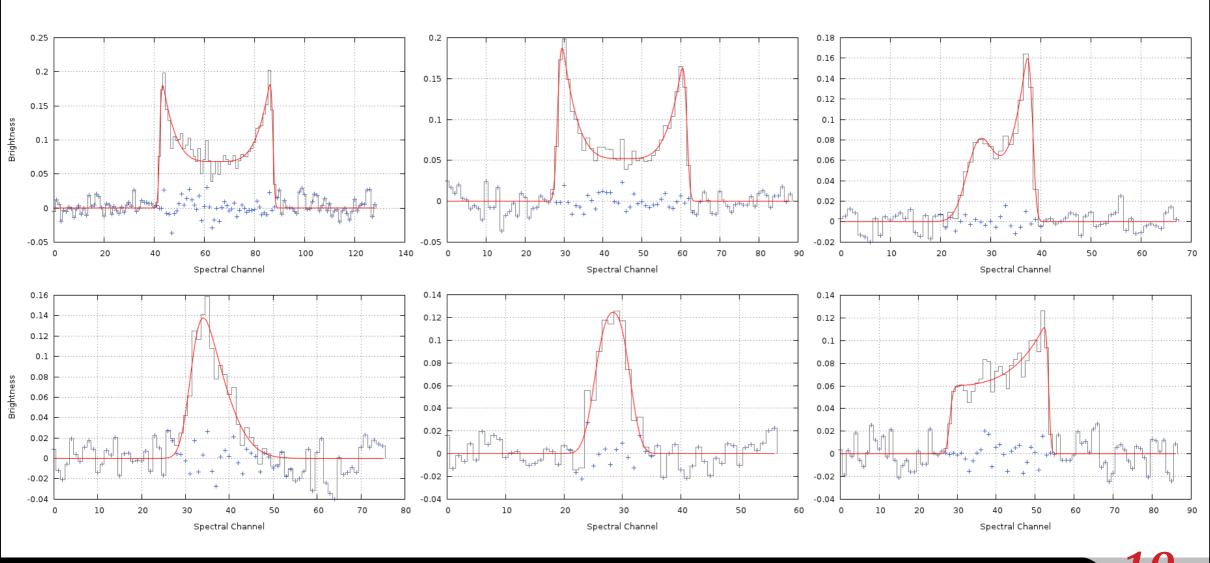


- ★ Properties of the Busy Function:
 - ► Very versatile; can mimic various shapes:
 - Double-peaked
 - Flat-topped
 - Gaussian









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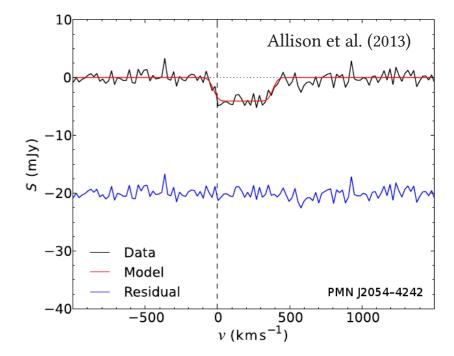
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- ★ Parametrisation of galaxies in large surveys
 - Advantage of fitting over 'direct' parametrisation:
 - Less sensitive to noise peaks \rightarrow more accurate for spectra of low *S*/*N*.
 - Covariance matrix \rightarrow calculation of statistical uncertainties.
 - Decomposition of confused sources possible.



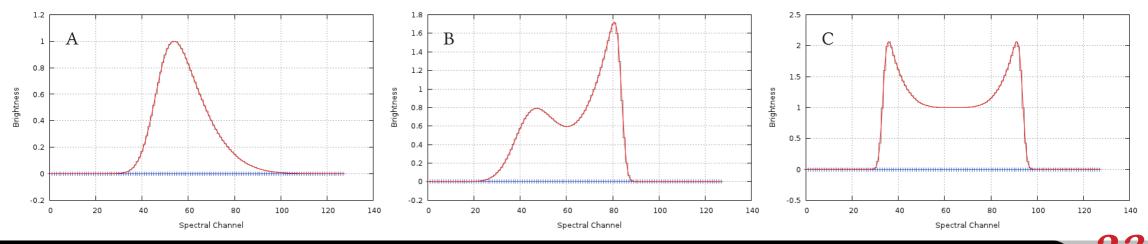
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 - Decomposition of confused sources possible.
- ★ Generation of mock profiles
 - ► Potential use:
 - Simulations / mock data cubes.
 - Filters for matched filtering techniques in source finding.
- ★ Applications beyond HI emission
 - ► HI stacking and absorption
 - ► CO spectra





