Lectures on radio astronomy: 3

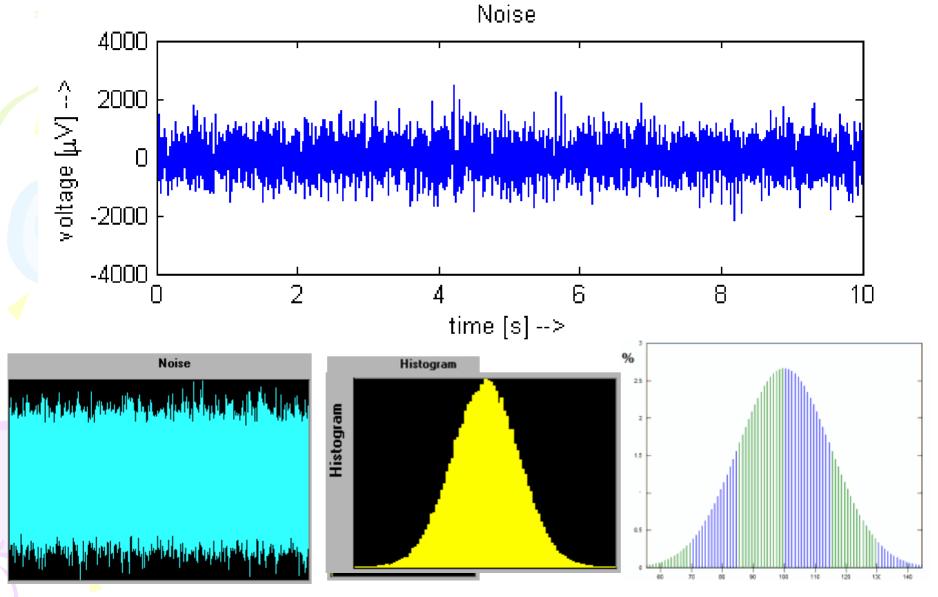
Richard Strom NAOC, ASTRON and University of Amsterdam

Receivers & noise

Signal we want (from sky) has unfortunate properties:

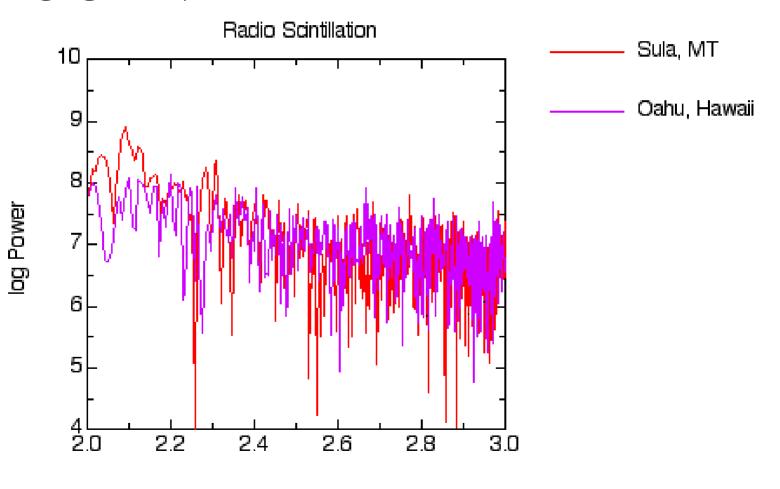
- Its statistical characteristics are just those of noise, indistinguishable from other background noise (from the ground, atmosphere, receiver, etc.)
- It is usually much weaker than other sources (ground, receiver, etc.)
- Detecting it requires top technology, and a lot of clever tricks also

An example of noise



Noise from solar pulse (spectrum)

Log-Log Power Spectra Solar Pulse March 26, 2002 20:23Z



log Frequency (mHz)

Telescope receiver system: essential elements –

- Sensitivity
- Tunable frequency
- Total (instantaneous) bandwidth
- Frequency channels/resolution
- Stability of output signal
- Dynamic range

Also useful are simplicity, ease of operation & maintenance, flexibility

Receiver sensitivity issues

- Choose low-noise components nowadays often FET/HEMTs; can be cooled (even to <4 K) for less thermal noise
- Minimize effect of lossy components (cables, connectors, atmosphere, filters): loss of -0.1 dB (= 2.3%, or factor 0.977) will add 2.3% × 290 K
 = 7 K to system noise. So, short cables, cooled filters, etc. before amplifier

Troposphere significant for $\lambda < 10$ cm; solutions?