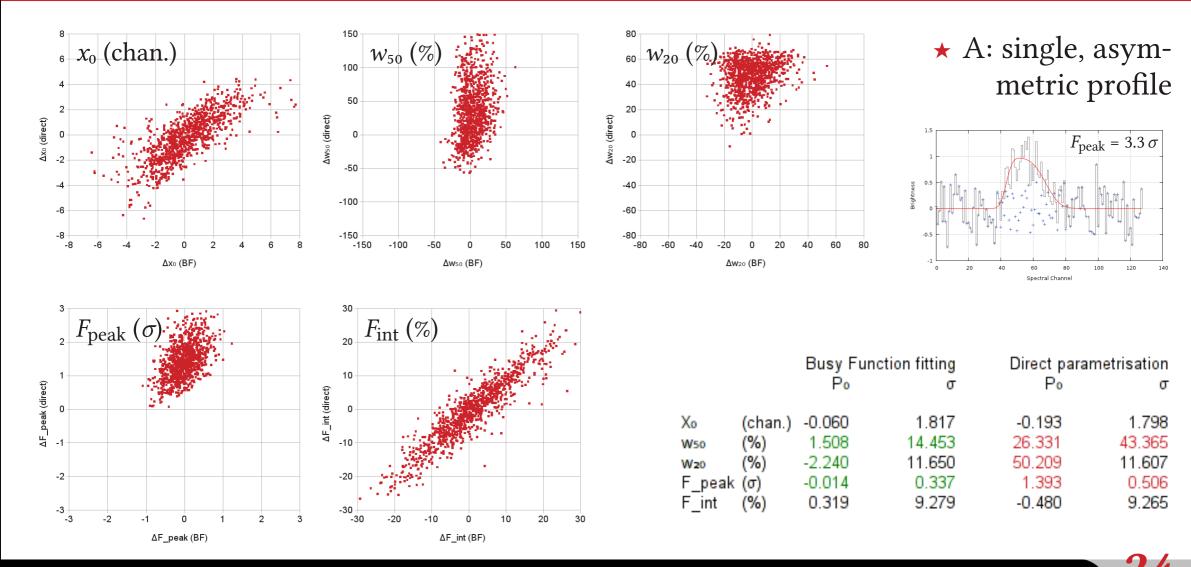


- ★ Systematic testing on model spectra
 - ► Generation via Busy Function models.
 - ► Three scenarios:
 - A: single, asymmetric profile
 - B: asymmetric double-horn profile
 - C: broad, symmetric double-horn profile
 - ▶ 1000 iterations with Gaussian noise added.
 - Galaxy parameters (w_{50} , w_{20} , F_{int} , etc.) derived numerically from BF parameters.