- Get above troposphere (mm telescopes are on mountains); go into space?
- Observe at high elevation. Atmospheric effect depends on thickness. Looking at zenith angle z (z=0° is straight up) increases thickness (and effect) by sec z
- Observe from dry site effect is mainly due to water vapor in troposphere
- Observe short λ when weather's good

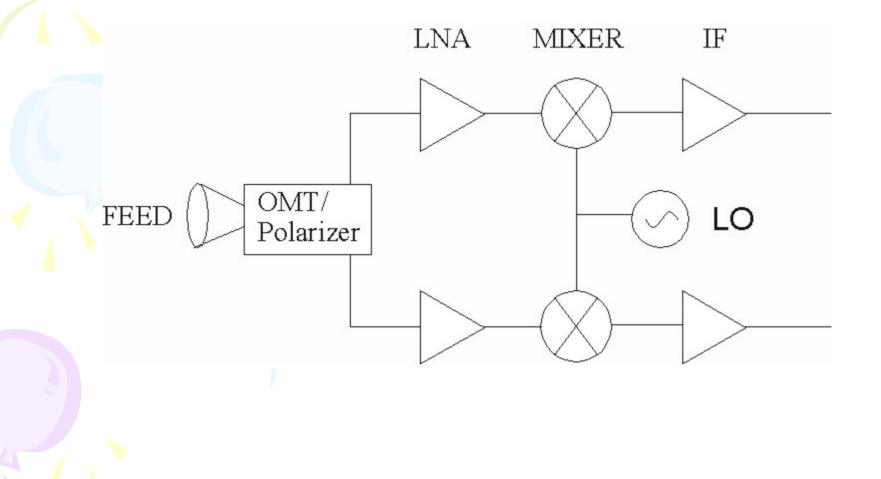
Telescopes like 15 m SEST: high (2500 m) and dry site



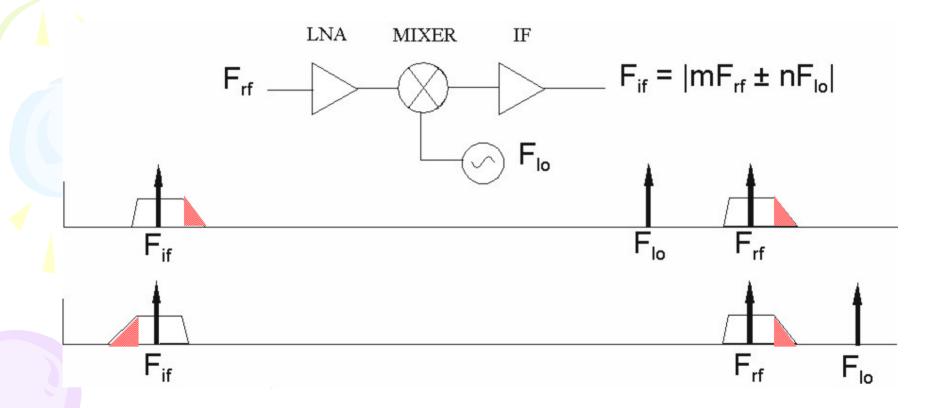
Frequency requirements of radio astronomy receivers

- Should be able to (quickly) tune to any frequency band
- Within that band, may want to have many channels over some range (line observations)
- For continuum, maximum possible bandwidth gives greatest sensitivity (includes more signal)

Structure of a typical superheterodyne receiver



Mixer used for frequency conversion of signal: $F_{rf} \Rightarrow F_{if}$



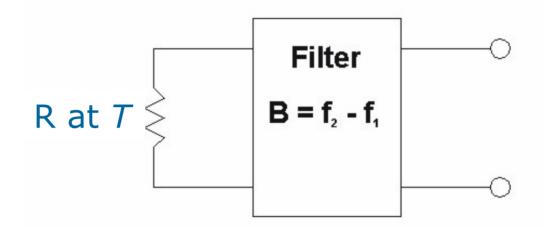
Mathematics of the superheterodyne system

- Basic idea is to multiply together signals of two different frequencies
- From the trigonometric identity: sinf₁ sinf₂ = ½cos(f₁ - f₂) - ½cos(f₁ + f₂)
- The result of multiplying 2 sinusoidal signals together is signals at the sum and difference frequencies; the latter gives us an intermediate frequency: $f_{\rm IF} = |f_{\rm sky} - f_{\rm LO}|$

Features of the superheterodyne system

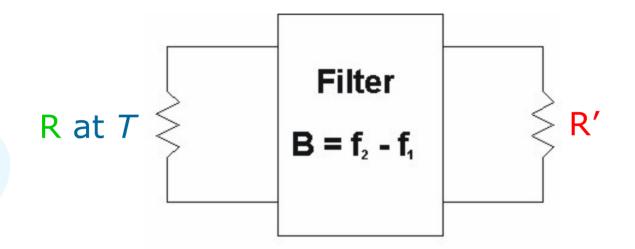
- A local oscillator (LO) signal is mixed with sky signal: converts sky to intermediate frequency (f_{IF})
- In general, 2 sky frequencies (upper and lower sidebands) are produced; may not be desirable, so filter one out if not wanted
- The same IF system can be used for different antenna signals

Power in noise signal: thermal voltage fluctuations



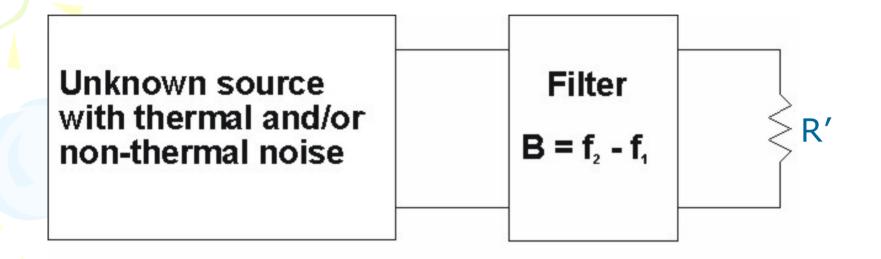
After filtering, voltage at right-hand output can be written: V²_{rms} = 4kTR∫x/(e^x - 1) df ; x = hf/kT
For x « 1, V²_{rms} = 4kTR (f₂ - f₁)

Available noise power



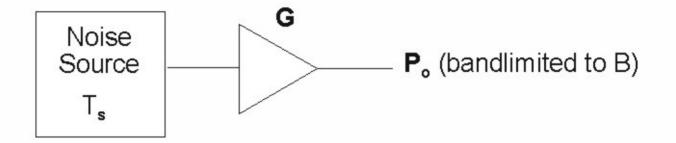
- The signal from resistor R, at temperature T, is filtered and limited to a bandwidth, B $(= f_2 f_1)$
- The resulting signal in resistor R' has a power, P_n = BkT

In a similar way, we can determine equivalent noise



- In a similar setup, we filter the signal from an unknown source
- From the power in resistor R', we can calculate: $T_s = P_n/kB$

What is the equivalent noise of the amplifier?



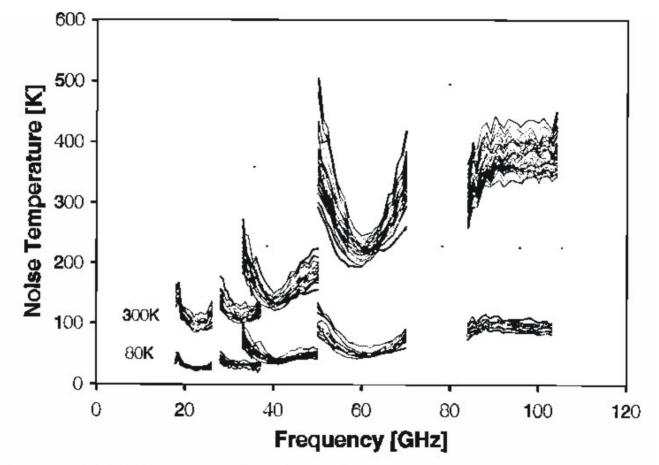
 $P_o = GkBT_s + K$

Define K = GkBT_e

Then, $P_o = GkB(T_s + T_e)$

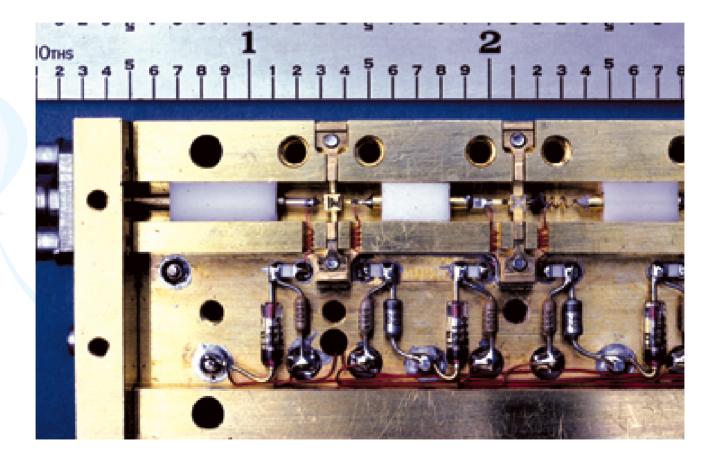
T_e is the amplifier Equivalent Input Noise Temperature