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120

140

 σ

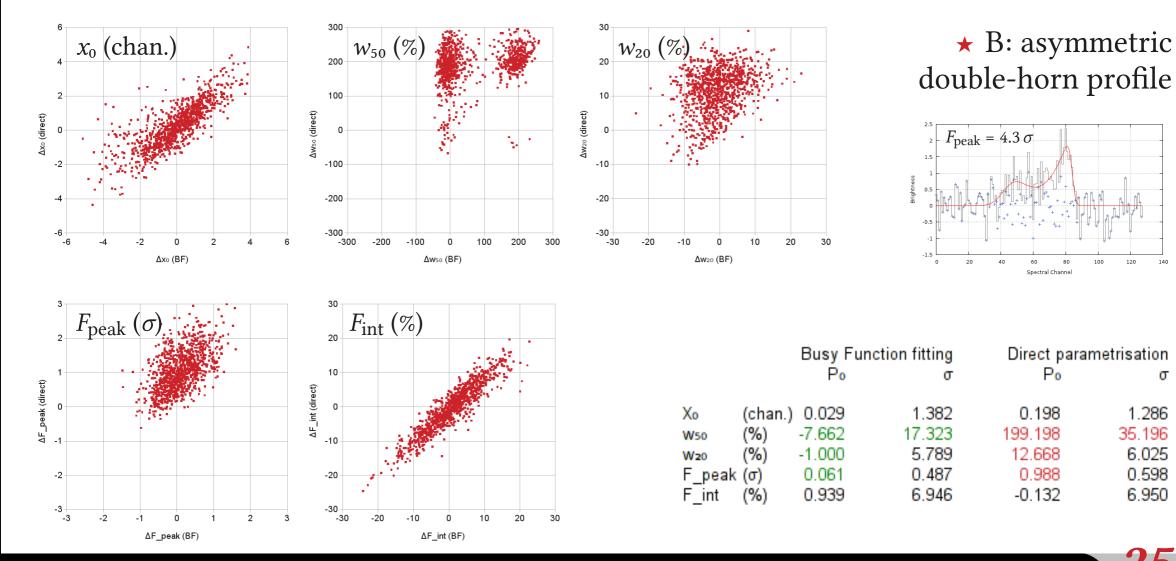
1.286

35.196

6.025

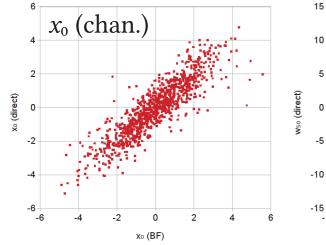
0.598

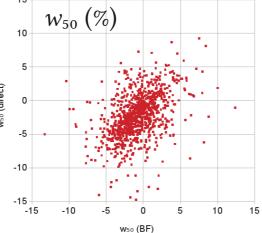
6.950

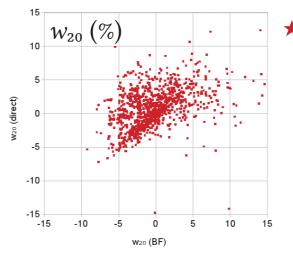


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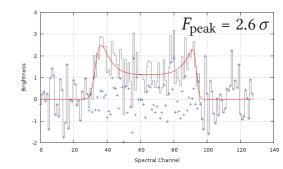




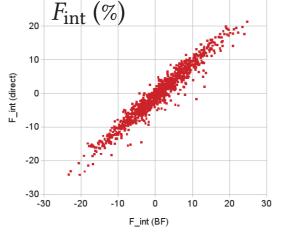




★ C: broad, symmetric double-horn profile



$_{2}$ F_{peak}	ak (σ)		2	F_{in}	t (%
1				0	
	27		F_int (direct)	0	
1			.= 	0	
-2			-2	0	
-3 -2	-1 0	1 2	-3	0 -30 -2	20



20

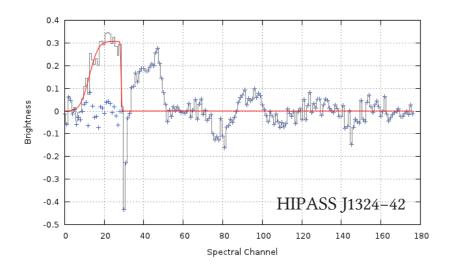
		Busy Fu	nction fitting	Direct parar	netrisation
		Po	σ	Po	σ
Xo	(chan.)	0.027	1.607	0.013	1.643
W50	(%)	-0.950	2.312	-2.294	3.046
W20	(%)	-1.115	2.989	0.633	2.841
F_peak	(σ)	0.365	0.391	1.531	0.468
F_int	(%)	1.152	7.866	0.194	7.957