HFET noise temperature

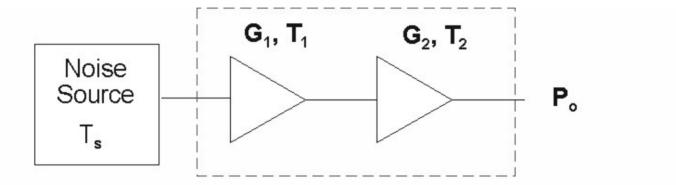


Data courtesy M. Pospieszalski of NRAO Central Development Laboratory

HFET (HEMT) Low Noise Amplifier (LNA)



What is the noise contribution of amplifiers in series?



 $\mathbf{P}_{o} = \mathbf{G}_{1}\mathbf{G}_{2}\mathbf{k}\mathbf{B}\mathbf{T}_{s} + \mathbf{G}_{1}\mathbf{G}_{2}\mathbf{k}\mathbf{B}\mathbf{T}_{1} + \mathbf{G}_{2}\mathbf{k}\mathbf{B}\mathbf{T}_{2}$

or,

 $P_{o} = G_{1}G_{2}kB (T_{s} + (T_{1} + T_{2}/G_{1}))$

So, Amplifier Cascade has equivalent noise T₁ + T₂/G₁

Example of receiver temperature calculation

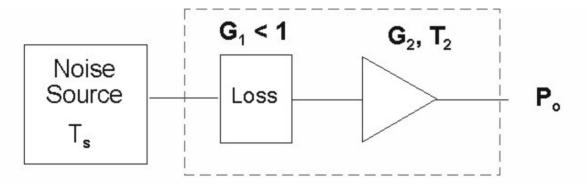
Receiver system, 3 amplifiers: 1, 2 & 3

- T₁=50 K, G₁=20 dB (=100×)
- T₂=300 K, G₂=10 dB (=10×)
- $T_3 = 500 \text{ K}$

 $T_N = 50 \text{ K} + 300 \text{ K}/100 + 500 \text{ K}/(10 \times 100)$ = 50 K + 3 K + 0.5 K = 53.5 K

So we see, 1st amplifier has greatest effect.

Noise contribution of input loss



Let L = $1/G_1$, then for ohmic loss at physical temperature T_o ,

the effective noise temperature of the loss is $(L-1)T_{o}$.

Effective noise temperature of the loss - amplifier cascade

The lesson, when designing a receiver, is...

- Put a low noise amplifier (LNA) with high gain ($G \ge 20 \text{ dB}$) at front
- Avoid any losses before the LNA (so, keep cables short, or use waveguide; avoid filters if possible, or cool them; keep atmospheric loss low – choose a good site)
- Noise from lossy element after LNA gets divided by LNA gain (G₁)

Final noise determined by T_N , bandwidth, duration

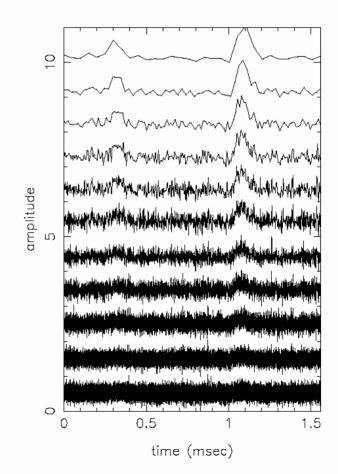
$$\sigma = \frac{T_N}{\sqrt{\Delta f \times \tau}}, \text{ where } \Delta f \text{ is bandwidth,}$$

and τ is integration time

 σ is the final (rms) noise, to be compared with source signal strength

Here is an example of time integration in practice

- Observation of pulse from ms pulsar
 PSR1937+21
- Integration time increases by 2× each step from bottom
- See pulse better, lose some detail
- [frequency smoothing gives similar result]

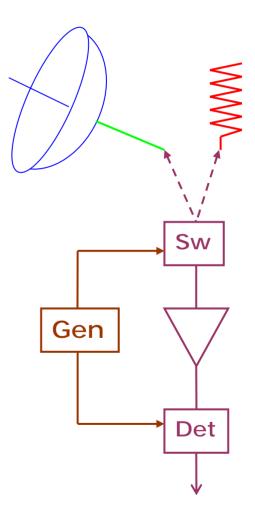


Having sensitivity is useless if stability is poor

- Amplifiers with high gain tend to be less stable
- To keep output stable, often add feedback loop: automatic gain control (AGC)
- Physicist Robert Dicke invented technique: switch to reference noise source, to monitor receiver.