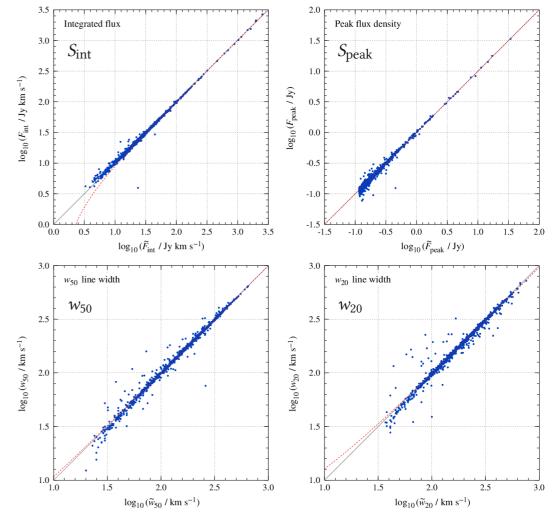


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- ★ Example: HIPASS Bright Galaxy Catalogue (Koribalski et al. 2004)
 - Automated fitting of all 1000 BGC sources.
 - ► Basic parametrisation based on fit.
 - Parameters: v_{0} , w_{50} , w_{20} , S_{peak} , S_{int} .







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★ Example: HIPASS Bright Galaxy Catalogue		Line w	width (w_{20}))			
		orig	ginal	,	I = 5	S/N	T = 3
(Koribalski et al. 2004)		direct	BF fit	direct	BF fit	direct	BF fi
Ctratarian	best-fit slope	0.96	0.96	0.90	0.87	0.89	0.8
► Strategies:	best-fit intercept $(\mathrm{km}\mathrm{s}^{-1})$	8.7	5.6	62.2	39.4	94.9	83.
"Direct" E tion according	within 5% of cat. $(\%)$	94.0	86.0	34.6	47.7	20.7	26.
 "Direct" vs. Busy Function parametrisation. 	within 10% of cat. $(\%)$	94.6	93.2	53.0	68.1	36.8	45.
• Different <i>S</i> / <i>N</i> : original, 5, and 3.	within 25% of cat. $(\%)$	96.7	97.9	72.2	82.0	56.7	65.
• Different 5710. original, 5, and 5.		Integrate	ed flux (F	$_{\rm int})$			
★ Conclusions:		orig	ginal	S/N	I = 5	S/N	T = 3
		direct	BF fit	direct	BF fit	direct	BF fi
Cononally accurate resource of relayer	best-fit slope	1.02	1.03	0.96	1.05	0.92	1.0°
Generally accurate recovery of galaxy	best-fit intercept $(Jy km s^{-1})$	-1.08	-1.35	2.01	-1.02	4.49	0.1
parameters from Busy Function fit.	within 5% of cat. $(\%)$	89.8	83.3	35.8	37.1	22.3	23.
parameters nom busy runction m.	within 10% of cat. (%)	96.9	95.5	65.6	66.9	42.5	43.
Ducy Function much many accurate them	within 25% of cat. (%)	98.9	99.1	93.2	91.4	77.4	76.4
 Busy Function much more accurate than 	F	eak flux o	lensity (F	$_{ m peak})$			
'direct' method for low <i>S</i> / <i>N</i> .		orig	ginal	S/N	I = 5	S/N	T = 3
		direct	BF fit	direct	BF fit	direct	BF fi
No difference for bright sources	best-fit slope	1.00	0.99	1.14	1.04	1.27	1.09
$(\rightarrow$ special case of peak flux).	best-fit intercept (Jy)	0.00	0.00	-0.01	-0.01	0.01	0.0
$(\rightarrow$ special case of peak mux).	within 5% of cat. $(\%)$	99.0	68.6	21.9	28.3	5.4	18.
No difference for integrated floor	within 10% of cat. $(\%)$	99.2	88.0	43.3	54.5	14.7	32.
No difference for integrated flux.	within 25% of cat. (%)	99.7	99.1	86.3	91.9	47.1	72.3