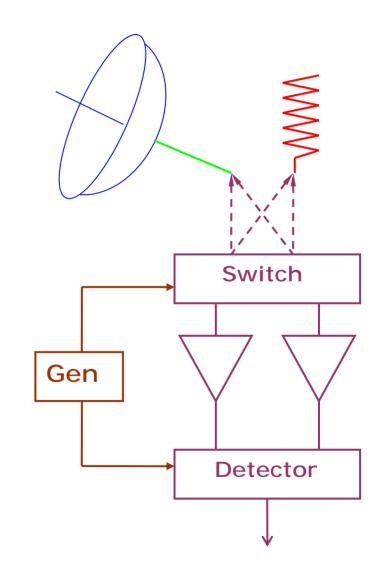
Example of a simple Dicke switch radio telescope

- Generate switching frequency, faster than system drift
- Demodulate at same frequency after detection
- Disadvantage is not all time spent on source: lose some observing time



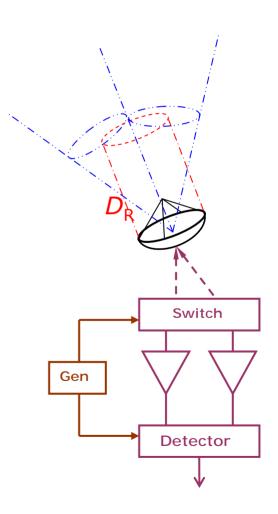
Avoid loss of observing time with two receivers

- Always observing sky and reference
- At end, average two difference signals
- Always need stable reference
- This system costs more (2 channels)

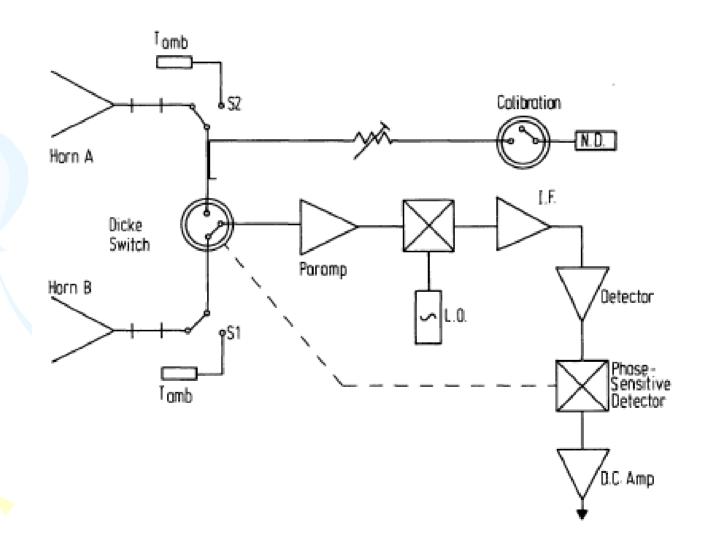


Dicke's technique widely used, in different ways

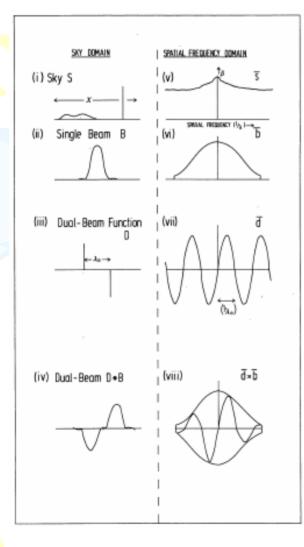
- For example, with two receivers, we can make two beams
- We can point one beam at source, other on empty sky.
- Using Dicke's switch, one beam becomes reference – can "switch out" effect of atmosphere.

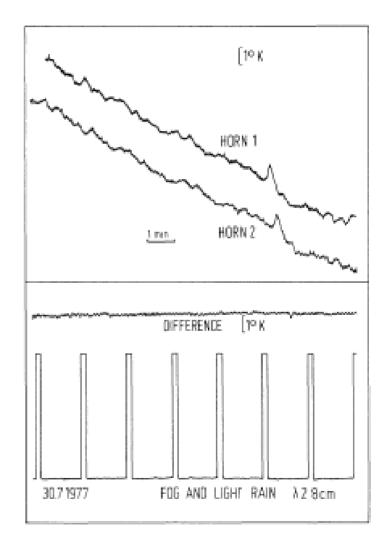


Effelsberg λ2.8 cm system (Emerson et al., 1979)

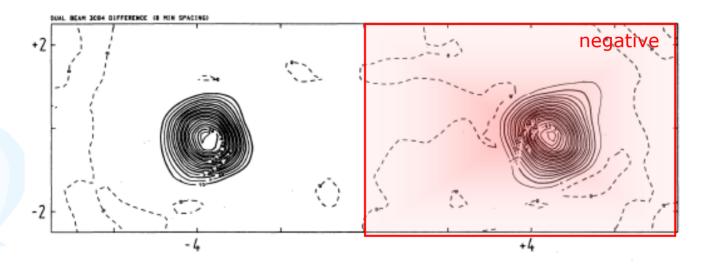


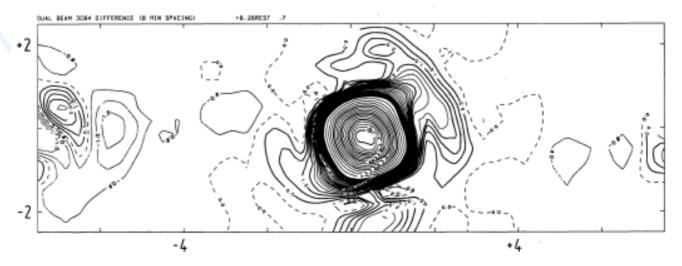
What dual-beam measures & example of data (in fog)





Observation of strong source 3C84: data & result



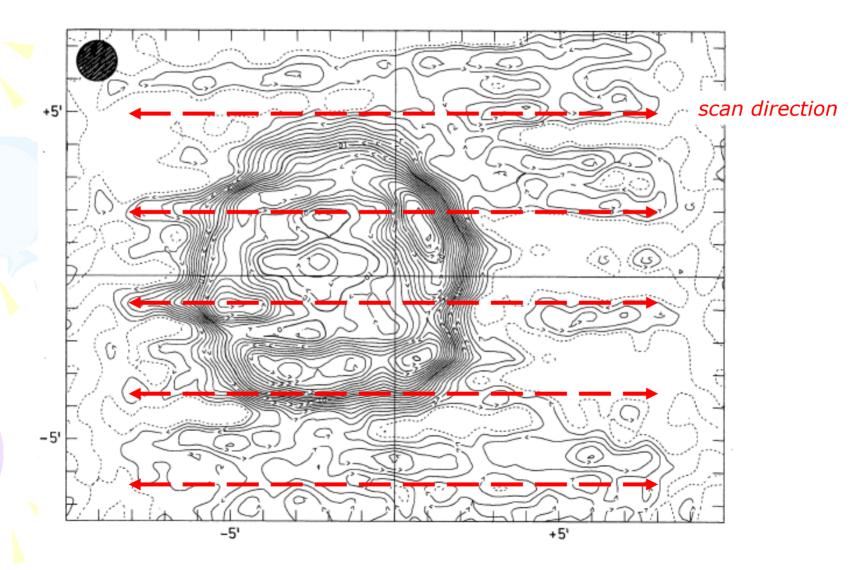


Technique can also be used for mapping extended sources

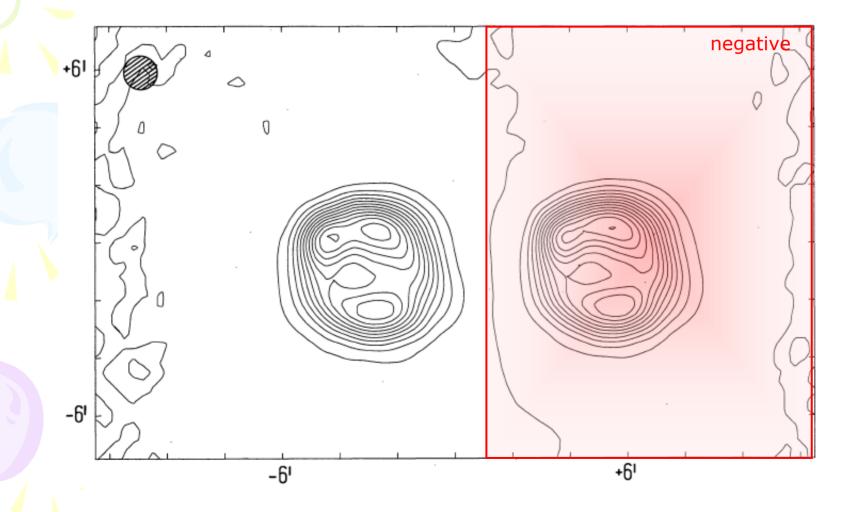
- For Effelsberg dish (100 m diameter)
 observing at λ=2.8 cm
- Rayleigh distance: $D_R \approx D^2/\lambda =$ $100^2/0.028 = 360 \text{ km}$
- Troposphere (where water is) is at 2-3 km altitude, so should be same in both beams