BF fit

0.8083.7 26.545.465.0

BF fit

BF fit

1.090.0018.132.872.2

1.070.1423.243.276.4



Calculation of Uncertainties

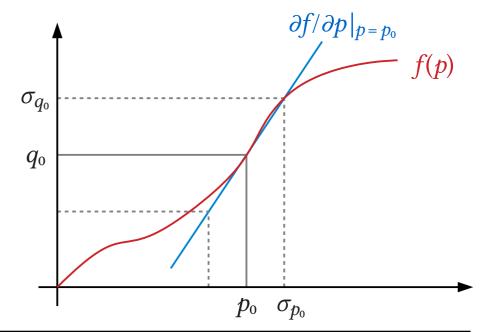


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Calculation of Uncertainties

- \star Linear propagation of covariance matrix
 - ► Assumptions:
 - Parameter vector, \vec{p} , and covariance matrix, $C_{\vec{p}}$, from Busy Function fit.
 - Derived parameters given by differentiable function, $\vec{q} = \vec{f}(\vec{p})$.
 - Jacobian matrix of $\vec{f}(\vec{p})$:
 - $\mathcal{J}_{ij} = \partial f_j / \partial p_i \approx [f_j(\vec{p} + \varepsilon_i \hat{e}_i) f_j(\vec{p})] / \varepsilon_i$
 - ► Error propagation law:
 - $C_{\vec{q}} = \mathbf{J} \cdot C_{\vec{p}} \cdot \mathbf{J}^{\mathrm{T}}$
 - ► Advantages:
 - Full covariance matrix "for free".
 - No analytic form of $\vec{f}(\vec{p})$ required.



Parameter	Value	Uncert. par. var.	Uncert. err. prop.	Difference (per cent)
Centroid	30.164	0.1216	0.1213	-0.25
w_{50}	51.612	0.08452	0.08648	2.32
w_{20}	53.485	0.1303	0.1245	-4.45
F_{peak}	0.348	0.004646	0.005157	11.00
$\dot{F_{ m int}}$	9.618	0.07491	0.07485	-0.08

Results of test on NGC 3351.



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★ BusyFit

- ► Stand-alone software.
- ► Requirements:
 - Written in C++ using GSL.
 - Should run on all Linux/Unix systems (e.g. Ubuntu, Mac OS).
- ► Features:
 - Reads spectrum from text file.
 - Automatic or manual determination of initial parameters.
 - Calculation of uncertainties.
 - Plotting of results using gnuplot.
- ► Download & instructions:

- 1 **2** # 0.4 0.35 0.3 0.25 Brightnes File Edit View Bookmarks Settings Help 0.2 terations completed: 10 0.15 Status: success 0.1 hi^2/dof = 1.071 0.05 -0.05 70 10 20 30 80 Spectral Channe -10.0853, 0.362781 [chan] 0.06808 13.94 [chan] 0.1404 [chan] 16.24 ± 0.1689 [flux] 0.3601 ± 0.007476 [flux × chan] 4.364 ± 0.0530 VARNING: Calculation of parameter uncertainties is experimental /home/BusyFit> BusyFit : tcsh
- http://www.atnf.csiro.au/people/Tobias.Westmeier/tools_software_busyfit.php





★ BFfit

- ► Written by Russell Jurek.
- ► C/C++ library with Python wrapper.
- ► Requirements:
 - Written in C/C++.
 - Needs cfitsio, cpgplot, and OpenMP.
- ► Features:
 - Variable number of free parameters based on Akaike Information Criterion.
 - Uses random initial parameters; no initial estimates needed.
 - Makes use of multiple CPU cores.
 - Comes with **Python** wrapper.
- ► Download & instructions:
 - http://code.google.com/p/busy-function-fitting/