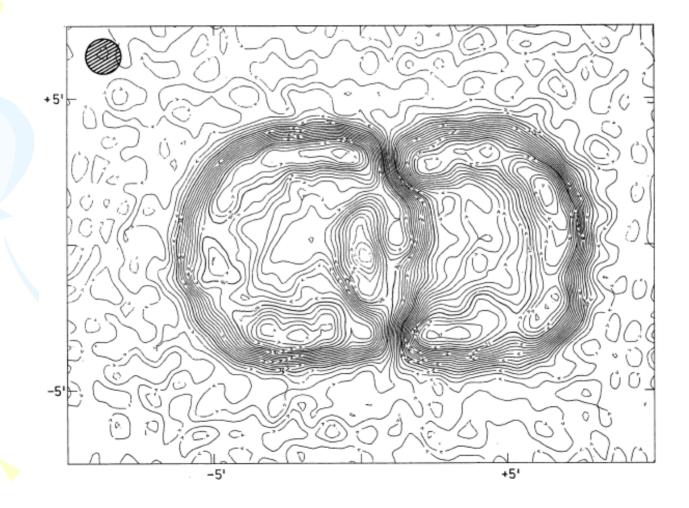
Single-beam map of 3C10, showing effects of atmosphere



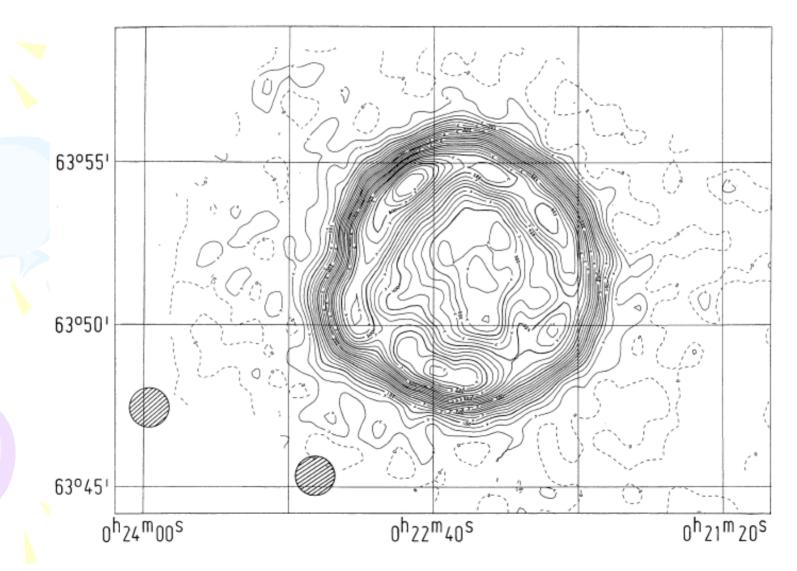
Cas A, beam separation = 8.2' arc: 2 images well separated



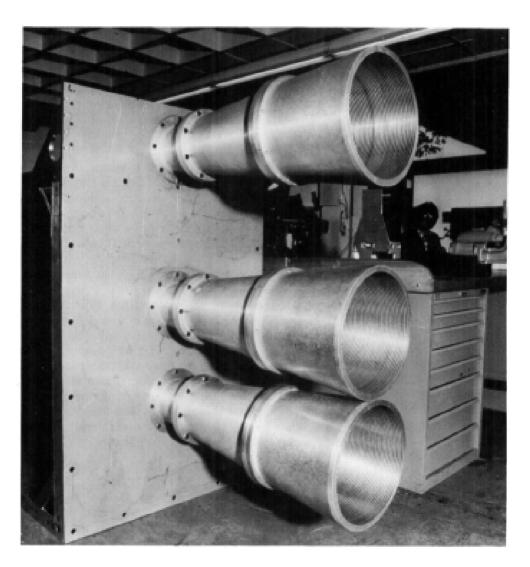
Images not always separated: 3C10, 5.5' arc beam distance