Russell:tcsh
File Edit View Bookmarks Settings Help
1. Creating model with 10 1 3 1 6 0 5 2. 2. Adding noise using 0 0. Fitting Busy Function Initialising fit params to: 8 -99 0.8 -99 2 -99 1.5 -99 7 -99 0 -99 5.15 -99 2.2 -99 -99 Trying: fit mode 1 Generating start seeds 0 25 50 75 100%
: : : : : **********
Using 8 threads across 8 cores Applying LVM to start seeds 0 25 50 75 100% : : : :
best_NOp = 4 Trying: fit mode -2 Using existing LVM starting seeds Using 8 threads across 8 cores Applying LVM to start seeds 0 25 50 75 100%
: : : : **********



★ SoFiA

- ► Source Finding Application for HI data cubes.
- ► Shiny graphical user interface (GUI).
- ► Easy creation of parameter files.
- ► Perfect desktop integration, e.g. Linux/KDE.

	Σ	🔷 SoFiA - SoFiA	A.par											
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	The	following s	sources have	been detecte	ed: [1,	2, 3, 4]								
		SoFiA: Para	ametrising so	urces										
						2, 3, 41 Parametrisation Output Filter Output ASS_2/Sculptor/testcube.fits Select								
					75%									
							n Output Filter Output /testcube.fits Select							
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		nput files ——												
		Data cube:	westmei/Docu	iments/Data/H	IIPASS/H	 IPASS_2/Sculptor/testcub	e.fits							
		Weights cube:	[I]							
							Jtput Filter Output							
		Mask cube:					Select							
_X_MAX	BBOX_X_MIN	BBOX_Y_MIN	BBOX_Y_MAX	BBOX_Z_MIN	F_PE									
218	1	1	186	0	68									
113	109	62	66	5	0.10									
45	30	134	146	33										
48	27	63	82	0	2.9									
1.01	172	27	25	15	0.10									

	Y	х	Z	BBOX_X_MAX	BBOX_X_MIN	BBOX_Y_MIN	BBOX_Y_MAX	BBOX_Z_MIN	F_P
1	169.56	4.60556	174.081	218	1	1	186	0	68
2	63.322	110.392	93.5043	113	109	62	66	5	0.10
3	139.368	35.5851	384.863	45	30	134	146	33	
4	72.463	38.2929	289.663	48	27	63	82	0	2.9
5	31.5236	177.433	28.4248	181	173	27	35	15	0.10
6	96.1879	21.8414	74.5967	29	11	91	103	69	0.11
7	113.961	133.288	70.4341	136	130	110	117	29	0.1
8	78.7868	164.42	140.766	168	161	75	83	62	0.2
9	106.027	151.044	193.526	158	145	100	113	122	1.3
10	112.521	91.1216	150.207	96	86	107	117	134	0.1
11	119.716	51.0129	257.61	55	46	115	124	240	0.12
12	137.042	26.9309	298.998	29	25	134	141	290	0.11
◀									• •
Sor	t by ID	-					C P	Reload 🙆	Close



SoFiA - Source Catalogue



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30	Pipeline Messages
/Perth 2013/test cat.xml	red
Innut	Input Filter Course Finding Mercine Decomptrication Output Filter Output
Input Input files	Input Filter Source Finding Merging Parametrisation Output Filter Output
	Input Filter Source Finding Merging Parametrisation Output Filter Output Data cube: p/Perth_2013/test.fits Select

3	F_FLAC	BF_Z	BF_CHI2	BF_F_PEAK	BF_W	F_TOT	BF_A	BF_C	F_INT	ELI
1	0	97.9193	37151.5	6586.17	0.75132	35933.6	6894.24	0.0482438	3.2279e+07	1
2	0	115.384	0.00175181	1.63078	1.56122	5.19457	1.66098	0	4666.26	1
3	0	114.064	2.56043e-13	4.4431	1.01494	9.0203	3.65361	0.352635	8102.9	-9
4	0	116.071	0.0110477	3.02953	1.81495	10.9177	3.06555	0	9807.32	-5
5	0	119.111	0.111913	8.84835	1.21237	22.2854	9.65191	0	20018.9	3
6	0	311.889	0.145602	3.09424	11.6834	56.4074	1.84916	0.00705344	50670.6	-9
7	0	296.766	0.000310432	1.0406	1.55386	3.36796	1.0945	0	3025.43	-1
8	0	327.283	0.30998	4.39429	11.6795	68.0602	1.23268	0.0233805	61138.2	-4
9	0	318.569	0.212662	4.01454	11.9508	78.5644	2.40617	0.00723815	70574.1	-8
10	0	311.721	0.0192765	2.02308	6.34653	24.8724	1.85868	0.00377484	22342.8	-5
11	0	317.892	0.00803409	2.54834	2.12709	19.7449	2.43076	0.17628	17736.7	-
12	0	326.989	4.71226e-14	1.27303	1.04266	2.88436	1.09246	0.389879	2591.01	-8
13	0	332.4	0.00913109	1.59382	6.04252	14.0958	0.757855	0.0417614	12662.2	9

Dwingeloo, 18 March 2014



/Users/attila/Documents/Work/ASKAP/

SoFiA - user input.tx

Pipeline Message

★ SoFiA

- ► Source Finding Application for HI data cubes.
- ► Shiny graphical user interface (GUI).
- ► Easy creation of parameter files.
- ► Perfect desktop integration, e.g. Mac OS X.
- ★ Download SoFiA
 - ► Current stable version: 0.2.1
 - https://github.com/SoFiA-Admin/SoFiA
 - ► SoFiA *wiki* and *bug reports* also available on GitHub.
 - Work in progress!

				Pipeline fin:	ished with exit	code 0.						
					Input	Input Filter	Source Findin	g Merging	Parametrisation	Output F	ilter Output	
				Input fi	les							
					Data cube: y/Perth_2013/test.fits Select Weights cube: Mask cube: Select							
X.												
0					SoFiA - Sour	rce Catalogue						
	F_FLAC	BF_Z	BF_CHI2	BF_F_PEAK	BF_W	F_TOT	BF_A	BF_C	F_INT	ELL		
1	0	97.9193	37151.5	6586.17	0.75132	35933.6	6894.24	0.0482438	3.2279e+07	19		
2	0	115.384	0.00175181	1.63078	1.56122	5.19457	1.66098	0	4666.26	1:		
3	0	114.064	2.56043e-13	4.4431	1.01494	9.0203	3.65361	0.352635	8102.9	-9.		
4	0	116.071	0.0110477	3.02953	1.81495	10.9177	3.06555	0	9807.32	-5!	C	
5	0	119.111	0.111913	8.84835	1.21237	22.2854	9.65191	0	20018.9	38		
6	0	311.889	0.145602	3.09424	11.6834	56.4074	1.84916	0.00705344	50670.6	-9.		
7	0	296.766	0.000310432	1.0406	1.55386	3.36796	1.0945	0	3025.43	-1:		
8	0	327.283	0.30998	4.39429	11.6795	68.0602	1.23268	0.0233805	61138.2	-4:		
9	0	318.569	0.212662	4.01454	11.9508	78.5644	2.40617	0.00723815	70574.1	-8.		
	0	311.721	0.0192765	2.02308	6.34653	24.8724	1.85868	0.00377484	22342.8	-58		
	0	317.892	0.00803409	2.54834	2.12709	19.7449	2.43076	0.17628	17736.7	-:		
		326.989	4.71226e-14	1.27303	1.04266	2.88436	1.09246	0.389879	2591.01	-80		
~	0	332.4	0.00913109	1.59382	6.04252	14.0958	0.757855	0.0417614	12662.2	9.		
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Summary & Conclusions

Dwingeloo, 18 March 2014





Summary & Conclusions

★ Busy Function:

- Simple analytic function for describing different galaxy HI profiles.
- ► Applications:
 - Automated fitting and parametrisation of galaxies.
 - Profiles for simulations/matched filtering.
- ► Testing on models and HIPASS data:
 - Much more accurate than "direct" parametrisation method, in particular for w_{50} , w_{20} , and S_{peak} of faint sources.
- ► Uncertainties from covariance matrix.
- ► Software:
 - **BusyFit** (stand-alone software by *T. Westmeier*)
 - **BFfit** (C/C++/Python library by *R. Jurek*)
 - SoFiA (source finder, includes Busy Function fitting)