3C10, final map separates and averages two images



Triple-horn system: 3 beams are even better



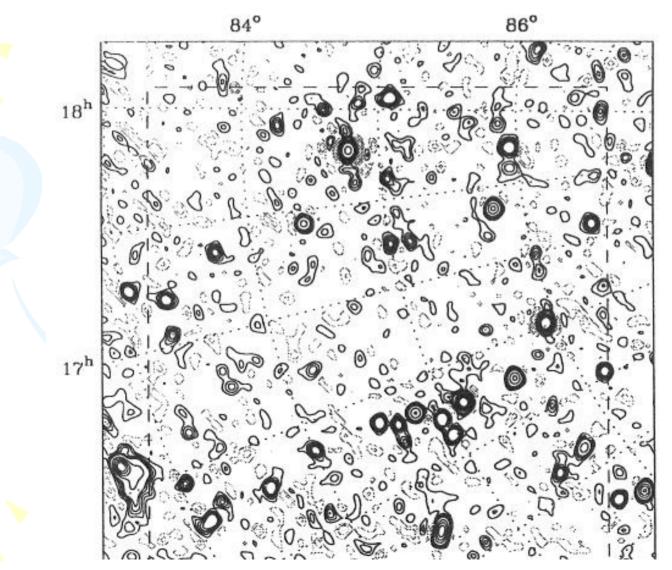
Two final sensitivity issues: polarization and confusion

- If we only observe with one antenna and receiver, we miss half the signal (for unpolarized sources).
- Must also have a second antenna with opposite sense of polarization
- Second antenna must have its own receiver system (so it costs more, but gives better sensitivity by √2)
 ⇒ Why is sensitivity better by √2?

Antenna with one polarization misses half the signal



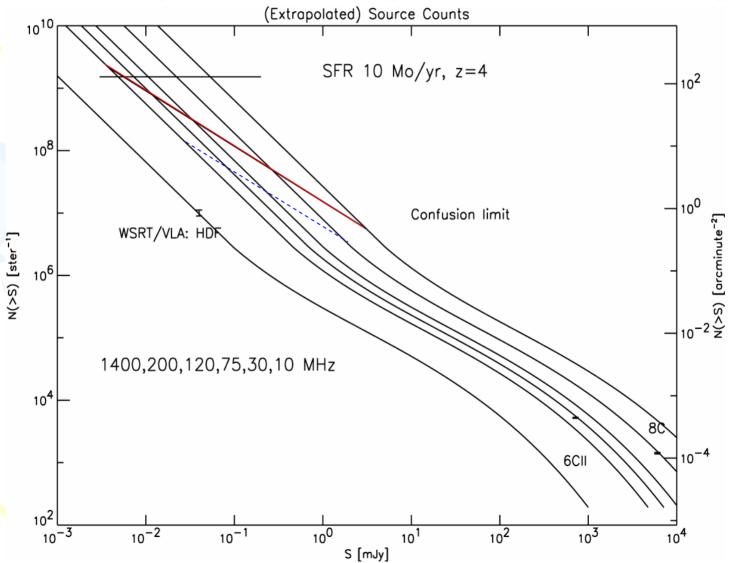
Confusion is where sources (almost) overlap each other



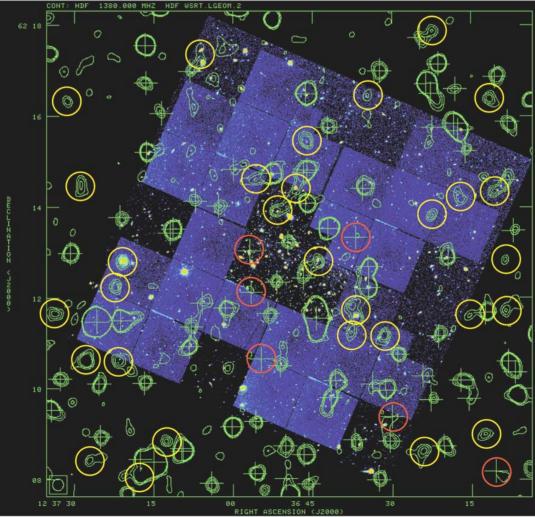
To overcome confusion requires a smaller beam

- Common definition of "confusion level" is 1 source/20 beams
- Source density increases as we go to weaker sources
- To estimate, need source number vs. strength curves (from observations); see next panel
- A more sensitive telescope needs greater angular resolution

Curves showing source density vs. S (flux density)



Hubble Deep Field (HDF), observed by WSRT & VLA



HCTHNUL ALHON ALMOND

Next lecture we will look at interferometers