The busy function: a new analytic function for describing the integrated 21-cm spectral profile of galaxies

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ABSTRACT

Accurate parametrization of galaxies detected in the 21-cm H1 emission is of fundamental importance to the measurement of commonly used indicators of galaxy evolution, including the Tully-Fisher relation and the HI mass function. Here, we propose a new analytic function, named the 'busy function', that can be used to accurately describe the characteristic doublehorn H1 profile of many galaxies. The busy function is a continuous, differentiable function that consists of only two basic functions, the error function, erf(x), and a polynomial, $|x|^n$, of degree n > 2. We present the basic properties of the busy function and illustrate its great flexibility in fitting a wide range of H1 profiles from the Gaussian profiles of dwarf galaxies to the broad, asymmetric double-horn profiles of spiral galaxies. Applications of the busy function include the accurate and efficient parametrization of observed H I spectra of galaxies and the construction of spectral templates for simulations and matched-filtering algorithms. We demonstrate the busy function's power by automatically fitting it to the H1 spectra of 1000 galaxies from the HI Parkes All-Sky Survey (HIPASS) Bright Galaxy Catalog, using our own c/c++ implementation, and comparing the resulting parameters with the catalogued ones. We also present two methods for determining the uncertainties of observational parameters derived from the fit.

Key words: line: profiles - methods: data analysis - radio lines: galaxies.

1 INTRODUCTION

Observations of the 21-cm emission line of neutral hydrogen provide measurements of several important parameters of galaxies, including their redshift, mass and rotational velocity, as well as evolutionary indicators such as the Tully-Fisher relation (Tully & Fisher 1977) and the H1 mass function (Zwaan et al. 1997). While highresolution H1 maps have been obtained for several hundred nearby galaxies using radio interferometers, the vast majority of catalogued H r properties of galaxies has been extracted from integrated spectra obtained with single-dish telescopes. Over the next decade, H1 surveys with the Square Kilometre Array (SKA; Dewdney et al. 2009) and some of its precursor and pathfinder instruments, such as Australian Square Kilometre Array Pathfinder (ASKAP; DeBoer et al. 2009) and Apertif (Oosterloo et al. 2009), will probe larger volumes of space to much greater depth than ever before. As a result, the number of H1-detected galaxies is expected to rise from currently 230000 (HYPERLEDA; Paturel et al. 2003) to more than half a million galaxies predicted for the planned all-sky surveys Widefield

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ASKAP *L*-band Legacy All-sky Blind surveY (WALLABY) and Westerbork Northern Sky HI Survey (WNSHS; Duffy et al. 2012). Yet, even in interferometric surveys like WALLABY, 95 per cent of all expected detections will be less than three beams across (assuming a beam size of 30 arcsec) and hence only marginally resolved, highlighting the importance of accurate parametrization methods based on the integrated H1 spectrum.

Integrated H1 line profiles encode much physical information. For example, (i) the frequency centroid of the H1 line measures the cosmological redshift plus peculiar motion of the galaxy, (ii) the integral of the H1 line provides a direct measure of the total H1 mass (Roberts 1962), (iii) the linewidth traces the projected circular velocity of the galaxy and hence its dynamical mass (Casertano & Shostak 1980) and (iv) the small-scale structure of the line profile encodes information on turbulent motion and warps (Sancisi 1976). Furthermore, the shape of the H1 line depends on disc asymmetries (Baldwin, Lynden-Bell & Sancisi 1980), extraplanar gas (Swaters, Sancisi & van der Hulst 1997; Heald et al. 2011), tidal tails and companions. Finally, observational settings, such as spectral resolution and noise level, also affect observed H1 lines. The efficient extraction of all this information from thousands of noisy H1 spectra requires a quick and accurate parametrization method



Thank You!

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